
Integration Manual

for MPC574XG DIO Driver

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Chapter 1

Revision History

Table 1-1. Revision History

Revision	Date	Author	Description
1.0	17-Feb-2017	Duc Ta (B53913)	Version for Calypso Release 1.0.0



Chapter 2

Introduction

This integration manual describes the integration requirements for Dio Driver for MPC574XG microcontrollers.

2.1 Supported Derivatives

The software described in this document is intended to be used with the following microcontroller devices of NXP Semiconductor .

Table 2-1. MPC574XG Derivatives

NXP Semiconductor	MPC5748G_LQFP176, MPC5748G_MAPBGA256, MPC5748G_MAPBGA324, MPC5747G_LQFP176, MPC5747G_MAPBGA256, MPC5747G_MAPBGA324, MPC5746G_LQFP176, MPC5746G_MAPBGA256, MPC5746G_MAPBGA324, MPC5748C_LQFP176, MPC5748C_MAPBGA256, MPC5748C_MAPBGA324, MPC5747C_LQFP176, MPC5747C_MAPBGA256, MPC5747C_MAPBGA324, MPC5746C_LQFP176, MPC5746C_MAPBGA256, MPC5746C_MAPBGA324, MPC5746C_MAPBGA100, MPC5745C_LQFP176, MPC5745C_MAPBGA256, MPC5745C_MAPBGA100, MPC5744C_LQFP176, MPC5744C_MAPBGA256, MPC5744C_MAPBGA100, MPC5746B_LQFP176, MPC5746B_MAPBGA256, MPC5746B_MAPBGA100, MPC5744B_LQFP176, MPC5744B_MAPBGA256,
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Table 2-1. MPC574XG Derivatives

	MPC5744B_MAPBGA100, MPC5745B_LQFP176, MPC5745B_MAPBGA256, MPC5745B_MAPBGA100
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All of the above microcontroller devices are collectively named as MPC574XG .

2.2 Overview

AUTOSAR (AUTomotive Open System ARchitecture) is an industry partnership working to establish standards for software interfaces and software modules for automobile electronic control systems.

AUTOSAR

- paves the way for innovative electronic systems that further improve performance, safety and environmental friendliness.
- is a strong global partnership that creates one common standard: "Cooperate on standards, compete on implementation".
- is a key enabling technology to manage the growing electrics/electronics complexity. It aims to be prepared for the upcoming technologies and to improve cost-efficiency without making any compromise with respect to quality.
- facilitates the exchange and update of software and hardware over the service life of the vehicle.

2.3 About this Manual

This Technical Reference employs the following typographical conventions:

Boldface type: Bold is used for important terms, notes and warnings.

Italic font: Italic typeface is used for code snippets in the text. Note that C language modifiers such "const" or "volatile" are sometimes omitted to improve readability of the presented code.

Notes and warnings are shown as below:

Note

This is a note.

2.4 Acronyms and Definitions

Table 2-2. Acronyms and Definitions

Term	Definition
API	Application Programming Interface
AUTOSAR	Automotive Open System Architecture
ASM	Assembler
BSMI	Basic Software Make file Interface
CAN	Controller Area Network
DEM	Diagnostic Event Manager
DET	Development Error Tracer
C/CPP	C and C++ Source Code
VLE	Variable Length Encoding
N/A	Not Applicable
MCU	Micro Controller Unit
DIO	Digital Input Output

2.5 Reference List

Table 2-3. Reference List

#	Title	Version
1	AUTOSAR 4.2 Rev0002Dio Driver Software Specification Document.	2.5.0
2	MPC5748G Reference Manual	Rev. 5, 12/2016
3	MPC5748G_1N81M_Rev.2 (official document) (1N81M)	Jun-16
4	MPC5748G_1N81M_0N78S_Comparison_Summary_v2_0 (internal document) (1N81M, 0N78S)	31.10.2016
5	MPC5746C_1N06M_Rev.4 (official document) (1N06M)	Jul-16
6	MPC5746C_cut1.1_cut2.0_cut2.1_comparison_v0 (internal document) (1N06M, 0N84S, 1N84S)	14-Sep-16
7	C3M_cut2.1_new_errata_20170113 (internal document) (1N84S)	13-Jan-17

Chapter 3

Building the Driver

This section describes the source files and various compilers, linker options used for building the Autosar Dio driver for NXP Semiconductor MPC574XG . It also explains the EB Tresos Studio plugin setup procedure.

