

Royal Institute of Technology

STATISTICAL
METHODS IN CS,
CH 10, 19, 20

Lecture 6

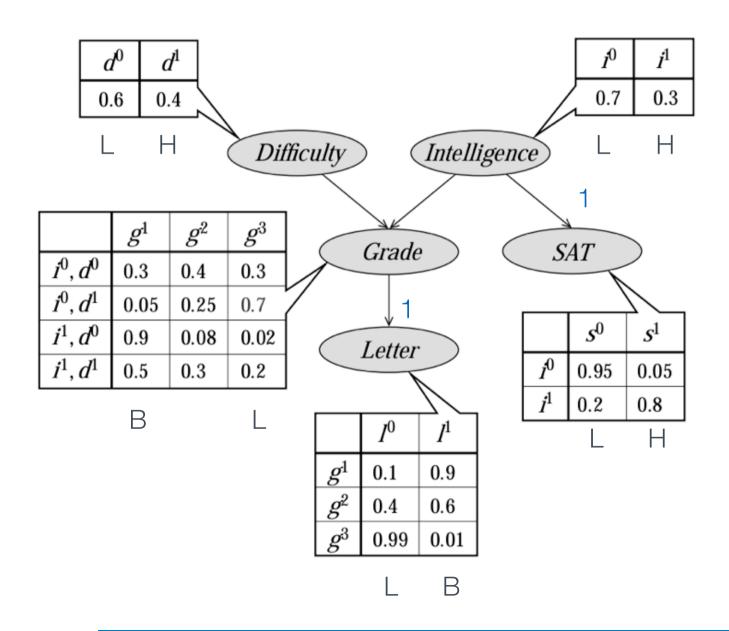
### LAST LECTURE

- **★** DGM
- Factorization of likelihood
- ⋆ MLE estimates for categorical CPDs
- ★ Factorization of posterior for decomposable prior
- ⋆ Posterior for categorical CPDs
- Semantics of the DAG, Independence

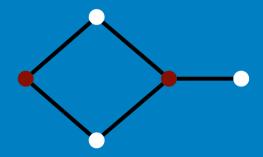
### THIS LECTURE

- ⋆ DP for trees
  - independent set
  - marginalization
- **★** UGMs
- Converting a DGM to a UGM

### EXTENDED STUDENT EXAMPLE

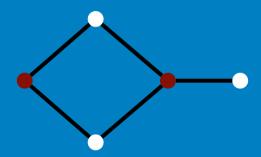


#### INDEPENDENT SET



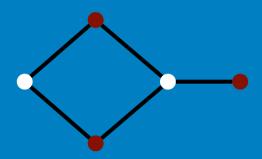
•  $I\subseteq V(G)$  is and independent set if there is no edge between any pair of vertices of V(G)

#### MAXIMUM INDEPENDENT SET



An independent set is a
 maximal independent set if
 it is not a proper subset of
 an independent set

#### MAXIMUM INDEPENDENT SET



An independent set is a
 maximum independent set
 if there is no larger
 independent set

### COMPUTATIONAL PROBLEM

- Maximum independent set
  - Input: graph G
  - ⋆ Output: a maximum independent set I of G
- NP-complete in general (etc)
- Easy for trees
  - \* Since including a leaf is always at least as beneficial as including its parent, for cherry better.

If you give me

I replace it by

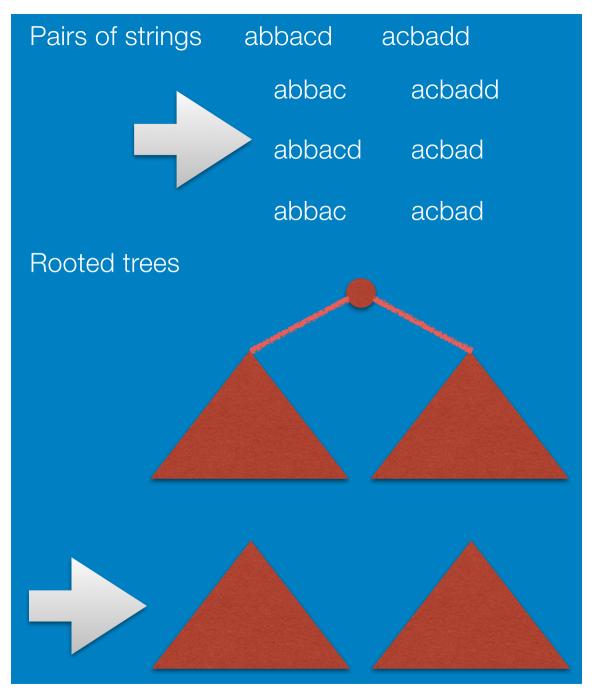


which is better

### COMPUTATIONAL PROBLEM

- \* Maximum weight independent set
  - ★ Input: graph G, and weight function w: V(G) → R
  - ⋆ Output: independent set I of G maximizing

