

# First project

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The background of the slide features a glowing blue square sensor chip, likely a pressure sensor, mounted on a circuit board. The chip is surrounded by glowing blue circuit lines that extend across the frame, creating a high-tech, digital aesthetic. The overall color scheme is dark blue with bright blue highlights from the glowing elements.

# Pressure Detection

Learn\_in\_Depth



# Agenda Style

01

Design Architecting

02

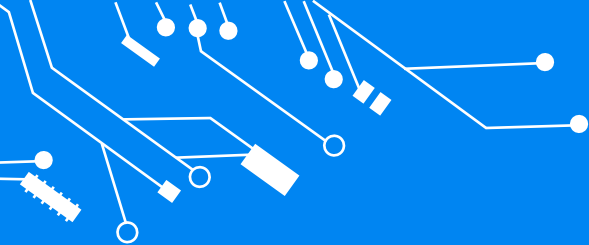
Code implementation

03

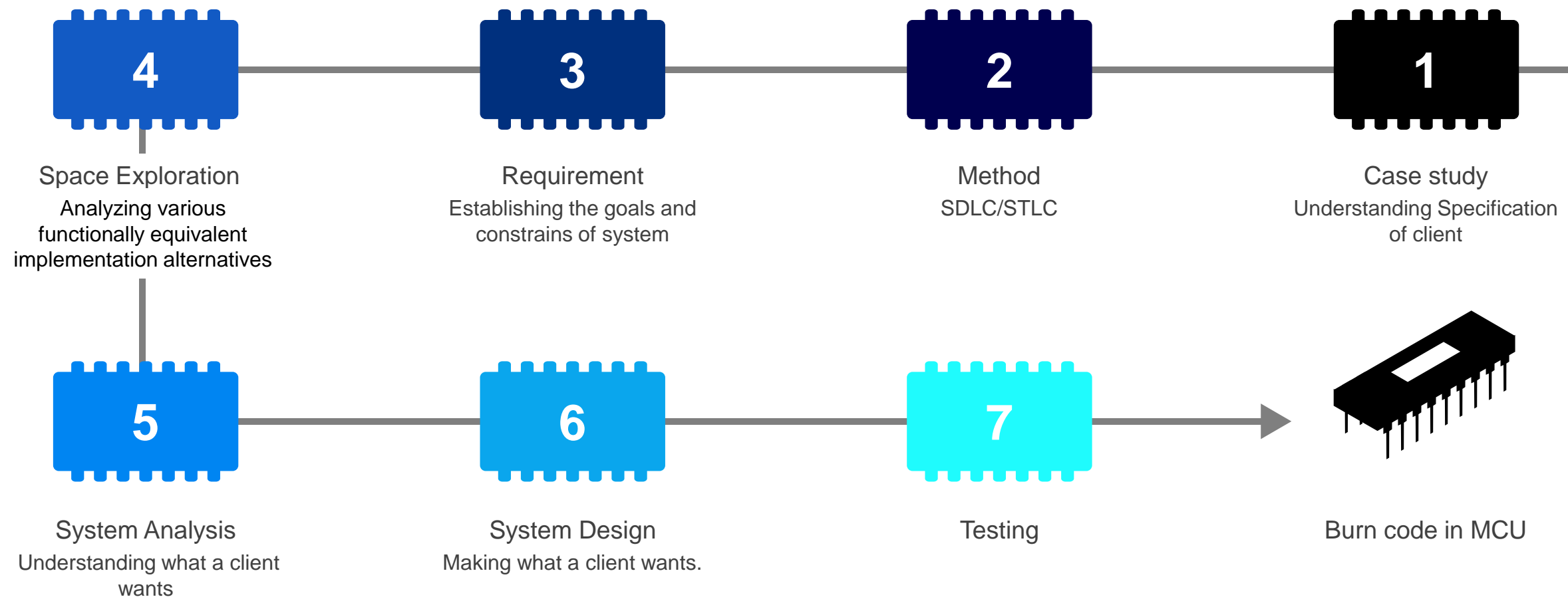
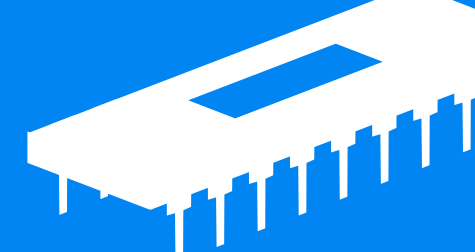
Compilation processes

04

Project simulation



# Design Architecting



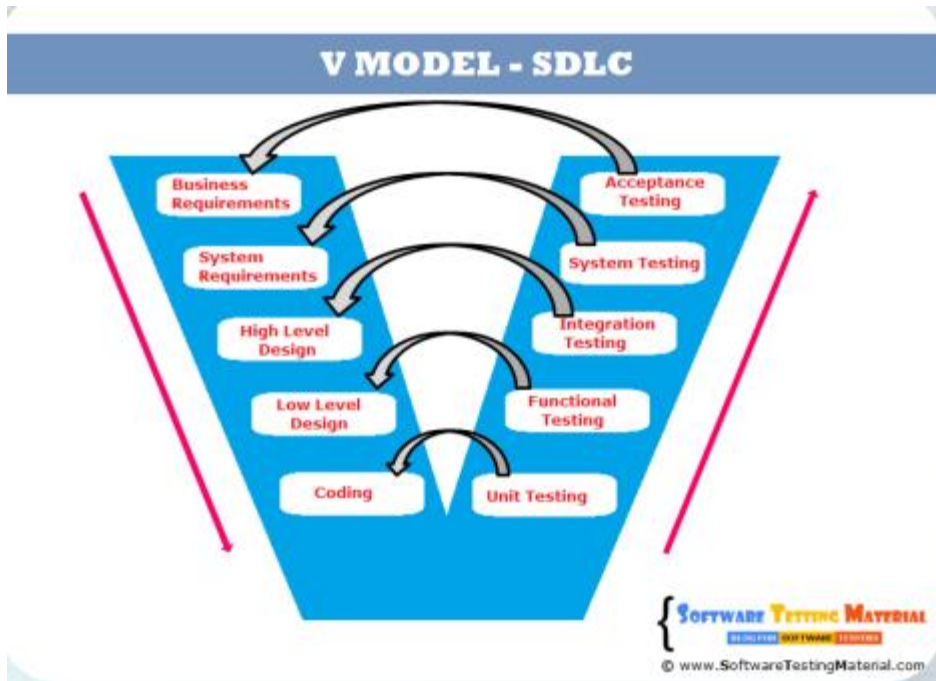
# Case Study



A "client" expects you to deliver the software of the following system:

