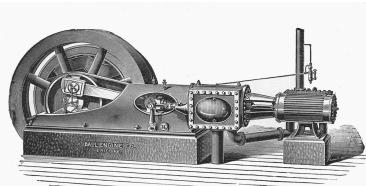


# Neural Networks

Ahmed Meshref

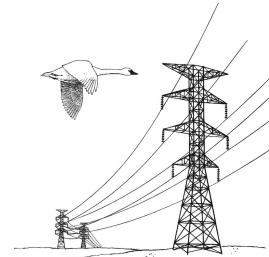
# THE 4TH INDUSTRIAL REVOLUTION IS HERE

Machines



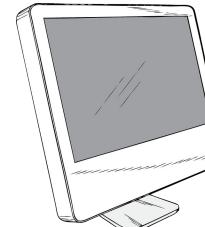
1760

Electricity



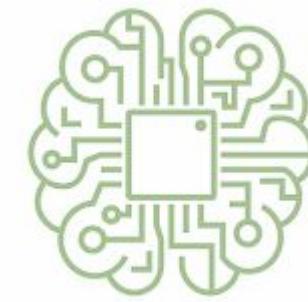
1900

Digital



1960

AI  
+\$16T



NOW

# WHAT IS AI

Take guessing out of decision-making

Decisions based on past evidence

A lot faster than humans can

# AI TRANSFORMING THE WORLD

## PROBLEMS WE COULDN'T TACKLE BEFORE

- Discovery and cure of new diseases like amyotrophic lateral sclerosis
- Safer driving. According to Bloomberg 25% of all cars on the road will be fully autonomous by 2036
- Smarter use of energy
- Preserving the environment and reversing the impact of climate change



# AI IS REVOLUTIONIZING INDUSTRIES – CASES

Ask what AI can't do



## AUTOMOTIVE

Autonomous Driving  
Object detection  
Mobility as service and connected vehicle



## FINANCIAL SERVICES

Claim fraud  
Customer service chatbots/routing  
Risk evaluation



## GOV'T & DEFENSE

Identifying threats  
Satellite imagery & Optimize logistics management  
Support emergency response teams



## HEALTHCARE

Improve Clinical Care  
Drive Operational Efficiency  
Speed Up Drug Discovery



## HIGHER EDUCATION/RESEARCH

Climate & Melting of Sea Ice Prediction  
Design more effective drugs and new treatments for diseases  
Predictive analytics in the sports industry



## INDUSTRIAL

Remaining Useful Life Estimation  
Failure Prediction  
Demand Forecasting



## OIL & GAS

Sensor Data Tag Mapping  
Anomaly Detection  
Robust Fault Prediction



## SMART CITIES

intelligent video analytics  
Optimize city resources from parking management to law enforcement and city services



## RETAIL

Supply Chain & Inventory Management  
Price Management / Markdown Optimization



## TELCO

Detect Network/Security Anomalies  
Forecasting Network Performance  
Network Resource Optimization (SON)

# AI VS ML VS DL

## ARTIFICIAL INTELLIGENCE

Any application using past data evidence to help computers answer future questions.

As computers, they can perform many more questions much faster than humans

Answer many more questions much faster and better

## MACHINE LEARNING

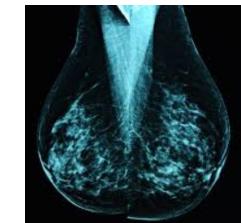
A lot of data + simple layer functions like linear regressions = teach computer to answer simple questions



How will ice-cream sales vary by the day of the week?

## DEEP LEARNING

A ton of data + complex layer functions = teach company to answer more complex questions, closer to humans



Look at this MRI scan, does this patient have cancer?

