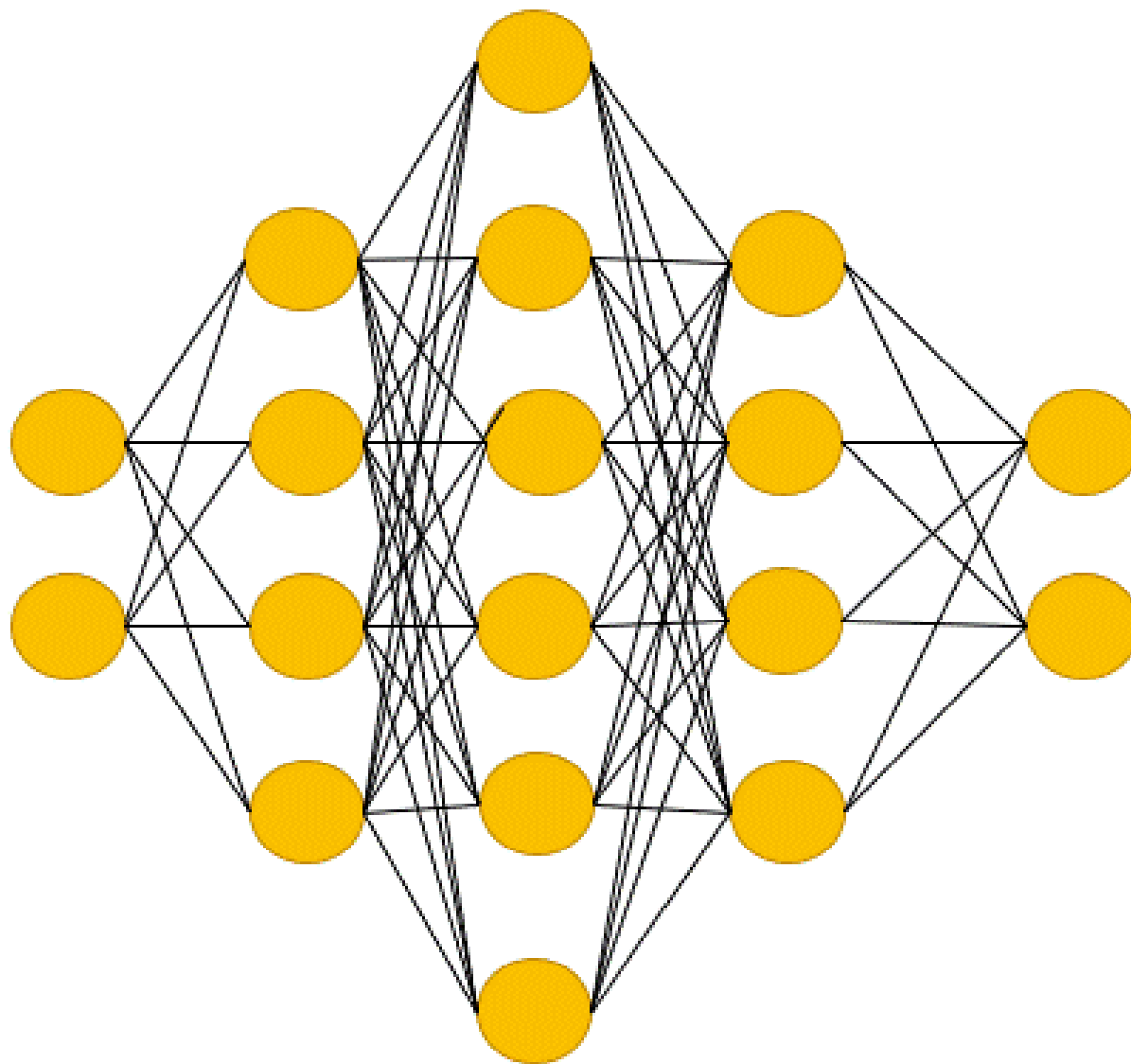




Let me ask,
Gru



What is the Price
of the Jet, Bob?
It must be 50K

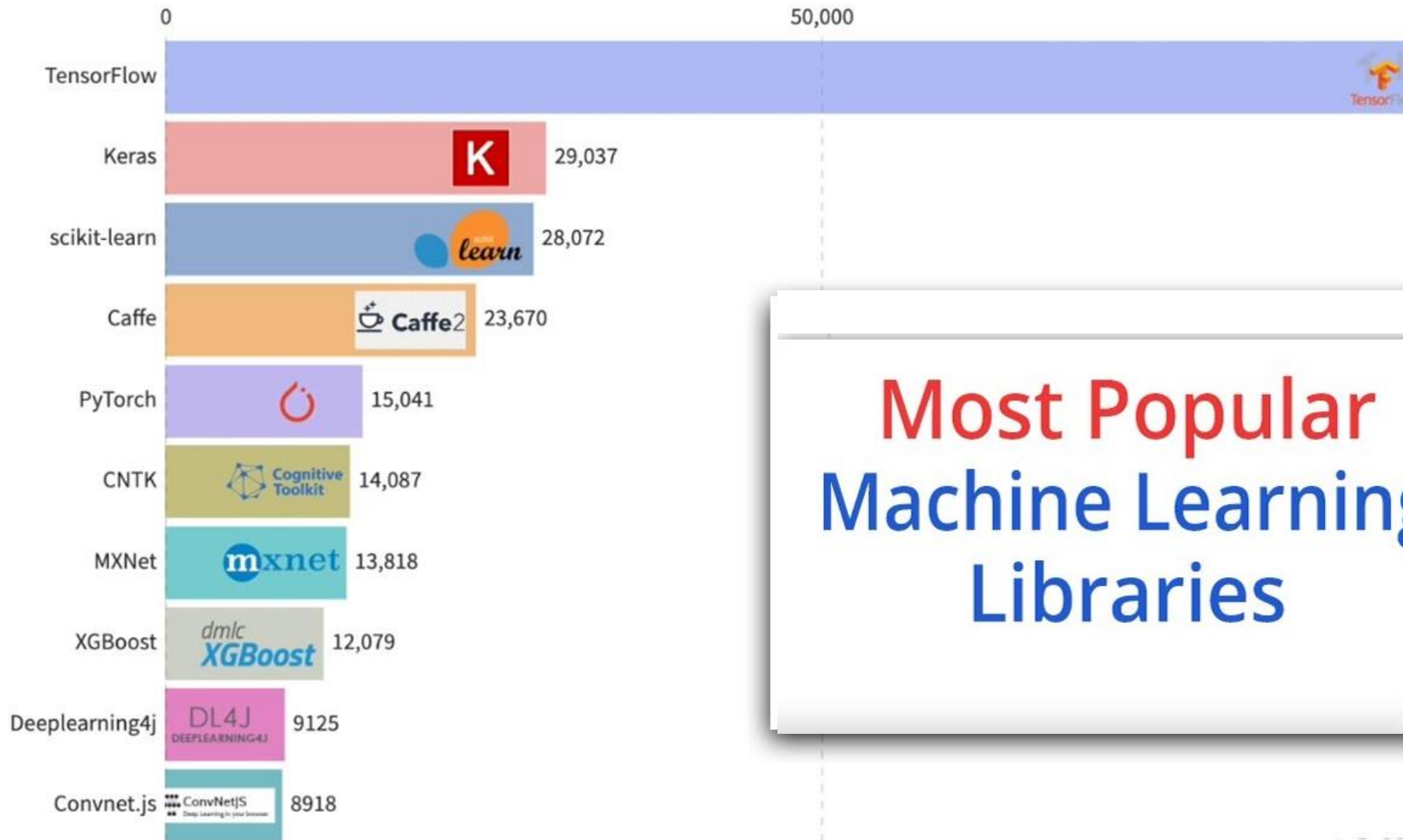


MOST POPULAR DEEP LEARNING LIBRARIES&PLATFORMS





DEEP LEARNING KÜTÜPHANELERİ



**Most Popular
Machine Learning
Libraries**



DEEP LEARNING KÜTÜPHANELERİ

Keras



Keras is an open source **neural network** library written in **Python**. It is capable of running on top of TensorFlow. It is designed to enable fast experimentation with **deep neural networks**.