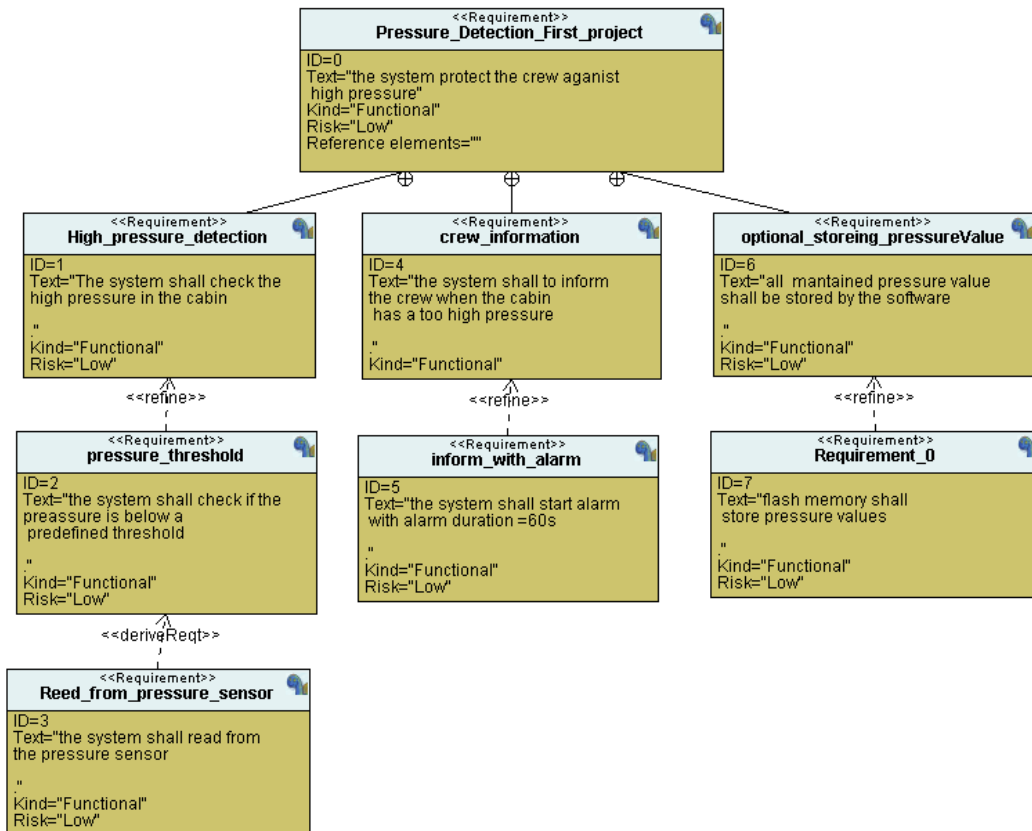
- ❖ Specification (from the client)
  - A pressure controller informs the crew of a cabin with an alarm when the pressure exceeds 20 bars in the cabin .
  - The alarm duration equals 60 seconds.
  - keeps track of the measured values.
  
- ❖ Pressure Controller: Assumptions
  - The controller set up and shutdown procedures are not modeled .
  - The controller maintenance is not modeled
  - The pressure sensor never fails
  - The alarm never fails
  - The controller never faces power cut

# Methods



The Software Development Life Cycle (SDLC) is a structured approach to software development that encompasses the processes, methodologies, and activities involved in creating and maintaining software systems. While the SDLC is applicable to various software development domains, including embedded software development, there are specific considerations and methodologies that are commonly used in the context of embedded software.

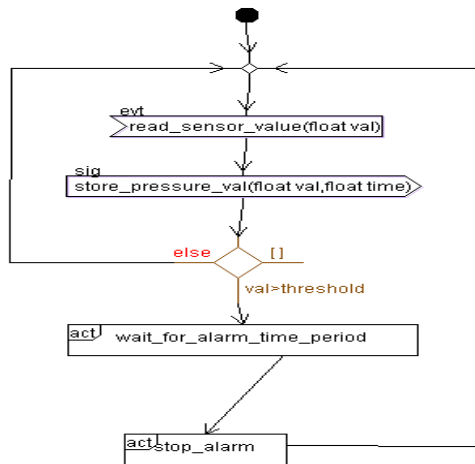
# Requirements



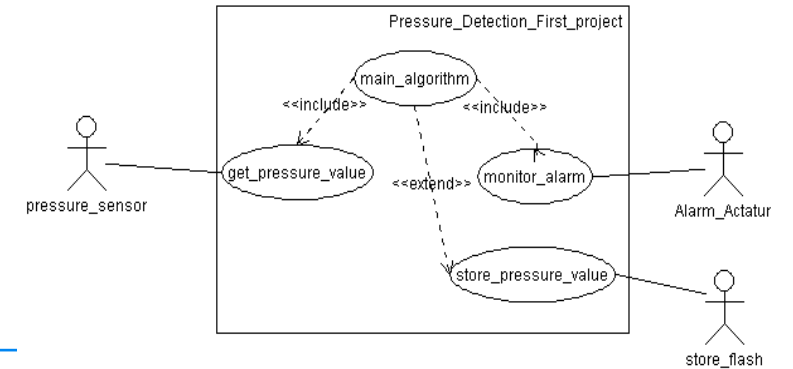
- A "client" expects you to deliver the software of the following system:
- ❖ Specification (from the client)
- ✓ A pressure controller informs the crew of a cabin with an alarm when the pressure exceeds 20 bars in the cabin.
- ✓ The alarm duration equals 60 seconds.
- ✓ Optional: keeps track of the measured values.