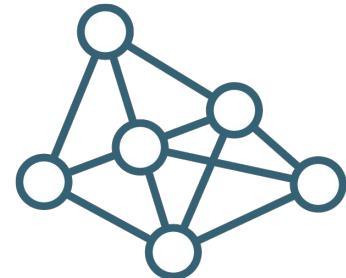
# DEEP LEARNING TOPICS



SPEECH/AUDIO  
PROCESSING



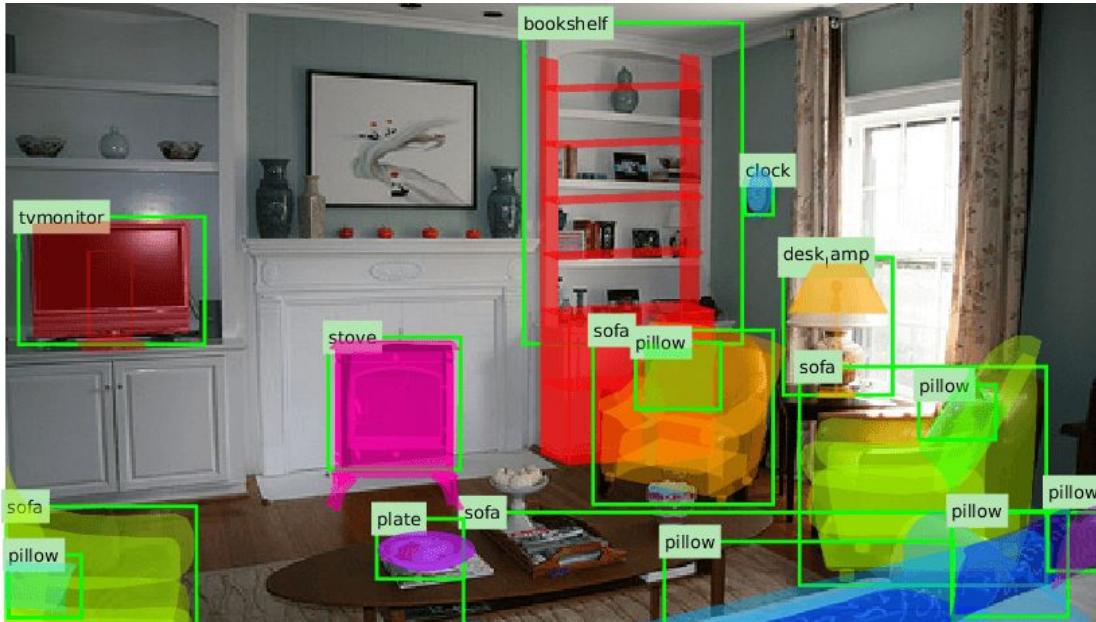
COMPUTER VISION



NATURAL LANGUAGE  
PROCESSING



# DEEP LEARNING APPLICATIONS

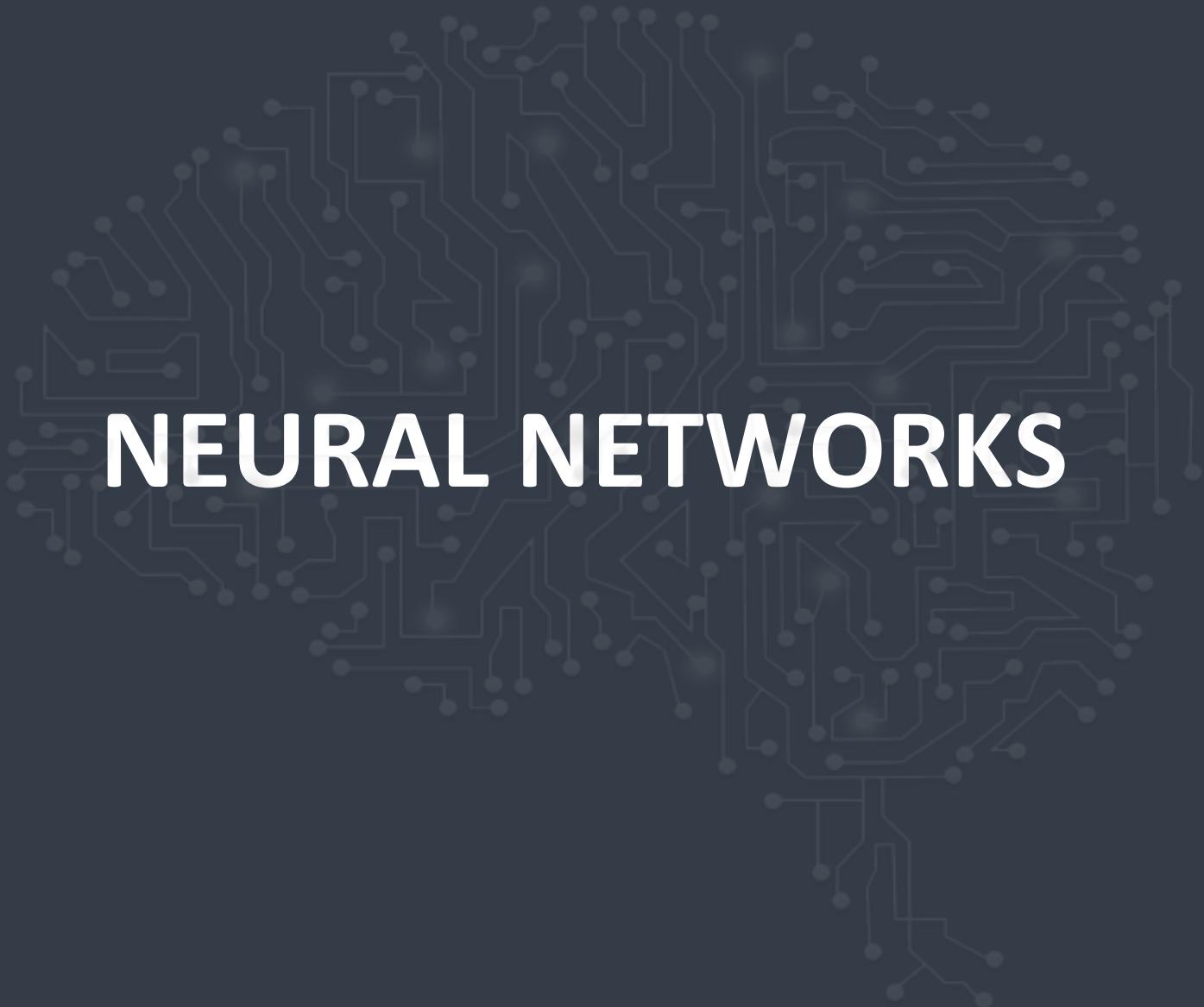


**Object Detection**



**Speech Recognition**

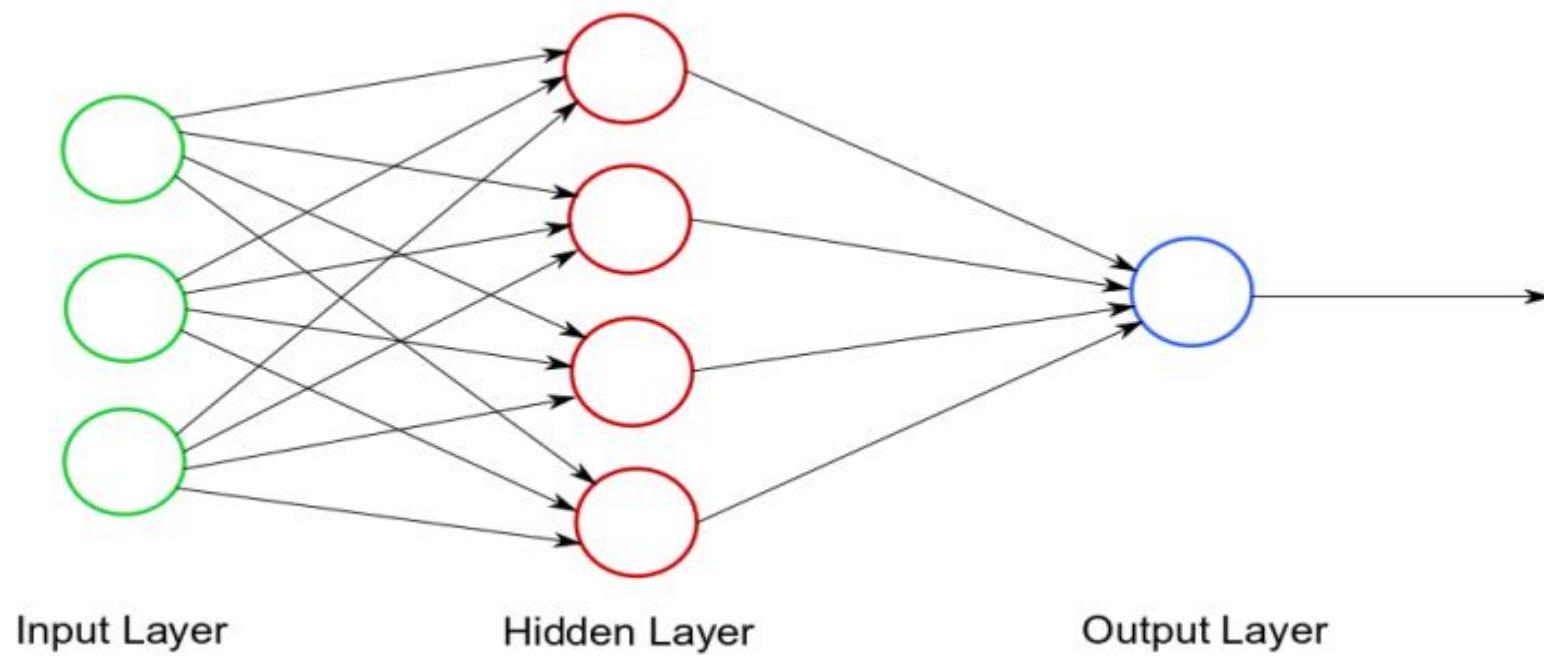
# NEURAL NETWORKS



# ARTIFICIAL NEURAL NETWORKS

The **heart** of deep learning

**Deep Learning** uses different **architecture of Neural Networks** to implement **Machine Learning**

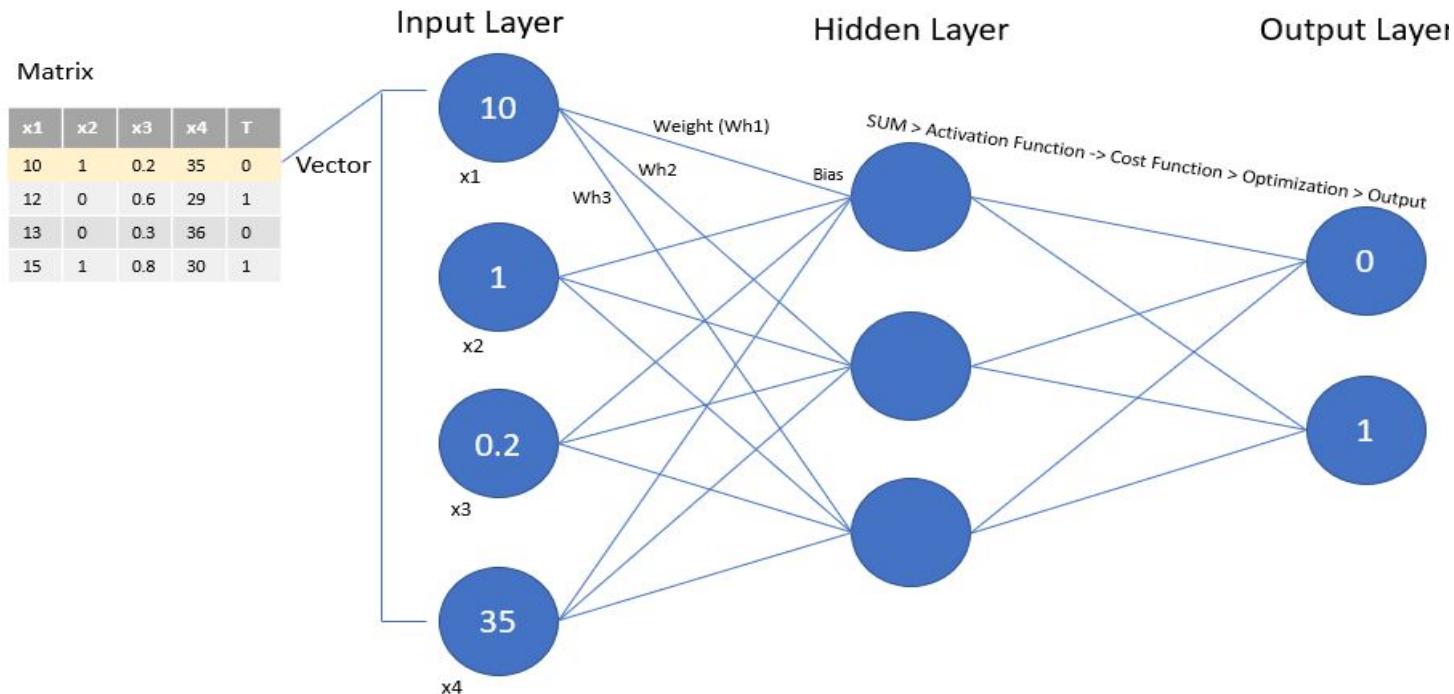


# ARTIFICIAL NEURAL NETWORKS

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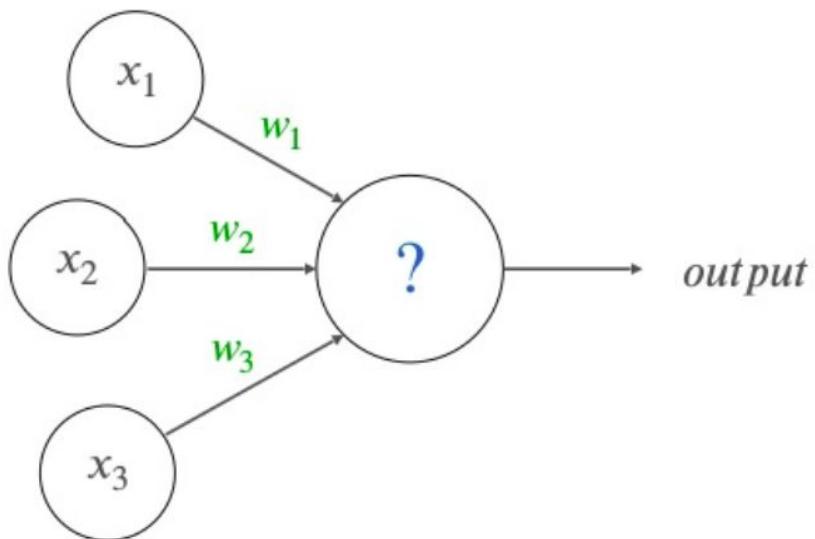