TensorFlow



TensorFlow is an open-source software library for dataflow programming across a range of tasks. It is a symbolic math library that is used for **machine learning** applications like neural networks.

PyTorch



PyTorch is an open source **machine learning** library for Python, based on Torch. It is used for applications such as **natural language processing** and was developed by Facebook's AI research group.

 **Theano**




Caffe2

Caffe is a deep learning framework, originally developed at University of California, Berkeley. It is open source, under a BSD license. It is written in C++, with a Python interface.



DEEP LEARNING KÜTÜPHANELERİ

	Languages	Tutorials and training materials	CNN modeling capability	RNN modeling capability	Architecture: easy-to-use and modular front end	Speed	Multiple GPU support	Keras compatible
Theano	Python, C++	++	++	++	+	++	+	+
TensorFlow	Python	+++	+++	++	+++	++	++	+
Torch	Lua, Python (new)	+	+++	++	++	+++	++	
Caffe	C++	+	++		+	+	+	
MXNet	R, Python, Julia, Scala	++	++	+	++	++	+++	
Neon	Python	+	++	+	+	++	+	
CNTK	C++	+	+	+++	+	++	+	



EPOCH, BATCHSIZE

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THE KITCHEN

KITCHEN



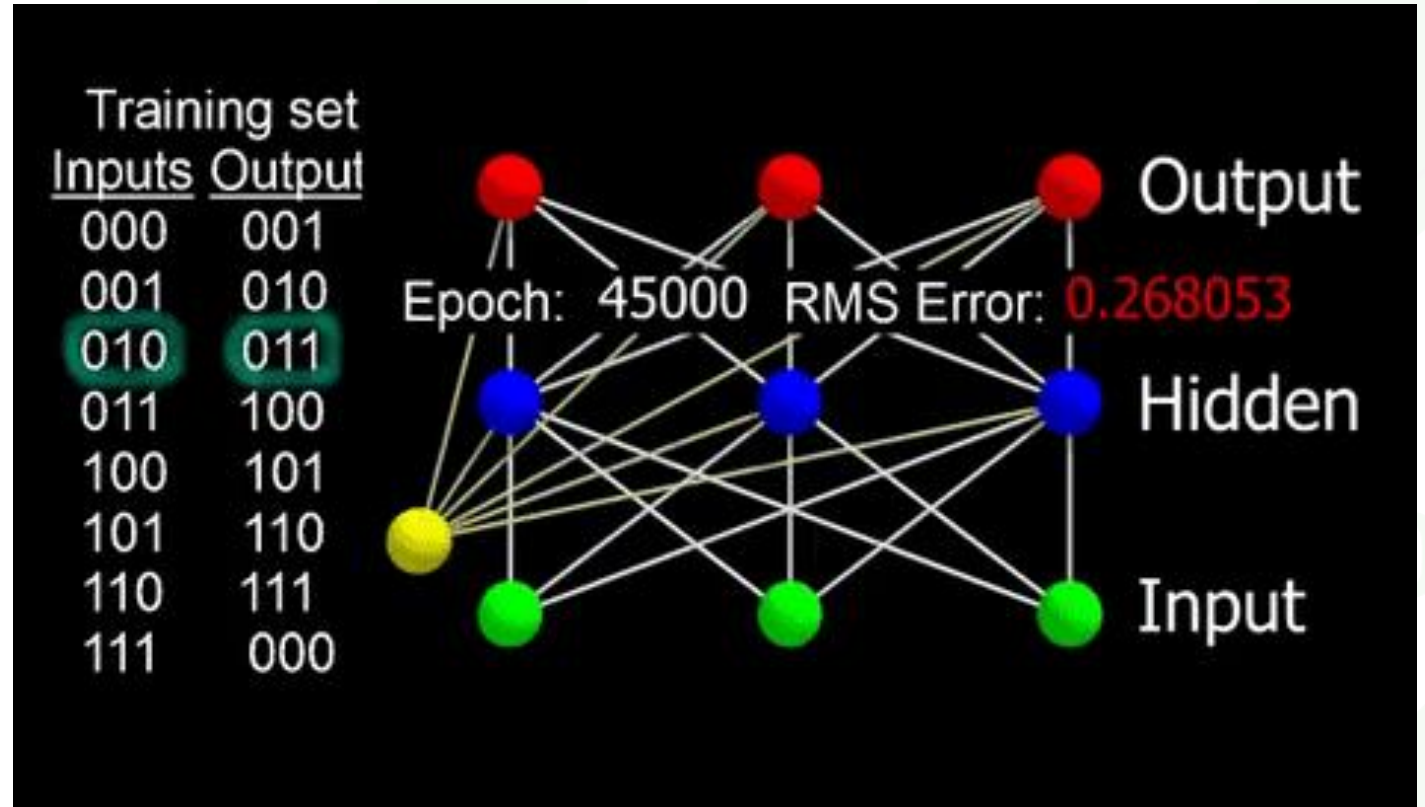




EPOCH

EPOCH

An **epoch** is a term used in [machine learning](#) and indicates the number of passes of the entire [training dataset](#) the machine learning algorithm has completed. Datasets are usually grouped into batches (especially when the amount of data is very large).