# System Analysis

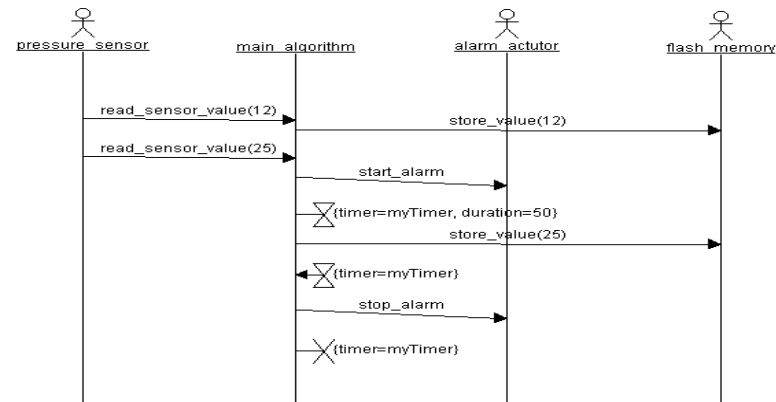
Diagram



Diagram

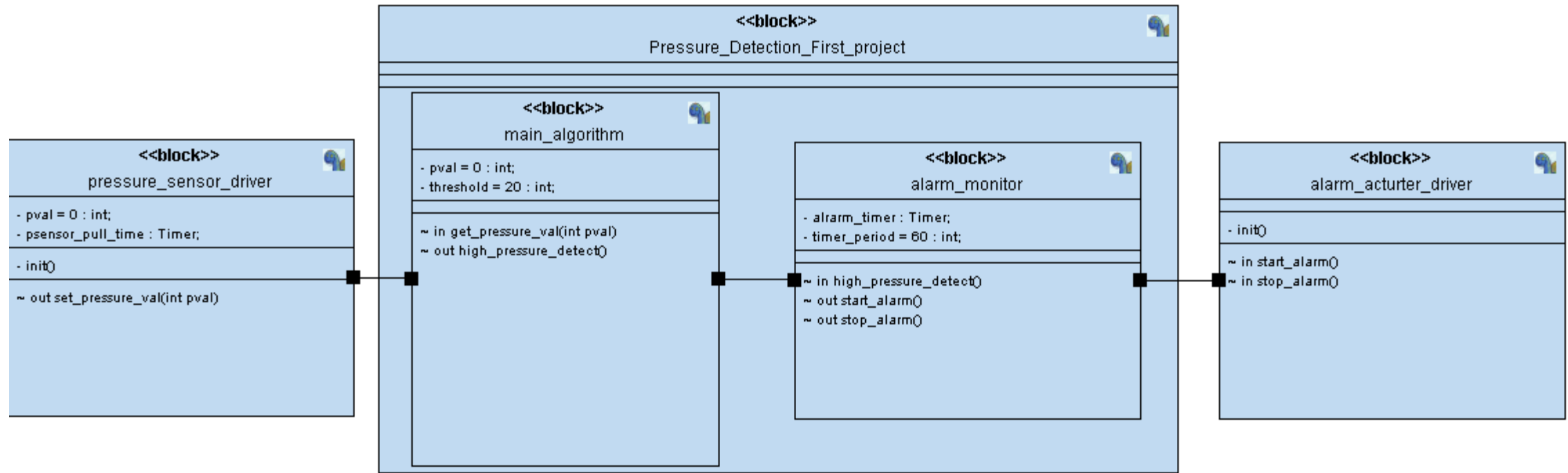


Diagram



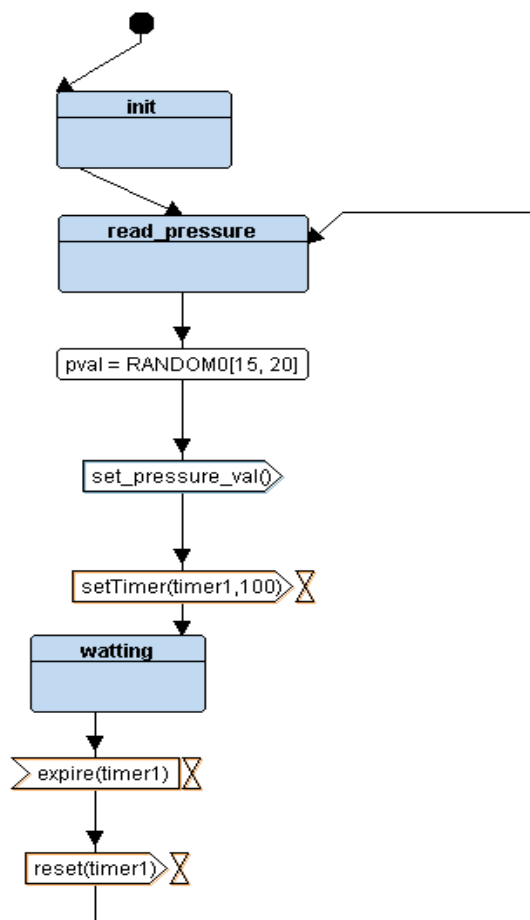


# System Design

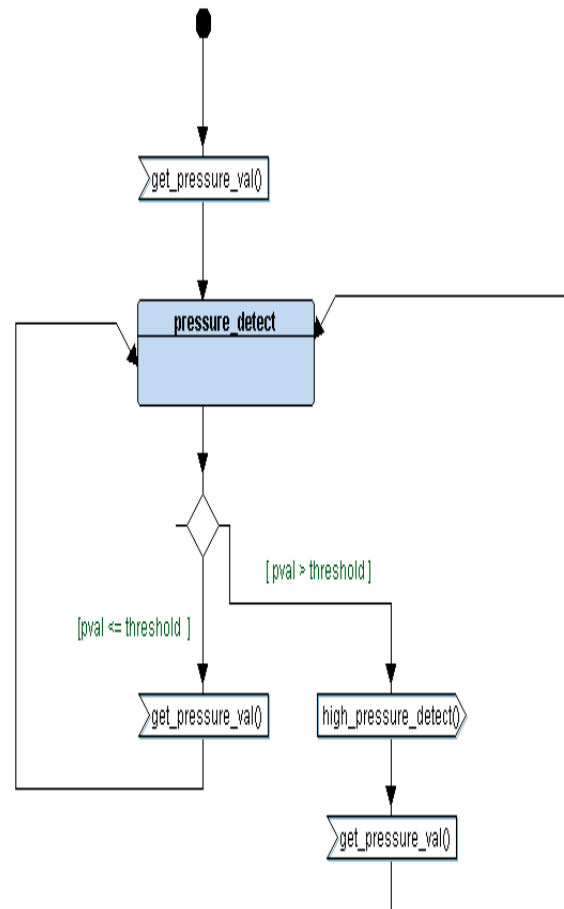


# System Design

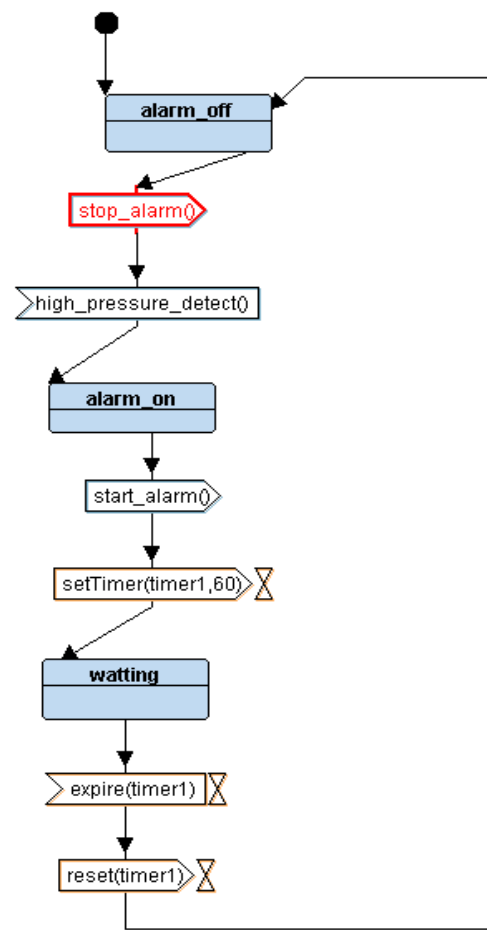
Pressure sensor



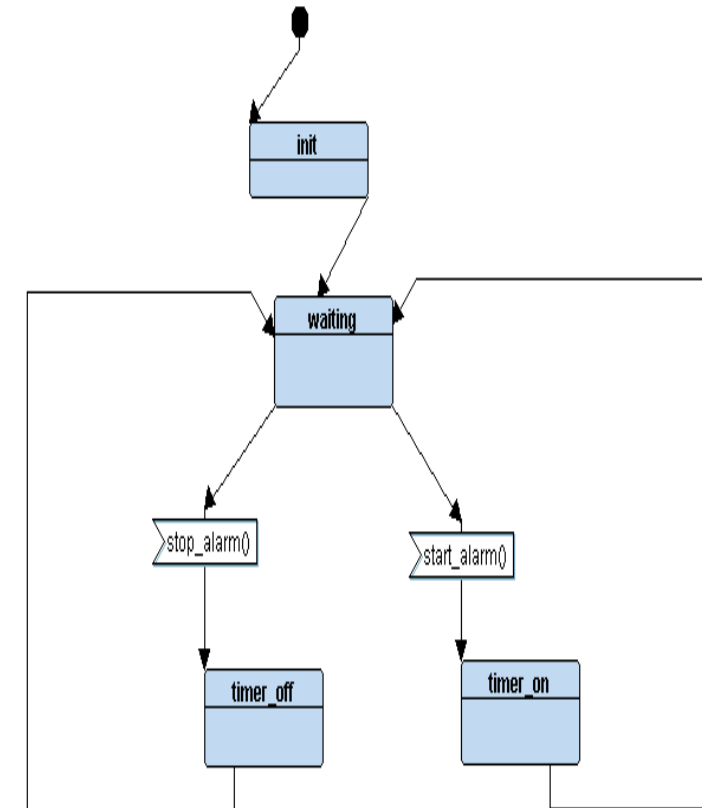
Main algorithm



Alarm monitor



Alarm actuator





# **Code Implementation**

**stm32f1036c**



```

/*
 * state.h
 *
 * Created on: Jun 27, 2023
 * Author: Egypt_Laptop
 */

#ifndef STATE_H
#define STATE_H

#include "STD_TYPES.h"

#define STATE_define(_state_) void st_##_state_()
#define STATE(_state_) st_##_state_

void set_pressure_val(uint8 prev);

void high_presure_detect();

void start_alarm();

void stop_alarm();

#endif /* STATE_H */

```

```

#include "driver.h"
#include "pressure_sensor.h"
#include "alarm_monitor.h"
#include "alarm.h"
#include "detect.h"
#include "STD_TYPES.h"

void setup()
{
    GPIO_INITIALIZATION();
    pre_sen_init();
    detect_st=STATE(pressure_detect);
    alr_mon_st=STATE(alarm_off);
    alarm_init();
}

int main() {
    setup();
    while(1)
    {
        pre_st();
        detect_st();
        alr_mon_st();
        alarm_st();
    }
}

```

```

/*
 * pressure_sensor.h
 *
 * Created on: Jun 27, 2023
 * Author: Egypt_Laptop
 */

#ifndef PRESSURE_SENSOR_H_
#define PRESSURE_SENSOR_H_

#include "state.h"

extern void (*pre_st)();

typedef enum{
    read_pressure,
    waiting
}pre_state_en;

extern pre_state_en pre_state_id;

STATE_define(read_pressure);

STATE_define(waiting);

void pre_sen_init();

```

```

#include "pressure_sensor.h"
