

DomStick: Bluetooth Game Controller PCB Based on Arduino Nano









Buttons

The buttons are connected directly to Ground without any external pull-up resistors, so you need to enable the Arduino's internal pull-up resistors on the input pins.

Pins Connections:

Top Button	D 5
Bottom Button	D3
Left Button	D2
Right Button	D4



Joystick

The joystick includes two axis-controlled variable resistors (X and Y axes) and a push button. Since the push button is not connected to an external pull-up resistor, you need to enable the Arduino Nano's internal pull-up resistor for its input pin.

Pins Connections:

X-Axis →	A1
Y-Axis ↑	A2
Push Button	D8



Bluetooth

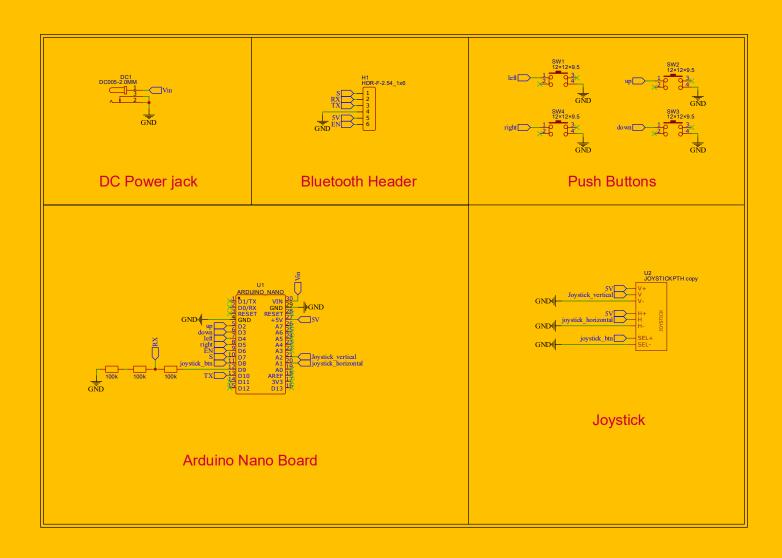
The Bluetooth module used is the HC-05, which can be configured to operate in Master-Slave mode. This allows it to establish a wireless connection between the DomStick and your robot.

To protect the HC-05's 3.3V RX pin, a voltage divider with three resistors is used to step down the Arduino's 5V TX signal to a safe 3.3V level.

Pins Connections:

Tx	D10
R×	D9
State	D7
Enable	D6

Schematic



Dimensions

