

## Curriculum Vitae - Ahmed H. Qureshi

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CONTACT INFORMATION	Assistant Professor Department of Computer Science Purdue University West Lafayette, IN 47907, USA	Phone: (765)-496-3071 E-mail: qureshi7@purdue.edu Webpage: <a href="https://github.com/ahmedhqureshi">qureshiahmed.github.io</a> Research Group: <a href="http://corallab.net">corallab.net</a>
RESEARCH INTERESTS	Our team is dedicated to advancing the field of robot planning and control through a combination of fundamental and applied research. Our primary objective is to develop robots that can operate effectively and safely in natural and dynamic human environments. To achieve this, we focus on a range of challenges, such as scalable and fast motion planning, active perception, human-in-the-loop robot manipulation, mobile navigation, and dynamic control. The ultimate goal of our research is to enhance people's lives and optimize workforce efficiency in various economic and healthcare sectors.	
EDUCATION	<b>University of California San Diego, USA</b> PhD, Intelligent Systems, Robotics and Control <ul style="list-style-type: none"><li>Thesis topic: Differentiable Neural Motion Planning under Task Constraints</li></ul> <b>Osaka University, Japan</b> Master of Engineering <ul style="list-style-type: none"><li>Thesis topic: Deep Reinforcement Learning for Human-Robot Interaction in the Real-World</li></ul> <b>National University of Sciences and Technology (NUST), Pakistan</b>	<b>2017 - 2021</b>   <b>2015 - 2017</b>  <b>2010 - 2014</b>
PROFESSIONAL EMPLOYMENTS	<b>Purdue University</b> West Lafayette, IN, USA <ul style="list-style-type: none"><li>Assistant Professor, Department of Computer Science</li><li>Director, Cognitive Robot Autonomy &amp; Learning (CoRAL) Lab</li><li>Affiliate Faculty, Purdue Center for Innovation in Control, Optimization, &amp; Networks</li></ul>	<b>2021 - Present</b>
HONORS AND AWARDS	<ul style="list-style-type: none"><li>Best Paper at ICLR Workshop on Neural Fields across Fields: Methods and Applications of Implicit Neural Representations 2023.</li><li>Two gold medals for outstanding undergraduate research by Pakistan Book of Records, 2019.</li><li>Outstanding Young Researcher by Heidelberg Laureate Forum, 2018.</li><li>Japanese Government MEXT Scholarship, 2015-2017.</li><li>NUST GPA-based scholarship, 2010-2014.</li></ul>	

## PUBLICATIONS

My undergraduate and graduate students are indicated with superscripts  $^U$  and  $^G$ , respectively.

## Patents

P2. **A.H.Qureshi**, R.Ni. Systems and Methods for Physics-informed Autonomous Robot Motion Planning, US Provisional App. 63/503,442.

P1. M.C.Yip, M.J.Bency, **A.H.Qureshi**. [Machine Learning based Fixed-Time Optimal Path Generation](#), US Patent App. 16/222,706, 2019.

## Peer-reviewed Journal

J14. V.Gupta $^G$ , P.Dhir $^G$ , J.Dani $^G$ , and **A.H.Qureshi**. [MANER: Multi-Agent Neural Rearrangement Planning of Objects in Cluttered Environments](#), IEEE/RAS Robotics and Automation Letters (RA-L) 2023. [To be presented at ICRA'24]

J13. Z.Wang $^G$  and **A.H.Qureshi**. [DeRi-Bot: Learning to Collaboratively Manipulate Rigid Objects via Deformable Objects](#), IEEE Robotics and Automation Letters 2023. [To be presented at ICRA'24]

J12. H.Ren $^G$  and **A.H.Qureshi**. [Robot Active Neural Sensing and Planning in Unknown Cluttered Environments](#), IEEE Transactions on Robotics, 2023. [Presented at IROS'23] (IF: 7.8)

J11. J.J.Johnson, **A.H.Qureshi**, and M.C.Yip. [Learning Sampling Dictionaries for Efficient and Generalizable Robot Motion Planning with Transformers](#), IEEE/RAS Robotics and Automation Letters (RA-L) 2023.(IF: 5.2)