#include "STD_TYPES.h"
#include "driver.h"
uint8 pval=0;

void (*pre_st)();

pre_state_en pre_state_id;

void pre_sen_init()
{
    //init pre_sensor
    pre_st=STATE(read_pressure);
}

STATE_define(read_pressure)
{
    pre_state_id=read_pressure;
    pval=getPressureVal();
    set_pressure_val(pval);
    pre_st=STATE(read_pressure);
}

STATE_define(waiting)
{
    pre_state_id=waiting;
    pre_st=STATE(read_pressure);
}

```

```

/*
 * detect.h
 *
 * Created on: Jun 27, 2023
 * Author: Egypt_Laptop
 */

#ifndef DETECT_H_
#define DETECT_H_

#include "state.h"

extern void (*detect_st) ();

typedef enum{
    pressure_detect
}detect_st_en;

extern detect_st_en detect_st_id;

STATE_define(pressure_detect);

#endif /* DETECT_H_ */

```

```

#include "detect.h"
#include "STD_TYPES.h"

uint8 pre_val=0;
uint8 last_val=0;
uint8 threshold=20;

void (*detect_st) ();

detect_st_en detect_st_id;

void set_pressure_val(uint8 pval)
{
    last_val=pre_val;
    pre_val=pval;
}

STATE_define(pressure_detect)
{
    detect_st_id=pressure_detect;
    if (pre_val > threshold && pre_val!=last_val)
    {
        high_presure_detect();
        detect_st=STATE(pressure_detect);
    }
    else
    {
        detect_st=STATE(pressure_detect);
    }
}

```



```

/*
 * alarm_monitor.h
 *
 * Created on: Jun 27, 2023
 * Author: Egypt_Laptop
 */

#ifndef ALARM_MONITOR_H_
#define ALARM_MONITOR_H_

#include "state.h"

extern void (*alr_mon_st)();

typedef enum{
    alarm_off,
    alarm_on,
    timer_waiting
}alr_mon_st_en;

extern alr_mon_st_en alr_mon_st_id;

STATE_define(alarm_off);
STATE_define(alarm_on);
STATE_define(timer_waiting);

#endif /* ALARM_MONITOR_H_ */

