

# Fitting the distribution of heights data

## Instructions

In this assessment you will write code to perform a steepest descent to fit a Gaussian model to the distribution of heights data that was first introduced in *Mathematics for Machine Learning: Linear Algebra*.

The algorithm is the same as you encountered in *Gradient descent in a sandpit* but this time instead of descending a pre-defined function, we shall descend the  $\chi^2$  (chi squared) function which is both a function of the parameters that we are to optimise, but also the data that the model is to fit to.

## How to submit

Complete all the tasks you are asked for in the worksheet. When you have finished and are happy with your code, press the **Submit Assignment** button at the top of this notebook.

## Get started

Run the cell below to load dependencies and generate the first figure in this worksheet.

```
In [29]: # Run this cell first to load the dependencies for this assessment,  
# and generate the first figure.  
from readonly.HeightsModule import *
```

## Background

If we have data for the heights of people in a population, it can be plotted as a histogram, i.e., a bar chart where each bar has a width representing a range of heights, and an area which is the probability of finding a person with a height in that range. We can look to model that data with a function, such as a Gaussian, which we can specify with two parameters, rather than holding all the data in the histogram.

The Gaussian function is given as,

$$f(\mathbf{x}; \mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(\mathbf{x} - \mu)^2}{2\sigma^2}\right)$$

The figure above shows the data in orange, the model in magenta, and where they overlap in green. This particular model has not been fit well - there is not a strong overlap.

Recall from the videos the definition of  $\chi^2$  as the squared difference of the data and the model, i.e  $\chi^2 = \|\mathbf{y} - f(\mathbf{x}; \mu, \sigma)\|^2$ . This is represented in the figure as the sum of the squares of the pink and orange bars.

Don't forget that  $\mathbf{x}$  and  $\mathbf{y}$  are represented as vectors here, as these are lists of all of the data points, the `abs-squared`<sup>2</sup> encodes squaring and summing of the residuals on each bar.

To improve the fit, we will want to alter the parameters  $\mu$  and  $\sigma$ , and ask how that changes the  $\chi^2$ . That is, we will need to calculate the Jacobian,

$$\mathbf{J} = \left[ \frac{\partial \chi^2}{\partial \mu}, \frac{\partial \chi^2}{\partial \sigma} \right].$$

Let's look at the first term,  $\frac{\partial \chi^2}{\partial \mu}$ , using the multi-variate chain rule, this can be written as,

$$\frac{\partial \chi^2}{\partial \mu} = -2(\mathbf{y} - f(\mathbf{x}; \mu, \sigma)) \cdot \frac{\partial f}{\partial \mu}(\mathbf{x}; \mu, \sigma)$$

Let's look at the first term,  $\frac{\partial(x^2)}{\partial\mu}$ , using the multi-variate chain rule, this can be written as,

$$\frac{\partial(x^2)}{\partial\mu} = -2(y - f(x; \mu, \sigma)) \cdot \frac{\partial f}{\partial\mu}(x; \mu, \sigma)$$

With a similar expression for  $\frac{\partial(x^2)}{\partial\sigma}$ ; try and work out this expression for yourself.

The Jacobians rely on the derivatives  $\frac{\partial f}{\partial\mu}$  and  $\frac{\partial f}{\partial\sigma}$ . Write functions below for these.

```
In [30]: # PACKAGE
import matplotlib.pyplot as plt
import numpy as np
```

```
In [31]: # GRADED FUNCTION

# This is the Gaussian function.
def f(x,mu,sig):
    return np.exp(-(x-mu)**2/(2*sig**2)) / np.sqrt(2*np.pi) / sig

# Next up, the derivative with respect to mu.
# If you wish, you may want to express this as f(x, mu, sig) multiplied by chain rule terms.
# === COMPLETE THIS FUNCTION ===
def dfdmu(x,mu,sig):
    return f(x, mu, sig) * (x- mu)/sig**2

# Finally in this cell, the derivative with respect to sigma.
# === COMPLETE THIS FUNCTION ===
def dfdsig(x,mu,sig):
    return -f(x, mu, sig)/sig + f(x, mu, sig) * (x-mu)**2*sig**-3
```

Next recall that steepest descent shall move around in parameter space proportional to the negative of the Jacobian, i.e.,  $\begin{bmatrix} \delta\mu \\ \delta\sigma \end{bmatrix} \propto -\mathbf{J}$ , with the constant of proportionality being the aggression of the algorithm.

Modify the function below to include the  $\frac{\partial(x^2)}{\partial\sigma}$  term of the Jacobian, the  $\frac{\partial(x^2)}{\partial\mu}$  term has been included for you.

```

In [32]: # GRADED FUNCTION

# Complete the expression for the Jacobian, the first term is done for you.
# Implement the second.
# === COMPLETE THIS FUNCTION ===
def steepest_step (x, y, mu, sig, aggression) :
    J = np.array([
        -2*(y - f(x,mu,sig)) @ dfdmu(x,mu,sig),
        -2*(y - f(x,mu,sig)) @ dfdsig(x,mu,sig) # Replace the ??? with the second element of the Jacobian.
    ])
    step = -J * aggression
    return step