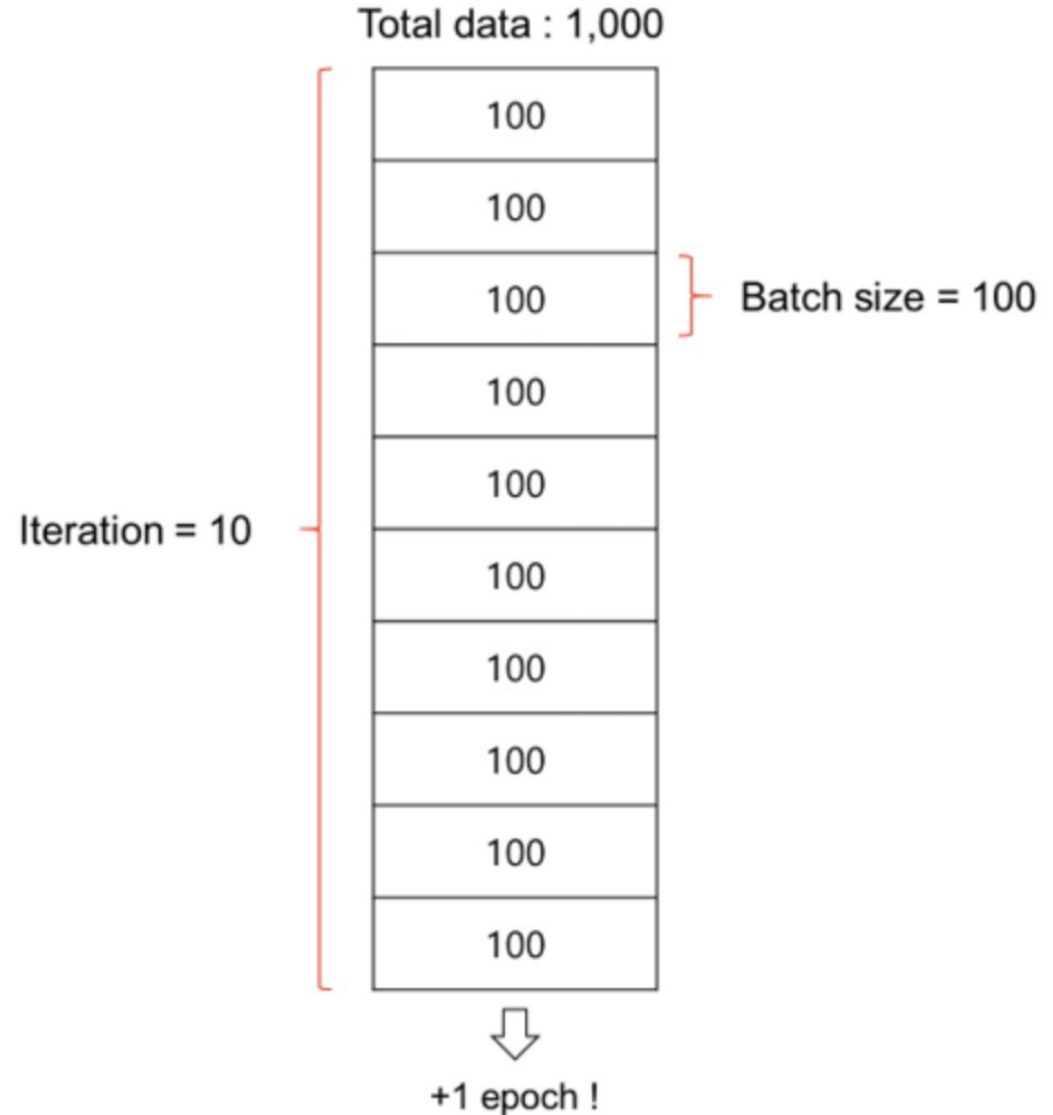




BATCHSIZE

BATCHSIZE

Batch size is a term used in machine learning and refers to **the number of training examples utilized in one iteration.**





DIFFERENCE BETWEEN BATCH AND EPOCH

Example: if you have 1000 training examples, and your batch size is 500, then it will take 2 iterations to complete 1 epoch.

Training examples = 1000



Batch size = 500

500
500

Batch 1

Batch 2



2
Iterations

Activate Windows
Go to Settings to activate Windows.



EPOCH

EPOCH

```
model.fit(x=X_train,y=y_train.values,  
          validation_data=(X_test,y_test.values),  
          batch_size=128,epochs=400)
```

Epoch

One epoch means, the entire dataset is passed forward and backward through the neural network once.



EPOCH

```
model.fit(x = X_train, y = y_train, batch_size = 32, epochs = 300)
```

```
Epoch 1/300  
22/22 [=====] - 4s 2ms/step - loss: 256629.3281  
Epoch 2/300  
22/22 [=====] - 0s 2ms/step - loss: 256489.2812  
Epoch 3/300  
22/22 [=====] - 0s 3ms/step - loss: 256325.5469
```



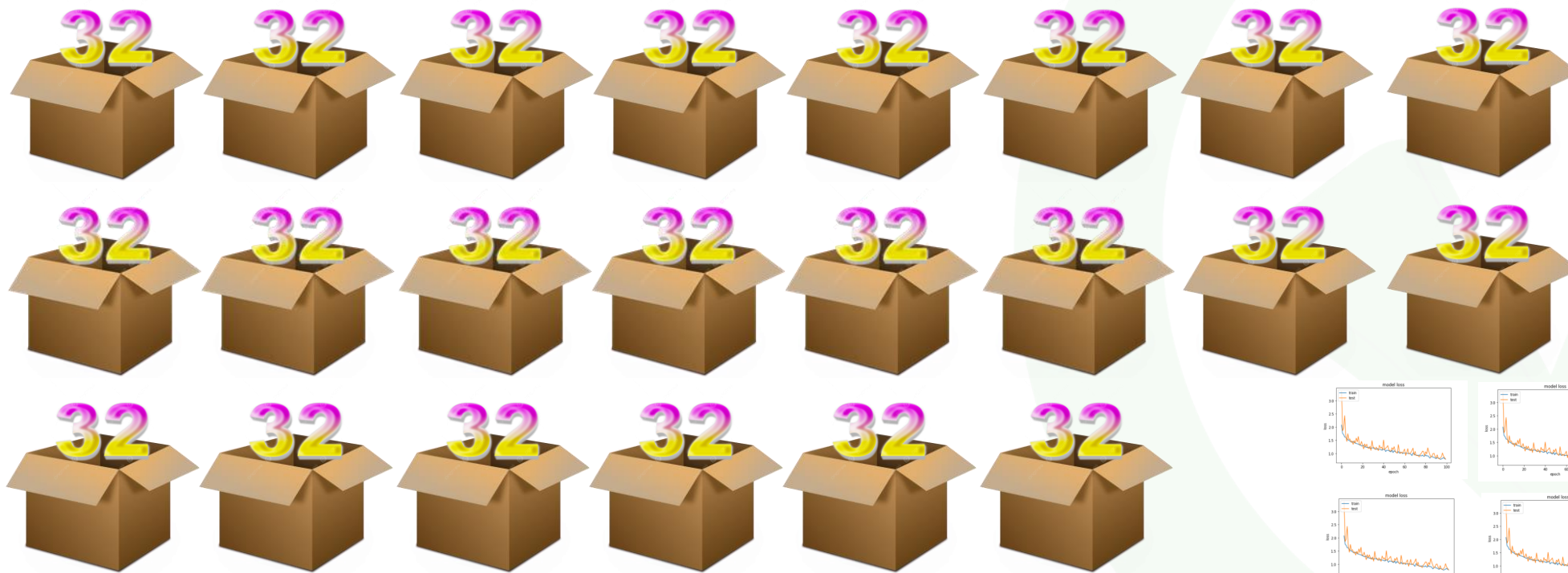
700 (TRAIN DATASI) / **32** (BATCH SIZE) = **22**

700 ÷ 32 =

21,875



$$700 \text{ (TRAIN DATASI)} / 32 \text{ (BATCH SIZE)} = 22$$

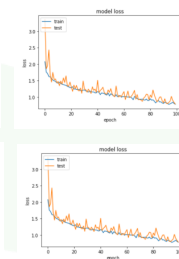
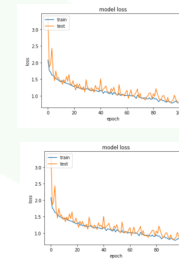
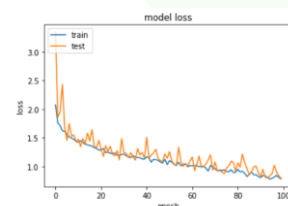
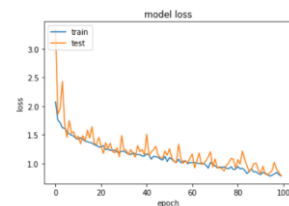
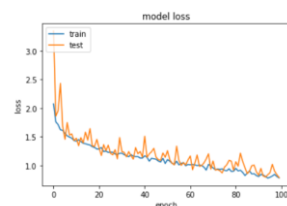
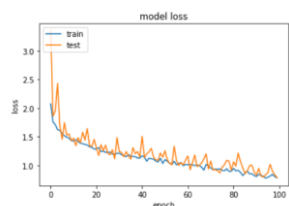
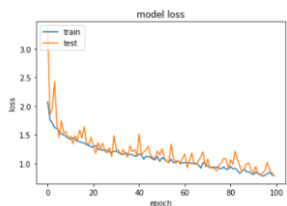


1

EPOCH

22

iteration

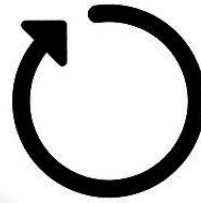




DIFFERENCE BETWEEN BATCH AND EPOCH

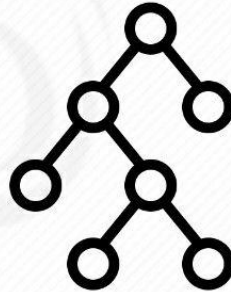
Epoch :

An Epoch represent one iteration over the entire dataset.