```

```

/*
#include "alarm_monitor.h"
#include "driver.h"

void (*alr_mon_st)();

alr_mon_st_en alr_mon_st_id;

void high_presure_detect()
{
    alr_mon_st=STATE(alarm_on);
}

STATE_define(alarm_off)
{
    alr_mon_st_id=alarm_off;
    stop_alarm();
}

STATE_define(alarm_on)
{
    alr_mon_st_id=alarm_on;
    start_alarm();
    alr_mon_st=STATE(alarm_off);
}

STATE_define(timer_waiting)
{
    alr_mon_st_id=timer_waiting;
    alr_mon_st=STATE(alarm_off);
}

```

```

/*
 * alarm.h
 *
 * Created on: Jun 27, 2023
 * Author: Egypt_Laptop
 */

#ifndef ALARM_H_
#define ALARM_H_

#include "state.h"

extern void (*alarm_st)();

typedef enum{
    alarm_start,
    alarm_stop,
    alarm_waiting
}alarm_st_en;

extern alarm_st_en alarm_st_id;

STATE_define(alarm_start);
STATE_define(alarm_stop);
STATE_define(alarm_waiting);

void alarm_init();

#endif /* ALARM_H_ */

```

```

/*
 * alarm.c
 *
 * Created on: Jun 27, 2023
 * Author: Egypt_Laptop
 */

#include "alarm.h"
#include "driver.h"

void (*alarm_st)();

alarm_st_en alarm_st_id;

void alarm_init()
{
    //alarm_init
    alarm_st=STATE(alarm_waiting);
}

void start_alarm()
{
    alarm_st=STATE(alarm_start);
}

void stop_alarm()
{
    alarm_st=STATE(alarm_stop);
}

```

```

STATE_define(alarm_start)
{
    alarm_st_id=alarm_start;
    Set_Alarm_actuator(0);
    Delay(2000000);
    alarm_st=STATE(alarm_waiting);
}

STATE_define(alarm_stop)
{
    alarm_st_id=alarm_stop;
    Set_Alarm_actuator(1);
    alarm_st=STATE(alarm_waiting);
}

STATE_define(alarm_waiting)
{
    alarm_st_id=alarm_waiting;
}

```

```

#include <stdint.h>
#include <stdio.h>

#define SET_BIT(ADDRESS,BIT)  ADDRESS |= (1<<BIT)
#define RESET_BIT(ADDRESS,BIT) ADDRESS &= ~(1<<BIT)
#define TOGGLE_BIT(ADDRESS,BIT) ADDRESS ^= (1<<BIT)
#define READ_BIT(ADDRESS,BIT) ((ADDRESS) & (1<<(BIT)))

#define GPIO_PORTA 0x40010800
#define BASE_RCC 0x40021000

#define APB2ENR *(volatile uint32_t *) (BASE_RCC + 0x18)

#define GPIOA_CRL *(volatile uint32_t *) (GPIO_PORTA + 0x00)
#define GPIOA_CRH *(volatile uint32_t *) (GPIO_PORTA + 0x04)
#define GPIOA_IDR *(volatile uint32_t *) (GPIO_PORTA + 0x08)
#define GPIOA_ODR *(volatile uint32_t *) (GPIO_PORTA + 0x0C)

void Delay(int nCount);
int getPressureVal();
void Set_Alarm_actuator(int i);
void GPIO_INITIALIZATION ();

```

```

#include "driver.h"
#include <stdint.h>
#include <stdio.h>
void Delay(int nCount)
{
    for(; nCount != 0; nCount--);
}

int getPressureVal() {
    return (GPIOA_IDR & 0xFF);
}

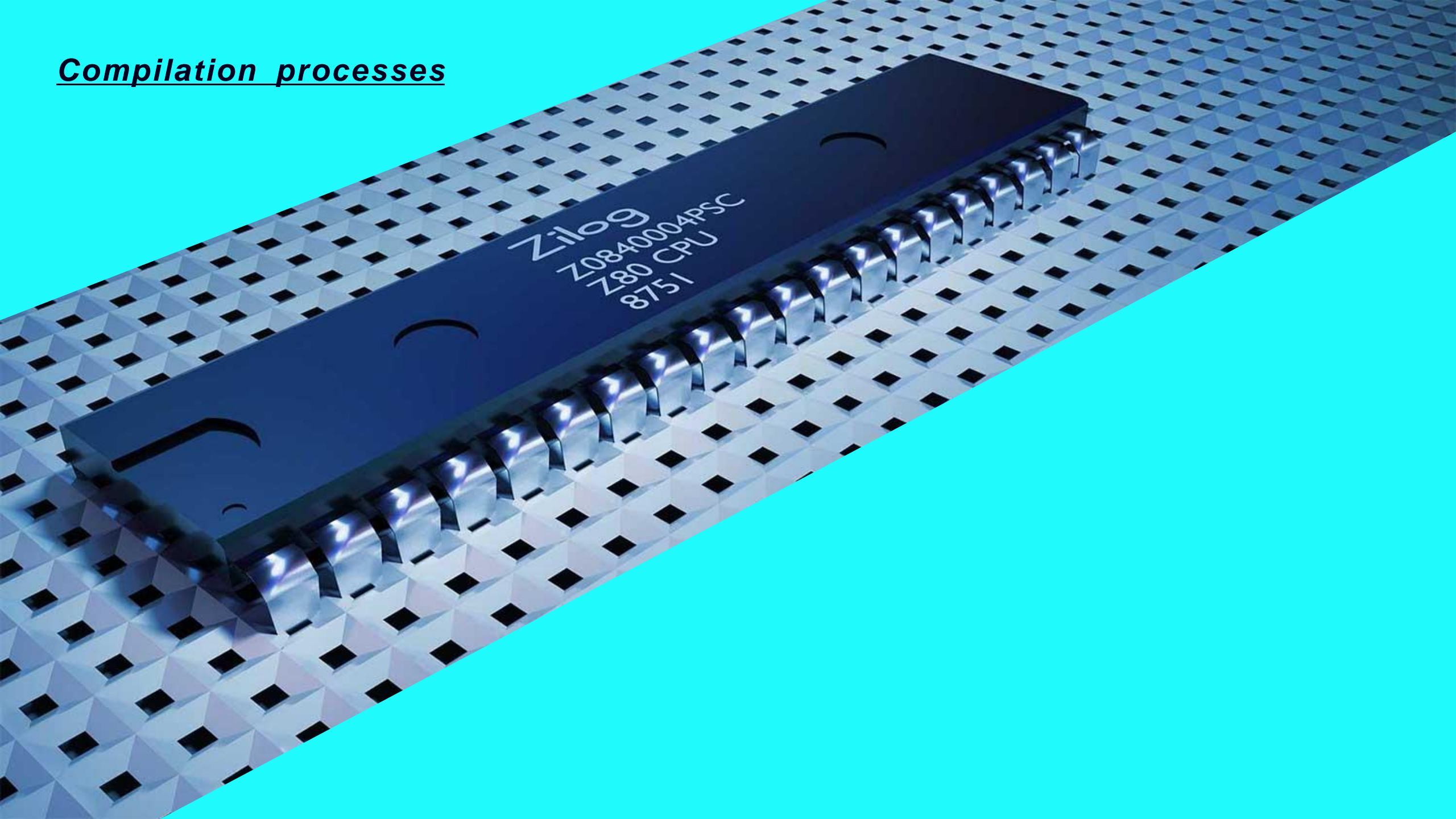
void Set_Alarm_actuator(int i) {
    if (i == 1) {
        SET_BIT(GPIOA_ODR, 13);
    }
    else if (i == 0) {
        RESET_BIT(GPIOA_ODR, 13);
    }
}

void GPIO_INITIALIZATION () {
    SET_BIT(APB2ENR, 2);
    GPIOA_CRL &= 0xFF0FFFFFFF;
    GPIOA_CRL |= 0x00000000;
    GPIOA_CRH &= 0xFF0FFFFFFF;
    GPIOA_CRH |= 0x22222222;
}