$$w(I) = \sum_{v \in I}$$





- What is a subproblem?
- What is a subsolution?
- How do we decompose into smaller subproblems?
- How do we combine subsolutions into larger?
- How do we enumerate?
- How many and what time?

### SUBPROBLEMS

# For every vertex v, 2 subproblems v out v in

Solution: weight of max weight independent set in the rooted subtree with v in or out

- Denote solutions s(v,in) and s(v,out)
  - i.e., the weight of the maximum weight independent set
- In the end the solution is max(w(root,in), w(root,out))
- Tracing back-pointers gives the actual set

For leaf I

lout •

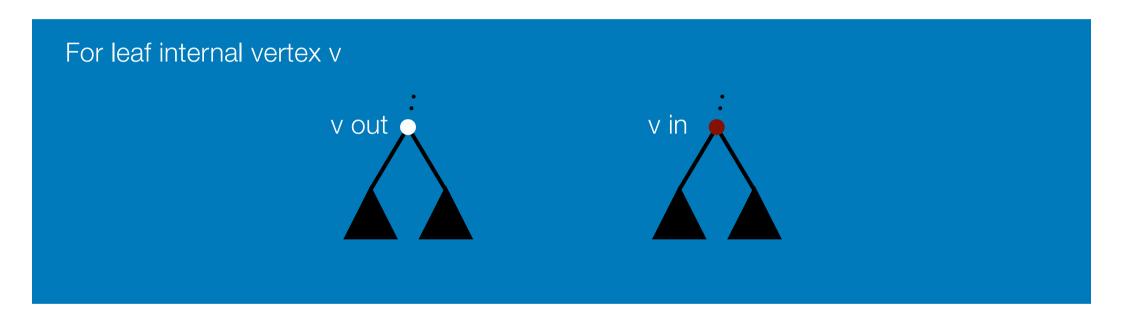
I in

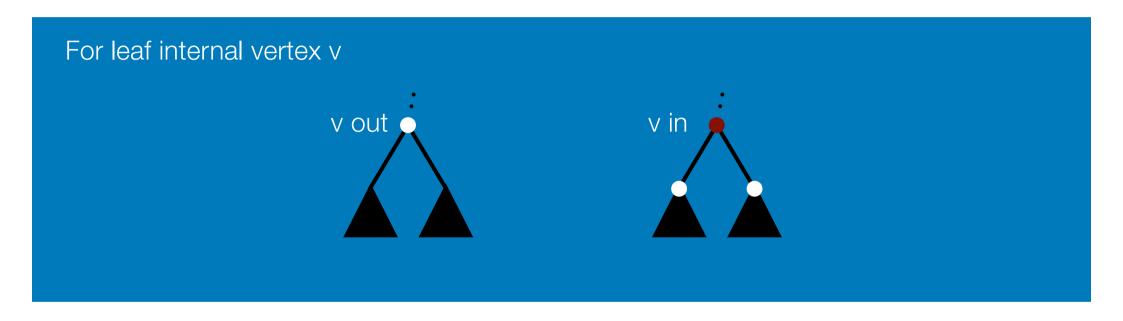


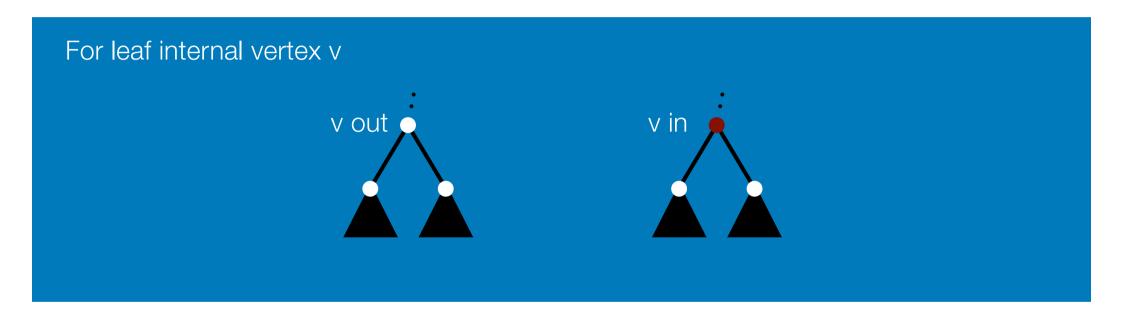
Solution: weight of max weight independent set in the rooted subtree with v in or out