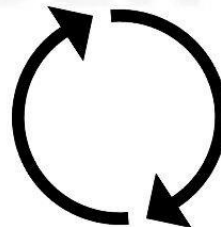
Batch :

We cannot pass the entire dataset into the Neural Network at once. So, we divide the dataset into number of batches.

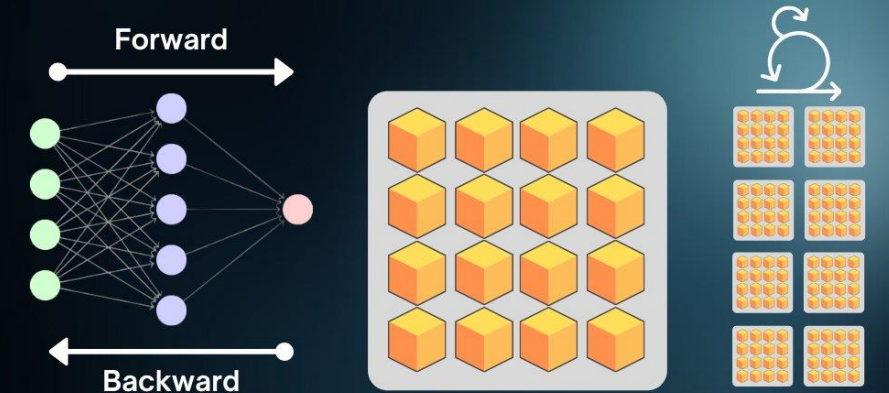


Iteration :

If we have 1000 images as Data and a batch size of 20, then an Epoch should run $1000/20 = 50$ iteration.



ROBOFIED



Epoch vs Batch Size vs Iteration

One Epoch is when an ENTIRE dataset is passed forward and backward through the neural network only ONCE.

Total number of training examples present in a single batch. Importantly, Batch Size & Number of Batches are different things.

Iterations is the number of batches needed to complete one epoch i.e. number of training examples/batch size.



GRADIENT DESCENT



GRADIENT DESCENT

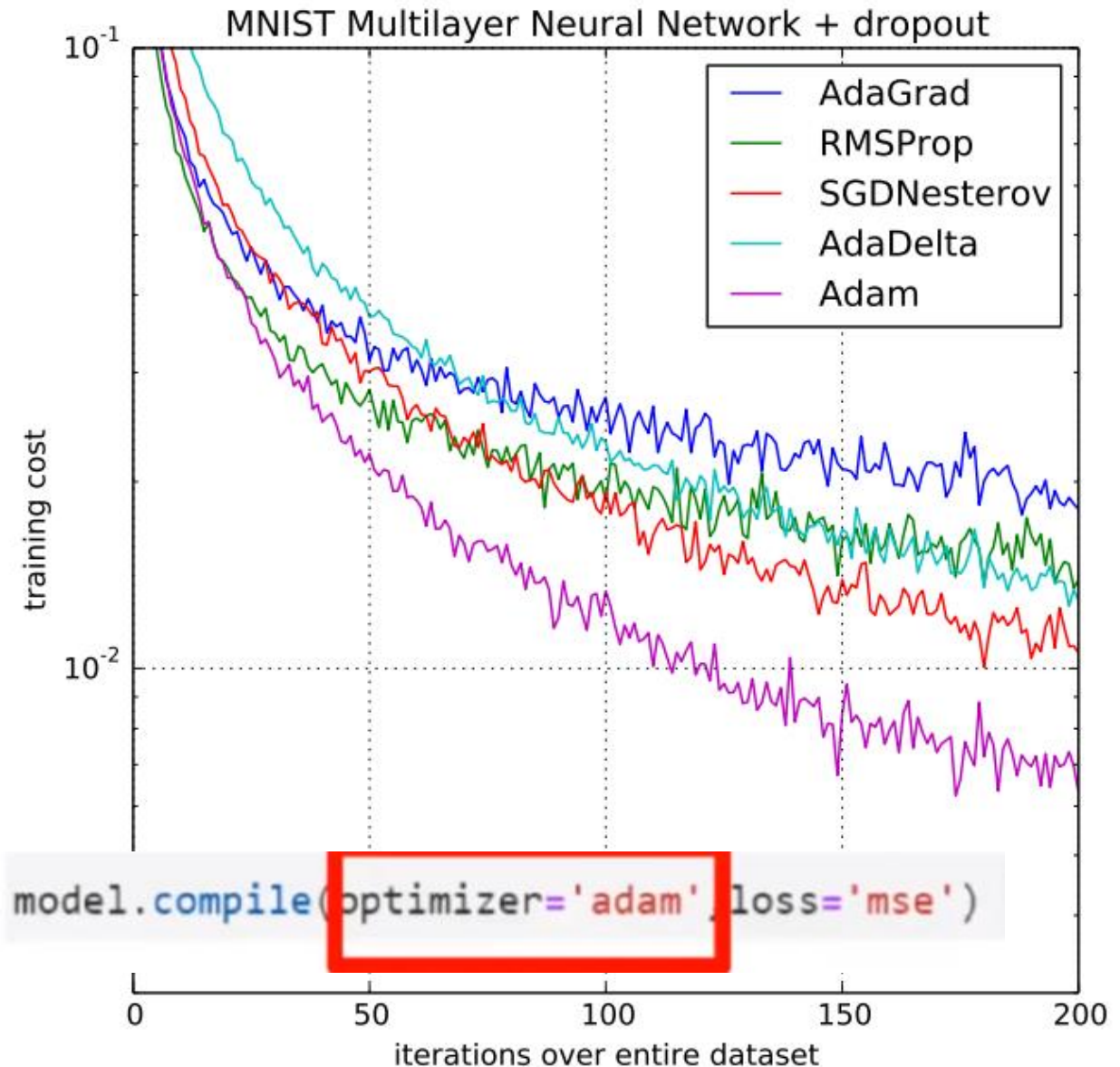




GRADIENT DESCENT

OPTIMIZER

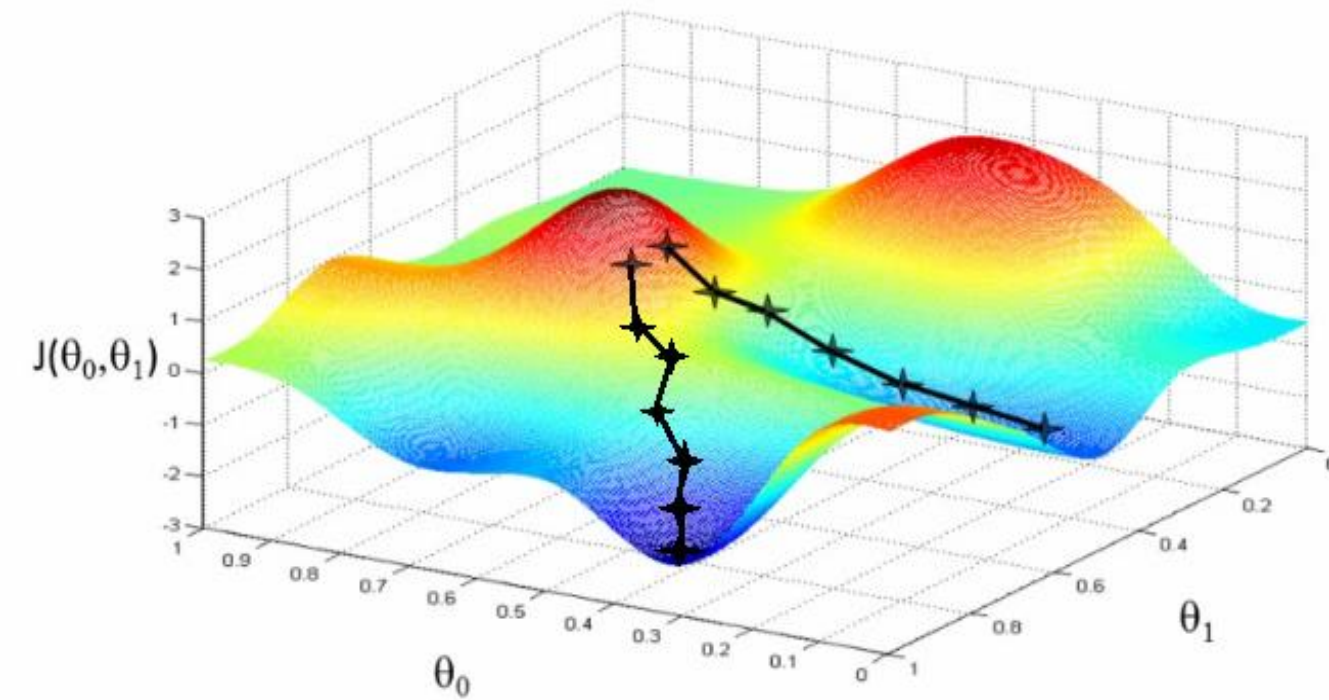
Gradient descent is an optimization algorithm that uses the gradient of the objective function to navigate the search space. Optimization is a mathematical discipline that determines the “best” solution in a quantitatively well-defined sense.





