



UTM
UNIVERSITI TEKNOLOGI MALAYSIA

SECJ3553: Artificial Intelligence

Project Proposal - Progress 1

System Name: Smart Traffic Management

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1. AI Solution

This AI-driven Traffic Management and Optimization solution leverages real-time traffic data, predictive models, and Reinforcement Learning (RL) to create an efficient and adaptive traffic control system. It optimises traffic flow by dynamically adjusting traffic signals, offers commuters a mobile app for real-time route suggestions, employs AI-based incident detection to enhance safety, and optimises public transportation services. User feedback and collaboration with stakeholders ensure continuous improvement. The system mitigates traffic congestion, reduces commuting times, and enhances the overall transportation experience, addressing the needs of both commuters and traffic authorities in the smart city..

2. Goal of AI Solution

- I. To reduce traffic congestion, by allowing the traffic lights to adapt to situations, such as heavy rains, traffic accidents and rush hours.
- II. Improve traffic safety, by identifying potential hazards, traffic accidents, presence of any emergencies such as ambulances and potential crimes.
- III. Provide and receive real-time traffic updates from main cameras and especially third party companies such as Maps and Waze.
- IV. Provide comprehensive traffic predictions for the future and apply it on a daily basis.
- V. Provide data driven suggestions for future developments, such as potential new routes, lanes and building zones.

3. Process of Emphasise in DT

In the realm of AI-driven traffic management, the key stakeholders include daily commuters, emergency responders, city authorities, and business owners/logistics companies. Their primary goals revolve around reaching their destinations safely, on time, and swiftly, all while ensuring road safety, efficiency, and smooth traffic flow. These stakeholders often encounter traffic congestion, road accidents, and road hazards, leading to frustrations about constant traffic congestion, inaccessibility during emergencies, and dissatisfaction with existing traffic systems, which results in unpredictable delays and inefficiencies. In response, they employ various strategies like carpooling, using public transport, altering plans, or taking alternative routes. They're bombarded with constant complaints and concerns and actively engage in discussions about traffic problems and potential solutions. Emotionally, they grapple with fear of accidents and hazards, frustration, stress, and pressure related to work and travel, while also seeking potential solutions and answers to alleviate these challenges

a. Summary

Who are they?	<ul style="list-style-type: none">● Daily commuters● Emergency responders● City authorities● Business owners and logistics
What do they do?	<ul style="list-style-type: none">● Reaching their destination safely● Reaching their destination on time● Reaching their destination swiftly● Ensure roads to be safe, efficient and flows smoothly
What do they see?	<ul style="list-style-type: none">● Traffic congestions● Road accidents● Road hazards
What do they say?	<ul style="list-style-type: none">● Frustration on the constant traffic congestions● Inaccessibility during emergencies● Subpar traffic systems● Unpredictable delays and inefficiencies
What do they do?	<ul style="list-style-type: none">● Carpooling● Using public transport● Delay, alter or cancelling of plans● Using alternative longer routes

What do they hear?	<ul style="list-style-type: none"> ● Constant complaints and concerns ● Traffic problems and potential solutions
What do they think and feel?	<ul style="list-style-type: none"> ● Fear of accidents and hazards ● Frustration and stress from traffic congestions ● Pressure from work and travelling ● Potential solutions and answers

4. Process of Defined in DT

Commuters and Traffic Authorities share a common challenge of addressing traffic-related issues, albeit from different perspectives. Commuters aim to navigate the roadways efficiently, seeking a safe and expedient journey while minimising delays and stress. Their primary concerns revolve around unpredictable road conditions, accidents, and congestion. On the other hand, Traffic Authorities strive to maintain overall road safety, promptly respond to incidents, and optimise traffic flow during rush hours. Their focus lies in reducing congestion, minimising accidents, and efficiently managing traffic systems. Despite distinct roles, both user groups share a fundamental interest in creating a smoother, safer, and more streamlined commuting experience.

a. Summary

Users	Problem	Pains	Goals	What Matters to Them
Commuters	<ul style="list-style-type: none"> ● Deal with traffic congestion ● Delays ● Accidents ● Unpredictable road conditions. 	<ul style="list-style-type: none"> ● Being late ● Dealing with erratic traffic conditions ● Going through stressful delays all happen during the commute. 	Travel safely, with as little traffic as possible, and to get to their destinations quickly and on schedule.	Minimal delays, stress-free commute, and reaching destinations faster.