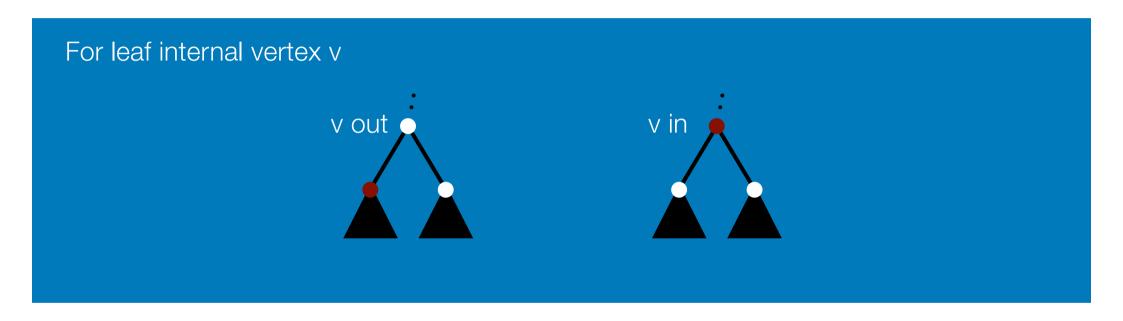
- s(l,out) := 0
- s(l,in) := w(l)

