

space
a set
is called
following

where

a basis
in then
can be
written
as

is basis
in V
can be
written

by sum
decomposing
then v_1
as v_1

$$av_1 + bv_2 = av_1 + bv_2.$$

$\theta = (c_1, -c_2)$ is also non-zero

$c_1, c_2 \neq 0$ because it

is linearly independent

$$\Rightarrow c_1 \neq 0, c_2 \neq 0$$

$$c_2 = v_2$$

$\Rightarrow c_1 \neq 0$

condition

2) Theorem:

If A & B are invertible matrix
of same size then AB is invertible
and

$$(AB)^{-1} = B^{-1}A^{-1}$$

* Proof:

$$\therefore (AB)(AB)^{-1} = I \quad (I \text{ is identity mat})$$

pre multiplying A^{-1} both side

$$A^{-1}(AB)(AB)^{-1} = A^{-1}I$$

$$(A^{-1}A)B(AB)^{-1} = A^{-1}$$

$$(I)B(AB)^{-1} = A^{-1}$$

$$B(AB)^{-1} = A^{-1}$$

pre multiplying B^{-1} on both sides

$$B \cdot B^{-1}(AB)^{-1} = A^{-1}B^{-1}BA \cdot B^{-1}A^{-1}$$

$$I(AB)^{-1} = A^{-1}B^{-1} \cdot B^{-1}A^{-1} = I \cdot (AB)^{-1} = (AB)^{-1}$$

$$(AB)^{-1} = A^{-1}B^{-1} \cdot B^{-1}A^{-1}$$

A set S with two or more vectors is

- ① linearly dependent if and only if at least one of the vector in S is expressible as a linear combination of the other vector in S .

Proof:

$$\text{Let } S = \{v_1, v_2, \dots, v_n\}$$

Assume that S is linearly dependent.

$k_1 v_1 + k_2 v_2 + \dots + k_n v_n = 0$
(and not all scalars are zero)

Let $k_1 \neq 0$

Divide by each term by k_1

$$v_1 + \frac{k_2}{k_1} v_2 + \dots + \frac{k_n}{k_1} v_n = 0$$

$$v_1 = \left(-\frac{k_2}{k_1}\right) v_2 + \dots + \left(-\frac{k_n}{k_1}\right) v_n$$

In similar manner if $k_2 \neq 0$

$$v_2 = \left(-\frac{k_1}{k_2}\right) v_1 + \dots + \left(-\frac{k_n}{k_2}\right) v_n$$

Conversely
is at least
 S that
in the
combination

$$k_1 = \\ k_2, k_3, \dots, k_n \\ k_1 \neq 0$$

S is

Theorem:
A finite
contain n
dependent

Proof:
for the
 $S = \{v_1, v_2, \dots, v_n\}$
linearly
if v_1, v_2, \dots, v_n are
because
linear
all o

i.e.

b) hold in
is subspace

use the vector
 v is a vector

$$W(-v) = -v + v = 0$$

Linear combination.

W is vector space

$(k_1 v_1 + k_2 v_2 + \dots + k_m v_m)$ is

a linear combination of W

System of homogeneous linear
eqn:

$Ax = 0$ if (Right side is
zero or if left side is zero)

⇒ Theorem -

if $Ax=0$ is a homogeneous linear
system of m equation and
 n -variables then the set of
solution vector is a subspace
of \mathbb{R}^n .

note)

Proof -

let W is the solution set of
system of linear equation of
 m -equation and n -variable

let x and x' be the sol
of $Ax=0$

i.e. $x, x' \in W$

$$Ax=0 \quad \text{①} \quad Ax'=0 \quad \text{②}$$

By add ① and ②.

$$Ax + Ax' = 0 + 0$$

$$x = A^{-1} b$$

To show there is one solution
we have

Let x_0 is solution of
given system.

$$Ax_0 = b$$

$$x_0 = A^{-1} b$$

$$\frac{1}{A^{-1} b}$$

$$Ax = b$$

$$x = A^{-1} b$$

matrix

$n \times n$

basis

y

$$\begin{bmatrix} a_{11} & a_{12} & \dots \\ a_{21} & a_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} =$$

$$\begin{bmatrix} I & | & U \\ 0 & | & V \\ \vdots & | & \vdots \\ 0 & | & W \end{bmatrix}$$

$$x = \\ b = \\ Ax = \\ (A) \\$$

black

side

2-1 22

Theorem 5.1:

let V be a vector space & u a vector in V and k is ~~the~~ a scalar. Then.

