

Transmission Modes

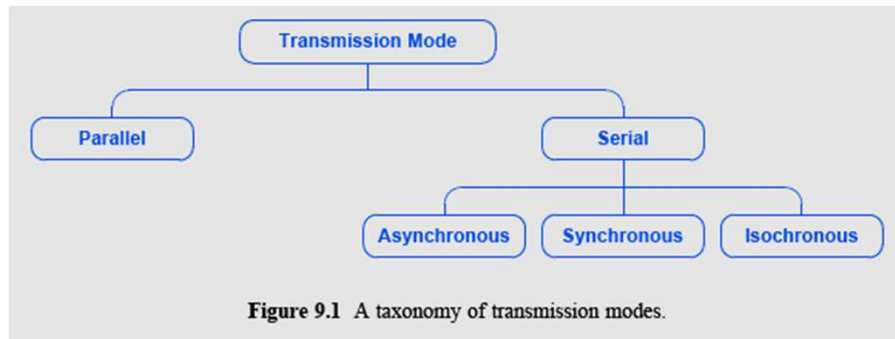
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A Taxonomy of Transmission Modes

- We use the term *transmission mode* to refer to the manner in which data is sent over the underlying medium
- Transmission modes can be divided into two fundamental categories:
- **Serial** — one bit is sent at a time
 - Serial transmission is further categorized according to timing of transmissions
- **Parallel** — multiple bits are sent at the same time
- Figure 9.1 gives an overall taxonomy of the transmission modes discussed in the chapter

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A Taxonomy of Transmission Modes



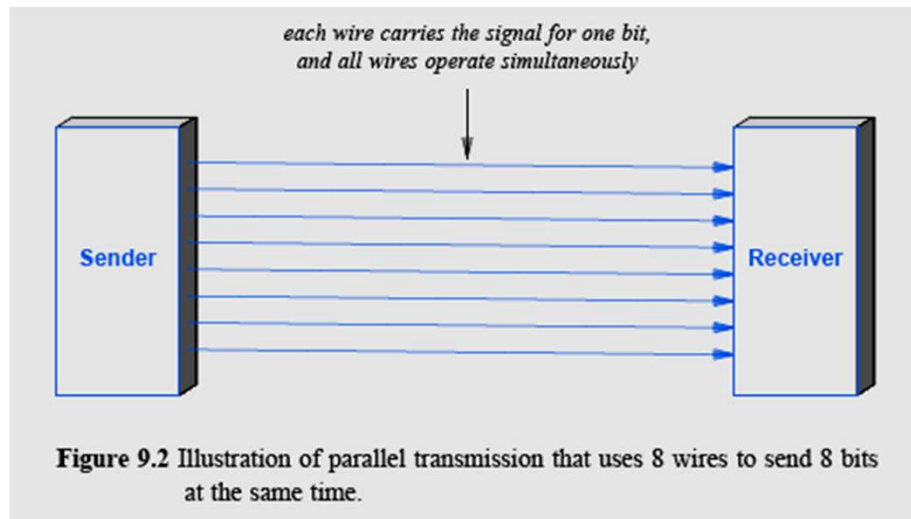
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Parallel Transmission

- **Parallel** transmission allows transfers of **multiple** data bits at the same time over separate media
- In general, parallel transmission is used with a wired medium that uses multiple, **independent wires**
- Furthermore, the signals on all wires are **synchronized** so that a bit travels across each of the wires at precisely the same time
- Figure 9.2 illustrates the concept, and shows why engineers use the term parallel to characterize the wiring

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9.3 Parallel Transmission



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Parallel Transmission

- The figure omits two important details:
 - First, in addition to the parallel wires that each carry data
 - a parallel interface usually contains other wires that allow the sender and receiver to coordinate
 - Second, to make installation and troubleshooting easy
 - the wires for a parallel transmission system are placed in a single physical cable
- A parallel mode of transmission has two chief advantages:
 - **High speed:** it can send **N** bits at the same time
 - a parallel interface can operate **N** times faster than an equivalent serial interface
 - **Match to underlying hardware:** Internally, computer and communication hardware uses parallel circuitry
 - a parallel interface matches the internal hardware well