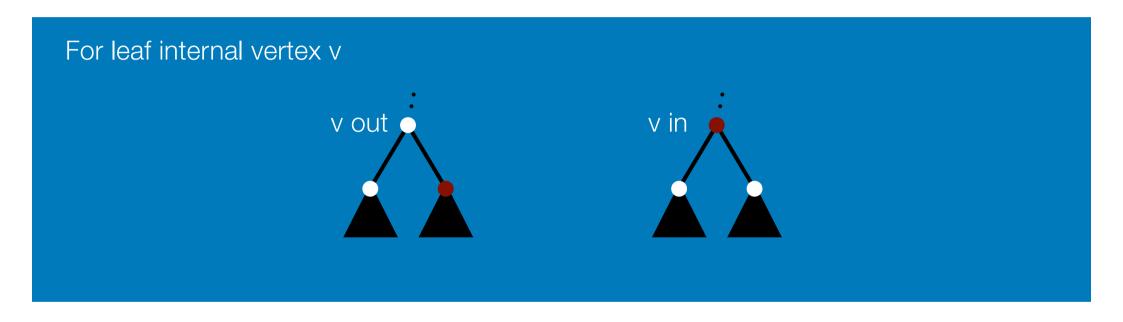
# SUBSOLUTIONS FOR INTERNAL

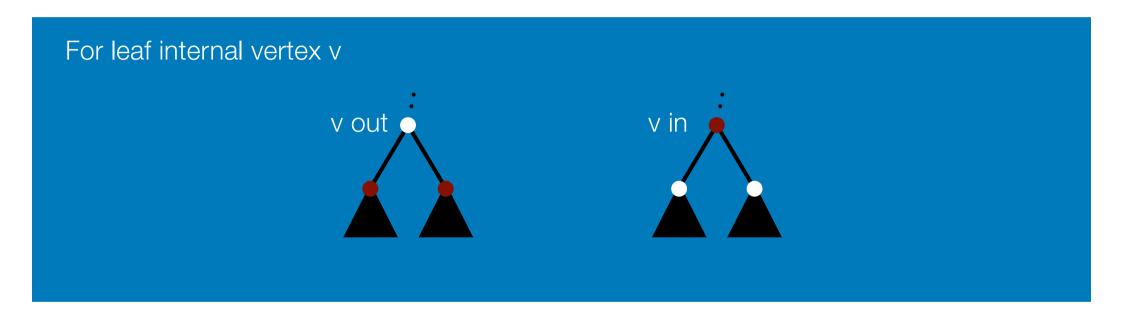








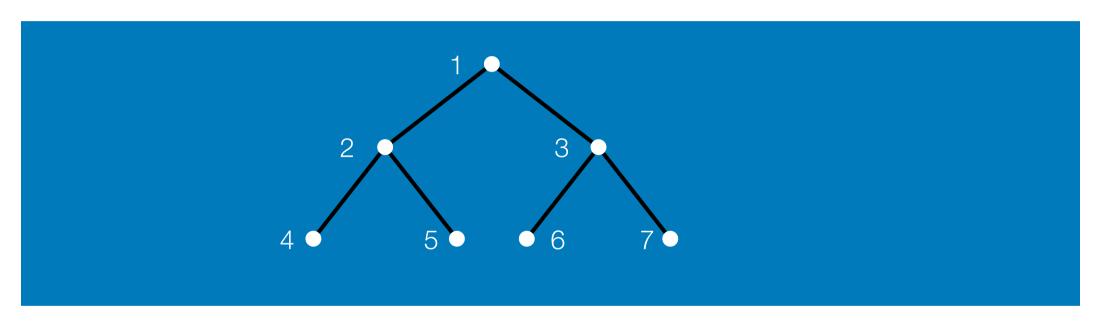




# 

- s(v,in) := w(v) + s(u,out) + s(u',out)
- $s(v,out) := \max_{a,b \in \{in, out\}} \{s(u,a) + s(u',b)\}$

### 



Vertex	1	2	3	4	5	6	7
w	5	14	2	3	4	8	9
in	29	14	2	3	4	8	9
out	31	7	17	0	0	0	0

### MARGINALIZE WITH EVIDENCE

$$p(\boldsymbol{X}_m | \boldsymbol{x}_e) = \frac{\sum_{\boldsymbol{x}_{V \setminus (m \cup e)}} p(\boldsymbol{X}_m, \boldsymbol{x}_{V \setminus (m \cup e)}, \boldsymbol{x}_e)}{\sum_{\boldsymbol{x}_{V \setminus e}} p(\boldsymbol{x}_{V \setminus e}, \boldsymbol{x}_e)}$$

- Boils down to marginalisation, i.e., summing out
- Summing out V binary hidden variables O(2<sup>V</sup>)
- K values  $O(K^{V})$

#### ALGORITHM -Marginalization tree dgm

- \* Given DGM with
  - G=T binary directed tree
  - Bernoulli CPDs
  - not summed out x<sub>e</sub>,
- $\star$  Compute  $\sum_{oldsymbol{x}_{V\setminus e}} p(oldsymbol{x}_{V\setminus e}, oldsymbol{x}_e)$
- \* Subproblem, subsolution

$$s(u,i) = \sum_{x_{V(T_u)\backslash e}} P(x_{V(T_u)\backslash (e\cup\{v\})}, x_{V(T_u)\cap e}|X_u = i)$$

#### ALGORITHM -Marginalization tree dgm

- \* Visit the vertices of T from leaves to root
  - \* when at leaf I

$$s(l,i) = \begin{cases} 0 \text{ if } l \in e \text{ and } x_l \neq i \\ 1 \text{ otherwise} \end{cases}$$

\* when at vertex u with children v and w



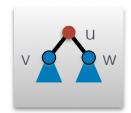
$$s(u,i) = \begin{cases} 0 \text{ if } u \in e \text{ and } x_u \neq i \text{ otherwise case below} \\ \left(\sum_{j \in \{0,1\}} P(X_v = j | X_u = i) s(v,j)\right) \left(\sum_{j \in \{0,1\}} P(X_w = j | X_u = i) s(w,j)\right) \end{cases}$$

# INTRODUCING AN "EDGE" PROBABILITY

- Visit the vertices and edges of T from leaves to root
  - \* when at edge uv (u has another child too)



$$s(uv, i) = \begin{cases} 0 \text{ if } u \in e \text{ and } x_u \neq i \text{ otherwise case below} \\ \sum_{j \in \{0,1\}} P(X_v = j | X_u = i) s(v, j) \end{cases}$$



when at vertex u with children v and w

$$s(u,i) = \begin{cases} 0 \text{ if } u \in e \text{ and } x_u \neq i \text{ otherwise case below} \\ \left(\sum_{j \in \{0,1\}} P(X_v = j | X_u = i) s(u,i)\right) \left(\sum_{j \in \{0,1\}} P(X_w = j | X_u = i) s(u,i)\right) \end{cases}$$

$$s(u,i) = \begin{cases} 0 \text{ if } u \in e \text{ and } x_u \neq i \\ s(uv,i)s(uw,i) \text{ otherwise} \end{cases}$$