J10. **A.H.Qureshi**, J.Dong, A.Baig, and M.C.Yip. [Constrained Motion Planning Networks X](#), IEEE Transactions on Robotics 2021. (IF: 6.123)

J9. L.Li, Y.Miao, **A.H.Qureshi**, and M.C.Yip. [MPC-MPNet: Model-Predictive Motion Planning Networks for Fast, Near-Optimal Planning under Kinodynamic Constraints](#), IEEE Robotics and Automation Letters 2021. (IF: 3.608)

J8. **A.H.Qureshi**, J.Dong, A.Choe, and M.C.Yip. [Neural Manipulation Planning on the Constraint Manifolds](#), IEEE/RAS Robotics and Automation Letters 2020. (IF: 3.608)

J7. **A.H.Qureshi**, Y.Miao, A.Simeonov, and M.C.Yip. [Motion Planning Networks: Bridging the Gap Between Learning-based and Classical Motion Planners](#), IEEE Transactions on Robotics 2020. (IF: 6.123)

J6. **A.H.Qureshi**, Y.Nakamura, Y.Yoshikawa and H.Ishiguro. [Intrinsically motivated reinforcement learning for human-robot interaction in the real-world](#), Neural Networks, Vol 107, pp.23-33, 2018. (IF: 7.197)

J5. Zahid. Tahir, **A.H.Qureshi**, Y.Ayaz and R.Nawaz. [Potentially guided bidirectional-](#)

ized RRT\* for fast optimal path planning in cluttered environments, International Journal of Robotics and Autonomous Systems, Elsevier, Vol. 108, pp. 13-27, 2018. (IF: 2.638)

J4. **A.H.Qureshi** and Y.Ayaz. [Potential Functions Based Sampling Heuristic for Optimal Motion Planning](#), Autonomous Robots, DOI 10.1007/s10514-015-9518-0, 2015. (IF: 2.066)

J3. **A.H.Qureshi** and Y.Ayaz. [Intelligent Bidirectional Rapidly-Exploring Random Trees for Optimal Motion Planning in Complex Cluttered Environments](#), International Journal of Robotics and Autonomous Systems, Elsevier, Vol. 68, pp. 1-11, 2015. (IF: 1.256)

J2. **A.H.Qureshi**, S.Mumtaz, Y.Ayaz, O.Hasan, M.S.Muhammad and M.T.Mahmood. [Triangular Geometrised Sampling Heuristic For RRT\\* Motion Planner](#), International Journal of Advanced Robotic Systems (IJARS), InTech Publishers, 12:10, 2015. (IF: 0.526)

J1. S. A. Khan, Y. Ayaz, M. Jamil, S. O. Gillani, M. Naveed, **A. H. Qureshi** and K. F Iqbal. [Collaborative optimal reciprocal collision avoidance for mobile robots](#), Journal of Control and Automation, 8(8), 203-212.

#### Peer-reviewed Conference Proceedings

C29. R.Ni<sup>G</sup> and **A.H.Qureshi**. [Physics-informed Neural Motion Planning on Constraint Manifolds](#), IEEE/RAS International Conference on Robotics and Automation (ICRA), 2024.

C28. D.Lawson<sup>G</sup> and **A.H.Qureshi**. [Merging Decision Transformers: Weight Averaging for Forming Multi-Task Policies](#), IEEE/RAS International Conference on Robotics and Automation (ICRA), 2023.

C27. Z.Xiong<sup>G</sup>, J.Eappen<sup>G</sup>, D.Lawson<sup>U</sup>, **A.H.Qureshi**, and S.Jagannathan. [Co-learning Planning and Control Policies Using Differentiable Formal Task Constraints](#), IEEE/RAS International Conference on Robotics and Automation (ICRA), 2024.

C26. J.J.Johnson, **A.H.Qureshi**, and M.C.Yip. [Zero-Shot Constrained Motion Planning Transformers Using Learned Sampling Dictionaries](#), IEEE/RAS International Conference on Robotics and Automation (ICRA), 2024.