Traffic Authorities	<ul style="list-style-type: none"> • Control traffic during rush hour • React quickly to collisions • Maintain general road safety. 	<ul style="list-style-type: none"> • Managing traffic congestion • Responding quickly to incidents • Optimising traffic flow. 	Maintain efficient traffic flow, react quickly to problems, and successfully operate traffic lights.	Reducing traffic congestion, minimising accidents, and optimising traffic management.
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Knowledge Representation (KR)

b. Current Problem

1. Traffic Congestion:
 - i. Constant traffic congestion causes frustration for travellers on a daily basis since it results in unpredictable delays and inefficiency.
2. Road Safety Concerns
 - i. Road accidents, dangers, and difficulties in effectively regulating traffic flow are encountered by commuters and law enforcement, which have an effect on overall road safety.
3. Inefficient Traffic Management
 - i. Stakeholder dissatisfaction originates from the perception that the current transportation systems are inadequate.

c. Proposed Solution

In order to achieve our goal, we have determined the two key aspects that will assist our AI in determining the steps to be taken. First is the use of sensors that will detect the presence of cars on the lanes of the traffic light and the amount of cars that are waiting, in order to determine whether it is congested or not. Second is the use of cameras, to gauge the vision constraint of the area that shall determine if it is raining or foggy, scan for any hazards such as accidents, unsafe objects or crime and lastly the presence of any emergency responders such as the ambulance or police.

From these data, the AI shall analyse and predict the possible effects of such events and give real time updates to the traffic authorities & third party apps and determine which settings of the traffic light to be used. The relevant authorities shall also be contacted whenever a presence of hazards are detected by the camera.

In regards to the settings of the traffic light, the traffic light shall shorten the time of green if there are not more cars detected, or lengthen the time if congestion are detected, depending on the other affecting lanes and traffic lights. Similarly, in case of vision constraint, the traffic light shall be longer when green, with regards to the other affecting lanes and traffic lights, due to the nature of driving during such an event.

Additionally, the traffic lights shall be green when emergency responders are on route. Lastly, the traffic lights timer will take necessary action depending on the type of hazards detected, always prioritising the safety of commuters.

d. KR of the system

Congestion_Detection (Sensor), S	Vision_Detection (Camera), V			Actions	
S = Empty or Congested (X)	V = Vision Constraint (A)	V = Hazards (B)	V = Emergency Responders (C)	Real_Time_Update_And_Predictions, UP	Contact_Authorities, CA
1	1	1	1	1	1
1	1	1	0	1	1
1	1	0	1	1	0
1	1	0	0	1	0
1	0	1	1	1	1
1	0	1	0	1	1
1	0	0	1	1	0
1	0	0	0	1	0
0	1	1	1	1	1
0	1	1	0	1	1
0	1	0	1	1	0
0	1	0	0	1	0
0	0	1	1	1	1
0	0	1	0	1	1
0	0	0	1	1	0
0	0	0	0	0	0

KR 1:

IF (S=X) = TRUE AND (V=A) = TRUE AND (B=A) = TRUE AND (C=A) = TRUE
THEN (UP=A) = TRUE, (CA=A) = TRUE.

KR 2:

IF (S=X) = TRUE AND (V=A) = TRUE AND (B=A) = TRUE AND (C=A) = FALSE
THEN (UP=A) = TRUE, (CA=A) = TRUE.

KR 3:

IF (S=X) = TRUE AND (V=A) = TRUE AND (B=A) = FALSE AND (C=A) = TRUE
THEN (UP=A) = TRUE, (CA=A) = FALSE .

KR 4:

IF (S=X) = TRUE AND (V=A) = TRUE AND (B=A) = FALSE AND (C=A) =
FALSE THEN (UP=A) = TRUE, (CA=A) = FALSE .

KR 5:

IF (S=X) = TRUE AND (V=A) = FALSE AND (B=A) = TRUE AND (C=A) = TRUE
THEN (UP=A) = TRUE, (CA=A) = TRUE.

KR 6:

IF (S=X) = TRUE AND (V=A) = FALSE AND (B=A) = TRUE AND (C=A) =
FALSE THEN (UP=A) = TRUE, (CA=A) = TRUE.

KR 7:

IF (S=X) = TRUE AND (V=A) = FALSE AND (B=A) = FALSE AND (C=A) =
TRUE THEN (UP=A) = TRUE, (CA=A) = TRUE.