3.1 Build Options

The Dio driver files are compiled using

- Windriver DIAB DIAB_5_9_6_2
- Green Hills Multi 7.1.4 / Compiler 2015.1.6

The compiler, linker flags used for building the driver are explained below:

Note

The TS_T2D35M10I0R0 plugin name is composed as follow:

TS_T = Target_Id

D = Derivative_Id

M = SW_Version_Major

I = SW_Version_Minor

R = Revision

(i.e. Target_Id = 2 identifies PA architecture and Derivative_Id = 35 identifies the MPC574XG)

3.1.1 DIAB Compiler/Linker/Assembler Options

Table 3-1. Compiler Options

Option	Description
-tPPCE200Z4204N3VEN:simple	Sets target processor to PPCE200Z4204N3VEN, generates ELF using EABI conventions, No floating point support (minimizes the required runtime), selects simple environment settings for Startup Module and Libraries
-tPPCE200Z210N3VEN:simple	Sets target processor to PPCE200Z210N3VEN, generates ELF using EABI conventions, No floating point support (minimizes the required runtime), selects simple environment settings for Startup Module and Libraries
-Xdialect-ansi	Follow the ANSI C standard with some additions
-XO	Enables extra optimizations to produce highly optimized code
-g3	Generate symbolic debugger information and do all optimizations.
-Xsize-opt	Optimize for size rather than speed when there is a choice
-Xsmall-data=0	Set Size Limit for 'small data' Variables to zero.
-Xsmall-const=0	Set Size Limit for "small const" Variables to zero.
-Xaddr-sconst=0x11	Specify addressing for constant static and global variables with size less than or equal to -Xsmall-const to far-absolute.
-Xaddr-sdata=0x11	Specify addressing for non-constant static and global variables with size less than or equal to -Xsmall-data in size to far-absolute.
-Xno-common	Disable use of the 'COMMON' feature so that the compiler or assembler will allocate each uninitialized public variable in the .bss section for the module defining it, and the linker will require exactly one definition of each public variable
-Xnested-interrupts	Allow nested interrupts
-Xdebug-dwarf2	Generate symbolic debug information in dwarf2 format
-Xdebug-local-all	Force generation of type information for all local variables
-Xdebug-local-cie	Create common information entry per module
-Xdebug-struct-all	Force generation of type information for all typedefs, struct, union and class types
-Xforce-declarations	Generates warnings if a function is used without a previous declaration
-ee1481	Generate an error when the function was used before it has been declared
-Xmacro-undefined-warn	Generates a warning when an undefined macro name occurs in a #if preprocessor directive
-Xlink-time-lint	Enable the checking of object and function declarations across compilation units, as well as the consistency of compiler options used to compile source files
-W:as,-l	Pass the option '-l' (lower case letter L) to the assembler to get an assembler listing file
-Wa,-Xisa-vle	Instruct the assembler to expect and assemble VLE (Variable Length Encoding) instructions rather than BookE instructions.
-DAUTOSAR_OS_NOT_USED	-D defines a preprocessor symbol and optionally can set it to a value. AUTOSAR_OS_NOT_USED: By default in the package, the drivers are compiled to be used without Autosar OS. If the drivers are used with Autosar OS, the compiler option '-DAUTOSAR_OS_NOT_USED' must be removed from project options
-DUSE_SW_VECTOR_MODE	-D defines a preprocessor symbol and optionally can set it to a value. USE_SW_VECTOR_MODE: By default in the package, drivers are compiled to be used with interrupt controller configured to be in hardware vector mode. In case of AUTOSAR_OS_NOT_USED, the compiler option "-DUSE_SW_VECTOR_MODE" must be added to the list of compiler options to be used with interrupt controller configured to be in software vector mode.

Table continues on the next page...

Table 3-1. Compiler Options (continued)

Option	Description
-DDIAB	-D defines a preprocessor symbol and optionally can set it to a value. This one defines the DIAB preprocessor symbol.
-DDISABLE_MCAL_INTERMODULE_ASRCHECK	-D defines a preprocessor symbol to disable the inter-module version check for AR_RELEASE versions. DISABLE_MCAL_INTERMODULE_ASRCHECK: By default in the package, drivers are compiled to perform the inter-module version check as per Autosar BSW004. When the inter-module version check needs to be disabled then the DISABLE_MCAL_INTERMODULE_ASRCHECK global define must be added to the list of compiler options.
-c	Stop after assembly, produce object file.