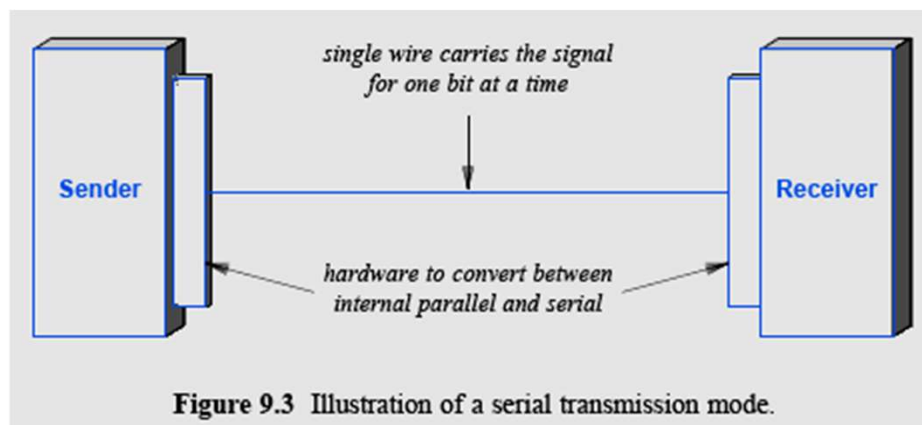
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Serial Transmission

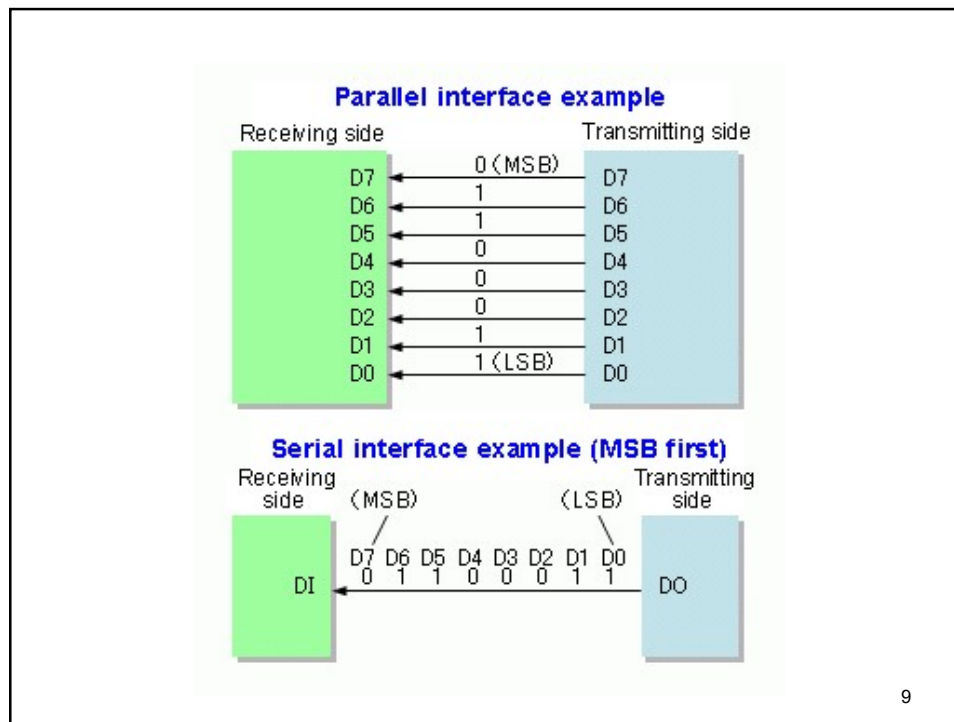
- **Serial** transmission
 - sends one bit at a time
- It may seem that anyone would choose parallel transmission for high speeds
 - However, most communication systems use serial mode
- There are two main reasons
 - First, serial networks can be extended over long distances at much less cost
 - Second, using only one physical wire means that there is never a timing problem caused by one wire being slightly longer than another
- Sender and receiver must contain a hardware that converts data from the parallel form used in the device to the serial form used on the wire
- Figure 9.3 illustrates the configuration

