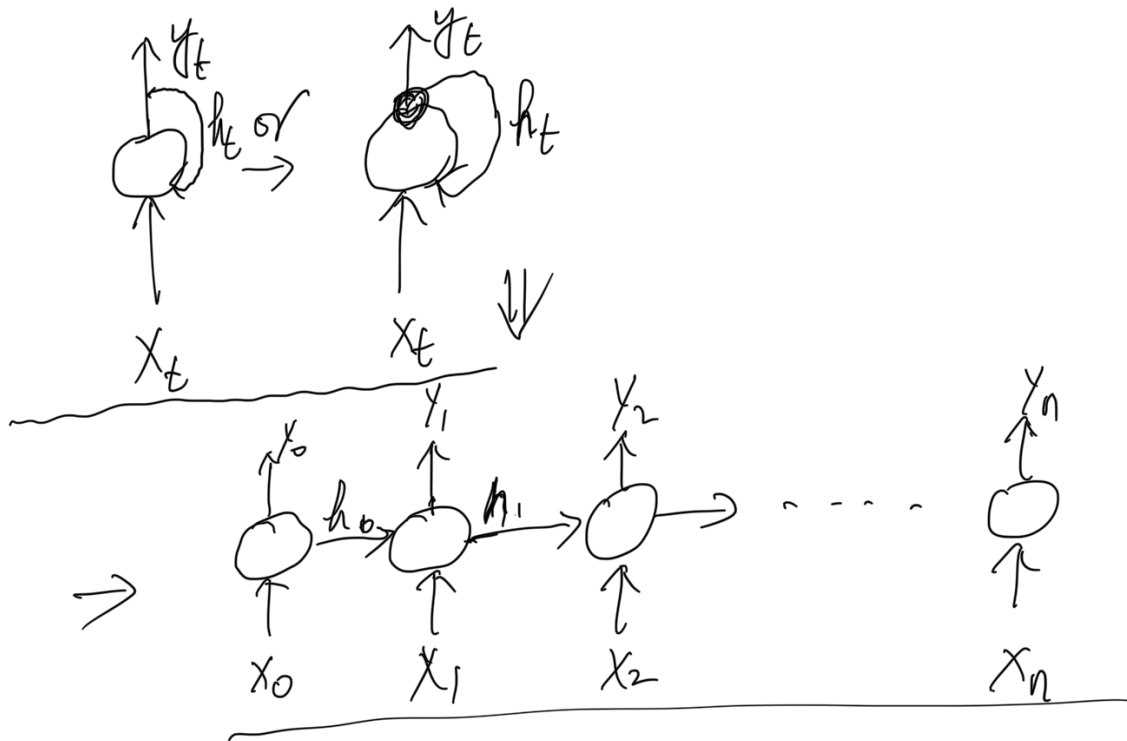


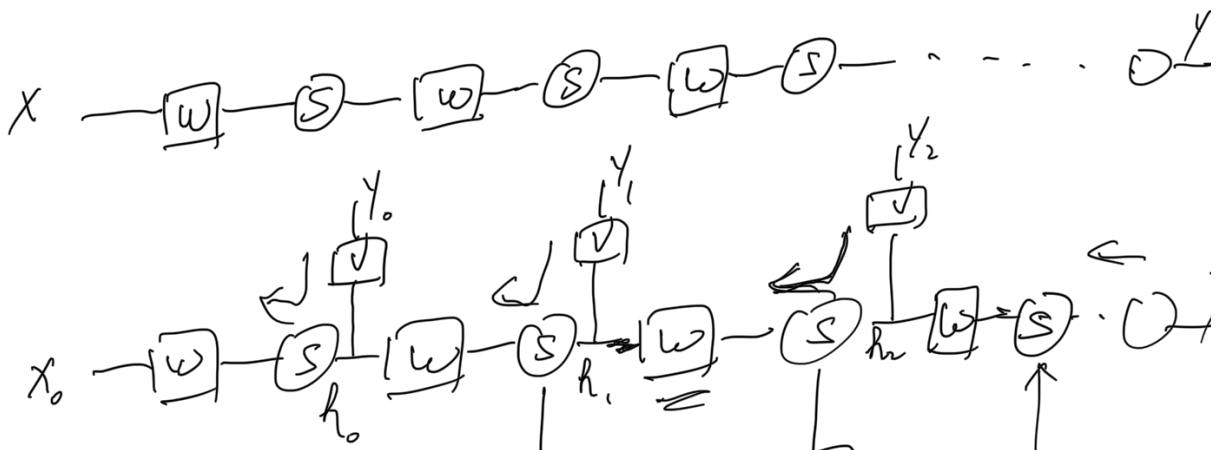
Lecture 7

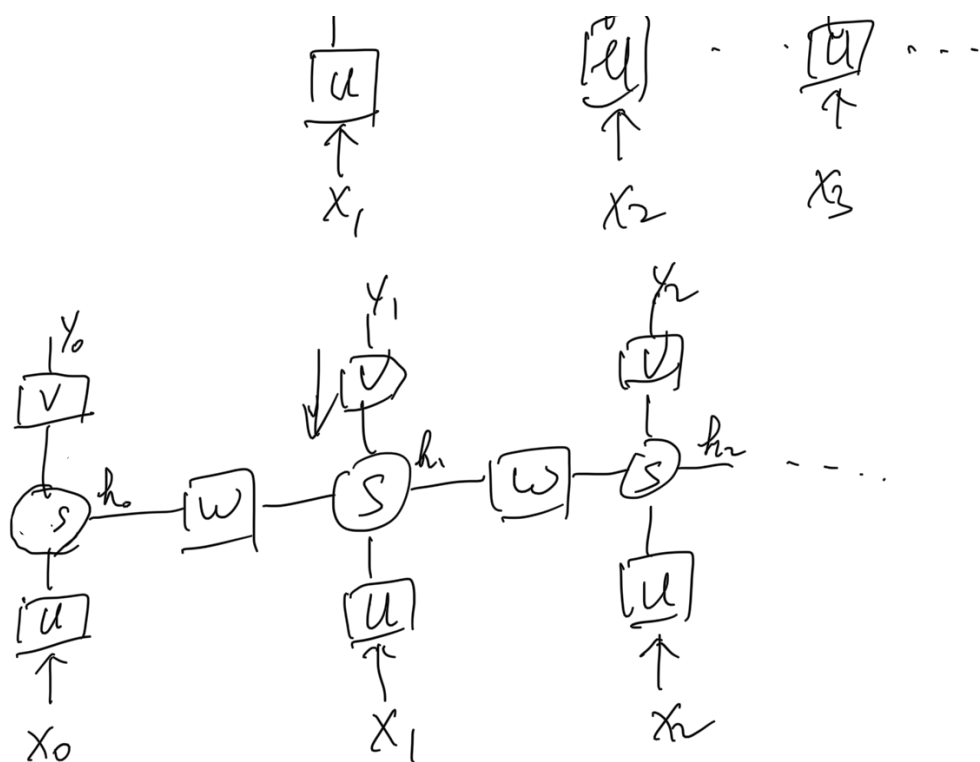


$$h_t = f(x_t, h_{t-1}) \quad h_1 = f(x_1, h_0)$$

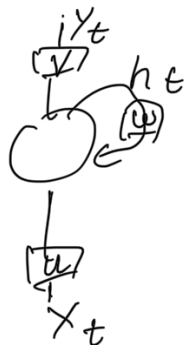
$$\underline{y_t} = \underline{g(x_t, h_t)}$$

$$= g(\underline{v}, h_t)$$





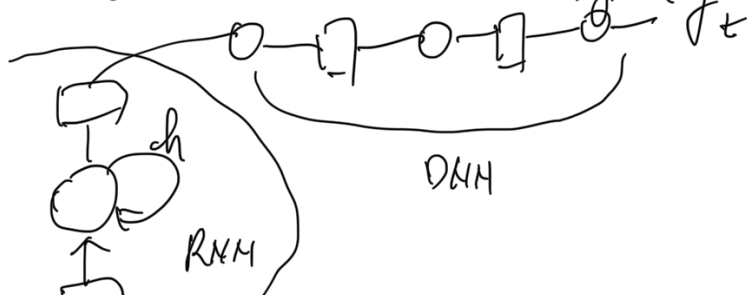
w, u, v



$$h_t = \tanh(w h_{t-1} + u x_t + b_h)$$

$$y_t = \text{softmax}(\underline{v h} + b_y)$$

or softmax
sigmoid y_t



$$\begin{array}{c}
 \begin{array}{c} | \\ \hline \uparrow \\ X \end{array} \\
 1 : (y'_0, \dots, y'_n) \text{ vs } (\hat{y}'_0, \dots, \hat{y}'_n) \\
 \vdots \\
 m : (y^m_0, \dots, y^m_n) \text{ vs } (\hat{y}^m_0, \dots, \hat{y}^m_n)
 \end{array}$$

$$L = \left(\sum_{j=1}^m \right) \frac{\sum_{i=1}^n L(y^j_i, \hat{y}^j_i)}{m}$$

$$\frac{\partial L}{\partial v} = \frac{\partial L}{\partial y} \frac{\partial y}{\partial o} \frac{\partial o}{\partial v}$$

