|  |  |
| --- | --- |
| PEAS | |
| Performance | The comfortable trip, Safety, Maximum Distance |
| Environment | Roads, Traffic, Vehicles |
| Actuator | Steering wheel, Accelerator, Brake, Mirror |
| Sensor | |  | | --- | | Camera, GPS, Odometer | |  | |

|  |  |
| --- | --- |
| ODESA | |
| **Observability** | **Partial** |
| **Deterministic** | **Stochastic** |
| **Episode** | **Sequential** |
| **Static** | **Dynamic** |
| **Agent** | **Multi-agent** |

Agent-type: learning agent