GRADIENT DESCENT

Gradient descent is the process of using gradients to find the minimum value of the cost function, while backpropagation is calculating those gradients by moving in a backward direction in the neural network.





GRADIENT DESCENT

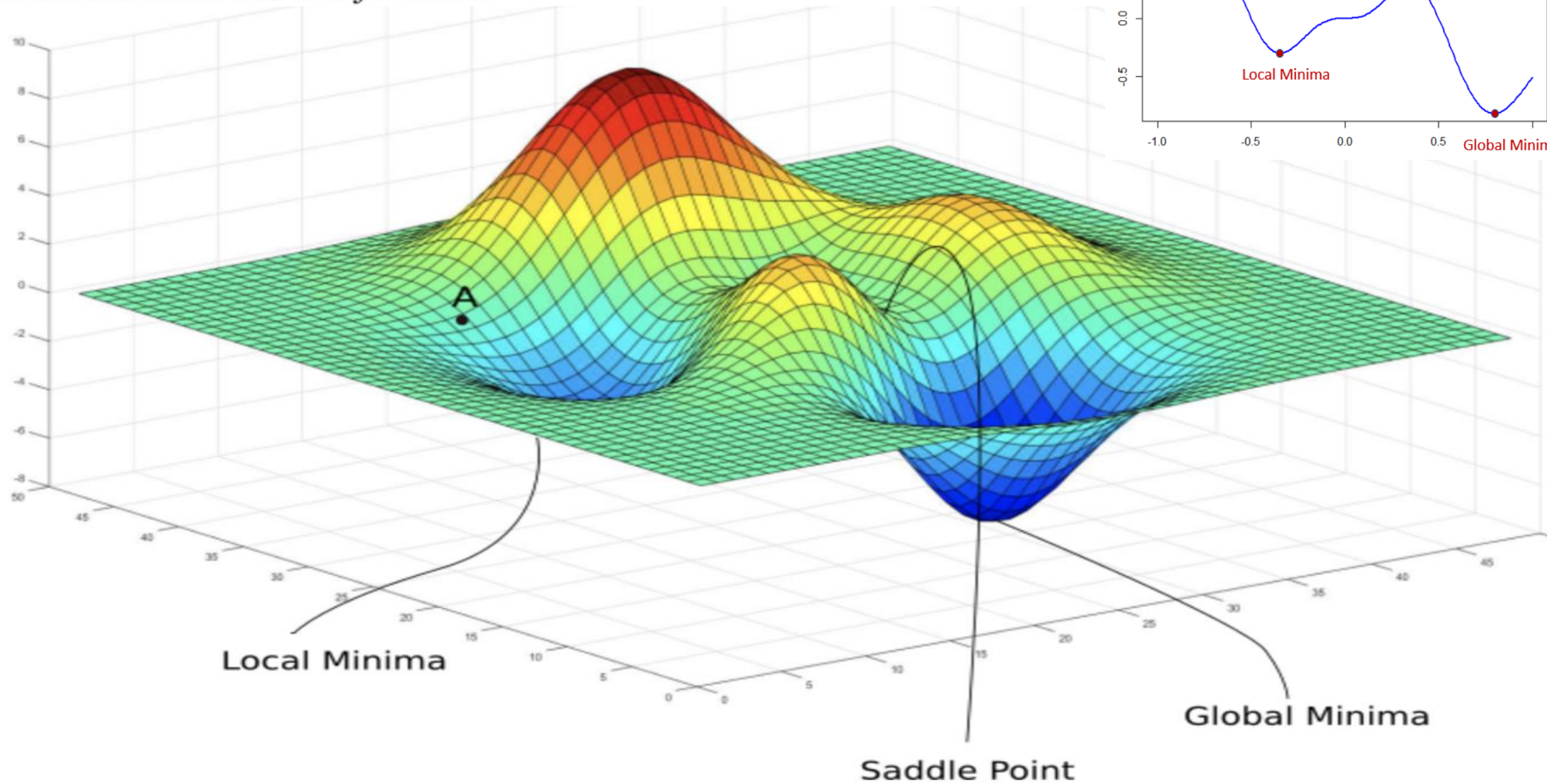