C25. W.Chen<sup>U</sup>, H.Ren<sup>G</sup>, and **A.H.Qureshi**. [Language-guided Active Sensing of Confined, Cluttered Environments via Object Rearrangement Planning](#), Submitted to the IEEE/RAS International Conference on Robotics and Automation (ICRA), 2024.

C24. V.K.Nivash<sup>G</sup> and **A.H.Qureshi**. [SIMMF: Semantics-aware Interactive Multiagent Motion Forecasting for Autonomous Vehicle Driving](#), IEEE/RAS International Conference on Robotics and Automation (ICRA), 2024.

C23. H.Ren<sup>G</sup> and **A.H.Qureshi**. [Neural Rearrangement Planning for Object Retrieval from Confined Spaces Perceivable by Robot's In-hand RGB-D Sensor](#), IEEE/RAS International Conference on Robotics and Automation (ICRA), 2024.

- C22. M. Kulshrestha<sup>G</sup> and **A.H.Qureshi**. [Structural Concept Learning via Graph Attention for Multi-Level Rearrangement Planning](#), International Conference on Robot Learning (CoRL), 2023
- C21. X. Chen<sup>U</sup>, A. Iyer<sup>U</sup>, Z. Wang<sup>G</sup>, and **A.H.Qureshi**. [Efficient Q-Learning over Visit Frequency Maps for Multi-agent Exploration of Unknown Environments](#), IEEE/RSJ International Conference on Intelligent Robot and Systems (IROS), 2023
- C20. D.Lawson<sup>U</sup> and **A.H.Qureshi**. [Control Transformer: Robot Navigation in Unknown Environments through PRM-Guided Return-Conditioned Sequence Modeling](#), IEEE/RSJ International Conference on Intelligent Robot and Systems (IROS), 2023
- C19. R.Ni<sup>G</sup> and **A.H.Qureshi**. [Progressive Learning for Physics-informed Neural Motion Planning](#), Robotics: Science & Systems, 2023
- C18. R.Ni<sup>G</sup> and **A.H.Qureshi**. [NTFields: Neural Time Fields for Physics-Informed Robot Motion Planning](#), International Conference on Representation Learning (ICLR), 2023 [\[Spotlight\]](#)
- C17. A.K.Keshari<sup>G</sup>, H.Ren<sup>G</sup>, and **A.H.Qureshi**. [CoGrasp: 6-DoF Grasp Generation for Human-Robot Collaboration](#), IEEE/RAS International Conference on Robotics and Automation (ICRA), 2023
- C16. Z.Xiong<sup>G</sup>, J.Eappen<sup>G</sup>, **A.H.Qureshi**, and S.Jagannathan. [Model-free Neural Lyapunov Control for Safe Robot Navigation](#), IEEE/RSJ International Conference on Intelligent Robot and Systems (IROS), 2022.
- C15. **A.H.Qureshi**, A.Mousavian, C.Paxton, M.C.Yip, and D.Fox. [NeRP: Neural Rearrangement Planning for Unknown Objects](#), Robotics: Science & Systems, 2021.
- C14. J.Johnson, L.Li, F.Liu, **A.H.Qureshi**, and M.C.Yip. [Dynamically Constrained Motion Planning Networks for Non-Holonomic Robots](#), Proceedings of IEEE/RSJ International Conference on Intelligent Robot and Systems (IROS), pp. 6937-6943, Las Vegas, USA (Virtual) 2020.
- C13. **A.H.Qureshi**, J. J. Johnson, Y. Qin, T. West, B. Boots, and M.C.Yip. [Composing Task-Agnostic Policies via Deep Reinforcement Learning](#), International Conference on Representation Learning (ICLR), 2020.
- C12. **A.H.Qureshi**, B. Boots, and M.C.Yip. [Adversarial Imitation Via Variational Inverse Reinforcement Learning](#), International Conference on Representation Learning (ICLR), 2019.
- C11. **A.H.Qureshi**, A.Simeonov, M.J.Bency, M.C.Yip. [Motion Planning Networks](#), IEEE RAS International Conference on Robotics and Automation (ICRA), pp. 2118-2124, Montreal, Canada 2019.
- C10. M.J.Bency, **A.H.Qureshi**, M.C.Yip. [Neural Path Planning: Fixed Time, Near-](#)

[Optimal Path Generation via Oracle Imitation](#), Proceedings of IEEE/RSJ International Conference on Intelligent Robot and Systems (IROS), pp. 3965-3972, Macau 2019.