```



## Compilation processes



```
//startup code
```

```
/*LEARN_IN_DEPTH
```

```
UNIT2_LESSON2_LAP2
```

```
ENG: AHMED HASSAN
```

```
*/
```

```
#include "STD_TYPES.H"
```

```
extern uint32 stack_top;
```

```
extern uint32 _S_DATA;
```

```
extern uint32 _E_DATA;
```

```
extern uint32 _S_BSS;
```

```
extern uint32 _E_BSS;
```

```
extern uint32 _E_text;
```

```
extern int main(void);
```

```
void Rest_Handler();
```

```
void init_sect(void);
```

```
void Default_handler(void)
```

```
{
```

```
    Rest_Handler();
```

```
}
```

```
void NMI_Handler(void)    __attribute__((weak , alias("Default_handler")));
```

```
void H_Fault_Handler(void) __attribute__((weak , alias("Default_handler")));
```

```
void MM_Handler(void)    __attribute__((weak , alias("Default_handler")));
```

```
void Bus_Handler(void)   __attribute__((weak , alias("Default_handler")));
```

```
void Usage_Fault_Handler(void) __attribute__((weak , alias("Default_handler")));
```

```
uint32 vectors[] __attribute__((section(".vectors"))) =
```

```
{
```

```
    (uint32) &stack_top,
```

```
    (uint32) &Rest_Handler,
```

```
    (uint32) &NMI_Handler,
```

```
    (uint32) &H_Fault_Handler,
```

```
    (uint32) &MM_Handler,
```

```
    (uint32) &Bus_Handler,
```

```
    (uint32) &Usage_Fault_Handler,
```

```
};
```

```
void Rest_Handler(void)
```

```
{
```

```
    init_sect();
```

```
    main();
```

```
}
```

```
void init_sect(void)
```

```
{
```

```
    uint32 DATA_size = (uint32*)&_E_DATA - (uint32*)&_S_DATA;
```

```
    uint8 *P_src = (uint8*)&_E_text;
```

```
    uint8 *P_dst = (uint8*)&_S_DATA;
```

```
    for (uint32 i=0;i<DATA_size;i++)
```

```
    {
```

```
        *((uint8*)P_dst++) = *((uint8*)P_src++);
```

```
    }
```

```
    uint32 bss_size = (uint32*)&_E_BSS - (uint32*)&_S_BSS;
```

```
    P_dst = (uint8*)&_S_BSS;
```

```
    for (uint32 i=0;i<bss_size;i++)
```

```
    {
```

```
        *((uint8*)P_dst++) = (uint8)0;
```

```
    }
```





```
gufts/First_Project (main)
$ arm-none-eabi-gcc.exe -c -I .-mcpu=cortex-m3 main.c -o main.o

Egypt_Laptop@DESKTOP-P909616 MINGW64 /d/Communication/02-embeded system/Gitup_Repo/Master5_Fist_term_progufts/First_Project (main)
$ arm-none-eabi-objdump.exe -t main.o

main.o:      file format elf32-littlearm

SYMBOL TABLE:
00000000 l    df *ABS* 00000000 main.c
00000000 l    d  .text 00000000 .text
00000000 l    d  .data 00000000 .data
00000000 l    d  .bss 00000000 .bss
00000000 l    d  .comment 00000000 .comment
00000000 l    d  .ARM.attributes 00000000 .ARM.attributes
00000000 g    F  .text 0000004c setup
00000000    *UND* 00000000 GPIO_INITIALIZATION
00000000    *UND* 00000000 pre_sen_init
00000000    *UND* 00000000 alarm_init
00000000    *UND* 00000000 detect_st
00000000    *UND* 00000000 st_pressure_detect
00000000    *UND* 00000000 alr_mon_st
00000000    *UND* 00000000 st_alarm_off
0000004c g    F  .text 00000060 main
00000000    *UND* 00000000 pre_st
00000000    *UND* 00000000 alarm_st

Egypt_Laptop@DESKTOP-P909616 MINGW64 /d/Communication/02-embeded system/Gitup_Repo/Master5_Fist_term_progufts/First_Project (main)
$ arm-none-eabi-objdump.exe -h main.o

main.o:      file format elf32-littlearm

Sections:
Idx Name          Size      VMA           LMA           File off  Algn
  0 .text          000000ac 00000000 00000000 00000034 2**2
    CONTENTS, ALLOC, LOAD, RELOC, READONLY, CODE
  1 .data          00000000 00000000 00000000 000000e0 2**0
    CONTENTS, ALLOC, LOAD, DATA
  2 .bss           00000000 00000000 00000000 000000e0 2**0
    ALLOC
  3 .comment       0000004a 00000000 00000000 000000e0 2**0
    CONTENTS, READONLY
  4 .ARM.attributes 0000002a 00000000 00000000 0000012a 2**0
    CONTENTS, READONLY

Egypt_Laptop@DESKTOP-P909616 MINGW64 /d/Communication/02-embeded system/Gitup_Repo/Master5_Fist_term_progufts/First_Project (main)
```

```
gufts/First_Project (main)
$ arm-none-eabi-gcc.exe -c -I .-mcpu=cortex-m3 driver.c -o driver.o

Egypt_Laptop@DESKTOP-P909616 MINGW64 /d/Communication/02-embeded system/Gitup_Repo/Master5_Fist_term_progufts/First_Project (main)
$ arm-none-eabi-objdump.exe -t driver.o

driver.o:     file format elf32-littlearm

SYMBOL TABLE:
00000000 l    df *ABS* 00000000 driver.c
00000000 l    d  .text 00000000 .text
00000000 l    d  .data 00000000 .data
00000000 l    d  .bss 00000000 .bss
00000000 l    d  .comment 00000000 .comment
00000000 l    d  .ARM.attributes 00000000 .ARM.attributes
00000000 g    F  .text 00000040 Delay
00000040 g    F  .text 00000028 getPressureVal
00000068 g    F  .text 00000068 Set_Alarm_actuator
000000d0 g    F  .text 0000008c GPIO_INITIALIZATION

Egypt_Laptop@DESKTOP-P909616 MINGW64 /d/Communication/02-embeded system/Gitup_Repo/Master5_Fist_term_progufts/First_Project (main)
$ arm-none-eabi-objdump.exe -h driver.o

driver.o:     file format elf32-littlearm

Sections:
Idx Name          Size      VMA           LMA           File off  Algn
  0 .text          0000015c 00000000 00000000 00000034 2**2
    CONTENTS, ALLOC, LOAD, RELOC, READONLY, CODE
  1 .data          00000000 00000000 00000000 00000190 2**0
    CONTENTS, ALLOC, LOAD, DATA
  2 .bss           00000000 00000000 00000000 00000190 2**0
    ALLOC
  3 .comment       0000004a 00000000 00000000 00000190 2**0
    CONTENTS, READONLY
  4 .ARM.attributes 0000002a 00000000 00000000 000001da 2**0
    CONTENTS, READONLY
```

```
mit5_Fist_term_progufts/First_Project (main)
$ arm-none-eabi-gcc.exe -c -I .-mcpu=cortex-m3 pressure_sensor.c -o pressure_sensor.o

Egypt_Laptop@DESKTOP-P909616 MINGW64 /d/Communication/02-embeded system/Gitup_Repo/Master5_Fist_term_progufts/First_Project (main)
$ arm-none-eabi-objdump.exe -t pressure_sensor.o

pressure_sensor.o:  file format elf32-littlearm

SYMBOL TABLE:
00000000 l    df *ABS* 00000000 pressure_sensor.c
00000000 l    d  .text 00000000 .text
00000000 l    d  .data 00000000 .data
00000000 l    d  .bss 00000000 .bss
00000000 l    d  .comment 00000000 .comment
00000000 l    d  .ARM.attributes 00000000 .ARM.attributes
00000000 g    o  .bss 00000001 pval
00000004 g    o  .bss 00000004 pre_st
00000008 g    o  .bss 00000001 pre_state_id
00000000 g    F  .text 0000002c pre_sen_init
0000002c g    F  .text 00000064 st_read_pressure
00000000    *UND* 00000000 getPressureVal
00000000    *UND* 00000000 set_pressure_val
00000090 g    F  .text 0000003c st_waiting

Egypt_Laptop@DESKTOP-P909616 MINGW64 /d/Communication/02-embeded system/Gitup_Repo/Master5_Fist_term_progufts/First_Project (main)
$ arm-none-eabi-objdump.exe -h pressure_sensor.o

pressure_sensor.o:  file format elf32-littlearm

Sections:
Idx Name          Size      VMA           LMA           File off  Algn
  0 .text          000000cc 00000000 00000000 00000034 2**2
    CONTENTS, ALLOC, LOAD, RELOC, READONLY, CODE
  1 .data          00000000 00000000 00000000 00000100 2**0
    CONTENTS, ALLOC, LOAD, DATA
  2 .bss           00000009 00000000 00000000 00000100 2**2
    ALLOC
  3 .comment       0000004a 00000000 00000000 00000100 2**0
    CONTENTS, READONLY
  4 .ARM.attributes 0000002a 00000000 00000000 0000014a 2**0
    CONTENTS, READONLY
```

```
$ arm-none-eabi-gcc.exe -c -I .-mcpu=cortex-m3 detect.c -o detect.o

Egypt_Laptop@DESKTOP-P909616 MINGW64 /d/Communication/02-embeded system
nit5_First_term_proguets/First_Project (main)
$ arm-none-eabi-objdump.exe -t detect.o
```

```
detect.o:      file format elf32-littlearm
```