Leo Learns the Ropes

at Project Chimps

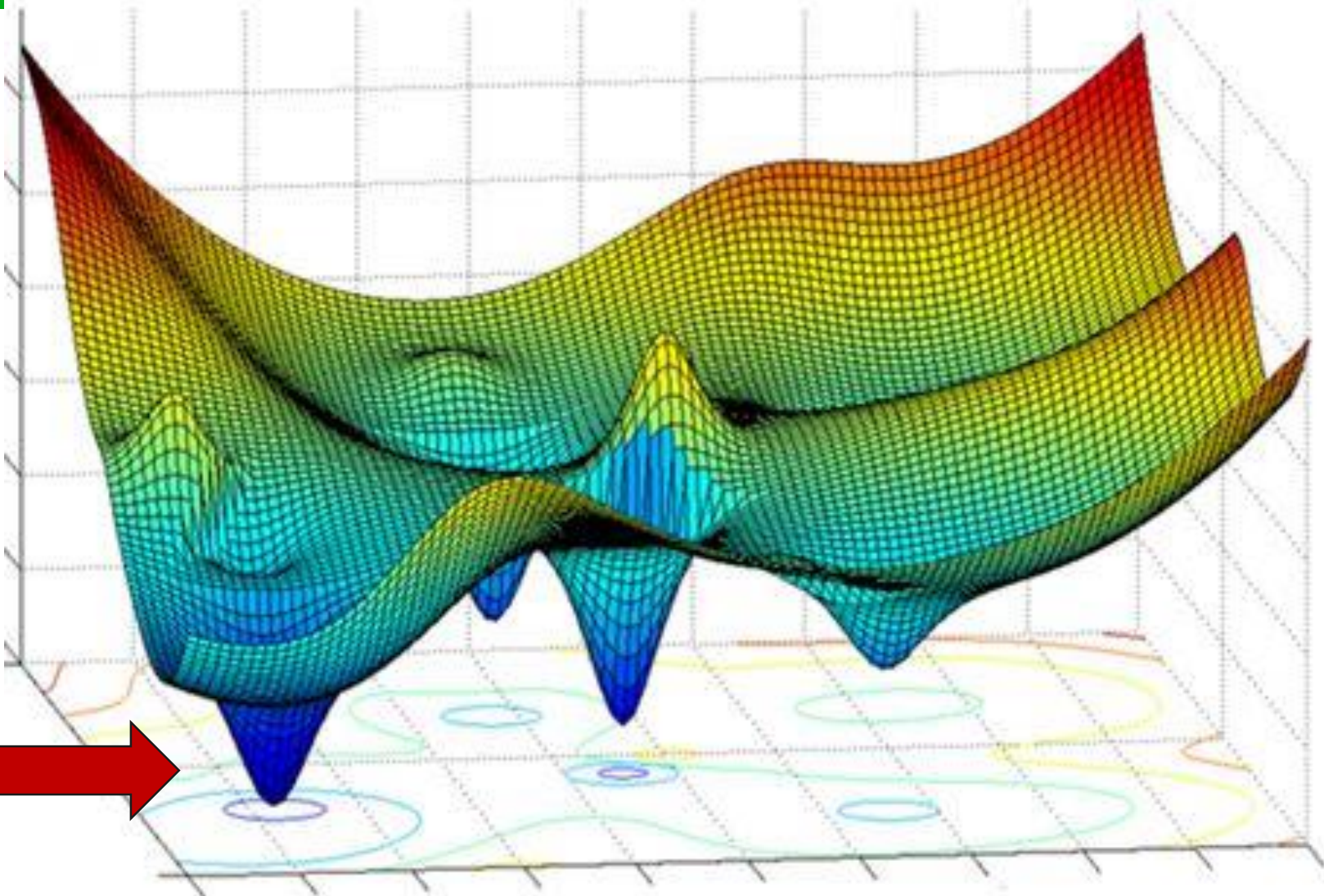


The objective of a ML model, is to find parameters, weights or a structure that **minimises** the cost function.

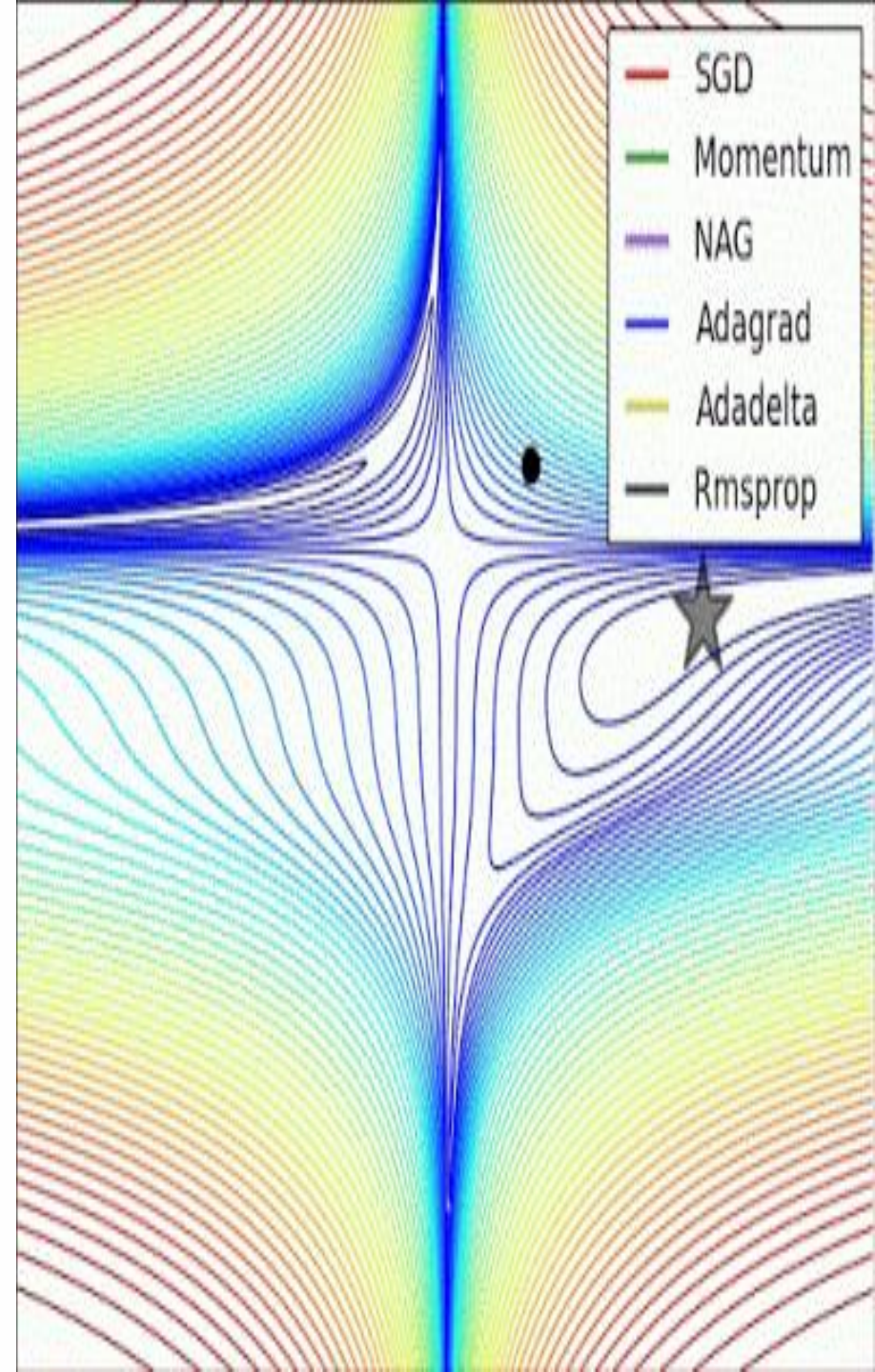
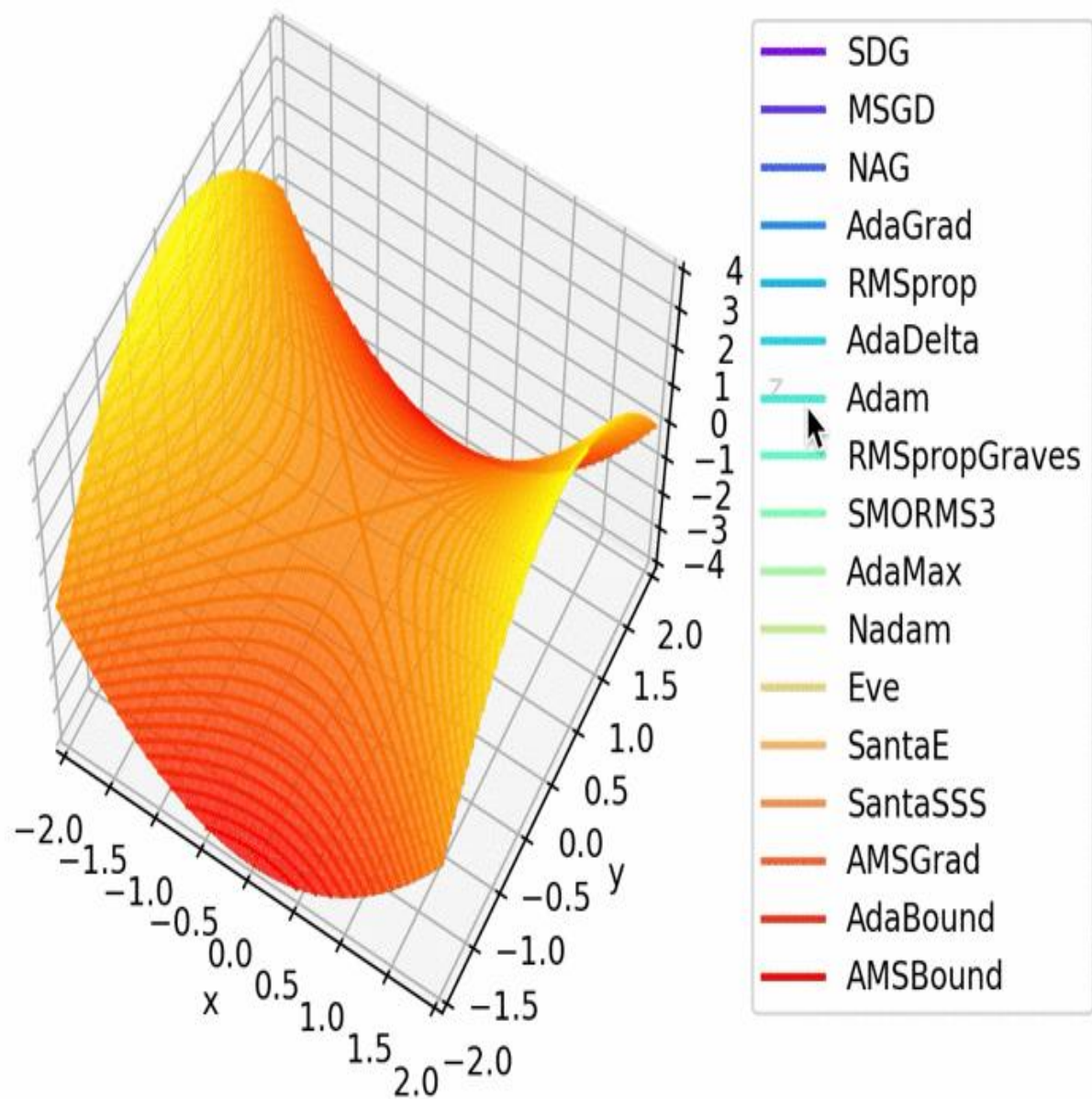