Table 3-2. Assembler Options

Option	Description
-tPPCE200Z4204N3VEN:simple	Sets target processor to PPCE200Z4204N3VEN, generates ELF using EABI conventions, No floating point support (minimizes the required runtime), selects simple environment settings for Startup Module and Libraries
-tPPCE200Z210N3VEN:simple	Sets target processor to PPCE200Z210N3VEN, generates ELF using EABI conventions, No floating point support (minimizes the required runtime), selects simple environment settings for Startup Module and Libraries
-g	Dump the symbols in the global symbol table in each archive file.
-Xisa-vle	Expect and assemble VLE (Variable Length Encoding) instructions rather than Book E instructions. The default code section is named .text_vle instead of .text, and the default code section fill "character" is set to 0x44444444 instead of 0. The .text_vle code section will have ELF section header flags marking it as VLE code, not Book E code.
-Xasm-debug-on	Generate debug line and file information
-Xdebug-dwarf2	Generate symbolic debug information in dwarf2 format
-Xsemi-is-newline	Treat the semicolon (;) as a statement separator instead of a comment character.

Table 3-3. Linker Options

Option	Description
-tPPCE200Z4204N3VEN:simple	Sets target processor to tPPCE200Z4204N3VEN, generates ELF using EABI conventions, No floating point support (minimizes the required runtime), selects simple environment settings for Startup Module and Libraries
-tPPCE200Z210N3VEN:simple	Sets target processor to tPPCE200Z210N3VEN, generates ELF using EABI conventions, No floating point support (minimizes the required runtime), selects simple environment settings for Startup Module and Libraries
-Xelf	Generates ELF object format for output file
-m6	Generates a detailed link map and cross reference table
-Xlink-time-lint	Enable the checking of object and function declarations across compilation units, as well as the consistency of compiler options used to compile source files

3.1.2 GHS Compiler/Linker/Assembler Options

Table 3-4. Compiler Options

Option	Description
-cpu=ppc5748gz4204	Selects target processor: ppc5748gz4204
-cpu=ppc5748gz210	Selects target processor: ppc5748gz210
-ansi	Specifies ANSI C with extensions. This mode extends the ANSI X3.159-1989 standard with certain useful and compatible constructs.
-noSPE	Disables the use of SPE and vector floating point instructions by the compiler.
-Ospace	Optimize for size.
-sda=0	Enables the Small Data Area optimization with a threshold of 0.
-vle	Enables VLE code generation
-dual_debug	Enables the generation of DWARF, COFF, or BSD debugging information in the object file
-G	Generates source level debugging information and allows procedure call from debugger's command line.
--no_exceptions	Disables support for exception handling
-Wundef	Generates warnings for undefined symbols in preprocessor expressions
-Wimplicit-int	Issues a warning if the return type of a function is not declared before it is called
-Wshadow	Issues a warning if the declaration of a local variable shadows the declaration of a variable of the same name declared at the global scope, or at an outer scope
-Wtrigraphs	Issues a warning for any use of trigraphs
--prototype_errors	Generates errors when functions referenced or called have no prototype
--incorrect_pragma_warnings	Valid #pragma directives with wrong syntax are treated as warnings
-noslashcomment	C++ like comments will generate a compilation error
-preprocess_assembly_files	Preprocesses assembly files
-nostartfile	Do not use Start files
--short_enum	Store enumerations in the smallest possible type
--diag_error 223	Sets the specified compiler diagnostic messages to the level of error
-DAUTOSAR_OS_NOT_USED	-D defines a preprocessor symbol and optionally can set it to a value. AUTOSAR_OS_NOT_USED: By default in the package, the drivers are compiled to be used without Autosar OS. If the drivers are used with Autosar OS, the compiler option '-DAUTOSAR_OS_NOT_USED' must be removed from project options
-DUSE_SW_VECTOR_MODE	-D defines a preprocessor symbol and optionally can set it to a value. USE_SW_VECTOR_MODE: By default in the package, drivers are compiled to be used with interrupt controller configured to be in hardware vector mode. In case of AUTOSAR_OS_NOT_USED, the compiler option "-DUSE_SW_VECTOR_MODE" must be added to the list of compiler options to be used with interrupt controller configured to be in software vector mode.
-DDISABLE_MCAL_INTERMODULE_ASR_CHECK	-D defines a preprocessor symbol to disable the inter-module version check for AR_RELEASE versions. DISABLE_MCAL_INTERMODULE_ASR_CHECK: By default in the package, drivers are compiled to perform the inter-module version check as per Autosar BSW004. When the inter-module version check needs to be disabled then the DISABLE_MCAL_INTERMODULE_ASR_CHECK global define must be added to the list of compiler options.
-DGHS	-D defines a preprocessor symbol and optionally can set it to a value. This one defines the GHS preprocessor symbol.
-c	Produces an object file (called input-file.o) for each source file.