```

## Test your code before submission

To test the code you've written above, run all previous cells (select each cell, then press the play button [▶] or press shift-enter). You can then use the code below to test out your function. You don't need to submit these cells; you can edit and run them as much as you like.

```

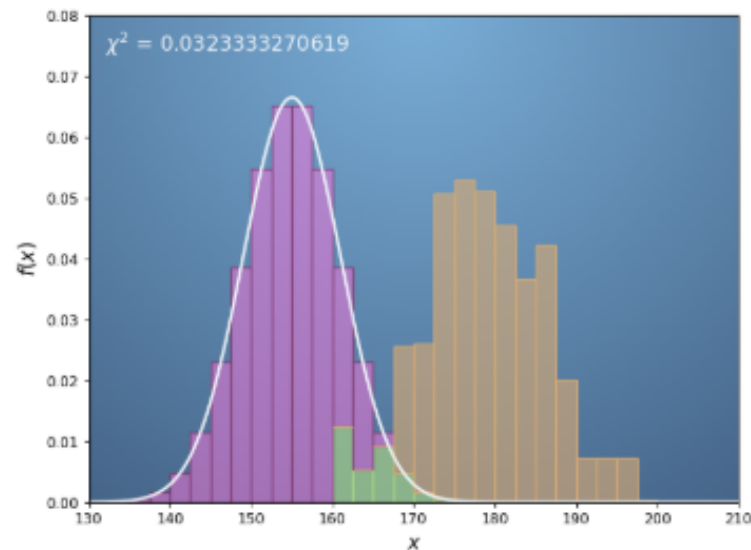
In [33]: # First get the heights data, ranges and frequencies
x,y = heights_data()

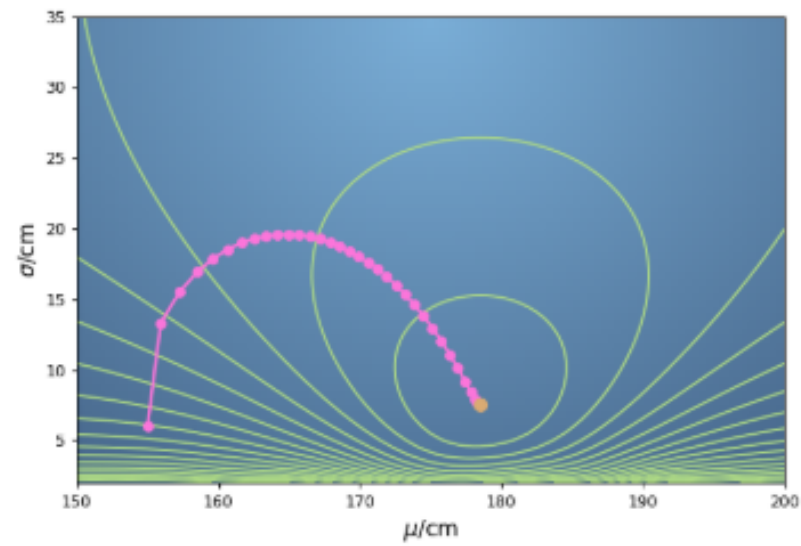
# Next we'll assign trial values for these.
mu = 155 ; sig = 6
# We'll keep a track of these so we can plot their evolution.
p = np.array([mu, sig])

# Plot the histogram for our parameter guess
histogram(f, [mu, sig])
# Do a few rounds of steepest descent.
for i in range(50) :
    dmu, dsig = steepest_step(x, y, mu, sig, 2000)
    mu += dmu
    sig += dsig
    p = np.append(p, [[mu,sig]], axis=0)
# Plot the path through parameter space.
contour(f, p)
# Plot the final histogram.
histogram(f, [mu, sig])

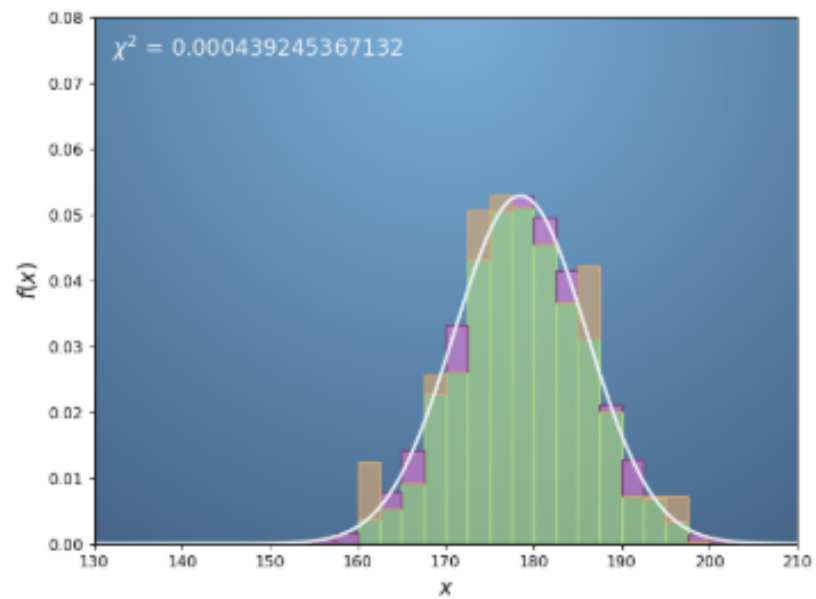
```

<IPython.core.display.Javascript object>





<IPython.core.display.Javascript object>



Note that the path taken through parameter space is not necessarily the most direct path, as with steepest descent we always move perpendicular to the contours.