#### MAR(3|NA| |/A| |()N | |RHH | )(3|M

\* Subproblem, subsolution



$$s(uv,i) = \sum_{x_{V(T_v)\backslash e}} P(x_{V(T_v)\backslash e}, x_{V(T_v)\cap e} | X_u = i)$$

$$s(uv, i) = \sum_{j \in \{0,1\}} P(X_v = j | X_u = i) s(v, j)$$

# ZOOM IN ON NON-LEAVES

- Visit the vertices and edges of T from leaves to root
  - \* when at edge uv (u has another child too)



$$s(uv, i) = \begin{cases} 0 \text{ if } u \in e \text{ and } x_u \neq i \text{ otherwise case below} \\ \sum_{j \in \{0,1\}} P(X_v = j | X_u = i) s(v, j) \end{cases}$$

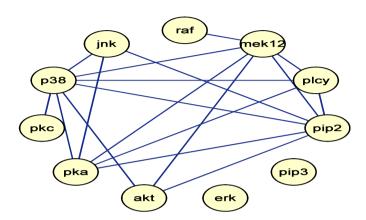


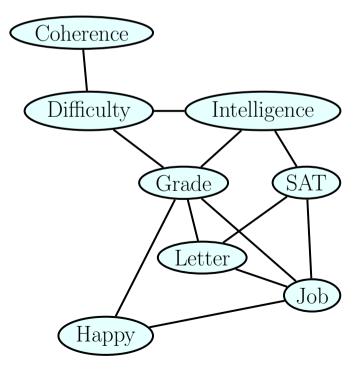
when at vertex u with children v and w

$$s(u,i) = \begin{cases} 0 \text{ if } u \in e \text{ and } x_u \neq i \text{ otherwise case below} \\ \left(\sum_{j \in \{0,1\}} P(X_v = j | X_u = i) s(u,i)\right) \left(\sum_{j \in \{0,1\}} P(X_w = j | X_u = i) s(u,i)\right) \end{cases}$$

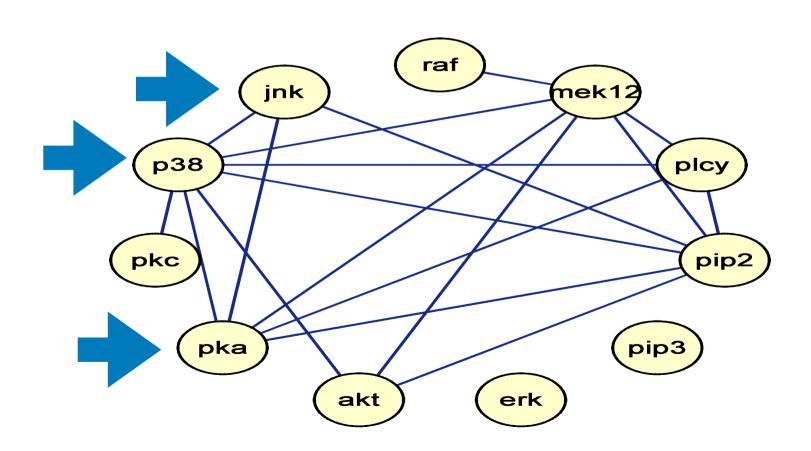
$$s(u,i) = \begin{cases} 0 \text{ if } u \in e \text{ and } x_u \neq i \\ s(uv,i)s(uw,i) \text{ otherwise} \end{cases}$$

- UGMs Undirected graphical models
- What is the direction between 2 pixels, 2 proteins?
- Probabilistic interpretation?
- p factorizes over G can be expressed as normalized product over factors associated with cliques