C9. **A.H.Qureshi** and Michael.C.Yip . [Deeply Informed Neural Sampling For Robot Motion Planning](#), Proceedings of IEEE/RSJ International Conference on Intelligent Robot and Systems (IROS), pp. 6582-6588, Madrid, Spain 2018.

C8. **A.H.Qureshi**, Z.Tahir, G.Tariq, Y.Ayaz. [Re-planning Using Delaunay Triangulation for Real Time Motion Planning in Complex Dynamic Environments](#), IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM), pp. 905-911, Auckland, New Zealand 2018.

C7. **A.H.Qureshi**, Y.Nakamura, Y.Yoshikawa and H.Ishiguro. [Show, Attend and Interact: Perceivable Social Human-Robot Interaction through Neural Attention Q-Network](#), Proceedings of IEEE/RAS International Conference on Robotics and Automation (ICRA), pp.1639-1645, Singapore 2017.

C6. **A.H.Qureshi**, Y.Nakamura, Y.Yoshikawa and H.Ishiguro. [Robot gains social intelligence through multimodal deep reinforcement learning](#), Proceedings of IEEE/RAS International Conference on Humanoid Robots, pp. 745-751, Cancun Mexico, 2016.

C5. **A.H.Qureshi**, S.Mumtaz, Y. Ayaz, and O. Hasan. [Augmenting RRT\\*-Planner with Local Trees for Motion Planning in Complex Dynamic Environments](#), Proceedings of IEEE/RAS 19th International Conference on Methods and Models in Automation and Robotics (MMAR), pp. 657-662, Miedzyzdroje, Poland 2014.

C4. **A.H.Qureshi**, S.Mumtaz, Y.Ayaz, O.Hasan and W.Y.Kim. [Adaptive Potential guided directional RRT\\*](#), Proceedings of International Conference on Robotics and Biomimetics (ROBIO), pp. 1887-1892, China, 2013.

C3. B.Ali, **A.H.Qureshi**, Y.Ayaz, N.Muhammad and W.Y.Kim. [Human tracking by a mobile robot using 3D features](#), Proceedings of International Conference on Robotics and Biomimetics (ROBIO), pp. 2464-2469, Shenzhen, China, 2013.

C2. **A.H.Qureshi**, K.F.Iqbal, S.M.Qamar, F.Islam, Y.Ayaz and N.Muhammad. [Potential guided directional-RRT\\* for accelerated motion planning in cluttered environments](#), Proceedings of International Conference on Mechatronics and Automation (ICMA), pp. 519-524, Takamatsu, Japan, 2013.

C1. S. M. Qamar, K. F. Iqbal, **A.H.Qureshi**, N. Muhammad, Y. Ayaz, and A. G. Abbasi [A solution to Perceptual Aliasing through Probabilistic Fuzzy Logic and SIFT](#), Proceedings of IEEE/ASME International Conference on Advanced Intelligent Mechatronics (pp. 1393-1398). IEEE.

## Workshop Papers

W10. R.Ni<sup>G</sup> and **A.H.Qureshi**. Physics-informed Neural Networks for Robot Motion under Constraints, ICRA 2024 RoboNerF: 1st Workshop On Neural Fields In Robotics.

W9. R.Ni<sup>G</sup> and **A.H.Qureshi**. Physics-informed Neural Motion Planning on Constraint Manifolds, ICRA 2024 workshop on A Future Roadmap for Sensorimotor Skill Learning for Robot Manipulation.