KR 8:

IF (S=X) = TRUE AND (V=A) = FALSE AND (B=A) = FALSE AND (C=A) =
FALSE THEN (UP=A) = TRUE, (CA=A) = FALSE.

KR 9:

IF (S=X) = FALSE AND (V=A) = TRUE AND (B=A) = TRUE AND (C=A) = TRUE
THEN (UP=A) = TRUE, (CA=A) = TRUE.

KR 10:

IF (S=X) = FALSE AND (V=A) = TRUE AND (B=A) = TRUE AND (C=A) =
FALSE THEN (UP=A) = TRUE, (CA=A) = TRUE.

KR 11:

IF (S=X) = FALSE AND (V=A) = TRUE AND (B=A) = FALSE AND (C=A) =
TRUE THEN (UP=A) = TRUE, (CA=A) = FALSE .

KR 12:

IF (S=X) = FALSE AND (V=A) = TRUE AND (B=A) = FALSE AND (C=A) =
FALSE THEN (UP=A) = TRUE, (CA=A) = FALSE .

KR 13:

IF (S=X) = FALSE AND (V=A) = FALSE AND (B=A) = TRUE AND (C=A) =
TRUE THEN (UP=A) = TRUE, (CA=A) = TRUE.

KR 14:

IF (S=X) = FALSE AND (V=A) = TRUE AND (B=A) = FALSE AND (C=A) =
FALSE THEN (UP=A) = TRUE, (CA=A) = FALSE .

KR 15:

IF (S=X) = FALSE AND (V=A) = FALSE AND (B=A) = FALSE AND (C=A) =
TRUE THEN (UP=A) = TRUE, (CA=A) = FALSE .

KR 16:

IF (S=X) = FALSE AND (V=A) = FALSE AND (B=A) = FALSE AND (C=A) =
FALSE THEN (UP=A) = FALSE , (CA=A) = FALSE .

e. Explanation KR

KR 1:

If the sensors detect that the lanes are empty or are congested and the camera detects a vision constraint, presence of hazards and the presence of emergency responders, the system will make new predictions, give real time updates & change the traffic light settings, and contact the authorities.

KR 2:

If the sensors detect that the lanes are empty or are congested and the camera detects a vision constraint and presence of hazards, the system will make new predictions, give real time updates & change the traffic light settings, and contact the authorities.

KR 3:

If the sensors detect that the lanes are empty or are congested and the camera detects a vision constraint and the presence of emergency responders, the system will make new predictions and give real time updates & change the traffic light settings.

KR 4:

If the sensors detect that the lanes are empty or are congested and the camera detects a vision constraint, the system will make new predictions and give real time updates & change the traffic light settings.

KR 5:

If the sensors detect that the lanes are empty or are congested and the camera detects the presence of hazards and the presence of emergency responders, the system will make new predictions, give real time updates & change the traffic light settings, and contact the authorities.

KR 6:

If the sensors detect that the lanes are empty or are congested and the camera detects a presence of hazard, the system will make new predictions, give real time updates & change the traffic light settings, and contact the authorities.

KR 7:

If the sensors detect that the lanes are empty or are congested and the camera detects the presence of emergency responders, the system will make new predictions and give real time updates & change the traffic light settings.

KR 8:

If the sensors detect that the lanes are empty, the system will make new predictions and give real time updates & change the traffic light settings.

KR 9:

If the camera detects a vision constraint, presence of hazards and the presence of emergency responders, the system will make new predictions, give real time updates & change the traffic light settings, and contact the authorities.

KR 10:

If the camera detects a vision constraint and presence of hazards, the system will make new predictions, give real time updates & change the traffic light settings, and contact the authorities.

KR 11:

If the camera detects a vision constraint and the presence of emergency responders, the system will make new predictions and give real time updates & change the traffic light settings.

KR 12:

If the camera detects a vision constraint, the system will make new predictions, give real time updates & change the traffic light setting.

KR 13:

If the camera detects the presence of hazards and the presence of emergency responders, the system will make new predictions, give real time updates & change the traffic light settings, and contact the authorities.

KR 14:

If the camera detects a presence of hazards, the system will make new predictions, give real time updates & change the traffic light settings, and contact the authorities.

KR 15:

If the camera detects the presence of emergency responders, the system will make new predictions, give real time updates & change the traffic light settings.