**Plain Vanilla architecture**



Each layer is connect to the other with different weight matrix represented on each arrow that indicates the importance of each neuron input to the output.

# HIDDEN LAYERS

Let's see how the hidden layers work



$$output = \begin{cases} 0, & \sum_{j=0}^n w_j x_j \leq \text{threshold} \\ 1, & \sum_{j=0}^n w_j x_j > \text{threshold} \end{cases}$$

Say,  $x_1, x_2, x_3 = 1, 1, 0$ . With weights as follows  $w_1, w_2, w_3 = 1, 1, 0$ . Assume that our threshold = 5 performing dot product we will get:

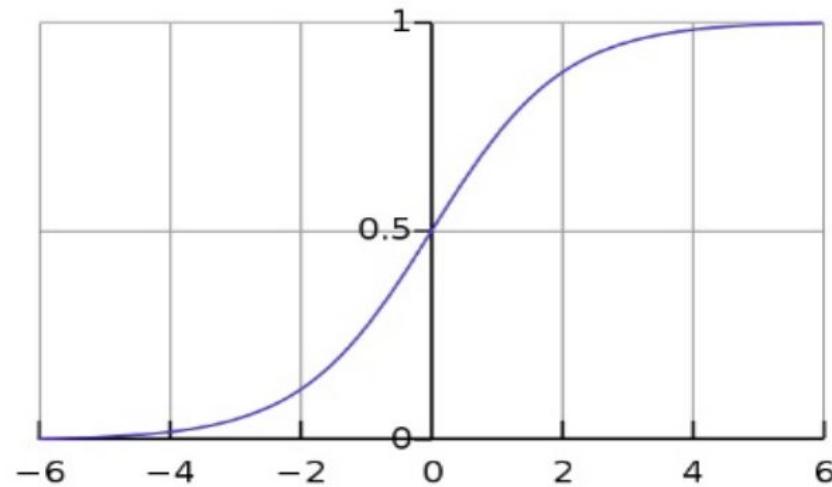
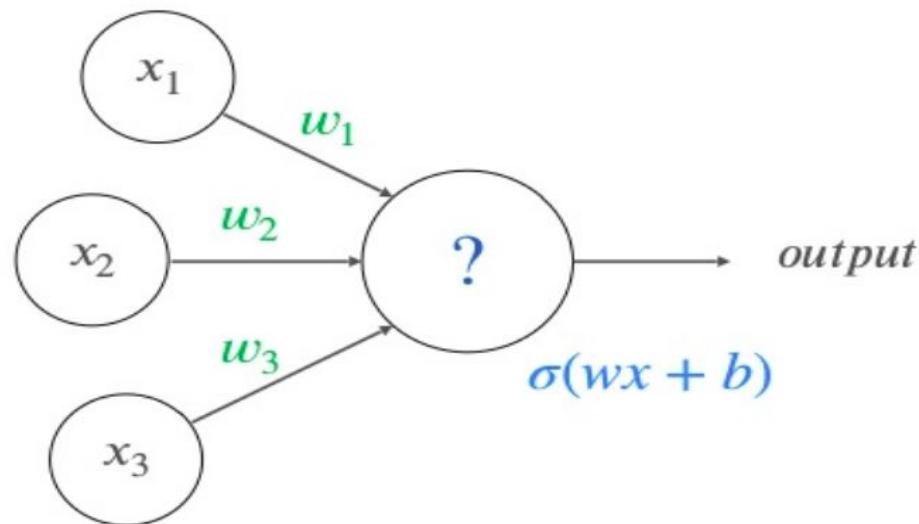
$$1 - w \cdot x = 2$$