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Serial Transmission



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Serial Transmission

- The hardware needed to convert data between an internal parallel form and a serial form can be straightforward or complex
 - depending on the type of serial communication mechanism
- In the simplest case, a single chip that is known as a **Universal Asynchronous Receiver and Transmitter** (UART) performs the conversion
- A related chip, **Universal Synchronous-Asynchronous Receiver and Transmitter** (USART) handles conversion for synchronous networks

Transmission Order: Bits and Bytes

- In serial mode, when sending bits, which bit should be sent across the medium first?
- Consider an integer: Should a sender transmit
 - the **Most Significant Bit** (MSB)
 - or the **Least Significant Bit** (LSB) first?
- We use the term **little-endian** to describe a system that sends the LSB first
- We use the term **big-endian** to describe a system that sends the MSB first
- Either form can be used, but the sender and receiver must agree

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Transmission Order: Bits and Bytes

- The order in which bits are transmitted does not settle the entire question of transmission order
 - Data in a computer is divided into bytes, and each byte is further divided into bits (typically 8 bits per byte)
 - Thus, it is possible to choose a byte order and a bit order independently
 - For example, Ethernet technology specifies that data is sent byte big-endian and bit little-endian
- Figure 9.4 illustrates the order in which Ethernet sends bits from a 32-bit quantity

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Transmission Order: Bits and Bytes

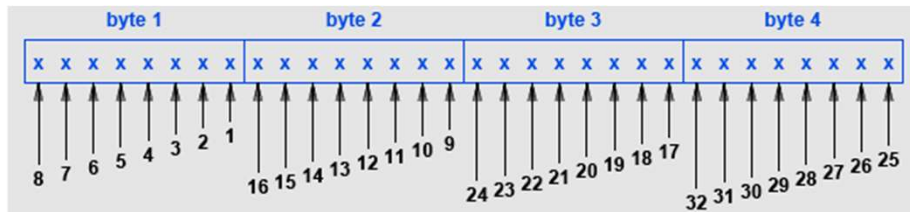


Figure 9.4 Illustration of byte big-endian, bit little-endian order in which the least-significant bit of the most-significant byte is sent first.

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Timing of Serial Transmission

- Serial transmission mechanisms can be divided into three broad categories (depending on how transmissions are spaced in time):
 - **Asynchronous** transmission can occur at any time
 - with an **arbitrary delay** between the transmission of two data items
 - **Synchronous** transmission occurs continuously
 - with **no gap** between the transmission of two data items
 - **Isochronous** transmission occurs at regular intervals
 - with a **fixed gap** between the transmission of two data items

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Asynchronous Transmission

- It is asynchronous if the system allows the physical medium to be **idle** for an arbitrary time between two transmissions
- The asynchronous style of communication is well-suited to applications that generate data at random
 - (e.g., a user typing on a keyboard or a user that clicks on a link)
- The disadvantage of asynchrony arises from the lack of coordination between sender and receiver
 - While the medium is idle, a receiver cannot know how long the medium will remain idle before more data arrives
- Asynchronous technologies usually arrange for a sender to transmit a few **extra bits** before each data item
 - to inform the receiver that a data transfer is starting
 - extra bits allow the receiver to synchronize with the incoming signal
 - the extra bits are known as a **preamble** or **start bits**

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RS-232 Asynchronous Character Transmission