W8. Z.Wang<sup>G</sup> and **A.H.Qureshi**. DeRi-Bot: Learning to Collaboratively Manipulate Rigid Objects via Deformable Objects, CoRL 2023 workshop on Learning for Soft Robots 2023. [\[Spotlight\]](#)

W7. K.Norman<sup>G</sup> and **A.H.Qureshi**. Analysis of Continuous Learning Models for Robot Motion Planning, IEEE/RSJ IROS Workshop on Policy Learning in Geometric Spaces 2023. [\[Oral Presentation\]](#)

W6. R.Ni<sup>G</sup> and **A.H.Qureshi**. Progressive Learning for Physics-informed Neural Motion Planning, RSS Workshop on Symmetries in Robot Learning 2023. [\[Oral Presentation\]](#)

W5. D.Lawson<sup>U</sup> and **A.H.Qureshi**. Merging Decision Transformers, ICLR Workshop on Reincarnating Reinforcement Learning 2023. [\[Spotlight\]](#)

W4. R.Ni<sup>G</sup> and **A.H.Qureshi**. Neural Time Fields for Physics-Informed Motion Planning, ICLR Workshop on Neural Fields across Fields: Methods and Applications of Implicit Neural Representations 2023. [\[Best Paper\]](#)

W3. **A.H.Qureshi**, Y.Miao M.C.Yip. Active Continual Learning for Planning and Navigation, ICML Workshop on Real World Experiment Design and Active Learning 2020.

W2. **A.H.Qureshi**, M.C.Yip. Adversarial Reward and Policy Learning Via Variational Inverse Optimal Control, Bay Area Machine Learning Symposium, August 2018.

W1. **A.H.Qureshi**, Y. Nakamura, Y. Yoshikawa, H. Ishiguro. Robot Learns Responsive Behavior through Interaction with People using Deep Reinforcement Learning, 3rd International Symposium on Cognitive Neuroscience Robotics, Dec 2016.

### Under Submission

P4. H.Ren<sup>G</sup> and **A.H.Qureshi**. Multi-Stage Monte Carlo Tree Search for Non-Monotone Object Rearrangement Planning in Narrow Confined Environments, Submitted to the IEEE RSJ International Conference on Intelligent Robot and Systems (IROS), 2024.

P3. Z.Wang<sup>G</sup> and **A.H.Qureshi**. DeRi-IGP: Manipulating Rigid Objects Using Deformable Objects via Iterative Grasp-Pull, Submitted to the IEEE/RAS Robotics and Automation Letters (RA-L), 2024.

P2. Z.Wang<sup>G</sup> and **A.H.Qureshi**. AnyPose: Anytime 3D Human Pose Forecasting via Neural Ordinary Differential Equations, Submitted to the IEEE/RSJ International Conference on Intelligent Robot and Systems (IROS), 2024.

P1. S.Singh<sup>G</sup> and **A.H.Qureshi**. Social Robot Navigation via Explicit Multiagent Motion Forecasting and Collision Modeling, Submitted to the IEEE/RSJ International Conference

on Intelligent Robot and Systems (IROS), 2024.

SEMINAR AND  
INVITED TALKS

- Physics Informed Neural Networks for Robot Motion Planning, IEEE/RSJ Workshop on Policy Learning in Geometric Spaces, Oct 2023.
- Visual Robot Learning for Planning & Control in Unknown Environments, Robotics and Automation Society Chapter of IEEE Eastern North Carolina Section, Mar 2022.
- Neural Task and Motion Planning in Unknown Environments, Brown University, Nov 2021.
- Emergence of a Mutualistic Relationship between Motion Planning and Machine Learning for Scalable Robot Control, Neural Computation Chalk Talk Series, UC San Diego, Oct 2020.
- Motion Planning Networks, University of Toronto, Canada (Virtual), Sep 2020.
- Deep Learning For Robotics, Neural Computing & Deep Learning Workshop, 6th Heidelberg Laureate Forum, Germany, Sep 2018.
- Learning-based motion planning and control, CRI Seminars, University of California San Diego, May 2018.
- Intrinsically Motivated Reinforcement Learning for Human-Robot Interaction in the Real-World, Artificial Intelligence Seminars, Osaka University, Japan, Nov 2017.
- Living with Robots- The Next Generation of Intelligent Machines, Information Technology University, Pakistan, Mar 2016.
- Sampling-based motion planning algorithms, Topics in Robotics Session, Osaka University, Japan, Apr 2015.