Table 3-5. Assembler Options

Option	Description
-cpu=ppc5748gz4204	Selects target processor: ppc5748gz4204
-cpu=ppc5748gz210	Selects target processor: ppc5748gz210
-G	Generates source level debugging information and allows procedure call from debugger's command line.
-list	Creates a listing by using the name of the object file with the .lst extension

Table 3-6. Linker Options

Option	Description
-cpu=ppc5748gz4204	Selects target processor: ppc5748gz4204
-cpu=ppc5748gz210	Selects target processor: ppc5748gz210
-nostartfiles	Do not use Start files.
-vle	Enables VLE code generation
--nocpp	Do not Generate Constructors/Destructors
-Mn	sort numerically the MAP file
-delete	The -delete option instructs the linker to remove functions that are not referenced in the final executable.
-ignore_debug_references	Ignores relocations from DWARF debug sections when using -delete. DWARF debug information will contain references to deleted functions that may break some third-party debuggers.
-keepmap	keeps the MAP file in case of link error

3.2 Files required for Compilation

This section describes the include files required to compile, assemble (if assembler code) and link the Dio driver for MPC574XG microcontrollers.

To avoid integration of incompatible files, all the include files from other modules shall have the same AR_RELEASE_MAJOR_VERSION and AR_RELEASE_MINOR_VERSION, i.e. only files with the same AUTOSAR major and minor versions can be compiled.

Dio Files

- ..\Dio_TS_T2D35M10I0R0\include\Dio.h
- ..\Dio_TS_T2D35M10I0R0\include\Dio_EnvCfg.h
- ..\Dio_TS_T2D35M10I0R0\include\Dio_Ipw.h
- ..\Dio_TS_T2D35M10I0R0\include\Dio_Reg_eSys_Siul2.h
- ..\Dio_TS_T2D35M10I0R0\include\Dio_Siul2.h
- ..\Dio_TS_T2D35M10I0R0\include\Siul2_IpVersion.h

- ..\Dio_TS_T2D35M10I0R0\src\Dio.c
- ..\Dio_TS_T2D35M10I0R0\src\Dio_Siul2.c

Dio Generated Files

- Dio_Cfg.c
- Dio_Cfg.h

Files from Base common folder

- ..\Base_TS_T2D35M10I0R0\include\Compiler.h
- ..\Base_TS_T2D35M10I0R0\include\Compiler_Cfg.h
- ..\Base_TS_T2D35M10I0R0\include\CompilerDefinition.h
- ..\Base_TS_T2D35M10I0R0\include\ComStack_Types.h
- ..\Base_TS_T2D35M10I0R0\include\Dio_MemMap.h
- ..\Base_TS_T2D35M10I0R0\include\Mcal.h
- ..\Base_TS_T2D35M10I0R0\include\Platform_Types.h
- ..\Base_TS_T2D35M10I0R0\include\Reg_eSys.h
- ..\Base_TS_T2D35M10I0R0\include\Reg_Macros.h
- ..\Base_TS_T2D35M10I0R0\include\Reg_LockMacros.h
- ..\Base_TS_T2D35M10I0R0\include\SilRegMacros.h
- ..\Base_TS_T2D35M10I0R0\include\Soc_Ips.h
- ..\Base_TS_T2D35M10I0R0\include\Std_Types.h
- ..\Base_TS_T2D35M10I0R0\include\StdRegMacros.h

Files from Det folder:

- ..\Det_TS_T2D35M10I0R0\include\Det.h
- ..\Det_TS_T2D35M10I0R0\src\Det.c

Files from Rte folder:

- ..\Rte_TS_T2D35M10I0R0\include\SchM_Dio.h
- ..\Rte_TS_T2D35M10I0R0\src\SchM_Dio.c

3.3 Setting up the Plug-ins

The Dio driver was designed to be configured by using the EB Tresos Studio (version EB tresos Studio 21.0.0 b160607-0933 or later.)