$$2 - 2 > 5$$

$$3 = \text{Output} = 0$$

# ACTIVATION FUNCTION

The more common artificial neuron

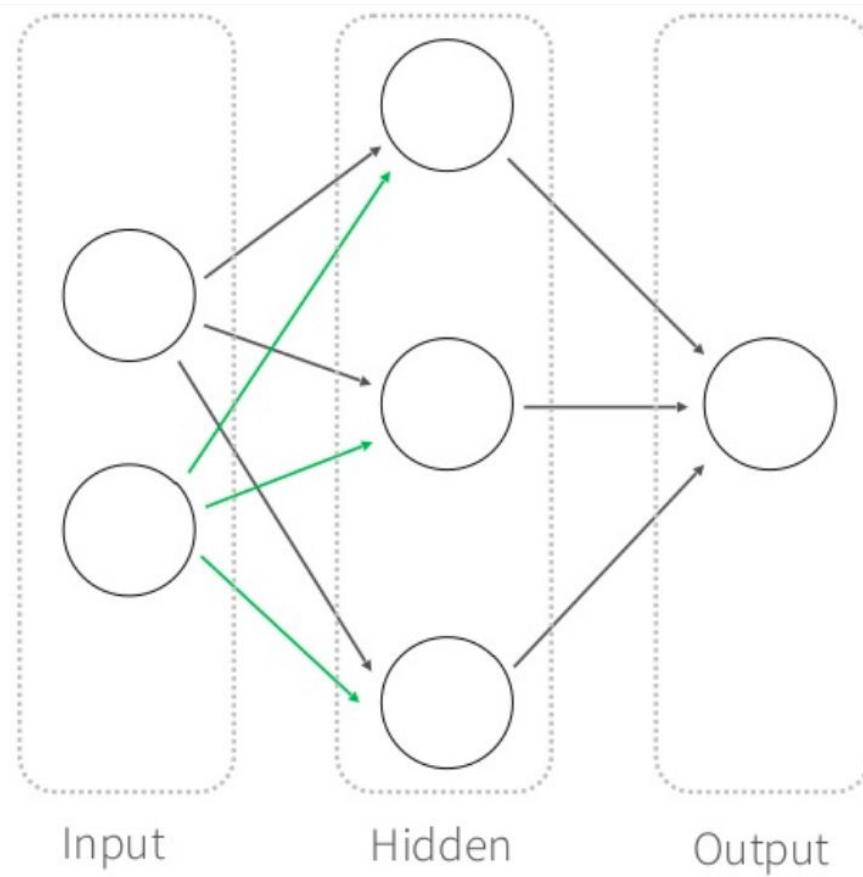


Instead of  $[0, 1]$ , now  $(0\dots 1)$

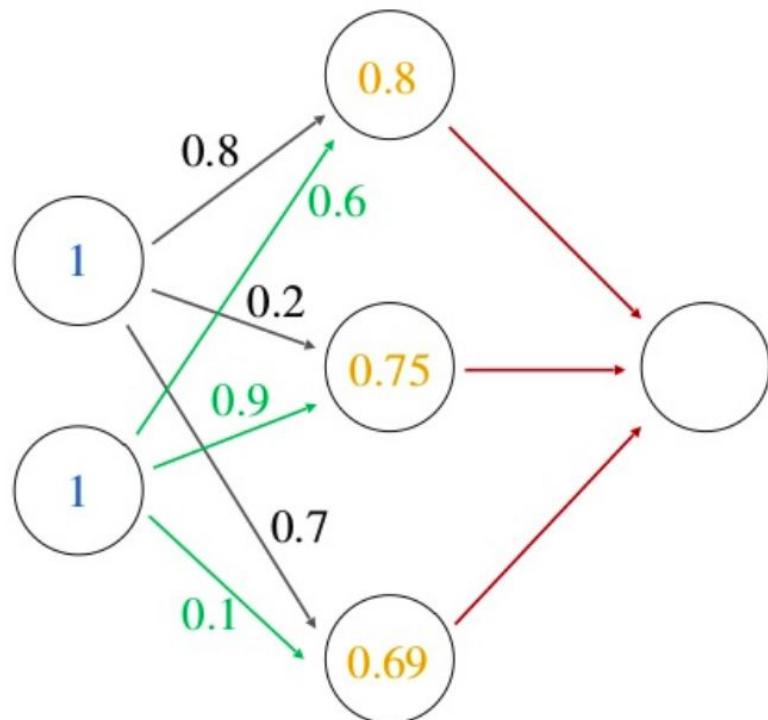
Where output is defined by  $\sigma(wx + b)$

Adding the bias ( $b$ ) is important in controlling the neuron. Also, its **value allows us to shift the activation function to the left or right**, which may be critical for successful learning.

# EXAMPLE



# EXAMPLE

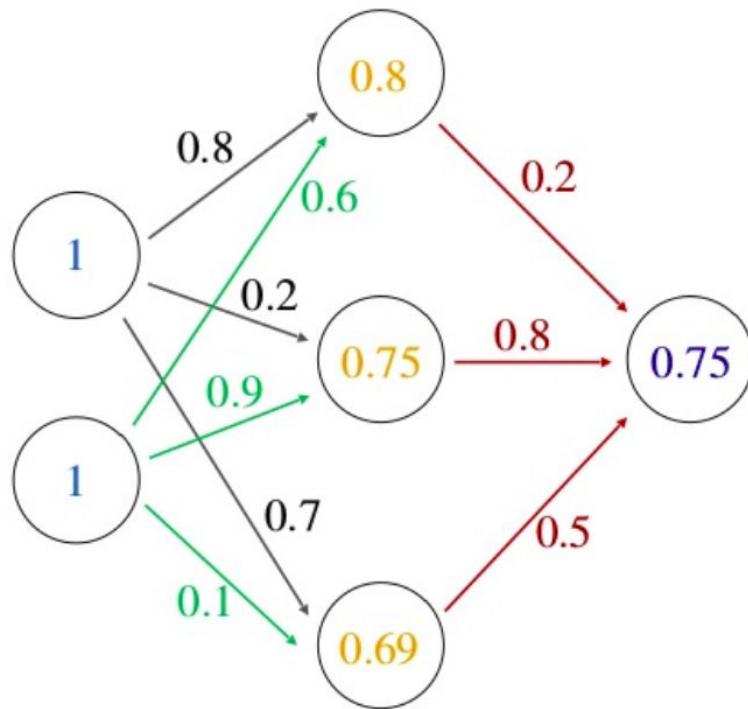


$$h_1 = \sigma(1x0.8 + 1x0.6) = 0.80$$

$$h_2 = \sigma(1x0.2 + 1x0.9) = 0.75$$

$$h_3 = \sigma(1x0.7 + 1x0.1) = 0.69$$

# EXAMPLE



$$\begin{aligned}out &= \sigma(0.2x0.8 + 0.8x0.75 + 0.5x0.69) \\&= \sigma(1.105) \\&= 0.75\end{aligned}$$

# COMPUTER OPERATION TO PERFORM FFNN

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \text{ vector (input layer)}$$

$$W = \begin{bmatrix} w_1 & w_2 \\ w_4 & w_5 \\ x_3 & w_6 \end{bmatrix} \text{ matrix (the weights for hidden layer 1)}$$

*the output is given by*

$$\begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} = \begin{bmatrix} w_1 & w_2 \\ w_4 & w_5 \\ x_3 & w_6 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \text{ (the product of vector and matrices)}$$

$$\begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} = \begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} + \text{bias}$$

*finally,*

$$\begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} = f\left(\begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix}\right) \text{ (activation step)}$$

# CODE EXAMPLE

```
In [8]: import numpy as np
def sigmoid(x):
    #applying the sigmoid function
    return 1 / (1 + np.exp(-x))

input_vector = np.array([1, 2])
w = np.random.randn(3, 2)
b = 1
h = w.dot(input_vector) + b
h = sigmoid(h)
w2 = np.random.randn(3, 1)
y = np.dot(w2.transpose(), h)
y = sigmoid(y)
print(y)
[1 if y > .5 else 0]
```

```
[0.7964323]
```

