

SOS

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Main Application Flow

Implement an application that calls the SOS module and use 2 tasks -

Task 1: Toggle LED_0 (Every 300 Milli-Seconds)

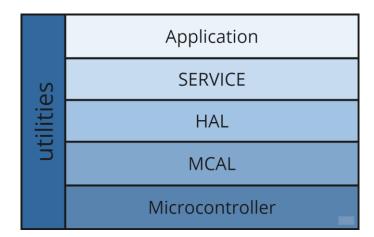
Task 2: Toggle LED_1 (Every 500 Milli-Seconds)

Make sure that these tasks occur periodically and forever

When pressing PBUTTON0, the SOS will stop

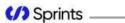
When Pressing PBUTTON1, the SOS will run

High Level Design



Layered Architecture

Application Layer:



This is the topmost layer of the software stack, which contains the actual application logic. It interacts with the lower layers to perform its tasks. It is responsible for implementing the desired functionality of the system.

SERVICE Layer:

This layer plays a key role in abstracting and encapsulating the low-level hardware details provided by the MCAL. It provides a set of services, functions, and interfaces that enable the application layer to interact with the underlying hardware

HAL Layer:

This layer provides an abstraction for external devices connected to the microcontroller. The HAL layer provides interface to access external devices and hides the implementation details from the application layer.

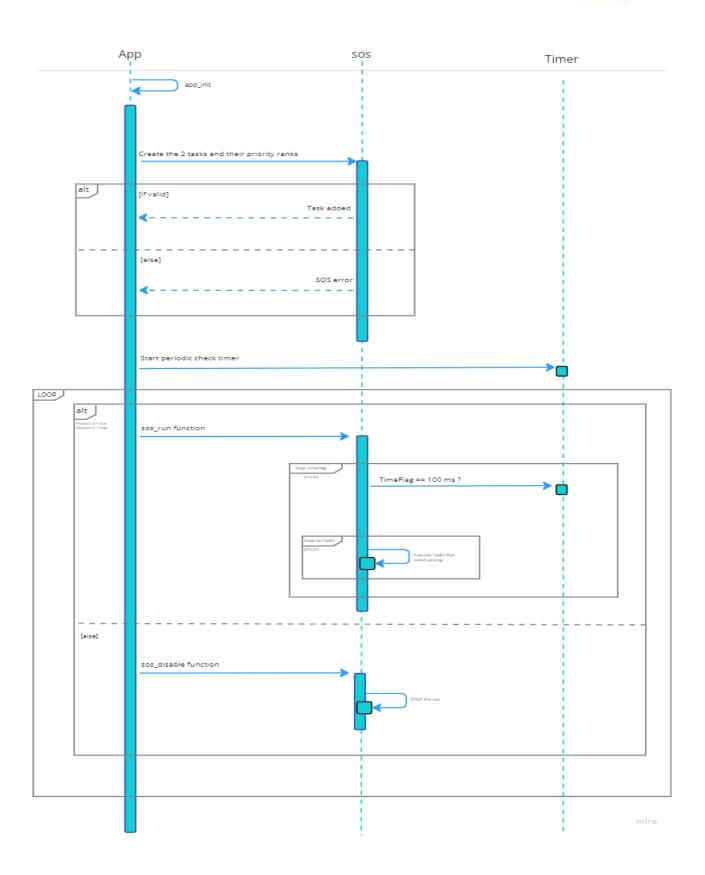
MCAL Layer:

(Microcontroller Abstraction Layer): This layer provides an abstraction for the microcontroller hardware. It includes low-level drivers for peripherals. It hides the hardware details and provides a uniform interface to the upper layers.

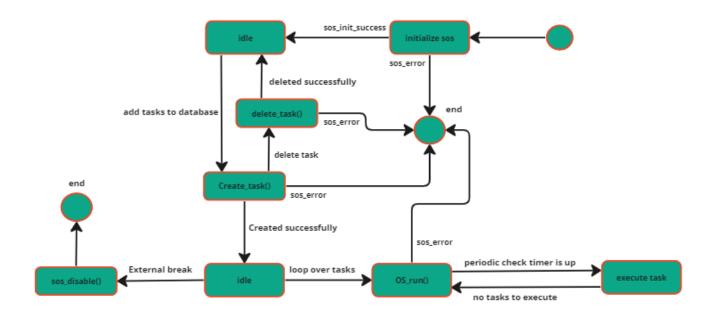
Microcontroller:

This layer represents the physical hardware layer consisting of the microcontroller chip. The microcontroller is responsible for executing the code stored in its memory and controlling the behavior of the system.