RESEARCH  
GROUP

**Current Ph.D. Students**

- |   |                    |
|---|--------------------|
| • Hanwen Ren, CS, Purdue University         | Jan 2022 - Present |
| • Zixing Wang, CS, Purdue University        | Jan 2022 - Present |
| • Ruiqi Ni, CS, Purdue University           | Jan 2022 - Present |
| • Syed Talha Bukhari, CS, Purdue University | Aug 2022 - Present |
| • Yubin Koh, CS, Purdue University          | Aug 2023 - Present |
| • Tassos Manganaris, CS, Purdue University  | Aug 2023 - Present |
| • Yuchen Liu, CS, Purdue University         | Aug 2023 - Present |

**Current Visiting Ph.D. Students**

- |   |                    |
|---|--------------------|
| • Zikang Xiong, CS, Purdue University<br>– co-advised with Prof. Suresh Jagannathan | Jan 2022 - Present |
|---|--------------------|

**Current M.S. Students**

- |  |                    |
|--|--------------------|
| • Aathman Tharmasanthiran, CS, Purdue University | Sep 2023 - Present |
| • Gabriella Giachini, ME, Purdue University      | Jun 2023 - Present |

**Current B.S. Students**

- |   |                    |
|---|--------------------|
| • Aakanksha Shripal, ECE, Purdue University | Sep 2023 - Present |
| • Alexiy Buynitsky, CS, Purdue University   | Aug 2023 - Present |
| • Guna Avula, CS, Purdue University         | Jan 2023 - Present |

- Daniel Chen, CS, Purdue University Mar 2022 - Present
- Xuyang Chen, CS, Purdue University Sep 2021 - Present
- Daniel Lawson, CS, Purdue University Aug 2021 - Present

### Visiting Ph.D. Students Alumni

- Jacob Johnson, ECE, UCSD Aug 2021 - Oct 2023  
– co-advised with Prof. Michael Yip (ECE, UCSD)
- Manav Kulshrestha, CS, Purdue University Aug 2022 - Jun 2023
- Zhiquan Wang, CS, Purdue University Sep 2021 - Sep 2022  
– co-advised with Prof. Bedrich Benes

### M.S. Thesis Students Alumni

- Krishnan N. Vidyaa, ECE, Purdue University (Co-Chair) Aug 2022 - May 2024  
– Title: Multi-agent Trajectory Prediction for Autonomous Vehicles
- Abhinav K. Keshari, ECE, Purdue University (Co-Chair) Oct 2021 - Apr 2023  
– Title: Vision-Language Model for Robot Grasping
- Kendal Norman, CS, Purdue University (Chair) Aug 2021 - Jul 2023  
– Title: Analysis of Continuous Learning Models For Trajectory Representation
- Vivek Gupta, CS, Purdue University (Chair) May 2022 - Jul 2023  
– Title: Multi-agent Neural Rearrangement Planning of Objects in Cluttered Environments

### M.S. Students Alumni

- Veera Adithya Dittakavi, ECE, Purdue University May 2023 - Aug 2023
- Prabhpreet Singh Dir, AAE, Purdue University Sep 2021 - Dec 2022
- Kartik A. Pant, AAE, Purdue University Oct 2021 - May 2022
- Akshaj Uppala, CS, Purdue University Aug 2022 - May 2023
- Shivam Bhat, CS, Purdue University May 2023 - Dec 2023
- Joseph P. Kawiecki, ECE, Purdue University Jan 2023 - Dec 2023
- Shyamvanshikumar Singh, CS, Purdue University Nov 2022 - Dec 2023

### B.S. Students Alumni

- Shyawn Zahid, CS, Purdue University Feb 2022 - May 2022
- Latif Adurzada, Math, Purdue University Feb 2022 - May 2022
- Vlada Volyanskaya, CS, Purdue University May 2022 - Aug 2022
- Andrew Showalter, ME, Purdue University Aug 2022 - Dec 2022
- Jeegn Dani, CS, Purdue University Jan 2022 - Dec 2022
- Jacob Zietek, CS, Purdue University Nov 2022 - Dec 2023
- Ashvin Iyer, CS, Purdue University May 2022 - May 2023