SYMBOL TABLE:

```
00000000 l      df *ABS* 00000000 detect.c
00000000 l      d .text 00000000 .text
00000000 l      d .data 00000000 .data
00000000 l      d .bss 00000000 .bss
00000000 l      d .comment 00000000 .comment
00000000 l      d .ARM.attributes 00000000 .ARM.attributes
00000000 g      o .bss 00000001 pre_val
00000001 g      o .bss 00000001 last_val
00000000 g      o .data 00000001 threshold
00000004 g      o .bss 00000004 detect_st
00000008 g      o .bss 00000001 detect_st_id
00000000 g      F .text 00000048 set_pressure_val
00000048 g      F .text 00000090 st_pressure_detect
00000000      *UND* 00000000 high_presure_detect
```

```
Egypt_Laptop@DESKTOP-P909616 MINGW64 /d/Communication/02-embeded system
nit5_First_term_proguets/First_Project (main)
$ arm-none-eabi-objdump.exe -h detect.o
```

```
detect.o:      file format elf32-littlearm
```

Sections:

Idx	Name	Size	VMA	LMA	File off	Algn
0	.text	000000d8	00000000	00000000	00000034	2**2
	CONTENTS, ALLOC, LOAD, RELOC, READONLY, CODE					
1	.data	00000001	00000000	00000000	0000010c	2**0
	CONTENTS, ALLOC, LOAD, DATA					
2	.bss	00000009	00000000	00000000	00000110	2**2
	ALLOC					
3	.comment	0000004a	00000000	00000000	00000110	2**0
	CONTENTS, READONLY					
4	.ARM.attributes	0000002a	00000000	00000000	0000015a	2**0
	CONTENTS, READONLY					

```
nit5_First_term_proguets/First_Project (main)
$ arm-none-eabi-gcc.exe -c -I .-mcpu=cortex-m3 alarm_monitor.c -o alarm_monitor.o

Egypt_Laptop@DESKTOP-P909616 MINGW64 /d/Communication/02-embeded system/Gitup_Repo/Maste
nit5_First_term_proguets/First_Project (main)
$ arm-none-eabi-objdump.exe -t alarm_monitor.o
```

```
alarm_monitor.o:  file format elf32-littlearm
```

