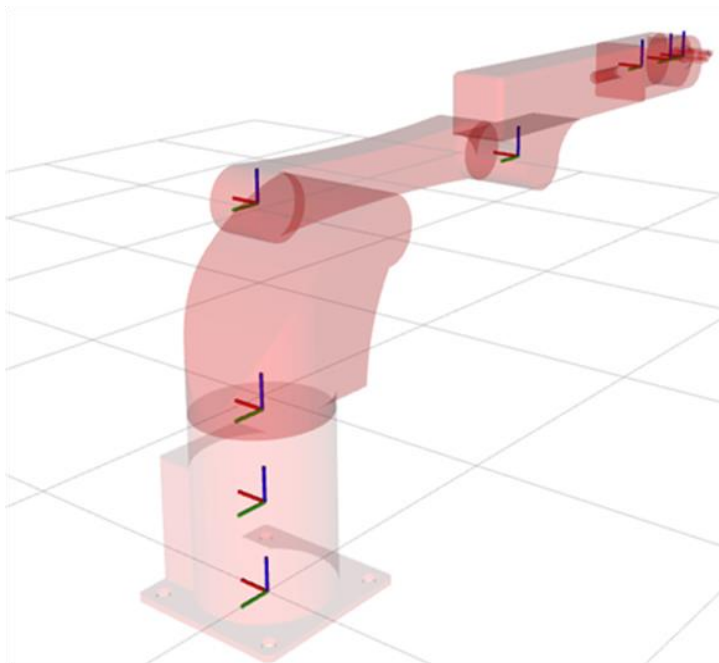




Industrial Robotics

TASK 3

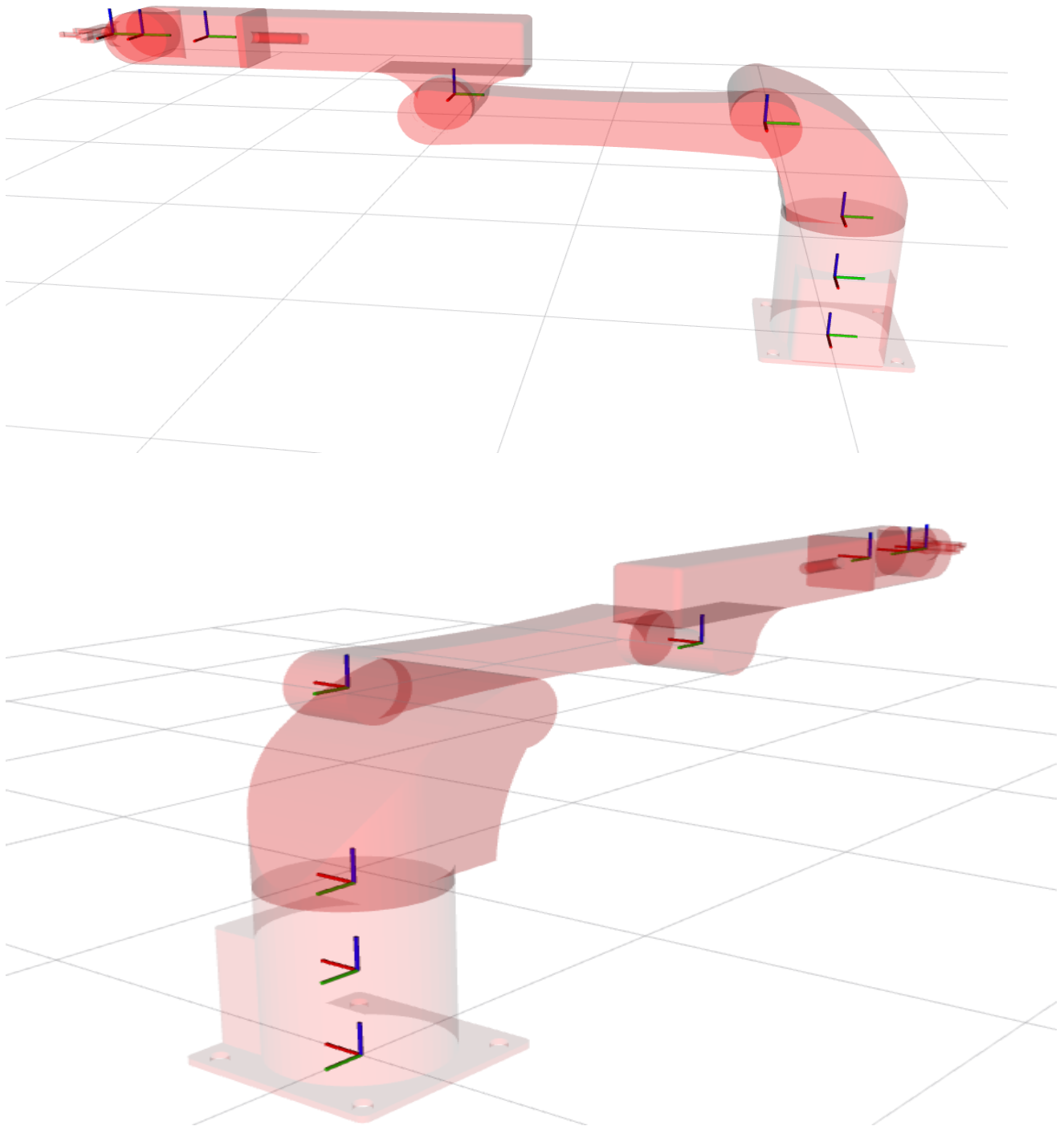


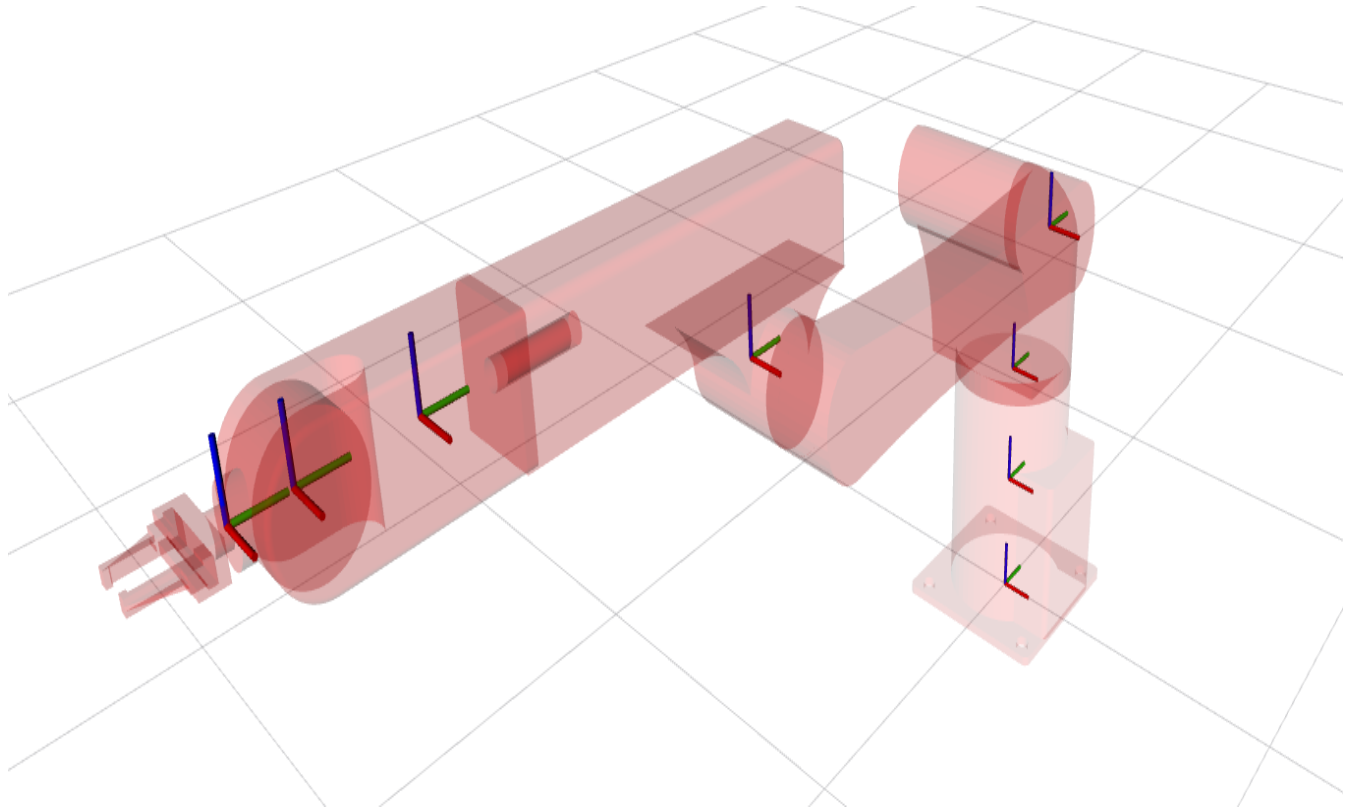
Ahmed Abdallah Youssef
15P8114

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16P8221

Model Section

The model taken from Rviz workspace is as shown in the following figures.