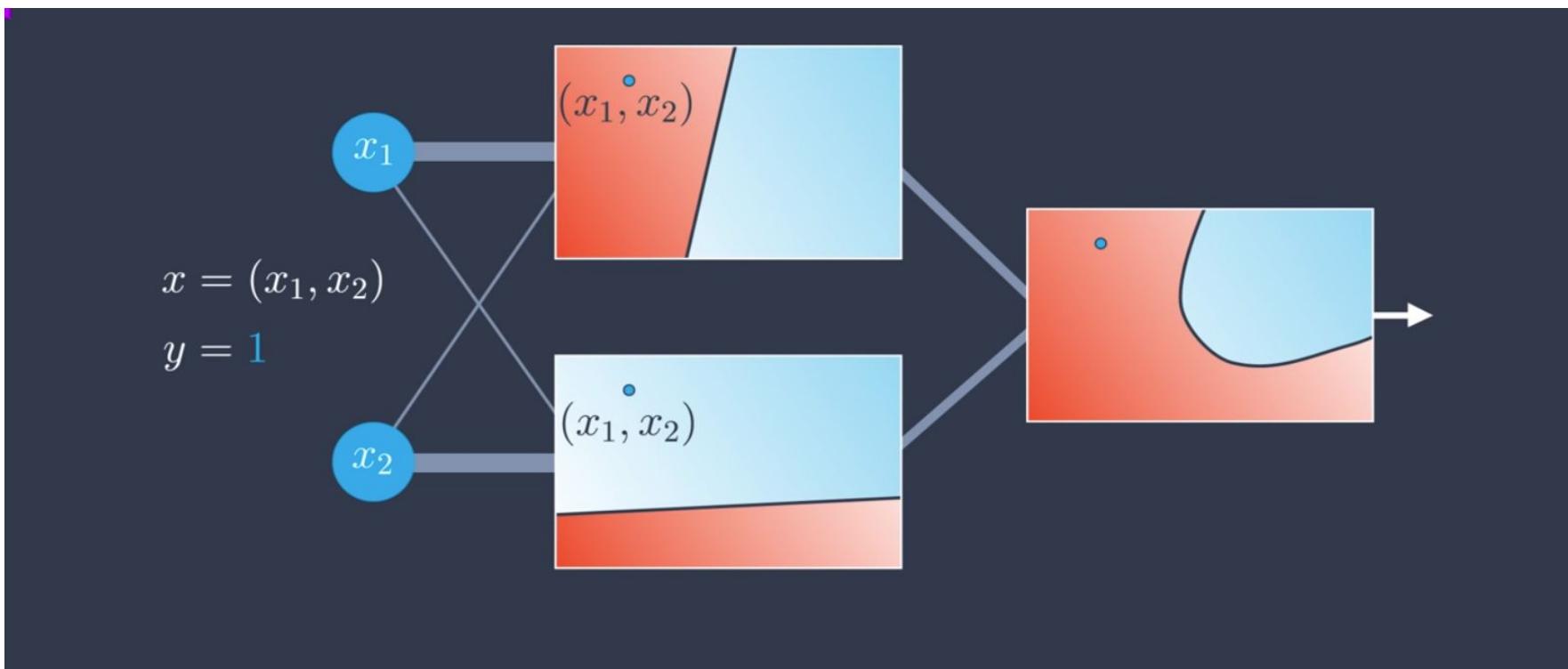


# OPTIMIZATION

# ERRORS

All of the previous process is called **Feedforward** which indicates the process of feeding our Neural Network with the data and plugin that into the sigmoid function to get a probability for the output between 0 and 1

**Q: What if we misclassified our points?**



# FORMULATE A PROBLEM

The network needs to make predictions as close as possible to the real values. To measure this, we use a metric of how wrong the predictions are, the **error** to improve the neural network **weights**

## Mean Square Error Function:

$$E = \frac{1}{2} \sum_{\mu} \sum_j [y_j^{\mu} - \hat{y}_j^{\mu}]^2$$

Where

- 1-  $y_{\text{hat}}$  represents the prediction and  $y$  is the true value.
- 2- The variable  $j$  represents the output units of the network. So this inside sum is saying for each output unit, find the difference between the true value  $y$  and the predicted value from the network then square the difference, then sum up all those squares.
- 3- The variable  $\mu$  indicates loop over all of the data point that we feed our neural network with.

**To reach our goal, we need to minimize the error and we will user a method called backpropagation to do that.**

# BACKPROPAGATION

## **Big picture steps:**

- Do a feedforward operation.
- Comparing the output of the model with the desired output.
- Calculating the error.
- Running the feedforward operation backwards (backpropagation) to spread the error to each of the weights.
- Use this to update the weights, and get a better model.
- Continue this until we have a model that is good.

# BACKPROPAGATION

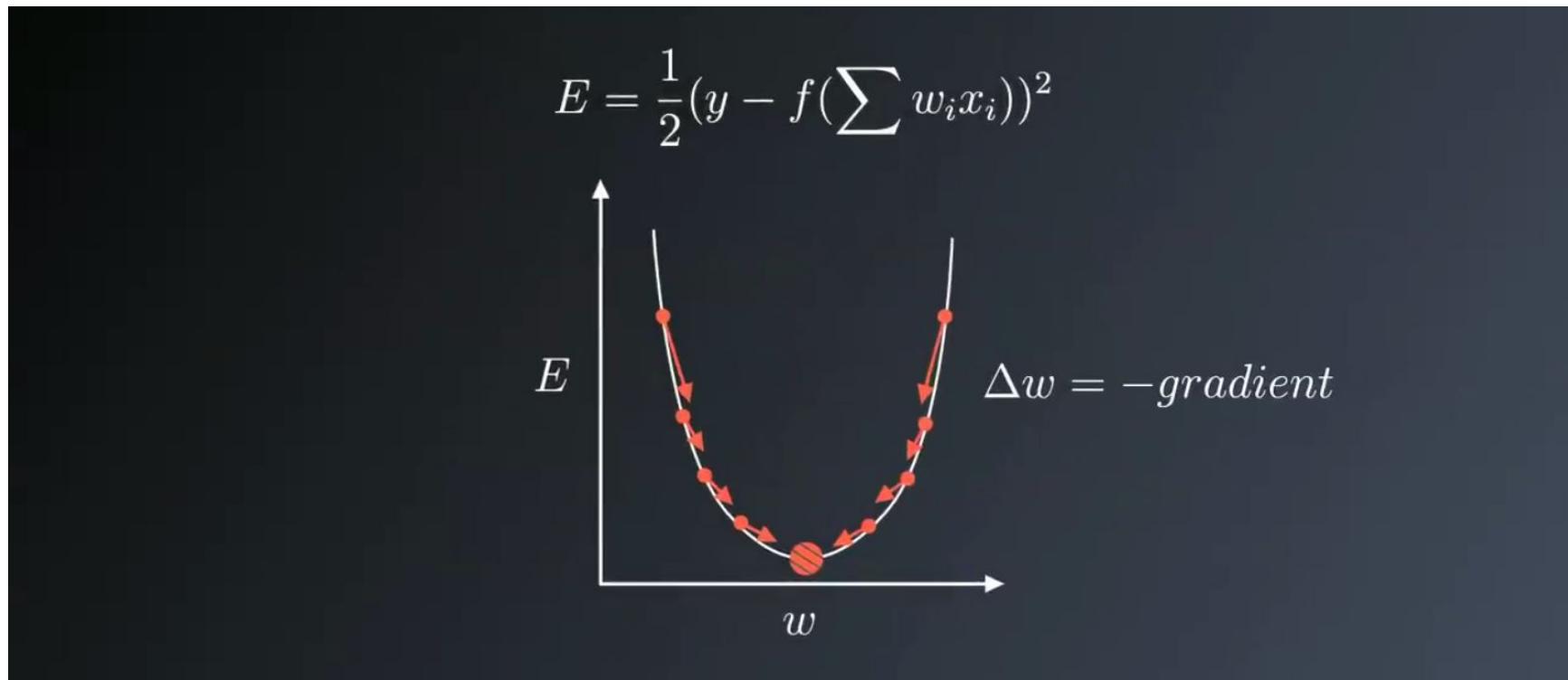
Backpropagation is the optimization of the neural network and it is simply optimizing the error function to get its minimum.