SYMBOL TABLE:

```
00000000 l      df *ABS* 00000000 alarm_monitor.c
00000000 l      d .text 00000000 .text
00000000 l      d .data 00000000 .data
00000000 l      d .bss 00000000 .bss
00000000 l      d .comment 00000000 .comment
00000000 l      d .ARM.attributes 00000000 .ARM.attributes
00000000 g      o .bss 00000004 alr_mon_st
00000004 g      o .bss 00000001 alr_mon_st_id
00000000 g      F .text 0000002c high_presure_detect
00000058 g      F .text 00000040 st_alarm_on
0000002c g      F .text 0000002c st_alarm_off
00000000      *UND* 00000000 stop_alarm
00000000      *UND* 00000000 start_alarm
00000098 g      F .text 0000003c st_timer_waiting
```

```
Egypt_Laptop@DESKTOP-P909616 MINGW64 /d/Communication/02-embeded system/Gitup_Repo/Maste
nit5_First_term_proguets/First_Project (main)
$ arm-none-eabi-objdump.exe -h alarm_monitor.o
```

```
alarm_monitor.o:  file format elf32-littlearm
```

Sections:

Idx	Name	Size	VMA	LMA	File off	Algn
0	.text	000000d4	00000000	00000000	00000034	2**2
	CONTENTS, ALLOC, LOAD, RELOC, READONLY, CODE					
1	.data	00000000	00000000	00000000	00000108	2**0
	CONTENTS, ALLOC, LOAD, DATA					
2	.bss	00000005	00000000	00000000	00000108	2**2
	ALLOC					
3	.comment	0000004a	00000000	00000000	00000108	2**0
	CONTENTS, READONLY					
4	.ARM.attributes	0000002a	00000000	00000000	00000152	2**0
	CONTENTS, READONLY					

```
nit5_First_term_proguets/First_Project (main)
$ arm-none-eabi-gcc.exe -c -I .-mcpu=cortex-m3 alarm.c -o alarm.o

Egypt_Laptop@DESKTOP-P909616 MINGW64 /d/Communication/02-embeded syst
nit5_First_term_proguets/First_Project (main)
$ arm-none-eabi-objdump.exe -t alarm.o
```

```
alarm.o:      file format elf32-littlearm
```

SYMBOL TABLE:

```
00000000 l      df *ABS* 00000000 alarm.c
00000000 l      d .text 00000000 .text
00000000 l      d .data 00000000 .data
00000000 l      d .bss 00000000 .bss
00000000 l      d .comment 00000000 .comment
00000000 l      d .ARM.attributes 00000000 .ARM.attributes
00000000 g      o .bss 00000004 alarm_st
00000004 g      o .bss 00000001 alarm_st_id
00000000 g      F .text 0000002c alarm_init
00000118 g      F .text 00000028 st_alarm_waiting
0000002c g      F .text 0000002c start_alarm
00000084 g      F .text 00000050 st_alarm_start
00000058 g      F .text 0000002c stop_alarm
000000d4 g      F .text 00000044 st_alarm_stop
00000000      *UND* 00000000 Set_Alarm_actuator
00000000      *UND* 00000000 Delay
```

```
Egypt_Laptop@DESKTOP-P909616 MINGW64 /d/Communication/02-embeded syst
nit5_First_term_proguets/First_Project (main)
$ arm-none-eabi-objdump.exe -h alarm.o
```

```
alarm.o:      file format elf32-littlearm
```

Sections:

Idx	Name	Size	VMA	LMA	File off	Algn
0	.text	00000140	00000000	00000000	00000034	2**2
	CONTENTS, ALLOC, LOAD, RELOC, READONLY, CODE					
1	.data	00000000	00000000	00000000	00000174	2**0
	CONTENTS, ALLOC, LOAD, DATA					
2	.bss	00000005	00000000	00000000	00000174	2**2
	ALLOC					
3	.comment	0000004a	00000000	00000000	00000174	2**0
	CONTENTS, READONLY					
4	.ARM.attributes	0000002a	00000000	00000000	000001be	2**0
	CONTENTS, READONLY					

Idx	Name	Size	VMA	LMA	File off	Algn
0	.text	00000134	00000000	00000000	00000034	2**2
	CONTENTS, ALLOC, LOAD, RELOC, READONLY, CODE					
1	.data	00000000	00000000	00000000	00000168	2**0
	CONTENTS, ALLOC, LOAD, DATA					
2	.bss	00000000	00000000	00000000	00000168	2**0
	ALLOC					
3	.vectors	0000001c	00000000	00000000	00000168	2**2
	CONTENTS, ALLOC, LOAD, RELOC, DATA					
4	.comment	0000004a	00000000	00000000	00000184	2**0
	CONTENTS, READONLY					
5	.ARM.attributes	0000002a	00000000	00000000	000001ce	2**0
	CONTENTS, READONLY					

```
arm-none-eabi-gcc.exe -c -g -gdwarf-2 -mcpu=cortex-m3 -I . alarm.c -o alarm.o
arm-none-eabi-gcc.exe -c -g -gdwarf-2 -mcpu=cortex-m3 -I . alarm_monitor.c -o alarm_monitor.o
arm-none-eabi-gcc.exe -c -g -gdwarf-2 -mcpu=cortex-m3 -I . detect.c -o detect.o
arm-none-eabi-gcc.exe -c -g -gdwarf-2 -mcpu=cortex-m3 -I . driver.c -o driver.o
arm-none-eabi-gcc.exe -c -g -gdwarf-2 -mcpu=cortex-m3 -I . main.c -o main.o
arm-none-eabi-gcc.exe -c -g -gdwarf-2 -mcpu=cortex-m3 -I . pressure_sensor.c -o pressure_sensor.o
arm-none-eabi-gcc.exe -c -g -gdwarf-2 -mcpu=cortex-m3 -I . startup.c -o startup.o
arm-none-eabi-ld.exe -T linker_script.ld alarm.o alarm_monitor.o detect.o driver.o main.o pressure_sensor.o startup.o -o pressure_detector.elf -Map=output.map
arm-none-eabi-objcopy.exe -O binary pressure_detector.elf pressure_detector.bin
>>>>>>>>>Build is Done<<<<<<<<<<<<
```



Write your OWN Linker & Startup & Makefile

write your algorithm according to:

SYSML/UML Design Flows and Diagrams which you are created according to the Requirements

Mastering Embedded System Online Diploma (KS)

[www.learn-in-depth.com](http://www.learn-in-depth.com)

First Term Project 1

Eng: Ahmed Hassan Kotp

## Pressure Sensor