- (a) $0u = 0$
- (b) $k0 = 0$
- (c) $(-1)u = -u$
- (d) If $ku = 0$ then $k=0$ or $u=0$.

Proof : (a)

By axiom (8)

$$0u + 0u = (0+0)u$$

$\therefore 0u$ by property of number

By axiom (5)

$$0u + (u + (-u)) = u + (-u)$$

3rd axiom $0u = 0$

$$0u + (u + (-u)) = 0u + (-u)$$

$$\therefore 0u = 0 \quad (\text{By additive identity})$$

(c) Proof

$$(-1)0 = -0$$

We have to prove that $1 + (-1)0 = -0$

$$(-1)0u = 0$$

By axiom (8) we have,

$$\therefore 1 + 0 = 0$$

Taking $(-1)0 + 0$

consider the vector.

$$\vec{i} = (1, 0, 0)$$

$$\vec{j} = (0, 1, 0)$$

$$\vec{k} = (0, 0, 1)$$

$$S = \{ \vec{i}, \vec{j}, \vec{k} \}$$

$$k_1 \vec{i} + k_2 \vec{j} + k_3 \vec{k}$$

$$(k_1, k_2, k_3) = (0, 0, 0)$$

$$k_1 \vec{i} + k_2 \vec{j} + k_3 \vec{k} = 0$$

$\{ \vec{i}, \vec{j}, \vec{k} \}$ is linearly independent

$$v_1 = (1, -2, 3), v_2 = (5, 6, -1),$$

$$v_3 = (3, 2, 1)$$

$$1c_1 v_1 + 1c_2 v_2 + 1c_3 v_3 = 0$$

$$1c_1 (1, -2, 3) + 1c_2 (5, 6, -1) + 1c_3 (3, 2, 1) = 0 \text{ (add)}$$

$$(1c_1 - 2c_2 + 3c_3, 5c_1 + 6c_2 + 2c_3, c_1 - 4c_2 + c_3) = (0, 0, 0)$$

$$1c_1 + 5c_2 + 3c_3 = 0$$

$$-2c_1 + 6c_2 + 2c_3 = 0$$

$$3c_1 - 4c_2 + c_3 = 0$$

rank if
row
column
ident

* Linear combinations

If $v_1, v_2, v_3, \dots, v_n$ are vectors in vector space V .

- (a) The set W of all linear combinations $k_1v_1 + k_2v_2 + \dots + k_nv_n$ is a subspace of V .

* Proof

We have to show that W is subspace of V .

The linear combination of

$$v_1, v_2, \dots, v_n$$

$$k_1v_1 + k_2v_2 + \dots + k_nv_n$$

$$0v_1 + 0v_2 + \dots + 0v_n$$

$$0 \in W$$

$$w = () + ()$$

Let $u, v \in W$

$$u = k_1v_1 + k_2v_2 + \dots + k_nv_n$$

$$v = c_1v_1 + c_2v_2 + \dots + c_nv_n$$

$$u+v = (k_1v_1 + k_2v_2 + \dots + k_nv_n) + (c_1v_1 + c_2v_2 + \dots + c_nv_n)$$

$$(k_1+c_1)v_1 + (k_2+c_2)v_2 + \dots + (k_n+c_n)v_n$$

$$(k_1+c_1) = k'_1$$

$$u+v = k'_1v_1 + k'_2v_2 + \dots + k'_nv_n$$

$$u+v \in W$$

(b)

Let

$u = 0$

$u+u = u$

$= u$

$\Rightarrow u = 0$

$$k_0u = 0$$

$$k_0u$$

Hence

u .

\therefore

$$S = \{v\}$$

$$W = SP$$

Imp Theorem

if S

g'

two

space

\in span

if

in

S'

\in

★ Real vector space:-

Let V be an arbitrary non empty set with two operation addition (+) and multiplication then following assumption should be.

(i) if $u, v \in V \Rightarrow u+v \in V$.

(ii) $uv = v + u \quad \forall u, v \in V$

(iii) $u + (v + w) = (u + v) + w$

(iv) $\exists 0 \in V \quad u+0 = 0+u = u$.

if true

(v) $u \in V \quad \exists -u$

$u - u = 0 \text{ or } u + u = 0$.

(vi) k be any scalar and $u \in V$.

(vii) $k(u+v) = ku+kv$.