Thinking of that mountain as our Error function plotted, then from the top of it, reaching the bottom of the mountain (the steepest point of the mountain) is our goal and the way to do that is by looking around us each time and finding the next steepest point (min error). So, we can find the best direction by calculating the *gradient* of the squared error function



# BACKPROPAGATION WITH GRADIENT DESCENT

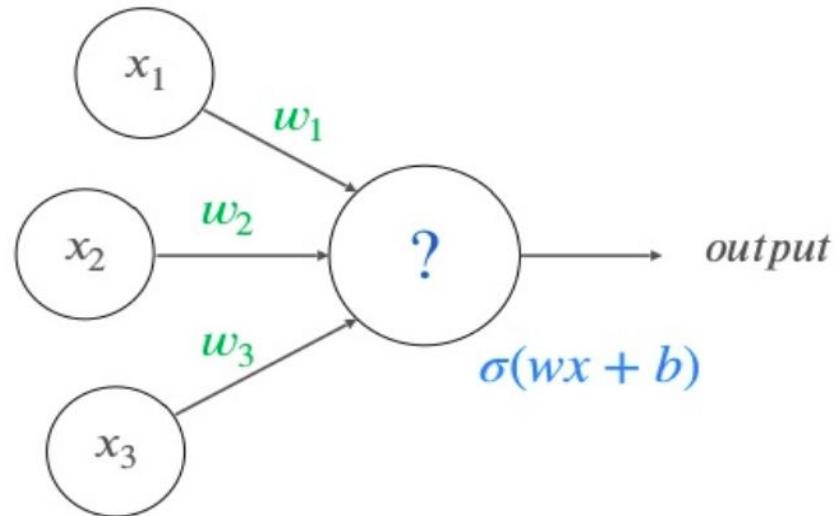
**Gradient descent** is an optimization algorithm that minimizes the error of each weight in our network to improve the results.



As shown, the error function is a function of each weight, so we need to get the partial derivative of the error function corresponding to each weight to reach the minimum of the error at that weight.

# CHAIN RULE

*Update the value of w1*



Our error function is a function of  $y_{\text{output}}$ , and our  $y_{\text{output}}$  is a function of  $h$ , and our  $h$  is a function of the weight. So, to get the partial derivative of the error function corresponding to the weight, we need to use the chain rule.

# MATH

$$\frac{\partial E(y_h)}{\partial W1} = \frac{\partial E(y_h)}{\partial y_h(h)} * \frac{\partial y_h(h)}{\partial h(w)} * \frac{\partial h(w)}{\partial W}$$

$$1 - E = \tfrac{1}{2}(y - y_h)^2$$

$$2 - \frac{\partial E(y_h)}{\partial y_h(h)} = -(y - y_h)$$

$$3 - y_h = \sigma(h(w))$$

$$4 - \frac{\partial y_h}{\partial h} = \sigma(h(w)) * (1 - \sigma(h(w)))$$

$$5 - h(w) = w_1x_1 + w_2x_2 + w_3x_3$$

$$6 - \frac{\partial h(w)}{\partial w_1} = x_1$$

$$\frac{\partial E(y_h)}{\partial W1} = -x_1(y - y_h)\sigma(w_1x_1 + w_2x_2 + w_3x_3)(1 - \sigma(w_1x_1 + w_2x_2 + w_3x_3))$$

# UPDATING THE WEIGHTS

$$w_i = w_i + \Delta w_i$$

$$\Delta w_i \propto -\frac{\partial E}{\partial w_i} \longrightarrow \text{THE GRADIENT}$$

$$\Delta w_i = -\eta \frac{\partial E}{\partial w_i}$$

↓  
LEARNING RATE

So, we update each weight with the negative value of the gradient which points towards the minimum multiplied by the learning rate (a length) that determines the step we take each time we update to reach the minimum.

The value of **learning rate** shouldn't be:

- 1- too big because we won't saturate in the global or local minimum
- 2- too small because it will make the process of reaching the minimum slow.