### TEACHING

- **Instructor**, CS558 Introduction to Robot Learning, Purdue University Spring, 2024
- **Guest Lecturer**, CS197: Honors Seminar, Purdue University Spring, 2024
- **Instructor**, CS49000 Introduction to Robotics, Purdue University Fall, 2023
- **Instructor**, CS593000 Robotics, Purdue University Spring, 2023
- **Guest Lecturer**, CS197: Honors Seminar, Purdue University Spring, 2023



- **Instructor**, CS49000 Introduction to Robotics, Purdue University Fall, 2022
- **Guest Lecturer**, CS397: Honors Seminar, Purdue University Fall, 2022
- **Instructor**, CS593000 Robotics, Purdue University Spring, 2022
- **Instructor**, CS592 Introduction to Robot Motion, Purdue University Fall, 2021
- **Guest Lecturer**, CS397: Honors Seminar, Purdue University Fall, 2021
- **Guest Lecturer**, CS591: Research Seminar, Purdue University Fall, 2021
- **Teaching Assistant**, Advances in Robot Manipulation, UC San Diego Spring, 2020
- **Co-Instructor**, Robot Reinforcement Learning, UC San Diego Fall, 2019
- **Teaching Assistant**, Cognitive Neuroscience Robotics, Osaka University Feb, 2016 - 2017
- **Teaching Assistant**, Circuits Analysis, NUST, PK Fall, 2011

## PROFESSIONAL ACTIVITIES

### University Service:

- Purdue CS Ph.D. Graduate Admissions, 2021-22, 2023-24
- Purdue CS Ph.D. Visit Day Committee, 2024
- Purdue CS Faculty Search, 2022-23
- Purdue CS Space Management Committee, 2021

### Ph.D. Committees

- Rashmi Bhaskara, CS, Purdue University
- Charles W Christoffer, CS PhD Preliminary Exam (July. 2022), Purdue University
- Md Masudur Rahman, CS PhD Preliminary Exam (Mar. 2023), Purdue University

### M.S. Committees

- Aniruddha Mukherjee, MS Thesis (TBD), CS, Purdue University
- Vivek Gupta, MS Thesis (Jul. 2023), CS, Purdue University (Chair)
- Kendal Norman, MS Thesis (Apr. 2023), CS, Purdue University (Chair)
- Abhinav K. Keshari, MS Thesis (Apr. 2023), ECE, Purdue University (Chair)

### Conference Program Committee

- Reactive and Sensor-Based Planning Session Co-chair, IEEE International Conference on Intelligent Robots and Systems (IROS) 2023.
- Area Chair, International Conference on Robot Learning 2023.
- Associate Editor, IEEE International Conference on Intelligent Robots and Systems (IROS) 2023.
- Associate Editor, IEEE International Conference on Robotics and Automation (ICRA) 2023.

### Journal Editorial Board Member

- Associate Editor, IEEE Transactions on Robotics (TRO) 2023-Present.
- Associate Editor, IEEE Robotics and Automation Letters (RA-L) 2022-Present.

### Workshop Organization

- Co-organizer, workshop on Machine Learning for Motion Planning, International Conference on Robotics and Automation (ICRA), May 2021.
- Organizer, workshop on Learning Representations for Planning and Control, IEEE/RSJ International Conference on Intelligent Robot and Systems (IROS), Macau, China, Nov 2019.

### **Government Activities**

- NSF IIS Panelist: 2022

### **Reviewer**

#### **Journals:**

- IEEE Transactions on Robotics 2021, 2022
- IEEE Robotics and Automation Letters 2020, 2022
- Cambridge Robotica 2014

#### **Conferences:**

- Conference on Neural Information Processing Systems (NeurIPS) 2021, 2022
- IEEE International Conference on Representation Learning (ICLR) 2019, 2020, 2021, 2022
- IEEE International Conference on Robotics and Automation (ICRA) 2019, 2020, 2022
- IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2018, 2020, 2022, 2024
- Robotics: Science and Systems (RSS) 2021, 2022
- Thirty-Seventh AAAI Conference on Artificial Intelligence 2022

### **Society Membership:**

- |   |                |
|---|----------------|
| • IEEE, Robotics and Automation Society | 2021 - Present |
| • IEEE, Member                          | 2021 - Present |

### REFERENCES

Available upon request