

ForgeSync "Global Industry 4.0"

Project Sector: Precision High-Tech Manufacturing (Automotive & Aerospace)

1. Project Overview: The Digital Nervous System

The Vision: "ForgeSync Core" is a next-generation **On-Premises-First** architecture. Unlike standard IT systems, **manufacturing cannot rely on a constant internet connection**. If the **connection** to the **cloud drops**, the **factory cannot stop**.

The Core Problem: The "Siloed" Factory

ForgeSync's 4 Global Mega-Factories (*Detroit, Stuttgart, Shanghai, São Paulo*) are currently "islands."

- **The 1% OEE Problem:** **Overall Equipment Effectiveness** is stuck at **68%**. Because data isn't synchronized, **managers don't know why machines** are **slowing** down **until the shift ends** (*This means 32% of our time and money is being wasted because machines are breaking down, running too slowly, or making broken parts*).
- **The Value:** Moving from 68% to 69% OEE is worth **\$45 Million/year** in **saved** materials, reduced energy, and higher output.
- **The Constraint:** All **production-critical logic** (*Machine Control, Safety, Quality Vision*) **must run On-Premises** at the Factory Edge to **ensure sub-10ms latency** and **99.99 uptime** during **network outages**.

2. Business Scenario & Operational Environment

The "On-Premises" Hierarchy:

Your **architecture must follow the industrial standard** where layers are **separated by function and physical location**:

| Layer | Location | Function | Requirement |
|-----------------------------------|-------------|---|--|
| Layer 0-2 (Shop Floor) | On-Premises | PLCs, Sensors, Robotic Arms. | Ultra-Low Latency: <10ms response time. |
| Layer 3 (Factory Edge) | On-Premises | Manufacturing Execution System (MES), Local Data Historian. | High Autonomy: Must run for 48 hours without internet. |
| Layer 4 (Corporate) | Global HQ | ERP Integration, Global OEE Analytics, Long-term AI Training. | Global Visibility: Aggregated data for executive decision-making. |

The "Forge" (Hardware Details):

1. **The Robotic Arm (The Worker):** A large **mechanical arm**. **If it moves too fast, it vibrates.** If it rubs against metal, it screeches. **If it works too hard, it gets hot.**
2. **The PLC (The Machine's Local Controller):** A rugged, **mini-computer inside** the machine. It executes "Move" or "Stop" commands. Your **software must tell** the PLC when to "STOP" instantly.
3. **The Sensors (The Senses)**

A **sensor** is a **tiny device** that **converts** a **physical** "feeling" into a **digital number**. You will **monitor 4 main sensors**:

| Sensor Name | What it feels | Digital Data | The "Danger" Sign |
|-------------------|--------------------------|----------------------|---|
| Vibration | The "shake" of the motor | Hertz (Hz) | <ul style="list-style-type: none"> ○ 12Hz is a happy hum. ○ 85Hz means a gear is loose. |
| Acoustic | High-pitched sound | Decibels (dB) | <ul style="list-style-type: none"> ○ 70dB is normal. ○ 95dB is a "Grinding" metal sound. |
| Thermal | Heat | Celsius (°C) | <ul style="list-style-type: none"> ○ 50°C is fine. ○ >80°C means the motor is melting. |
| Cycle Time | Speed of work | Seconds | <ul style="list-style-type: none"> ○ 2.1s is perfect. ○ 2.5s means the robot is lagging. |

Operational Constraints:

1. **Data Sovereignty:** By law, detailed "**Build Logs**" for aerospace parts produced in **Shanghai** or **Stuttgart** must **stay** on the **factory's physical servers for 10 years**. Only "**Summarized Health Stats**" can **leave the building**.
2. **The Firehose (Data Load):** 4 Factories x 12 Lines x 250 Sensors.
 - **High-Velocity (Vibration/Acoustic): 100 reports per second** (100 Hz).
 - **Low-Velocity (Thermal/Speed): 1 report per second** (1 Hz).
3. **Safety Interlock:** If the **centralized system sends a "Stop" command**, it must **reach** the machine in **under 5ms**.
4. **Hardware:** Each factory has its **own dedicated server room** with **high-availability clusters**.
5. **Latency Constraint (<5ms):** If a **machine** is "**Grinding**" you **cannot send** that **data** to the **Cloud** and **wait** for an **answer**. You **must process** it **locally** in **under 5 milliseconds** to **save** the **robot**.
6. **Autonomy Constraint (100% Uptime):** Even if the **factory loses internet**, the robots and your **software must keep working**.

3. The Assignment: 12 Detailed Tasks

Section 1: Strategic Mapping

- **Assignment 1: Business Vision to Technical Vision.**
- **Assignment 2: Functional & Non-Functional Requirements.**

Section 2: Architectural Selection

- **Assignment 3: Select Paradigm.**
- **Assignment 4: Select Model.**
- **Assignment 5: Select Architecture Style.**
- **Assignment 6: Select Architecture Pattern.**

Section 3: Technical Design & Flow

- **Assignment 7: High-Level Design (HLD).**
- **Assignment 8: Low-Level Design (LLD).**
- **Assignment 9: Component & Service Selection.**
- **Assignment 10: Create 3 ADRs (Architectural Decision Records).**

Section 4: Visualizing the Flow

- **Assignment 11: Create System Flow.**
- **Assignment 12: Final Architecture Picture.**