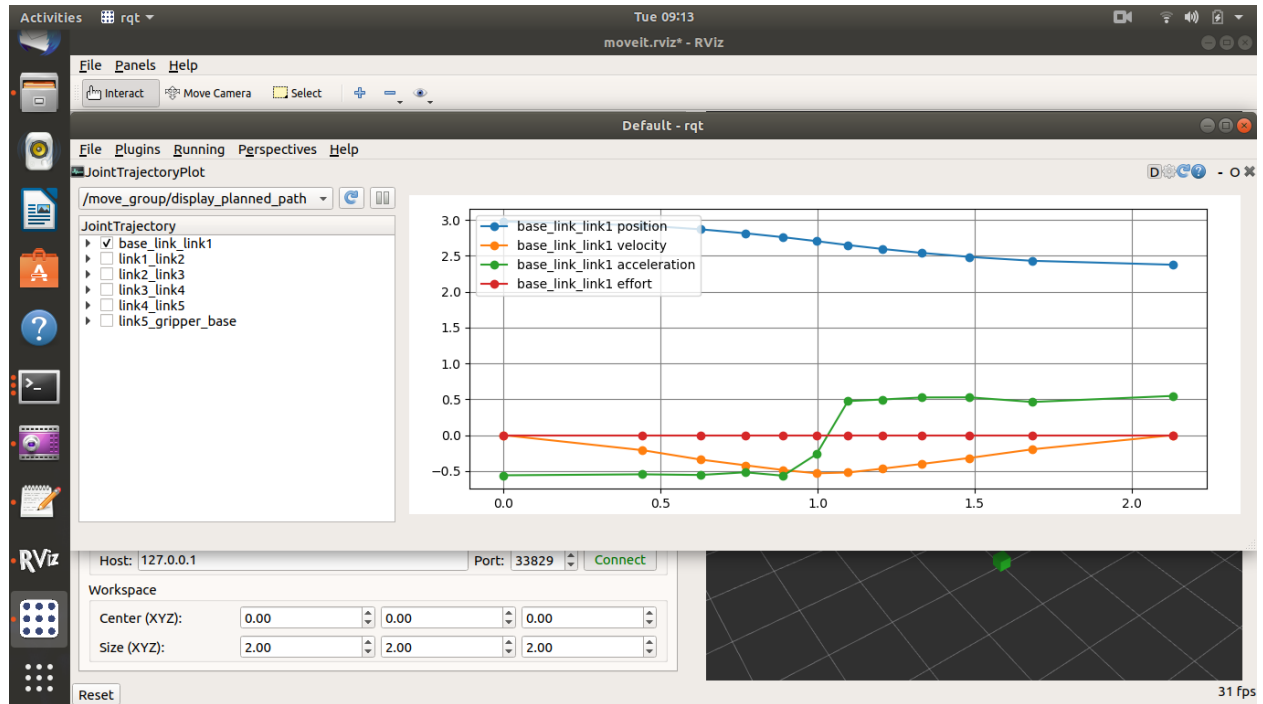




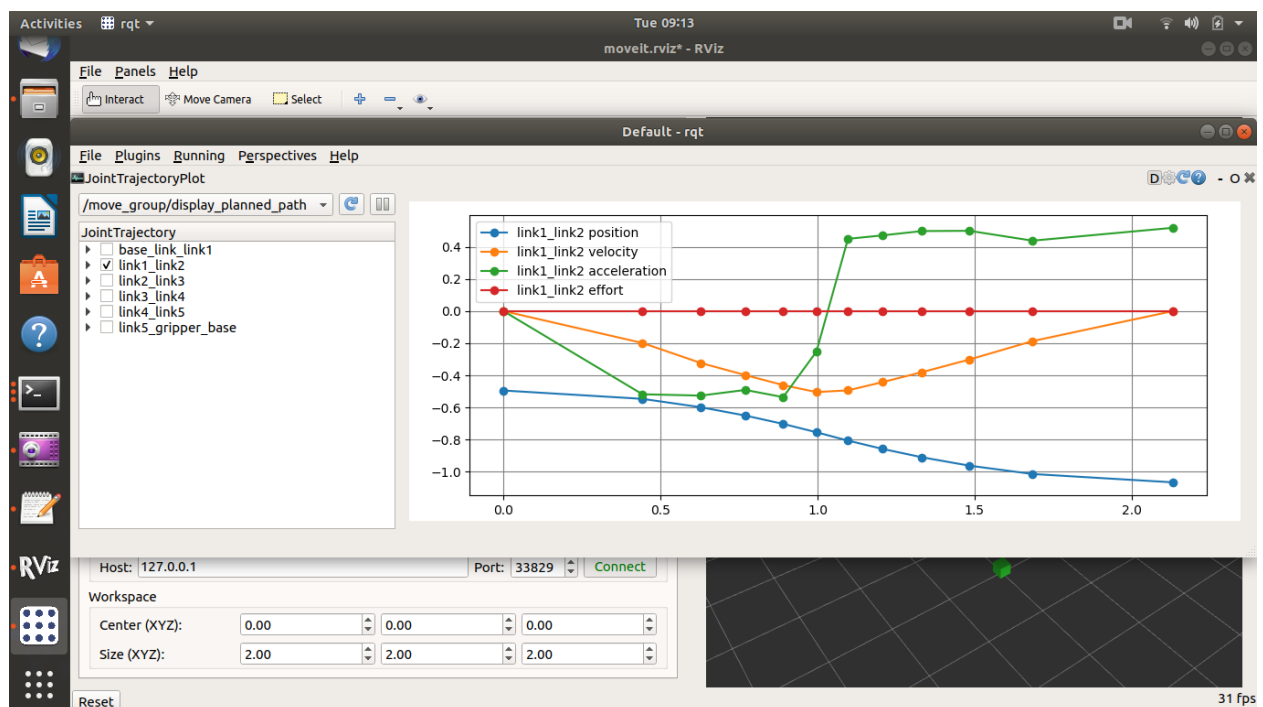