GRADIENT DESCENT

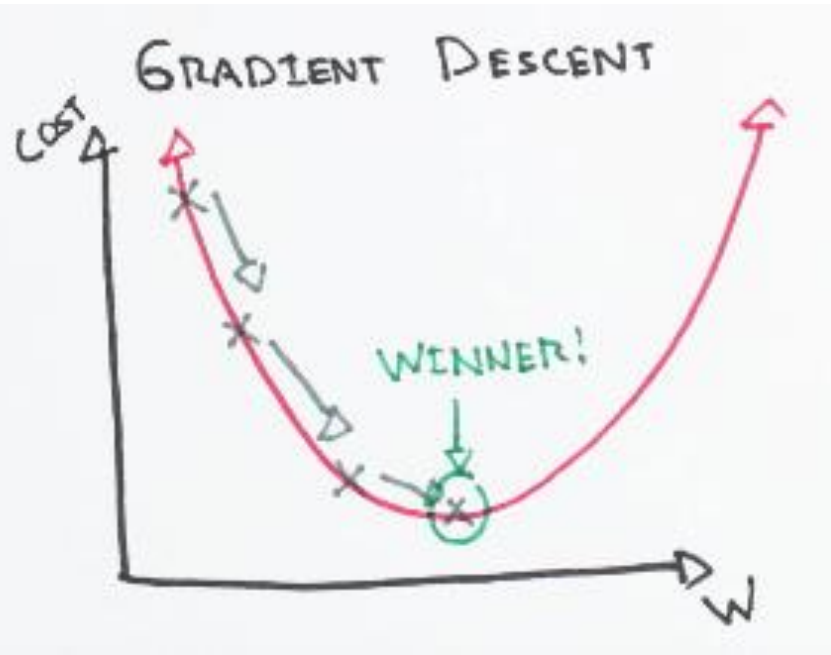


Optimizer comparison

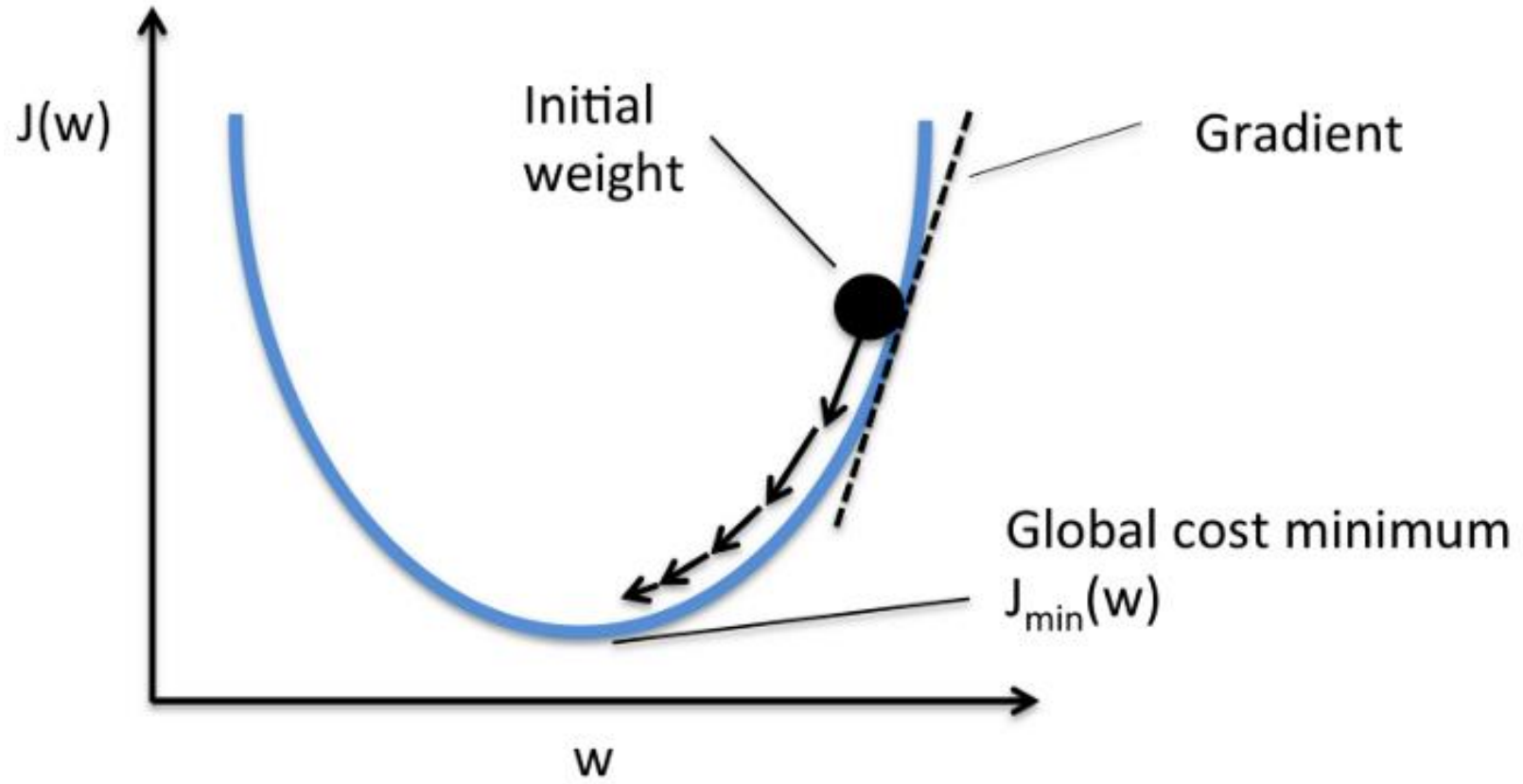




GRADIENT DESCENT



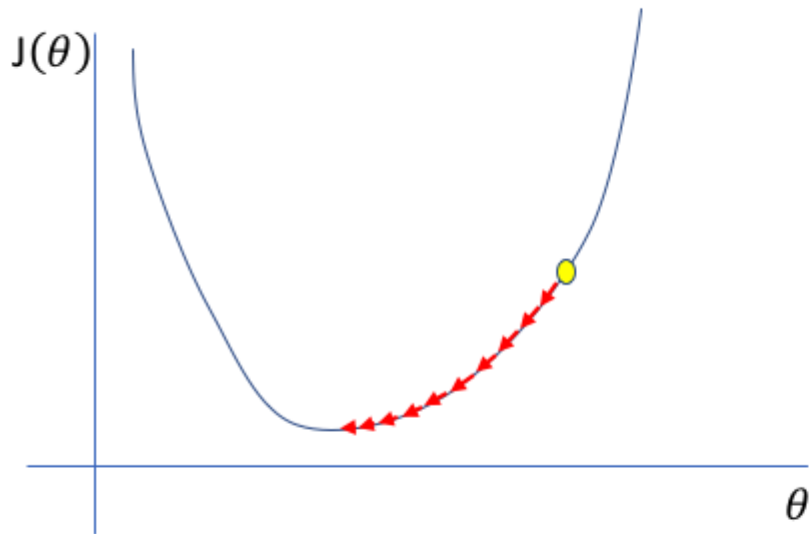
Step Size = slope x learning rate





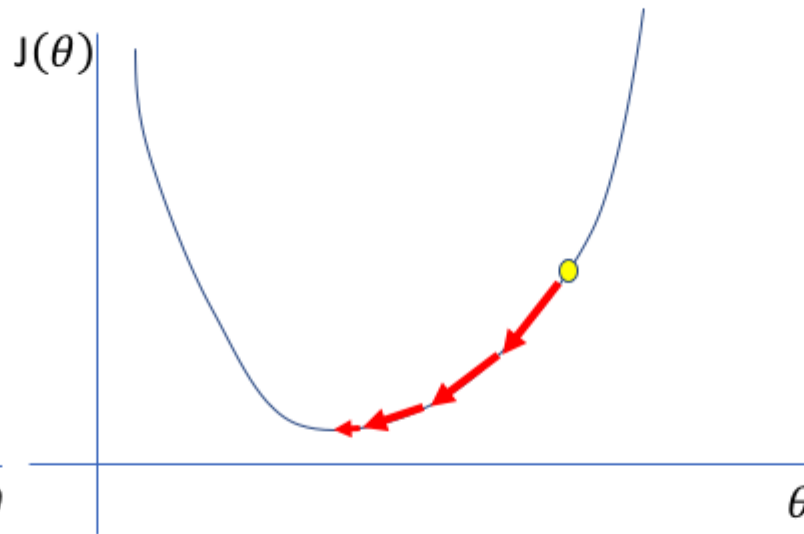
LEARNING RATE

Too low



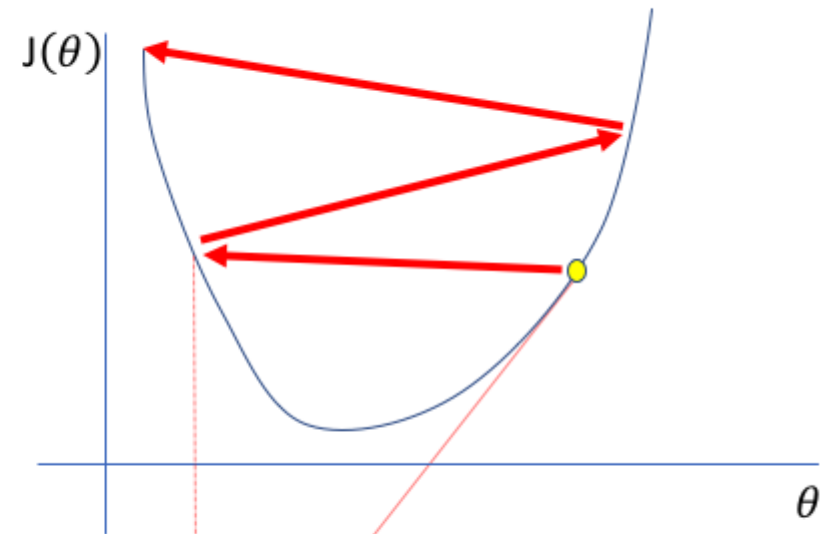
