# Assignment 2

### Assignment objective

The objective of this assignment is to learn:

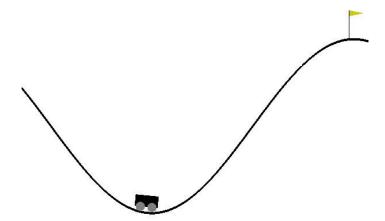
- How to use open Al gym environments.
- How to understand a given RL problem parameters.
- o The implementation of Monte Carlo, Q\_Learning and SARSA algorisms.
- o Comparing between the performances of the three algorisms.

### • Assignment Rules

- Due date is Tuesday May 2<sup>nd</sup>.
- This assignment will be delivered in groups of 4 students.
- Any cheats will got zero.

### • Assignment Description

In this assignment you are supposed to use another environment from Open AI gym classic environments, which is MountainCar-v0. The target of this game is to climb the hill and reach the yellow flag.



# Environment Description

You have a car and a mountain hill and your goal is to get an under powered car to the top of the hill (top = 0.5 position).

#### Observations

Type: Box (2)

Num	Observation	Min	Max
0	position	-1.2	0.6
1	velocity	-0.07	0.07

#### Actions

Type: Discrete (3)

Num	Action
0	push left
1	no push
2	push right

#### Reward

Reward is -1 for each time step, until the goal position of 0.5 is reached. There is no penalty for climbing the left hill, which upon reached acts as a wall.

## Starting State

Random position from -0.6 to -0.4 with no velocity.

# Episode Termination

The episode ends when you reach 0.5 position, or if 200 iterations are reached.

# Assignment Requirements

You are required to deliver the following:

- An implementation in python for Monte Carlo, Q\_Learning and SARSA algorithms based on the MountainCar-v0 environment.

  (4Marks)
- A comparison between the three algorithms in terms of accuracy and conversion time (in episodes).