Motion Planning Section

Trajectory for each Joint is shown in the following figures

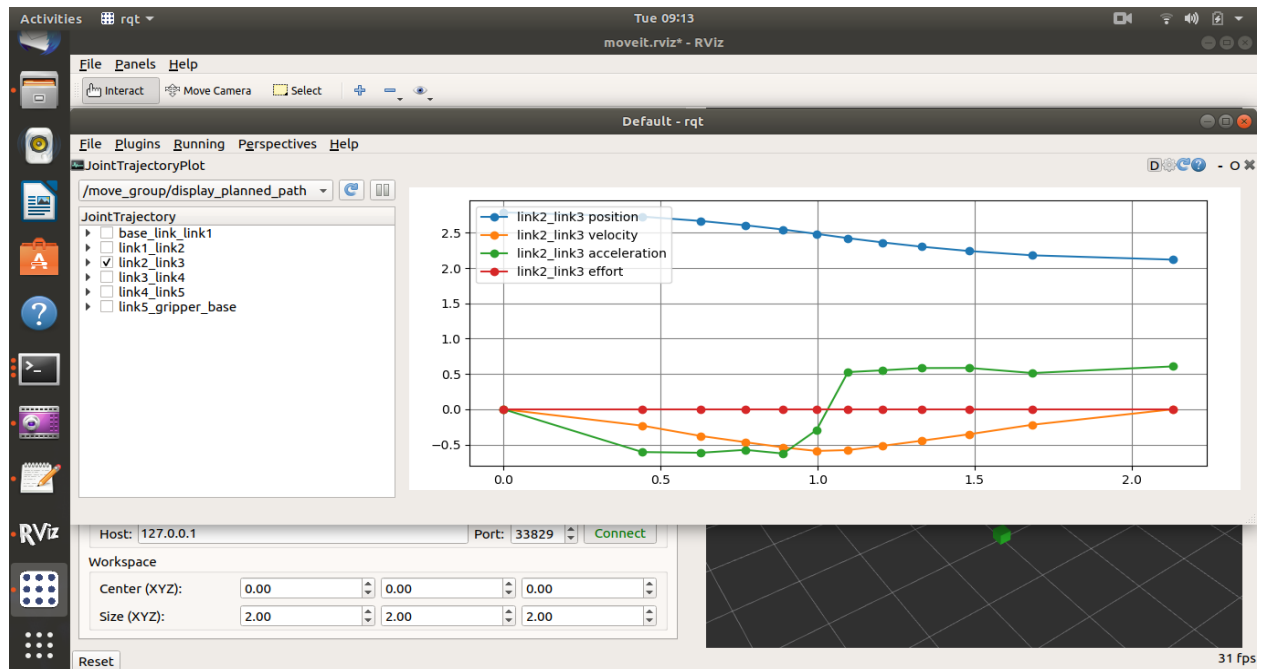
- Joint 1



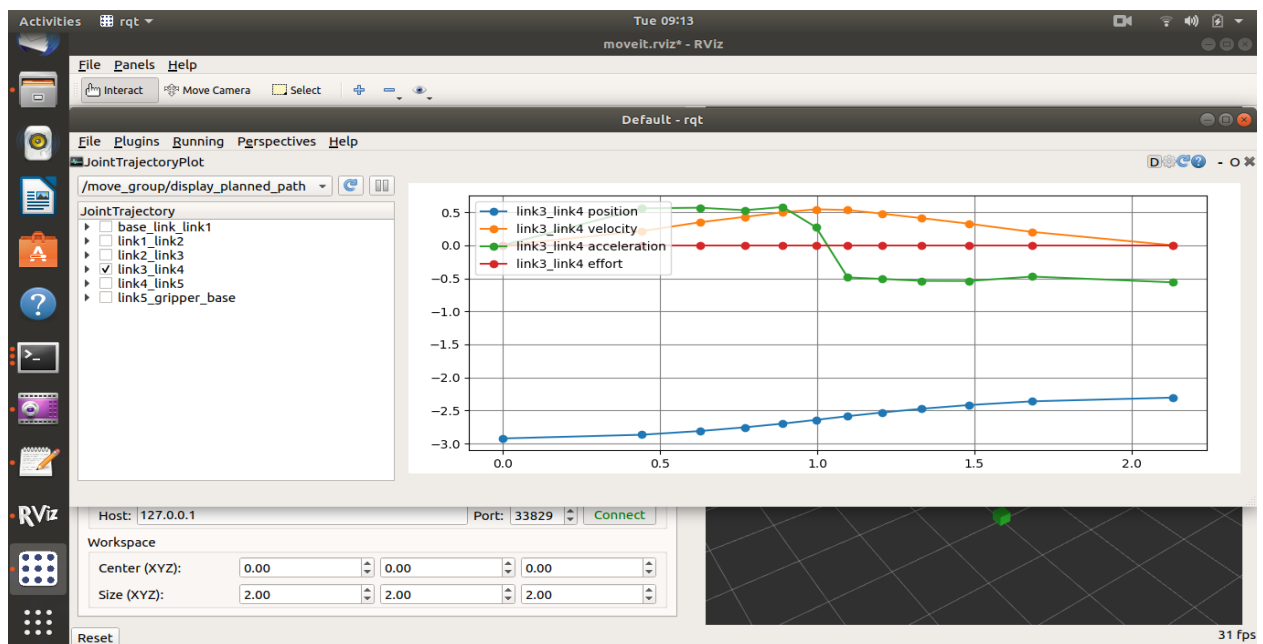
- Joint 2



