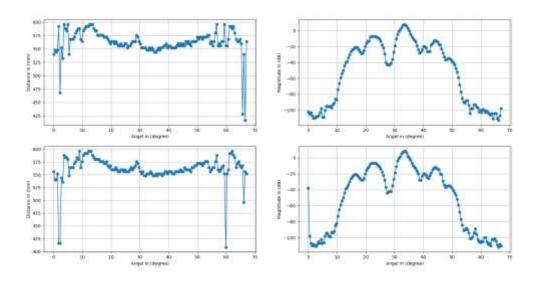
# **Environment:**



Distance between radar and object = 51 cm, Bin resolution = 4, Entering point = step number 27 ≅ 12.15 degree, Exit point = step number 109 ≅ 49.05 degree, Without CFAR, Total angel = 67.5 with step size = 1, Total number of steps = 150 step each step = 0.45 degree

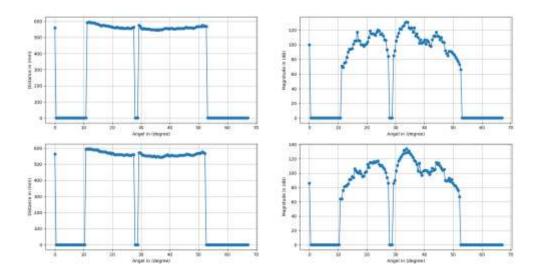


[-102, -105, -103, -107, -110, -110, -108, -108, -107, -103, -98, -109, -109, -100, -95, -95, -96, -95, -97, -93, -91, -86, -87, -74, -66, -59, -54, -50, -44, -40, -39, -34, -30, -26, -24, -23, -21, -21, -21, -24, -26, -29, -28, -25, -20, -16, -13, -13, -8, -7, -7, -7, -7, -8, -9, -10, -13, -18, -22, -29, -40, -43, -43, -43, -41, -36, -27, -19, -10, -5, -1, 1, 4, 7, 8, 7, 6, 3, 0, -4, -7, -10, -12, -14, -19, -24, -28, -27, -24, -20, -20, -22, -26, -26, -26, -18, -16, -13, -12, -13, -14, -17, -18, -23, -28, -33, -37, -36, -36, -38, -40, -43, -47, -52, -59, -68, -77, -85, -90, -91, -88, -88, -94, -104, -98, -98, -93, -93, -96, -97, -102, -100, -103, -99, -100, -103, -101, -103, -105, -106, -104, -111, -104, -104, -110, -113, -107, -98]

Table 1. 10, -106, -110, -111, -108, -110, -111, -108, -105, -107, -102, -107, -106, -98, -94, -95, -98, -99, -93, -94, -92, -85, -82, -73, -65, -59, -54, -50, -44, -39, -37, -34, -30, -26, -24, -22, -21, -21, -22, -24, -26, -28, -28, -26, -20, -16, -13, -11, -8, -7, -7, -7, -8, -10, -11, -14, -18, -22, -28, -37, -44, -43, -42, -42, -35, -27, -19, -11, -4, -1, 1, 5, 7, 8, 8, 6, 2, 0, -3, -7, -10, -12, -14, -17, -20, -28, -28, -23, -20, -20, -22, -25, -26, -22, -19, -15, -13, -12, -13, -14, -15, -20, -21, -29, -34, -37, -36, -35, -36, -38, -41, -44, -47, -52, -59, -68, -77, -84, -91, -90, -88, -90, -94, -101, -101, -99, -94, -89, -96, -102, -105, -106, -104, -105, -106, -104, -105, -106,

Distance between radar and object = 51 cm, Bin resolution = 4, Entering point = step number  $27 \cong 12.15$  degree, Exit point = step number  $109 \cong 49.05$  degree, With CFAR and calibration, Total angel = 67.5 with step size = 1, Total number of steps = 150 step each step = 0.45 degree, Threshold = 0.47

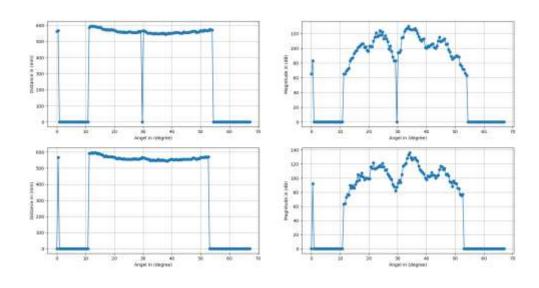
## Guard number = 5



### Row number # 1

## Row number # 2

# Guard number = 8



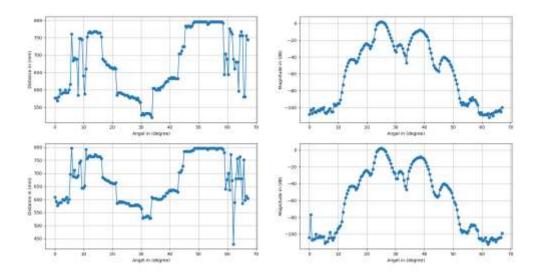
### **Environment:**



Distance between radar and object = 51 cm, Bin resolution = 4, Entering point = step number  $32 \cong$ 14.4 degree, Exit point = step number 109≅ 49.05 degree, Without CFAR, Total angel = 67.5 with step size = 1, Total number of steps = 150 step each step = 0.45 degree

106, -109, -109, -109, -109, -107, -112, -108, -104, -105, -104, -

Table 1704, 1707,



Distance between radar and object = 51 cm, Bin resolution = 4, Entering point = step number 27 ≅ 12.15 degree, Exit point = step number 104≅ 46.8 degree, With CFAR and calibration, Total angel = 67.5 with step size = 1, Total number of steps = 150 step each step = 0.47 degree

# Guard number = 5