(viii) $(k+m)u = ku+mu$

(ix) $(km)u = (km)u$.

(x) $1 \cdot u = u$.

Check whether the vector $V =$

$\{(x, y, z) \in \mathbb{R}^3 : 2x+3y^2-4z^2=0\}$ is a

vector space or not.

$(2, 0, 1), (8, 0, 2) \in V$

* Basis:-

If V is any vector space and $S = \{v_1, v_2, \dots, v_n\}$ is a set of vectors in V then S is called a basis for V if following four conditions are satisfied:

- (1) S is linearly independent.
- (2) S spans V .

If $S = \{v_1, v_2, \dots, v_n\}$ is a basis for a vector space V , then every vector v in V can be expressed in the form $v = c_1v_1 + c_2v_2 + \dots + c_nv_n$ in exactly one way.

* Proof:-

Since given that S is basis of V . It means S spans V by definition.

So every vector in V can be expressed as linear combination of vectors of S .

On contrary we say that we can write in two ways,
 $c_1v_1 + c_2v_2 + \dots + c_nv_n$
 $= d_1v_1 + d_2v_2 + \dots + d_nv_n$

Op ①

$a \in C(A, B)$
where
is linear
as $C(A, B)$

- $C_m \times C_n$
 $C_m \times C_n$

* Theorem:-

If $A \in C_m \times n$
is same
and
 $(AB)^{-1}$

* Proof:-

$\therefore (AB)^{-1}$
pre mult
 $A'(AB)$
 $(A'A)B$
 $(I)B$
 $B^{-1}A$
pre mult
 $B \cdot B^{-1}$
 $I(AB)$
 $(AB)^{-1}$

AP - 3

* show that
 $(A^T)^{-1} = A$

Solv:
 $A(A^T) = I$

Post multiplying $(A^T)^{-1}$ on L.S.

$$(AA^T)(A^T)^{-1} = I(A^T)^{-1}$$

$$I(A^T(A^T)^{-1}) = (A^T)^{-1}$$

$$A(I) = (A^T)^{-1}$$

$$A = (A^T)^{-1}$$

Part 2 Proof

If A is an invertible $n \times n$ matrix
then for each $n \times 1$ matrix b ,
the system of eq. $Ax=b$ has
exactly one solution namely
 $x = A^{-1}b$.

* Proof:

$$A(A^{-1}b) = b$$

$\Rightarrow x = A^{-1}b$ is a
solution of $Ax = b$.

$$Ax = b$$

Since A is non singular
pre multiplying A^T both side

$$A^T(Ax) = A^Tb$$

$$(A^TA)x = A^Tb$$

$$\because A^TA = I \quad Ix = A^Tb$$

$$x = A^Tb$$

To sh
we h
let
given
 A
 x

$$w(x) = f_1(x) + f_2(x) + \dots + f_n(x)$$

$$= f'_1(x) + f'_2(x) + \dots + f'_n(x)$$

$$= f''_1(x) + f''_2(x) + \dots + f''_n(x)$$

$$\vdots$$

$$= f_1^{(n)}(x) + f_2^{(n)}(x) + f_n^{(n)}(x)$$

$$f_1(x) = x, \quad f_2(x) = e^x, \quad f_3(x) = e^{2x}$$

$$w(x) = \begin{vmatrix} x & e^x & e^{2x} \\ 1 & e^x & 2e^{2x} \\ 0 & e^x & 4e^{2x} \end{vmatrix}$$

$$= x \begin{vmatrix} e^x & e^{2x} \\ e^x & 4e^{2x} \end{vmatrix} - 1 \begin{vmatrix} x & e^{2x} \\ 0 & 4e^{2x} \end{vmatrix} + 0$$

$$= x(4e^{2x} - 2e^{3x}) - 1(4e^{2x} - e^{3x})$$

$$= x(2e^{2x}) - 1$$

$$f_1(x) = 1, \quad f_2(x)$$

$$w(x) = \begin{cases} 1 & x \\ 0 & \text{else} \end{cases}$$

$$= 1 \left(\frac{4e^{3x}}{4e^{3x}} - \right.$$

$$= 2e^{3x}$$

if x is not linearly independent

$$f_1(x) = x$$

$$w(x) = \begin{cases} x & \\ 1 & \end{cases}$$

$$w(x) = x e$$

if $x = 0$ is else if

7 Proof:

if each vector in S is a linear combination of s
 $\text{Span } S \subseteq \text{Span } s$

$$\text{Span}(w_1, w_2, \dots, w_k) \subseteq \text{Span}(v_1, v_2, \dots, v_n)$$

if each vector in S' is linear combination of s .
 $\text{Span } S' \subseteq \text{Span } s$.