- Consider the transfer of characters across copper wires between a computer and a device such as a keyboard
 - each data item represents one character
- It is standardized by the **Electronic Industries Alliance** (EIA)
 - It has become the most widely used for character communication
 - Known as RS-232-C, and commonly abbreviated **RS-232**
- EIA standard specifies the details, such as
 - physical connection size (max cable length 50 feet long)
 - electrical details (range between -15v +15v)
 - the line coding being used
 - It can be configured to control the exact number of bits per second
 - It can be configured to send 7-bit or 8-bit characters
- Figure 9.5 illustrates how voltage varies at different stages
 - when a start bit, eight bits of a character, and a stop bit are sent

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RS-232 Asynchronous Character Transmission

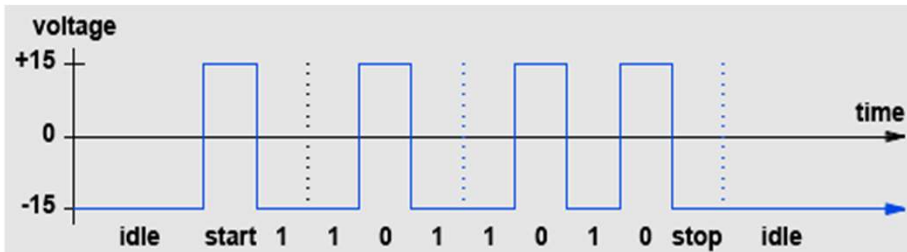


Figure 9.5 Illustration of voltage during transmission of an 8-bit character when using RS-232.

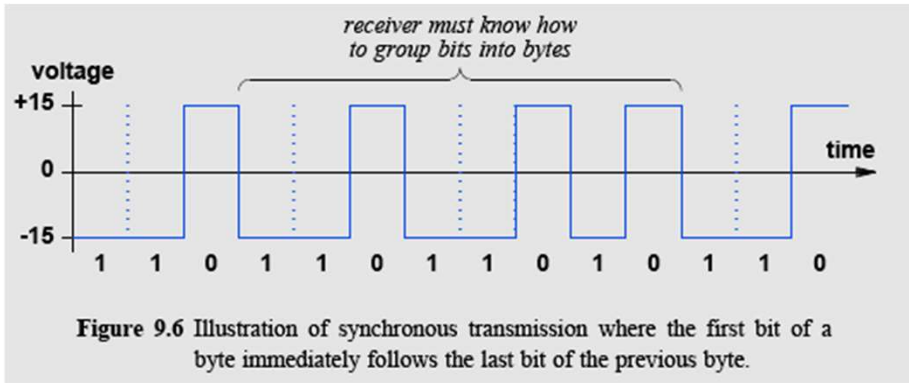
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Synchronous Transmission

- A synchronous mechanism transmits bits of data continually
 - with no idle time between bits
 - after transmitting the final bit of one data byte, the sender transmits a bit of the next data byte
- The sender and receiver constantly remain synchronized
 - which means less synchronization overhead
- Compare the 8-bit characters on
 - an asynchronous system as illustrated in Figure 9.5
 - and a synchronous system as illustrated in Figure 9.6
- Each character sent using RS-232 requires an extra start bit and stop bit
 - meaning that each 8-bit character requires a minimum of 10 bit times, even if no idle time is inserted
- On a synchronous system
 - each character is sent without start or stop bits

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Synchronous Transmission



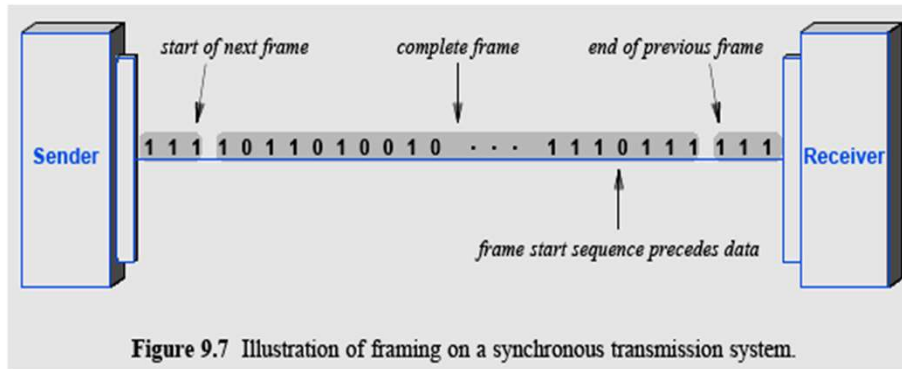
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Bytes, Blocks, and Frames

