# MAT292 Notes

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## Contents



# 1 Existence and Uniqueness Theorem

1. We need $f(t, y)$ continuous in the rectangle to get existence
2. We need $f_y(t, y)$ continuous in the rectangle to get uniqueness
3. E & U Theorem is sufficient but not necessary. i.e. these conditions imply solution but not having these conditions doesnt mean there is no solution

# 2 Autonomous Equations and Population Dynamics

## 2.1 Logistic Growth

If uninhibited, we assume exp. growth however in the long run,population is limited to $K$

Model: $y' = rh(y)y$

We want $h(y) \approx 1$ if $y$ is small, $h(y) < 1$ if $y < k$, $h(y) = 0$ if $y = k$ and $h(y) < 0$ if $y > K$

This can thus be modelled as $y' = r(1 - \frac{y}{k})y$. This has two equilibria namely at $y = 0$ and $yk$. The inflection points can be found by setting the derivative $y''$ to 0.

# 3 Direction Fields and Orbits

## 3.1 Reducing non homogeneous systems to homogeneous systems

Lets take a solution $x$ and write it as $x = \phi + v$ where $v$ is a constant. Then $x' = Ax + b \rightarrow \phi = A(\phi + v) + b$. Since $x_{eq} = A^{-1}b$, $Av + b = 0$ by the equilibrium condition $(\phi' - A\phi)$ we have that $\phi' = A\phi$. So that $x = \phi + x_{eq}$ where $\phi$ is a solution of the homogeneous system.

Every solution of the non homogeneous problem can be written as a solution of the homogeneous problem plus the equilibrium.

# 4 Laplace Transform

- Remark: The laplace transform will allow us to reduce solving an ODE to solving an algebraic equation
- Solve algebraic equation and use the inverse laplace transform to get the solution to the ODE
- Definition: If $f$ is defined on $[0, \infty]$, the Laplace Transform is defined as $F(s) = \int_0^\infty e^{-st} f(t)\, dt$
- We write $F = \mathcal{L}\{f\}$
- We use uppercase letters for Laplace transform e.g. $G(s)$ is the LT of $g(t)$
- Example: For $f(t) = e^{at}$, we get $F(s) = \mathcal{L}\{f\}(s) = \int_0^\infty e^{-st} e^{at}\, dt = \lim_{b \to \infty} \int_0^b e^{(a-s)t}\, dt = \lim_{b \to \infty} \frac{1}{a-s}\left(e^{(a-s)b} - 1\right) = \frac{1}{s-a}$ if $s > a$
- $\mathcal{L}\{1\} = \frac{1}{s}$
- Theorem: $\mathcal{L}\{c_1 f_1 + c_2 f_2\} = c_1 \mathcal{L}\{f_1\} + c_2 \mathcal{L}\{f_2\}$
- To find $\mathcal{L}\{\sin(at)\}$, write $\sin(at) = \frac{1}{2i}(e^{iat} - e^{-iat})$ and use the theorem above
- This will give $\frac{1}{2i}\left(\frac{1}{s-ia}\right) - \frac{1}{2i}\left(\frac{1}{s+ia}\right) = \frac{a}{s^2+a^2}$ for $s > 0$
- Example: LT of $f(t) = e^{2t}$ for $0 \leq t < 1$ and $f(t) = 4$ for $1 \leq t$
- Divide the integral into two seperate parts and evaluate it
- Exponential order: A function $f(t)$ is of exponential order for $M > 0$, $K > 0$ and $a \in \mathbb{R}$ if $|f(t)| \leq Ke^{at}$ for $t \geq M$ i.e. $f$ eventually becomes between two exponential functions
- Theorem: Every bounded function is of exponential order
- A function $f(t)$ is piecewise continuous on $[a, b]$ iff there are finitely many "jump points" between $a$ and $b$ $a \leq t_0 < t_1 < \cdots < t_{k-1} < t_k = b$ such that $f$ is continuous on each of the intervals $(t_i, t_{i+1})$ and $f$ has finite limits at the jump points.

- Theorem: If for a function $f(t)$, we have that $f$ is piecewise continuous on $[0, A]$ $\forall A \geq 0$ and $f$ is of exponential order for $M, k$ and $a$. Then $\mathcal{L}\{f\}$ exists for all $s > a$.

- Theorem: If $f(t)$ is of exponential order then we have: $F(s) \to 0$ as $s \to \infty$ where $F(s)$ is the L.T. of $f$

- Theorem: If $f$ is continuous and $f'$ is piecewise continuous on any interval $[0, A]$ and $f, f'$ are of exponential order for $M, k, a$ then $\mathcal{L}\{f'\}(s) = s\mathcal{L}\{f\}(s) - f(0)$ for $s > a$. Under the same conditions for $n$ derivatives, $\mathcal{L}\{f^{(n)}\}(s) = s^n\mathcal{L}\{f\}(s) - s^{n-1}f(0) - s^{n-2}f'(0) - \dots sf^{(n-2)}(0) - f^{(n-1)}(0)$

- Proof: $\mathcal{L}\{f'\}(s) = \int_0^\infty e^{-st}f'(t)\,dt = \lim_{b\to\infty}\left(\int_0^b e^{-st}f'(t)\,dt\right)$

  $= \lim_{b\to\infty}\left([e^{-st}f(t)]_0^b + \int_0^b f(t)se^{-st}\,dt\right) = \lim_{b\to\infty}\left(e^{-bs}f(b) - f(0) + s\int_0^b f(t)e^{-st}\,dt\right)$
  $= s\mathcal{L}\{f\}(s) - f(0)$ where $s > a$ (by definition of exponential order)

# 5 Inverse Laplace Transform

- Theorem: If $f(t), g(t)$ are piecewise continuous and of exponential order, then $\mathcal{L}\{f\} = \mathcal{L}\{g\} \implies f(t) = g(t)$

- Technicality: Take $f(t) = e^t$, $g(t) = \begin{cases} e^t & t \neq 5 \\ 0 & t = 5 \end{cases}$. Clearly $\mathcal{L}\{f\} = \mathcal{L}\{g\}$ but $f(t) \neq g(t)\ \forall t$

- Convention: We write $f(t) = g(t)$ as long as they are the same whenever they are continuous

- Definition: If $f$ is piecewise continuous and of exponential order and $\mathcal{L}\{f\}(s) = F(s)$, then we call $f(t) = \mathcal{L}^{-1}\{F\}(t)$

- There is a complex analysis formula (Mellin Transform) to find $\mathcal{L}^{-1}\{F\}$. However this is rarely used in practice and we instead use tables

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