Location of various files inside the module folder:

- VSMD (Vendor Specific Module Definition) file in EB tresos Studio XDM format:
 - ..\Dio_TS_T2D35M10I0R0\config\Dio.xdm
- VSMD (Vendor Specific Module Definition) file(s) in AUTOSAR compliant EPD format:

- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5744b_lqfp176.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5744b_mapbga100.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5744b_mapbga256.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5744c_lqfp176.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5744c_mapbga100.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5744c_mapbga256.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5745b_lqfp176.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5745b_mapbga100.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5745b_mapbga256.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5745c_lqfp176.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5745c_mapbga100.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5745c_mapbga256.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5746b_lqfp176.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5746b_mapbga100.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5746b_mapbga256.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5746c_lqfp176.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5746c_mapbga100.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5746c_mapbga256.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5746c_mapbga324.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5746g_lqfp176.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5746g_mapbga256.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5746g_mapbga324.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5747c_lqfp176.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5747c_mapbga256.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5747c_mapbga324.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5747g_lqfp176.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5747g_mapbga256.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5747g_mapbga324.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5748c_lqfp176.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5748c_mapbga256.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5748c_mapbga324.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5748g_lqfp176.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5748g_mapbga256.epd
- ..\Dio_TS_T2D35M10I0R0\autosar\Dio_mpc5748g_mapbga324.epd
- Code Generation Templates for Pre-Compile time configuration parameters:
 - ..\Dio_TS_T2D35M10I0R0\generate_PC\include\Dio_Cfg.h
 - ..\Dio_TS_T2D35M10I0R0\generate_PC\src\Dio_Cfg.c

Steps to generate the configuration:

Setting up the Plug-ins

1. Copy the module folders Dio_TS_T2D35M10I0R0, Base_TS_T2D35M10I0R0, Resource_TS_T2D35M10I0R0, Det_TS_T2D35M10I0R0, Rte_TS_T2D35M10I0R0 into the Tresos plugins folder.
2. Set the desired Tresos Output location folder for the generated sources and header files.
3. Use the EB tresos Studio GUI to modify ECU configuration parameters values.
4. Generate the configuration files.



Chapter 4

Function calls to module

4.1 Function Calls during Start-up

None.

4.2 Function Calls during Shutdown

None.

4.3 Function Calls during Wake-up

None.

Chapter 5

Module requirements

5.1 Exclusive areas to be defined in BSW scheduler

In the current implementation, DIO is using the services of Run-Time Environment (RTE) for entering and exiting the critical regions. RTE implementation is done by the integrators of the MCAL using OS or non-OS services.

For testing the Dio driver, stubs are used for RTE.

The following critical regions are used in the DIO driver:

5.1.1 DIO_EXCLUSIVE_AREA_00

Used in function Dio_Siul2_FlipChannel(), in order to make channels flipping atomic.

5.1.2 DIO_EXCLUSIVE_AREA_01

Used in function Dio_Siul2_WriteChannel(), in order to protect the read-modify-write operation in Dio_Siul2_FlipChannel().

5.2 Peripheral Hardware Requirements

The Dio driver uses SIUL2 peripheral.

Port pins that are available on a particular package are described in the MPC5748G Reference Manual.

The formula for calculating port and channel number for PINx is:

$PORT = PIN_x / 16$

$CHANNEL = PIN_x \% 16$

5.3 ISR to configure within OS – dependencies

None.

5.4 ISR Macro

None.