$$\text{Span}(w_1, w_2, \dots, w_k) \subseteq \text{Span}(v_1, v_2, \dots, v_n)$$

$$\text{Span } S' = \text{Span } s.$$

Conversely assume that

$$\text{Span } S = \text{Span } S'$$

if $v_i = a_1w_1 + a_2w_2 + \dots + a_kw_k$
for all scalars a_1, a_2, \dots, a_k .

Let $v_i \in \text{Span}(S)$ but $v_i \notin \text{Span}(S')$.

$$k_1v_1 + k_2v_2 + \dots + k_nv_n = 0.$$

$$\text{if } (k_1, k_2, \dots, k_n) \neq 0$$

it is linearly independent if
and iff $(k_1, k_2, \dots, k_n) = 0$
it is linearly dependent

consider the

$$i = (1, 2, 0, 0)$$

$$j = (0, 1, 0, 0)$$

$$k = (1, 0, 0, 0)$$

$$S = \{i, j\}$$

$$k_1i + k_2j$$

$$(k_1, k_2, 0, 0)$$

$$(k_1, 0, k_2, 0)$$

is

$$v_1 = (1, -2, 3)$$

$$v_3$$

$$k_1v_1 + k_2v_3$$

$$k_1(1, -2, 3)$$

$$(k_1, -2k_1, 3k_1)$$

$$k_1 + 5k_2 + 3k_3$$

$$-2k_1 + 6k_2$$

$$3k_1 = 1k_2 +$$

WVFC-102

(full) v

o u

o

+ subspace:-

If W is a set of one or more vectors from a vector space V, then W is a subspace of V if and only if the following conditions hold:

a) If u and v are vectors in W, then $u+v$ is in W

b) if k is any scalar and u is any vector in W, then ku is in W

+ Proof:-

Suppose that W is subspace if

V let $u, v \in W$

Since W is subspace then

$\Rightarrow u+v \in W$ (a fulfill)

if k is any scalar and

$u \in W$

$\therefore W$ is subspace

then $ku \in W$ (b fulfill))

Exercise 5.1

Assume that α & β hold we have to prove that W is subspace of V .

Let $U, W \in W$

$\Rightarrow U, V \in V$ (by using a).

(i) Let $U \in W$

$U + V = V + U$ (becz U, V are the vector from V and V is a vector space).

(ii) $U, V, W \in W$

$U + V + W = (U + V) + W$,

④ by part (i)

$\therefore U + V \in W$

Takeing $b = 0$

$bU \in W \quad : bU = 0$ (Because).

$0 \in W$.

So we can write

$U + 0 = 0 + U = U$.

Let $U, V \in W$

by part b,

$U + V \in W$

$b = -1$

$-1 \cdot U \in W$

By theorem.

$-1 \cdot U = -U$

$-U \in W$

Linear & Polynomial

Conversely assume that there is at least one vector in S that can be written in the form of linear combination of other vectors.

$$v_1 = c_1 v_2 + c_2 v_3 + \dots + c_n v_n$$

$$v_2 = c_1 v_1 + c_3 v_3 + \dots + c_n v_n$$

$$c_1 = 1, c_2 = -c_1, c_3 = -c_2, \dots, c_n = -c_{n-1}$$

$$\dots = c_{n-1} = -c_n$$

S is linearly dependent

Theorem

A finite set of vectors that contain the zero vector is linearly dependent.

Proof:

for the vectors v_1, v_2, \dots, v_n

$S = \{v_1, v_2, \dots, v_n, 0\}$ is

linearly dependent.

$$0v_1 + 0v_2 + 0v_3 + \dots + 1 \cdot 0 = 0$$

because 0 is written in linear combination in which all scalar are not zero.