# CODE

Click on github icon below for the code





# APPLICATION

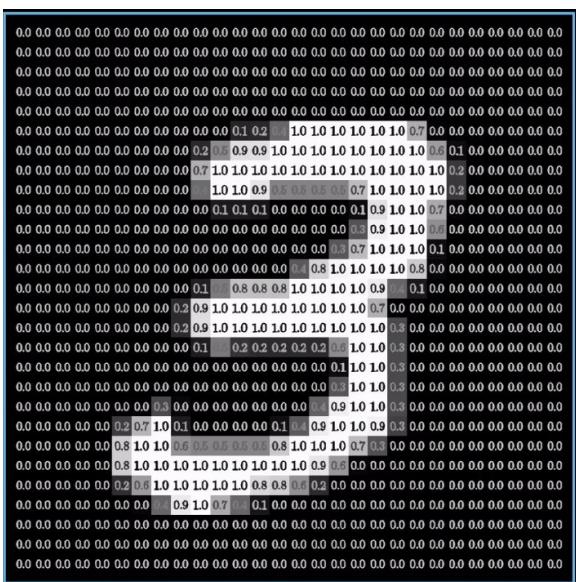
# ARTIFICIAL NEURAL NETWORKS

7 → 7 5 → 5

8 → 8 3 → 3

**2 → 2 4 → 4**

Let's think of a deep learning model that can **learn** the handwritten digits



# Sample input matrix

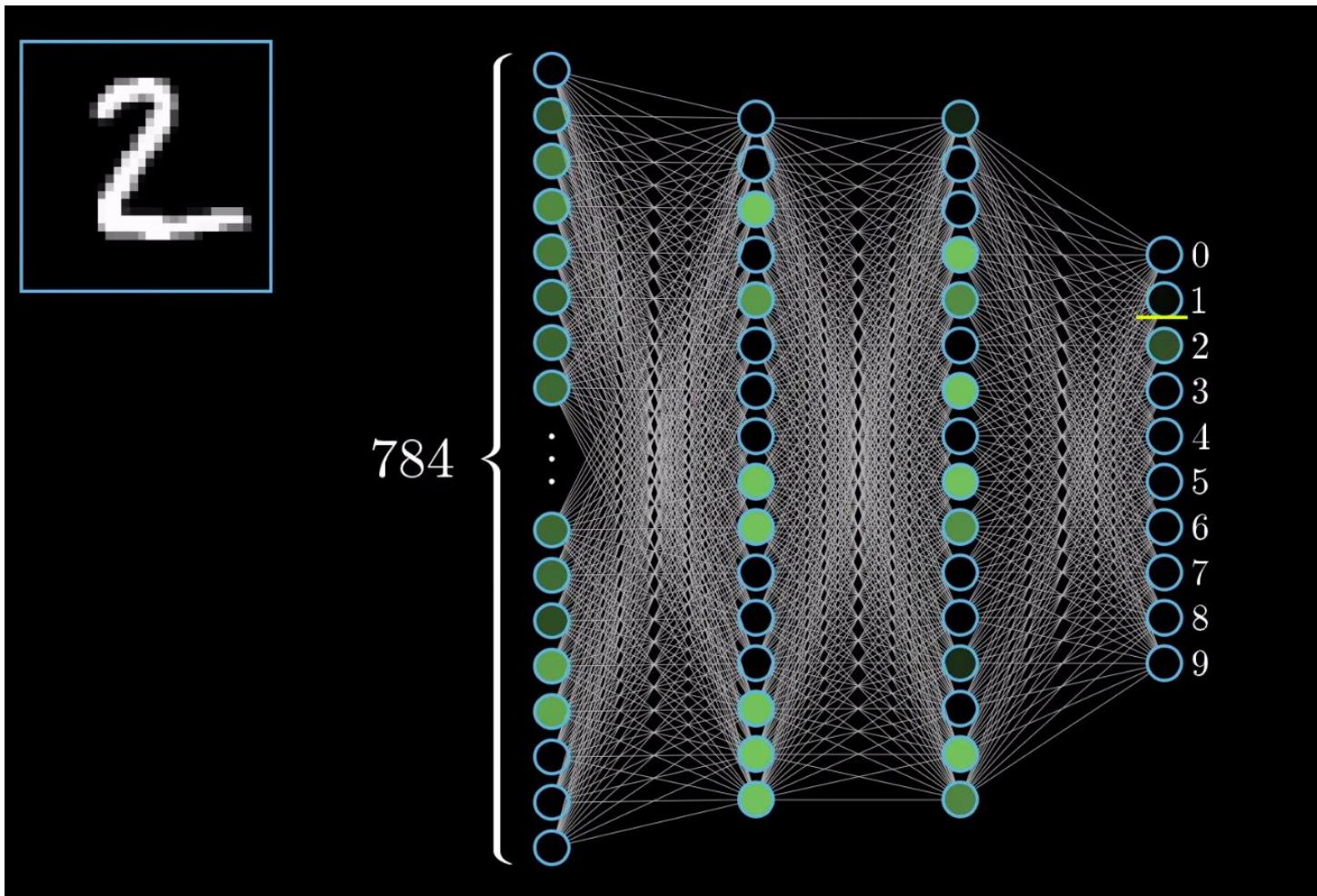


0  
1  
2  
**3**  
4  
5  
6  
7  
8  
9

## Output vector

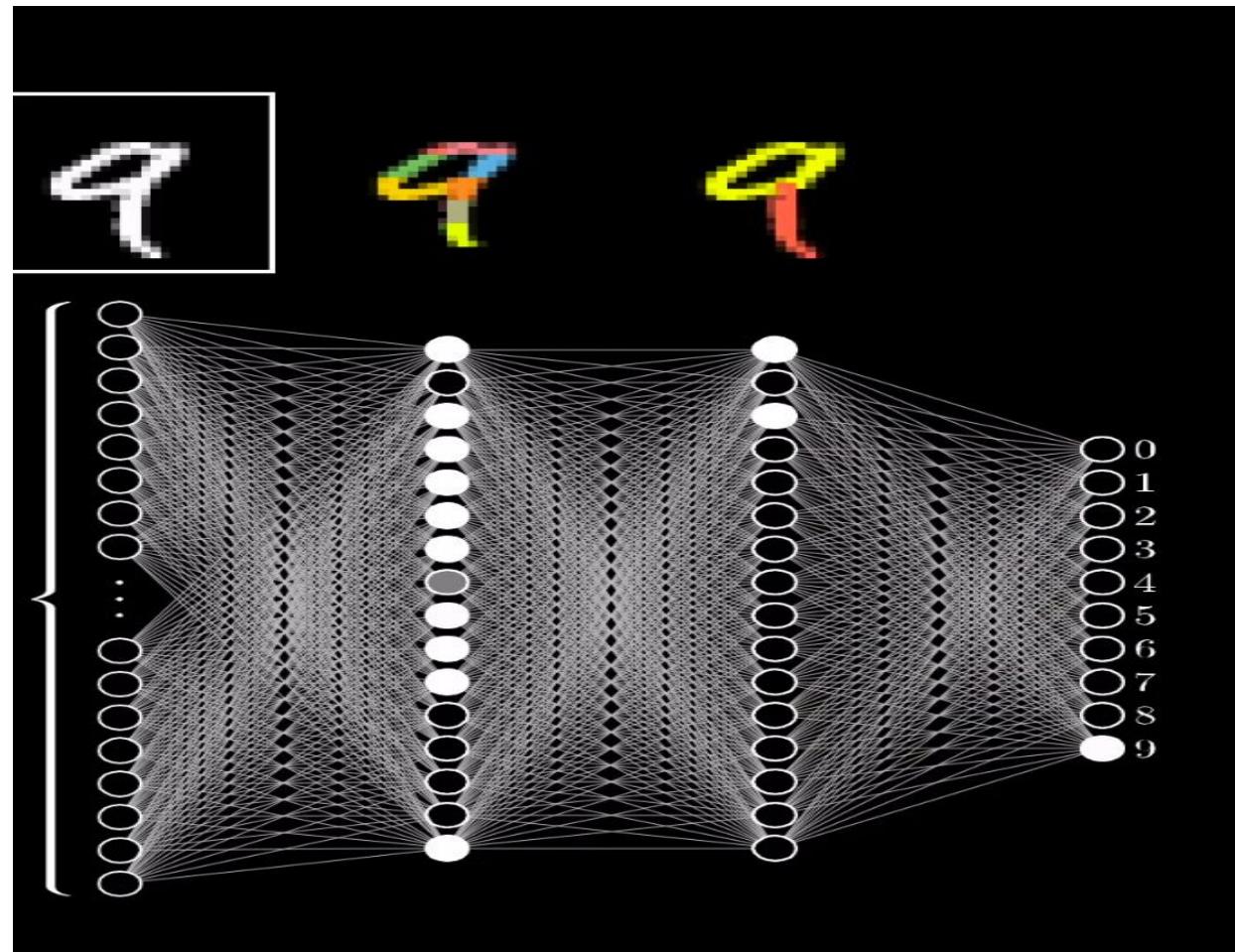
# NEURAL NETWORKS ARCHITECTURE

We can accomplish this with that architecture of neural network.