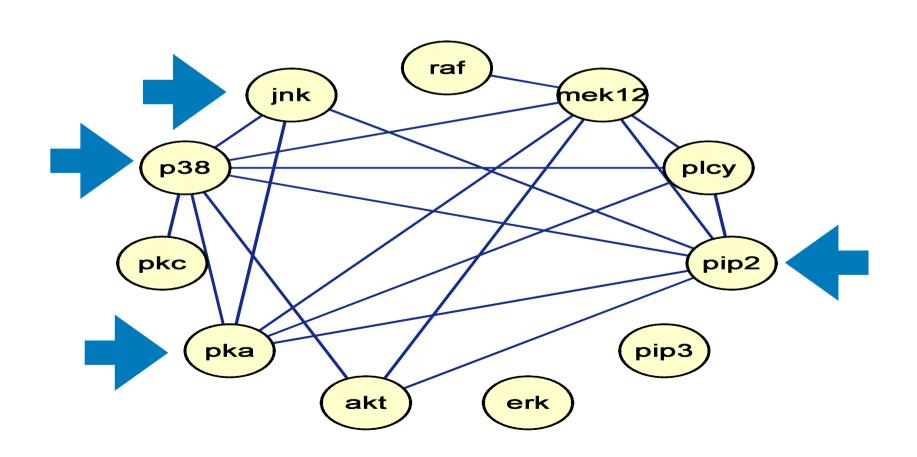




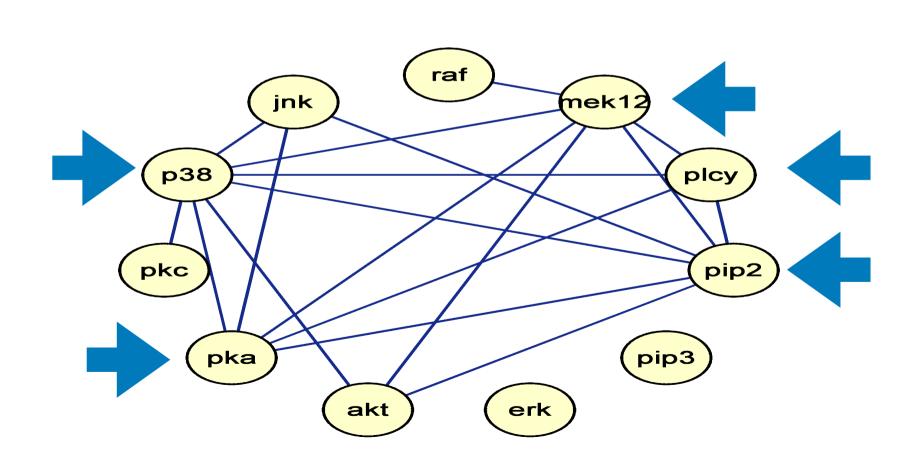
### EXAMPLE CLIQUE



# EXAMPLE MAXIMAL CIQUE



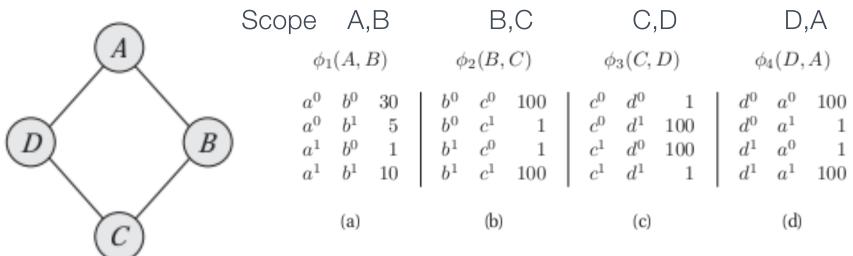
# EXAMPLE MAXIMUM CIQUE



### 

- \* An undirected graph G with so-called factors associated with its maximal cliques C(G) , for  $C \in C(G)$  factor  $\psi_C$
- $\star$   $\psi_C$  is a function from the clique's variables (the scope) to non-neg real numbers

$$p(x_1, \dots, x_V) = \frac{1}{Z} \prod_{C \in C(G)} \psi_C(x_C)$$
$$Z = \sum_{x_1, \dots, x_V} \prod_{C \in C(G)} \psi_C(x_C)$$