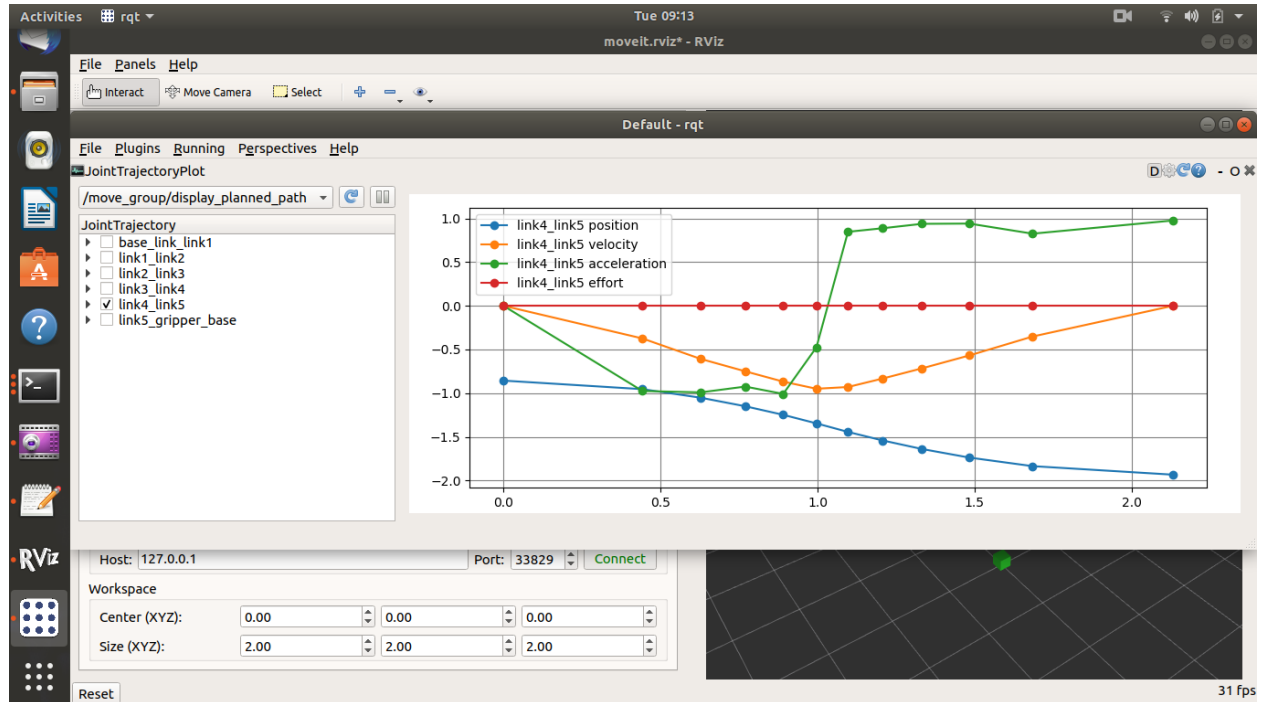
- Joint 3



- Joint 4



- Joint 5



- Joint 6