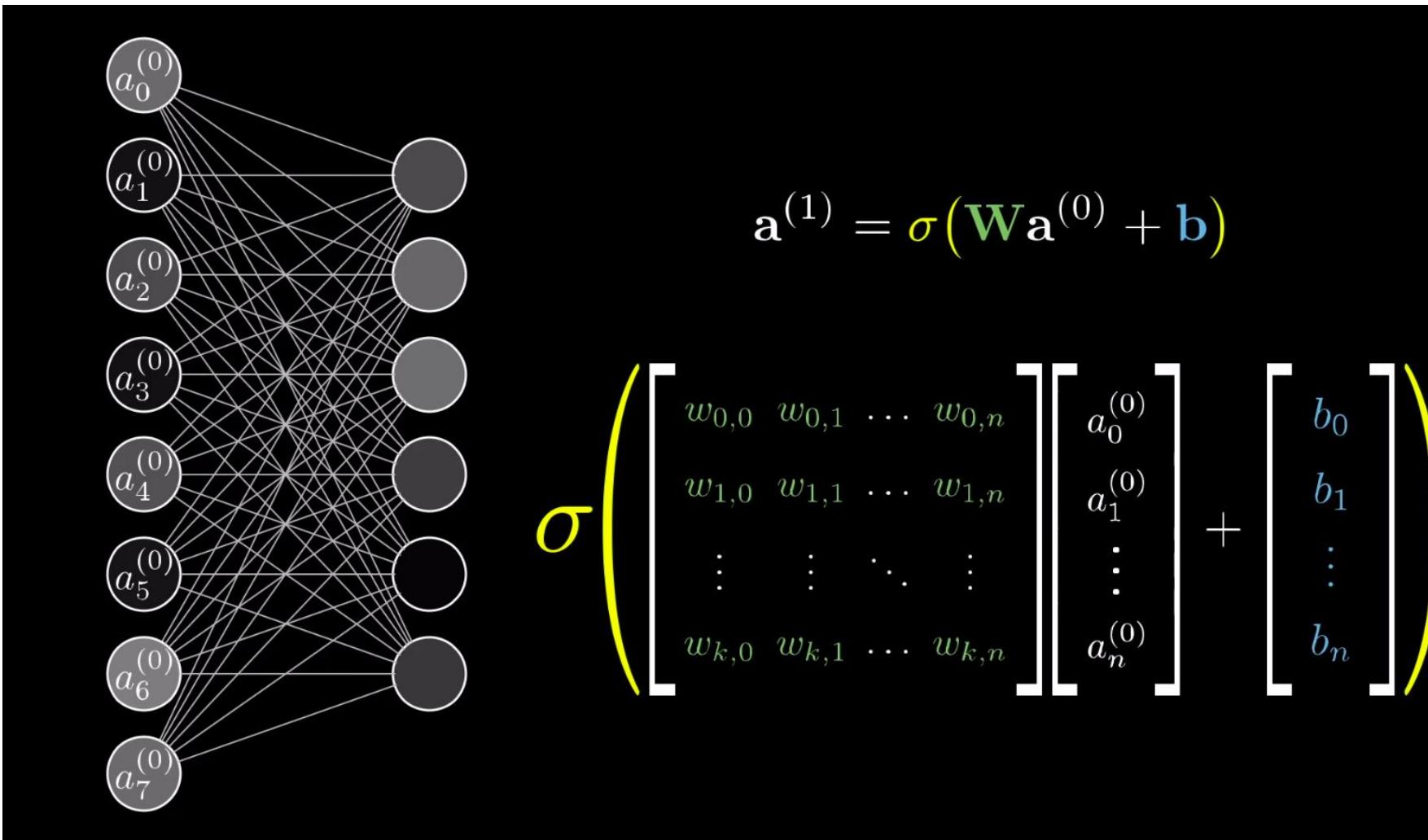
# LEARN HANDWRITTEN DIGITS

The way our brains identify a digit is by breaking it down to pieces. For each neuron in the hidden layer, it takes a punch of numbers (a vector) trying to detect an edge or curve in it. It tries to form a matrix where the curve shape appears in it to take it to the next layer level.



# LEARN HANDWRITTEN DIGITS

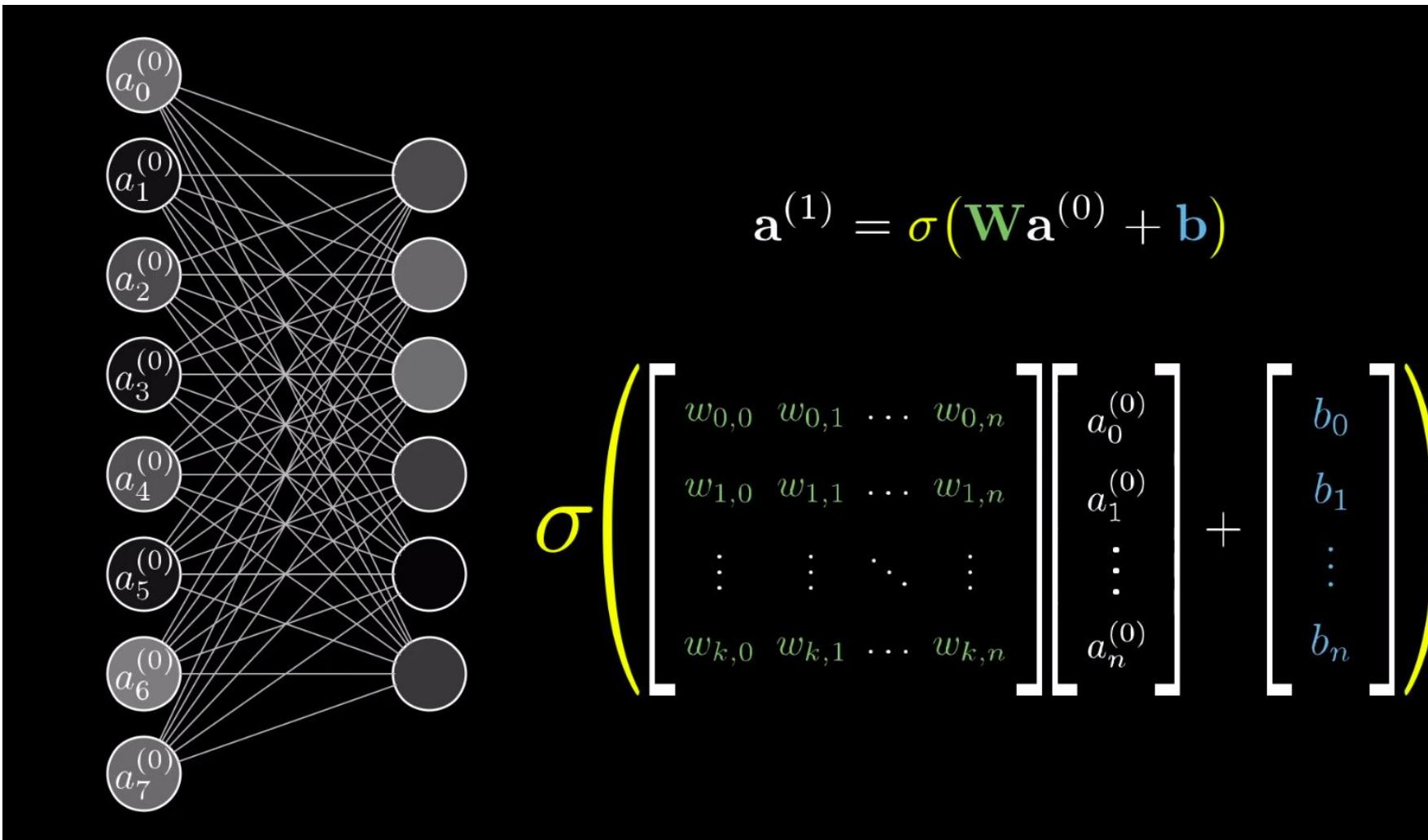
Each layer gives a vector of numbers, which corresponds to what can the layer detect and pass it to the next layer to get more information, or a clearer version of the information till we get a predication at the end.



Thinking of it from a linear Algebra prospective, we have an  $(k * m)$  weight matrix that connects two layers together and a  $(m * 1)$  input vector, performing a matrix by vector multiplication we will get a  $(k * 1)$  vector that represents the next layer after adding the bias and performing the activation function

# LEARN HANDWRITTEN DIGITS

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# LEARN HANDWRITTEN DIGITS APPLICATIONS



## Digit Recognition

This is a Machine Learning application that detects the Digit you write using pre-trained Tensorflow Model



## OCR Text Scanner - Image to Text

So Simple, Use the [OCR] Text Scanner app to basically used scanning and recognizing image text, handwritten or typed text format.



# THANK YOU!!!

ANY QUESTIONS?