5.5 Other AUTOSAR modules - dependencies

- **Port:** This module is necessary for providing APIs for overall configuration and initialization of the port structure which is used in the Dio module.
- **Det:** This module is necessary for enabling Development error detection. The API function used is Det_ReportError(). The activation/deactivation of Development error detection is configurable using 'DioDevErrorDetect' configuration parameter.
- **Base:** This module is necessary for a reference to the Wakeup source for this controller as defined in the ECU State Manager.
- **Resource:** Sub-Derivative model is selected from Resource configuration.
- **Rte:** Used to manage the exclusive area inside Dio module.
- **Ecuc:** This module is required for configuring the variant handling in Tresos.
- **Mcu:** The Microcontroller Unit Driver (MCU Driver) is primarily responsible for initializing and controlling the chips internal clock sources and clock prescalers. The clock frequency may affect the Trigger frequency, Conversion time and Sampling time.

5.6 Data cache restriction

None



Chapter 6

Main API Requirements

6.1 Main functions calls within BSW scheduler

None.

6.2 API Requirements

None.

6.3 Calls to Notification Functions, Callbacks, Callouts

None.

Chapter 7

Memory Allocation

7.1 Sections to be defined in Dio_MemMap.h

Table 7-1. MemMap sections present in the Dio driver code

Section name	Section type	Description
DIO_START_SEC_CODE	Code	Start of Memory Section for Code
DIO_STOP_SEC_CODE	Code	End of Memory Section for Code
DIO_START_SEC_CONFIG_DATA_UNSPECIFIED	Configuration Data	Start of Memory Section for Config Data
DIO_STOP_SEC_CONFIG_DATA_UNSPECIFIED	Configuration Data	End of Memory Section for Config Data

7.2 Linker command file

Memory shall be allocated for every section defined in Dio_MemMap.h

Chapter 8

Configuration parameters considerations

Configuration parameter class for Autosar Dio driver fall into the following variants as defined below:

8.1 Configuration Parameters

Configuration parameter class for Autosar DIO driver fall into the following variants as defined below:

Table 8-1. Configuration Parameters

Configuration Container	Configuration Parameters	Configuration Variant	Current Implementation
DioGeneral			
	DioDevErrorDetect	Pre Compile	Pre Compile
	DioVersionInfoApi	Pre Compile	Pre Compile
	DioReversePortBits	Pre Compile	Pre Compile
	DioFlipChannelApi	Pre Compile	Pre Compile
	DioReadZeroForUndefinedPortPins	Pre Compile	Pre Compile
	DioMaskedWritePortApi	Pre Compile	Pre Compile
	DioEnableUserModeSupport	Pre Compile	Pre Compile
DioPort			
	DioPortId	Pre Compile	Pre Compile
DioChannel			
	DioChannelId	Pre Compile	Pre Compile
DioChannelGroup			
	DioChannelGroupIdentification	Pre Compile	Pre Compile
	DioPortBitNumber	Pre Compile	Pre Compile
	DioPortOffset	Pre Compile	Pre Compile
	DioPortMask	Pre Compile	Pre Compile
CommonPublishedInformation			

Table continues on the next page...

Table 8-1. Configuration Parameters (continued)

Configuration Container	Configuration Parameters	Configuration Variant	Current Implementation
	ArMajorVersion	Pre Compile	Pre Compile
	ArMinorVersion	Pre Compile	Pre Compile
	ArReleaseRevisionVersion	Pre Compile	Pre Compile
	ModuleId	Pre Compile	Pre Compile
	SwMajorVersion	Pre Compile	Pre Compile
	SwMinorVersion	Pre Compile	Pre Compile
	SwPatchVersion	Pre Compile	Pre Compile
	VendorApilInfix	Pre Compile	Pre Compile
	VendorId	Pre Compile	Pre Compile

Chapter 9

Integration Steps

This section gives a brief overview of the steps needed for integrating Digital Input Output :

- Generate the required Dio configurations. For more details refer to section [Files required for Compilation](#)
- Allocate proper memory sections in Dio_MemMap.h and linker command file. For more details refer to section
- Compile & build the Dio with all the dependent modules. For more details refer to section [Building the Driver](#)



Chapter 10

External Assumptions for DIO driver

The section presents requirements that must be complied with when integrating DIO driver into the application.

[SMCAL_CPR_EXT172]

<< The pins for which the application intends to use Dio_FlipChannel() function at run-time shall be configured as Input-Output, because of the fact that this function writes the output buffer and returns the value from the input buffer. >>



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