$$f_1(x)$$

$$f_2(x)$$

$$f_3(x)$$

$$f_n(x)$$

$$w(x) = e^{nx}$$

x

x²

x³

x⁴

x⁵

x⁶

x⁷

x⁸

x⁹

x¹⁰

x¹¹

x¹²

x¹³

x¹⁴

x¹⁵

x¹⁶

x¹⁷

x¹⁸

x¹⁹

x²⁰

x²¹

x²²

x²³

x²⁴

x²⁵

x²⁶

x²⁷

x²⁸

x²⁹

x³⁰

x³¹

x³²

x³³

x³⁴

x³⁵

x³⁶

x³⁷

x³⁸

x³⁹

x⁴⁰

$$f_1(x) = 1 \quad f_2(x) = e^x \quad f_3(x) = e^{2x} \quad \dots$$

$$W(x) = \begin{vmatrix} 1 & e^x & e^{2x} \\ x & e^x & 2e^{2x} \\ 1 & e^x & 4e^{2x} \end{vmatrix}$$

$$= 1(4e^{3x} - 2e^{3x})$$

$$= 4e^{3x} - 2e^{3x}$$

$$= 2e^{3x}$$

If ans is not zero, it is linearly independent.

$$f_1(x) = x, \quad f_2(x) = \sin x$$

$$W(x) = \begin{vmatrix} x & \sin x \\ 1 & \cos x \end{vmatrix}$$

1 mark

$$W(x) = x \cos x - \sin x$$

If x=0 it is linearly dependent
else it is linearly independent

(3)

$$14x + 6y = 9$$

$$2 = 2x + 6y$$

$$18 = 2x + 12y$$

$$2 = 2x + 6y$$

$$16 = 6y$$

$$6y = 16 \Rightarrow y = 2$$

$$2 = 2x + 6(2)$$

$$2 = 2x + 12$$

$$2 - 12 = 2x$$

$$-10 = 2x \Rightarrow x = -5$$

$$w = -3U + 2V$$

$$(9, 2, 7) \in S$$

dim of UAV

not linear

UAV

$$z = -3 + 14(6, 2, 2)$$

$$z = -3 + 6(2, 2, 2)$$

$$z = -3 + 12, z = 9$$

Result: v
is new

is new

$$Bx = 0$$

x is 0 in basis

$$BAx = 0$$

$$A(BAx) = 0$$

is in EW

w is subspace of \mathbb{R}^n .

* linear combination

U(1, 2, -1)

V(6, 4, 2) $\in \mathbb{R}^3$

Show that w = (9, 2, 7) is
linear combination of U & V

w(4, -1, 3) is not linear
combination of U & V.

QED

$$w = k_1 U + k_2 V$$

$$(9, 2, 7) = k_1(1, 2, -1) + k_2(6, 4, 2)$$

$$= (k_1 + 2k_2, 2k_1 + 4k_2, -k_1 + 2k_2)$$

$$(9, 2, 7) = (k_1 + 6k_2, 2k_1 + 4k_2, -k_1 + 2k_2)$$

∴

$$k_1 + 6k_2 = 9$$

$$2 = 2k_1 + 4k_2$$

$$18 = 2k_1 + 4k_2$$

$$2 = 2k_1 + 4k_2$$

$$16 = 8k_2$$

$$k_2 = 2$$

$$9 = k_1 + 6$$

$$9 = k_1 + 12$$

$$9 - 12 = 12$$

$$k_1 = -3$$

$$w = -3U +$$

?

\mathbb{R}^n is a vector space.

A Vector Space is 2×2 matrices.

$$U = \begin{bmatrix} U_{11} & U_{12} \\ U_{21} & U_{22} \end{bmatrix} + V = \begin{bmatrix} V_{11} & V_{12} \\ V_{21} & V_{22} \end{bmatrix}$$

$$U + V = \begin{bmatrix} U_{11} + V_{11} & U_{12} + V_{12} \\ U_{21} + V_{21} & U_{22} + V_{22} \end{bmatrix}$$

A plane through origin is a vector space.

$$ax + by + cz = 0.$$

Check whether the vectors.

$$V = \{x, y, z \in \mathbb{R}^3 : 2x + 3y - 4z = 0\}.$$

$$\text{let } U = (2, 0, 1), \quad V = (8, 0, 2).$$

$$U + V = (10, 0, 3).$$

$$= 2(10) + 3(0) - 4(3)^2$$

$$= 20 + 0 - 36$$

$$= -16 \neq 0$$

$$V = \{(a, b, c) \in \mathbb{R}^3 : (a+b)c = 0\};$$

$$U = (3, 0, 2), \quad V = (4, 0, 3)$$

$$U + V = (12, 0, 5)$$

$$(12 + 0)5 = 0$$

$$(12)5 = 0$$

$$60 \neq 0.$$