- If the underlying synchronous mechanism must send bits continually
 - What happens if a sender does not have data ready to send at all times?
 - The answer lies in a technique known as **framing**:
 - an interface is added to a synchronous mechanism that accepts and delivers a block of bytes known as a **frame**
 - To insure that the sender and receiver stay synchronized
 - a frame starts with a special sequence of bits
 - Most synchronous systems include an idle sequence (or idle byte)
 - that is transmitted when the sender has no data to send
- Figure 9.7 illustrates the concept

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Bytes, Blocks, and Frames



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Isochronous Transmission

- Isochronous transmission
 - is designed to provide **steady bit flow** for multimedia applications
- Delivering such data at a steady rate is essential
 - because variations in delay known as **jitter** can disrupt reception (cause pops or clicks in audio/make video freeze for a short time)
- Isochronous network is designed to accept and send data at a fixed rate, **R**
 - Network interface is such that data must be handed to the network for transmission at exactly **R** bits per second
- For example, an isochronous mechanism designed to transfer voice operates at a rate of **64,000** bits per second
 - A sender must generate digitized audio continuously
 - A receiver must be able to accept and play the stream

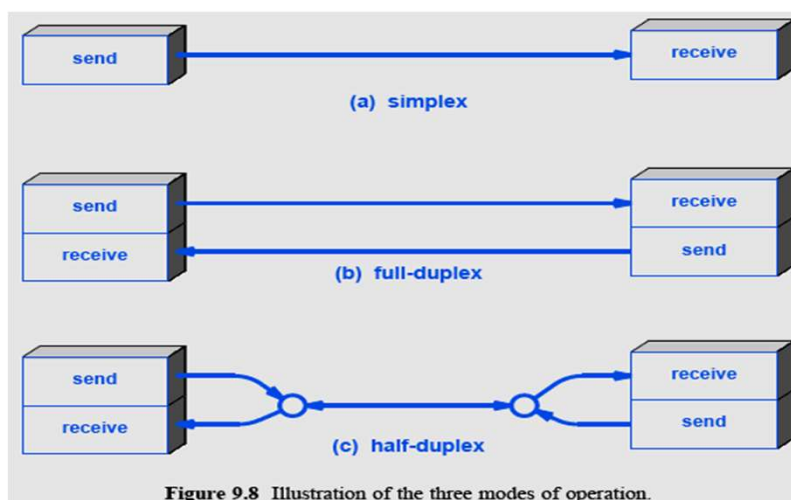
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Simplex, Half-Duplex, and Full-Duplex Transmission

- A communications channel is classified as one of three types: (depending on the direction of transfer)
 - Simplex
 - Full-Duplex
 - Half-Duplex
- **Simplex**: a simplex mechanism can only transfer data in a single direction
 - It is analogous to broadcast radio or television
 - Figure 9.8a illustrates simplex communication
- **Full-Duplex**: allows transmission in two directions simultaneously
 - It is analogous to a voice telephone conversation
 - in which a participant can speak even if they are able to hear background music at the other end
 - Figure 9.8b illustrates the concept

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Simplex, Half-Duplex, and Full-Duplex Transmission



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9.12 Simplex, Half-Duplex, and Full-Duplex Transmission

- **Half-Duplex:** A half-duplex mechanism involves a shared transmission medium
 - The shared medium can be used for communication in each direction
 - But the communication cannot proceed simultaneously
 - It is analogous to using **walkie-talkies** where only one side can transmit at a time
- An additional mechanism is needed at each end of a half-duplex communication that coordinates transmission
 - to insure that only one side transmits at a given time
- Figure 9.8c illustrates half-duplex communication

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