Sequence Diagram (FOR HQ ->S.D)



State Machine Diagram





Class Diagram

sos

- g_u8_task_counter
- g_u8_init_flag
- + str_sos_config_task_t
- + enu_sos_status_t
- + sos_init() : enu_sos_Status_t
- + sos_create_task(u8 u8_Priority, str_sos_configTask_t* str_sos_configTask) : enu_sos_Status_t
- + sos_delete_task(u8 u8_Priority): enu_sos_Status_t
- + sos_run(void) : enu_sos_Status_t
- + sos_deinit(void) : enu_sos_Status_t
- + sos_modify_task(u8 u8_Priority, str_sos_configTask_t* str_sos_configTask) : enu_sos_Status_t
- + sos_disable(void): enu_sos_Status_t

∖ USE

Timer

- + TIMER_2_init(Timer_Mode mode) : Timer_ErrorStatus
- + TIMER_2_start(Timer_Prescaler prescaler) : Timer_ErrorStatus
- + TIMER_2_stop(void): void
- + TIMER 2 setIntialValue(uint8 t value): Timer ErrorStatus
- + TIMER_2_OvfNum(double overflow) : Timer_ErrorStatus
- + TIMER_2_DELAY_MS(double _delay) : void
- + TIMER_2_INT(): void

miro



Drivers' Documentation (APIs)

```
typedef struct
{
    /* Selecting the periodicity of the selected task */
    u8 u8Periodicity;
    /* Assigning the pointer to the task function */
    void (*pfTask) (void);
} strOSConfigTask_t;

typedef Enum{
    OS_OK,
    OS_ERROR,
    PRIORITY_EMPTY,
    PRIORITY_FULL,
    OS_INIT,
    OS_INIT,
    OS_TASK_ADDED,
    OS_TASK_DELETED
    } enuOSErrorStatus_t;
```

Syntax	enuOSErrorStatus_t OS_Init ()
Description	A function to initialize the timer used in OS
Sync\Async	Synchronous
Reentrancy	Reentrant
Parameters (in)	void
Parameters (out)	None
Return value	<pre>typedef Enum{ OS_OK, OS_ERROR, PRIORITY_EMPTY, PRIORITY_FULL, OS_INIT, OS_TASK_ADDED, OS_TASK_DELETED } enuOSErrorStatus t;</pre>

Syntax	<pre>enuOSErrorStatus_t OS_CreateTask (u8 u8Priority, strOSConfigTask_t* strOSConfigTask_t)</pre>
Description	A function to create a certain task
Sync\Async	Synchronous
Reentrancy	Reentrant
Parameters (in)	*strOSConfigTask_t
Parameters (out)	None
Return value	typedef Enum{ OS_OK, OS_ERROR, PRIORITY_EMPTY, PRIORITY_FULL, OS_INIT, OS_TASK_ADDED, OS_TASK_DELETED
	} enuOSErrorStatus_t;



Syntax	tax enuOSErrorStatus_t OS_DeleteTask (u8 u8Priority)	
Description	A function to delete a certain task	
Sync\Async	Synchronous	
Reentrancy	Reentrant	
Parameters (in)	*strOSConfigTask_t	
Parameters (out)	None	
Return value	typedef Enum{ OS OK,	
	OS_ERROR,	
	PRIORITY_EMPTY, PRIORITY_FULL,	
	OS_INIT,	
	OS_TASK_ADDED,	
	OS_TASK_DELETED	
	<pre>} enuOSErrorStatus_t;</pre>	

Syntax	<pre>enuOSErrorStatus_t OS_modify_task (u8 u8Priority, strOSConfigTask_t* strOSConfigTask_t)</pre>
Description	A function to modify a certain task
Sync\Async	Synchronous
Reentrancy	Reentrant
Parameters (in)	*str0SConfigTask_t
Parameters (out)	None
Return value	typedef Enum{
	OS_OK,
	OS_ERROR,
	PRIORITY_EMPTY,
	PRIORITY_FULL,
	OS_INIT,
	OS_TASK_ADDED,
	OS_TASK_DELETED
	} enuOSErrorStatus t;

Syntax	<pre>void OS_Run(void)</pre>
Description	A function to run the OS
Sync\Async	Synchronous
Reentrancy	Reentrant
Parameters (in)	void
Parameters (out)	None
Return value	void

Syntax	<pre>void OS_disable ()</pre>
Description	A function to disable running of OS
Sync\Async	Synchronous
Reentrancy	Reentrant
Parameters (in)	void
Parameters (out)	None
Return value	void