Factors - misconception example

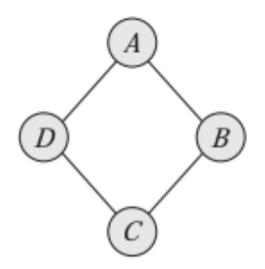
•

$$P(A, B, C, D) = \frac{1}{Z}\phi_1(A, B)\phi_2(B, C)\phi_3(C, D)\phi_4(D, A)$$

•

$$Z = \sum_{a,b,c,d} \phi_1(a,b)\phi_2(b,c)\phi_3(c,d)\phi_4(d,a)$$

#### PROBABILIS IC INTERPRETATION



Misconception

$$\phi_1(A = 1, B = 1)\phi_2(B = 1, C = 0)\phi_3(C = 0, D = 1)\phi_4(D = 1, A = 1)$$

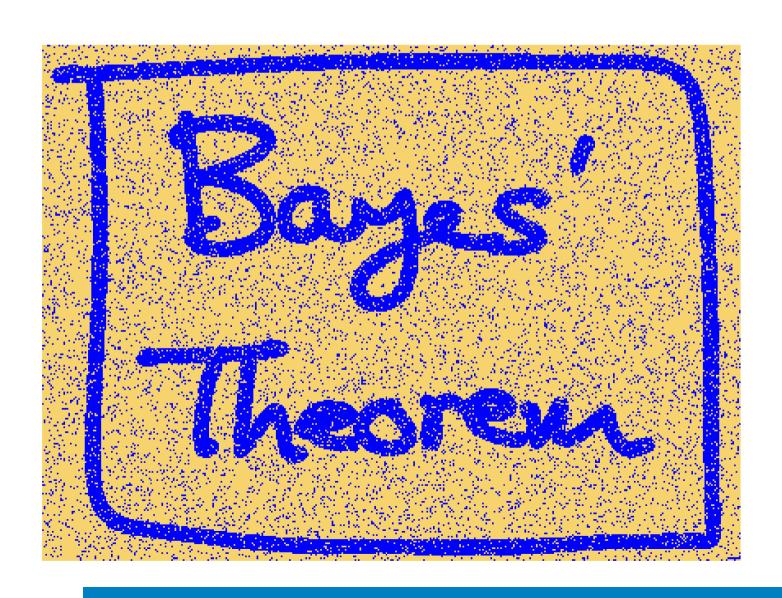
$$= 10 \cdot 1 \cdot 100 \cdot 100$$

$$= 1000000$$

$$Z = \sum_{a,b,c,d} \phi_1(a,b)\phi_2(b,c)\phi_3(c,d)\phi_4(d,a)$$

A FACTOR PRODUCT

### DE-NOISING



#### ISING MODEL-DE-NOISING

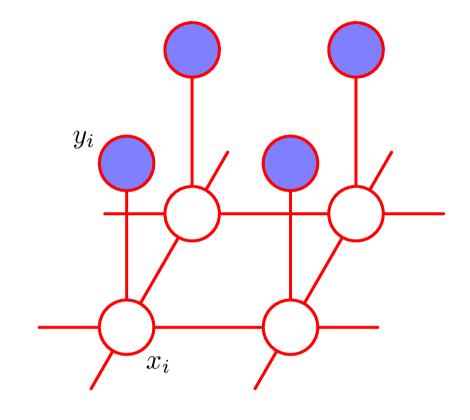
Values -1,1

Factors of form

$$e^{\beta x_i x_j}$$

and

$$e^{\eta x_i y_i}$$



#### ISING MODEL-DE-NOISING

Values -1,1

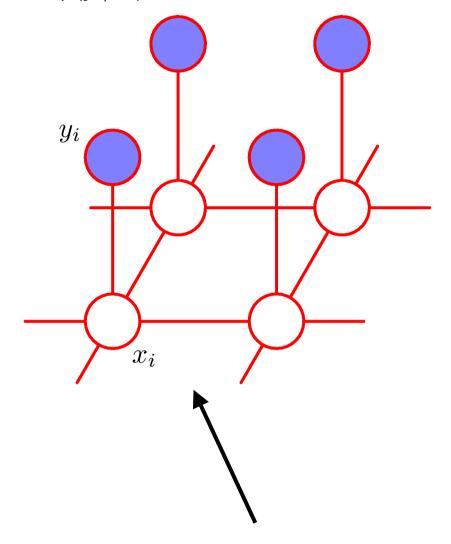
Factors of form

$$e^{\beta x_i x_j}$$

and

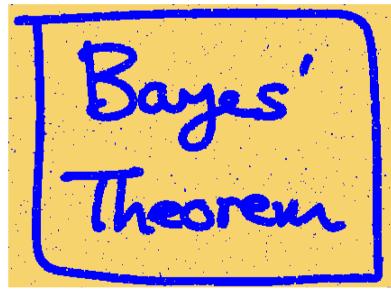
$$e^{\eta x_i y_i}$$

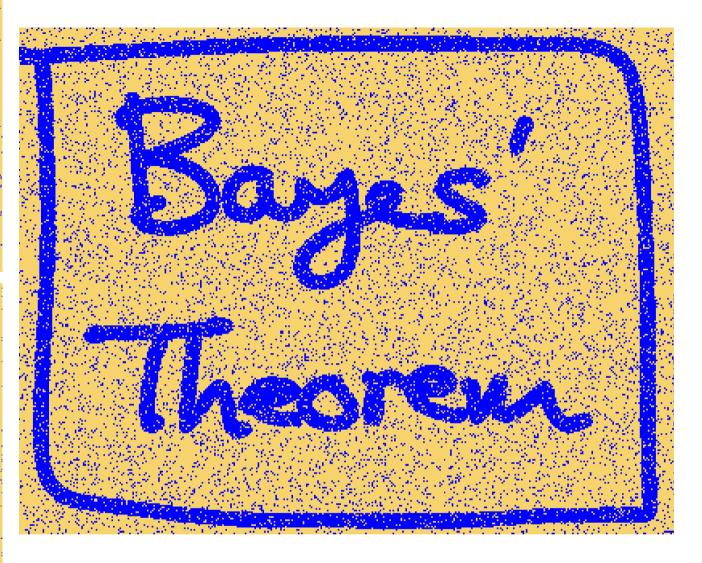
p(y | x ) ex Gaussian



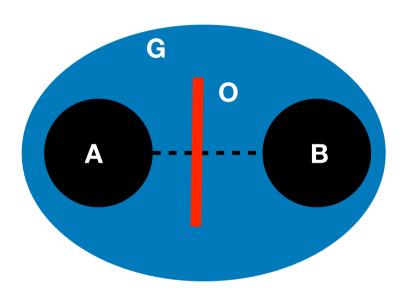
- ⋆ Bipartite graph
- Suggests iterative procedu