KR 16:

If the sensors and cameras do not detect anything, the traffic light will use the default setting..

f. First Order Logic (FOL)

- $\text{CarPresence}(x, \text{lane})$: Predicate indicating the presence of a car x in lane lane .
- $\text{WaitingCarsCount}(\text{lane}, \text{count})$: Predicate indicating the count of waiting cars in lane lane .
- $\text{Congested}(\text{lane})$: Predicate indicating that the lane lane is congested.
- VisionConstraint : Predicate indicating a vision constraint due to rain or fog.
- HazardDetected : Predicate indicating the presence of hazards such as accidents or unsafe objects.
- $\text{EmergencyRespondersPresent}$: Predicate indicating the presence of emergency responders.
- $\text{TrafficLightSettings}(\text{lane}, \text{colour}, \text{duration})$: Predicate indicating the settings of the traffic light for lane lane , with colour (red, green, yellow) and duration.
- $\text{ContactAuthorities}$: Predicate indicating the need to contact relevant authorities.

I. Car Detection and Congestion:

- A. $(\text{CarPresence}(x, \text{lane}) \Rightarrow \text{WaitingCarsCount}(\text{lane}, \text{count}))$
- B. $(\text{WaitingCarsCount}(\text{lane}, \text{count}) \wedge \text{count} > \text{threshold} \Rightarrow \text{Congested}(\text{lane}))$

II. Vision Constraint and Hazard Detection:

- A. $(\text{VisionConstraint} \Rightarrow \text{HazardDetected})$

III. Emergency Responders:

- A. $(\text{EmergencyRespondersPresent} \Rightarrow \text{TrafficLightSettings}(\text{lane}, \text{green}, \text{duration}))$

IV. Traffic Light Settings:

- A. $(\text{Congested}(\text{lane}) \Rightarrow \text{TrafficLightSettings}(\text{lane}, \text{red}, \text{duration}))$
- B. $(\text{VisionConstraint} \Rightarrow \text{TrafficLightSettings}(\text{lane}, \text{green}, \text{longer_duration}))$
- C. $(\text{HazardDetected} \Rightarrow (\text{TrafficLightSettings}(\text{lane}, \text{red}, \text{duration}) \wedge \text{ContactAuthorities}))$

V. Real-time Updates:

- A. $(\text{Congested}(\text{lane}) \Rightarrow \text{RealTimeUpdate}(\text{TrafficAuthorities}, \text{ThirdPartyApps}))$

B. (HazardDetected => RealTimeUpdate(TrafficAuthorities, ThirdPartyApps))

g. How KR solves the goal

1) Solving Traffic Congestion

KR rules (KR 1 to KR 8) address situations where the sensors detect congestion or emptiness in the lanes. In response, the system forecasts future events, provides real-time information, and modifies traffic light settings as necessary. This is in line with the objective of minimising traffic jams by dynamically adjusting traffic light timings in response to actual traffic situations.

2) Ensuring Safety and Hazard Detection

KR rules (KR 1, KR 2, KR 5, KR 6, KR 13, KR 14) incorporate camera data (Vision_Detection) to identify hazards, accidents, and emergency responders. The technology not only modifies traffic signals to accommodate emergency responders or hazards, but it also notifies authorities to ensure prompt action. This is in line with the objective of enhancing traffic safety through the rapid resolution of possible dangers.

3) Vision Constraints and Weather Conditions

KR rules (KR 1 to KR 4, KR 9 to KR 12) consider vision constraints (such as rain or fog) detected by cameras. Based on these circumstances, the system modifies the traffic light settings to make sure that the lights are adapted to account for decreased visibility. This is in line with the objective of offering a complete solution that takes the weather into account for the best possible traffic management.

4) Real-time Updates and Predictions

The Real_Time_Update_And_Predictions action (UP) is triggered in various KR rules, making certain that traffic authorities and other apps receive constant real-time updates and forecasts from the system. This is in line with the objective of improving overall situational awareness by sending and receiving real-time traffic updates.

5) Contacting Authorities

The Contact_Authorities action (CA) is triggered in specific KR rules (e.g., KR 1, KR 5, KR 13) when hazards or emergencies are detected. This helps achieve the objectives

of increased safety and prompt incident response by ensuring that pertinent authorities are notified as soon as possible.

6) Adaptive Traffic Light Settings

The KR rules specify how sensor and camera data should be used to modify the traffic signal settings. For instance, the green light duration could be shortened if congestion is found (KR 1). In the event of dangers, the system may respond differently according to the particular circumstances (KR 5, KR 13). This is consistent with the objective of optimising traffic flow through dynamic adaptation of traffic light timings.