$$\frac{\partial L}{\partial w} = \frac{\sum_{i=1}^n \frac{\partial L(y^j_i, \hat{y}^j_i)}{\partial w}}{m}$$

$$= \sum_{i=1}^n \frac{\partial L(y^j_i, \hat{y}^j_i)}{\partial w}$$

$$\frac{\partial L(y^j_i, \hat{y}^j_i)}{\partial w} = \frac{\partial L}{\partial y_i} \frac{\partial y_i}{\partial \underline{h_i}} \frac{\partial h_i}{\partial w}$$

$$\frac{\partial h_i}{\partial w} = \frac{\partial h_{i-1}}{\partial w} \dots \frac{\partial h_2}{\partial w}$$

$$\overline{\partial h_{i-1}} \quad \overline{\partial h_{i-2}} \quad \dots \quad \overline{\partial h_1}$$

if all of $\frac{\partial h_i}{\partial h_{i-1}} < 1$, ≈ 0 , vanishing

if all of $\frac{\partial h_i}{\partial h_{i-1}} > 1$, $\approx \infty$, Exploding

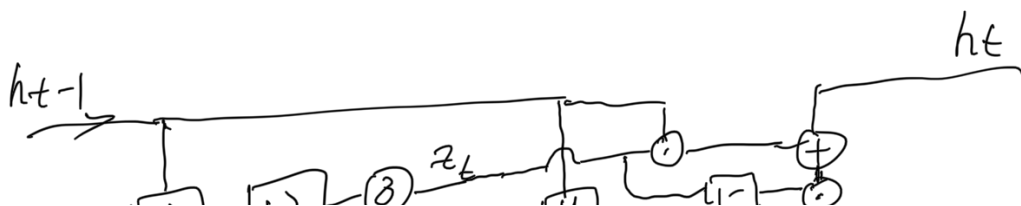
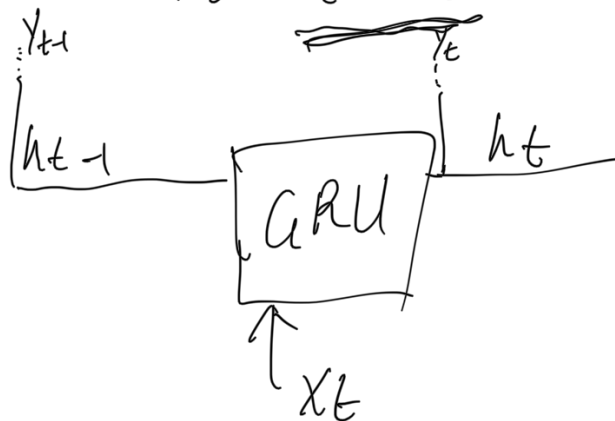
GRU.

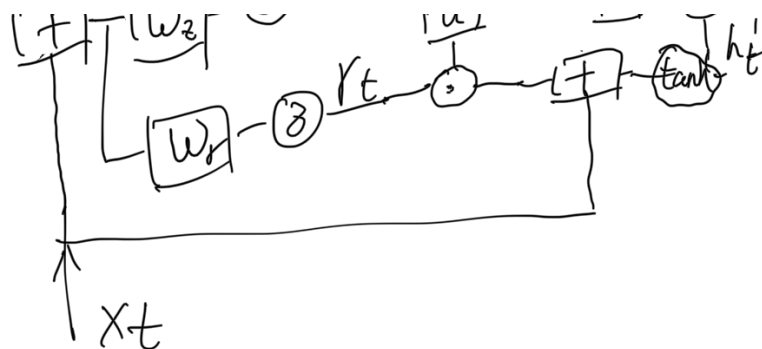
update gate $z_t = \sigma(w_z x_t + u_z h_{t-1} + b_z) \leftarrow \frac{1867}{1867}$

reset gate $r_t = \sigma(w_r x_t + u_r h_{t-1} + b_r) \leftarrow$

$$h'_t = \tanh(w_h x_t + r_t \odot u_h h_{t-1} + b_h) \leftarrow$$

$$h_t = z_t \odot h_{t-1} + (1 - z_t) \odot h'_t$$





$$\boxed{+} - \begin{bmatrix} \overline{} & \overline{} \\ \uparrow & \uparrow \\ x_t & h_{t-1} \end{bmatrix}$$

$$\begin{bmatrix} w & u \end{bmatrix} \begin{bmatrix} h_{t-1} \\ x_t \end{bmatrix}$$