 Large is the noisy image; upper, UGM de-noised; and lower, graph cut de-noised



#### SEPARATION AND CLOF UGM

- ★ A is separated from B given O in G if there is no path between A and B in G\O
- ★ In a graph G,

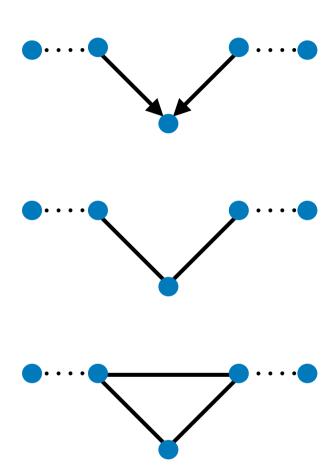
$$m{x}_A \perp_G m{x}_B | m{x}_O$$



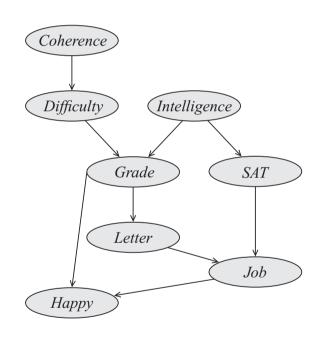
A is separated from B given O

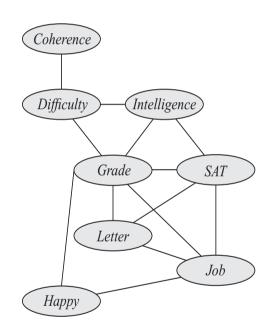
#### MORALIZATION

- Moralization add edge between any two parents
- We can moralize a DGM and get a UGM having no more independence relations
- Each family is a clique in the moralized UGM



### CONVERTING DGM TO UGM





- Moralize and remove directions
  - does not introduce new independencies!
- Use CPDs as factors

## EXACT ALGORITHMS FOR GRAPHICAL MODELS

- Many problems are NP-hard (marginalization etc.)
- ★ For trees, many of them can be solved by DP
- \* When the graph is "tree-like" find a representation of the "tree-likes" and use it to guide DP
- ★ Unfortunately, finding the representation is not always easy
- Next time assuming the representation is given.
- Independent set as exercise.
- Then marginalization.