A small learning rate requires many updates before reaching the minimum point

Just right



The optimal learning rate swiftly reaches the minimum point

Too high

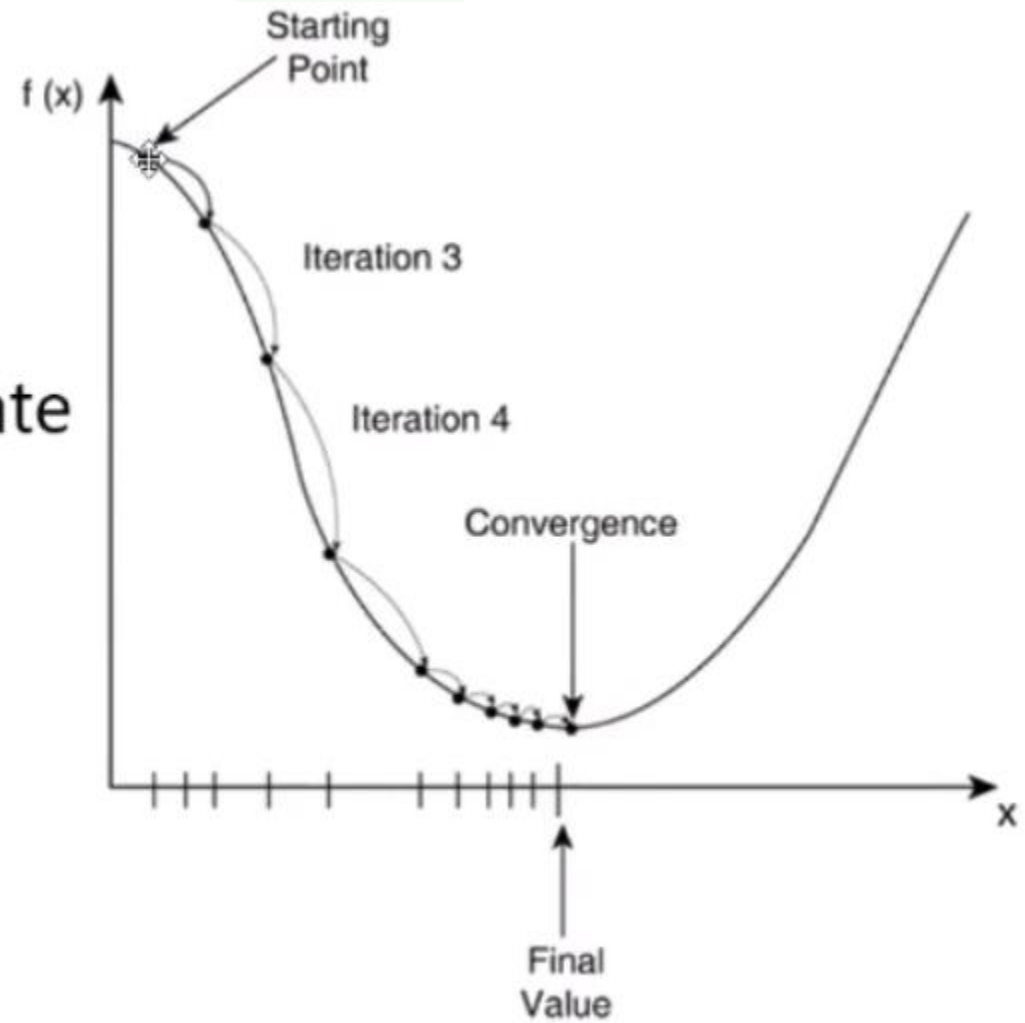


Too large of a learning rate causes drastic updates which lead to divergent behaviors



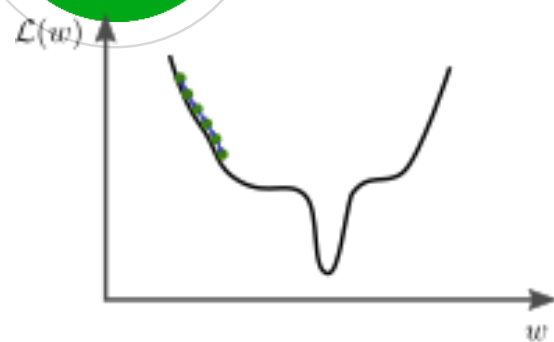
LEARNING RATE

Step Size = slope \times learning rate

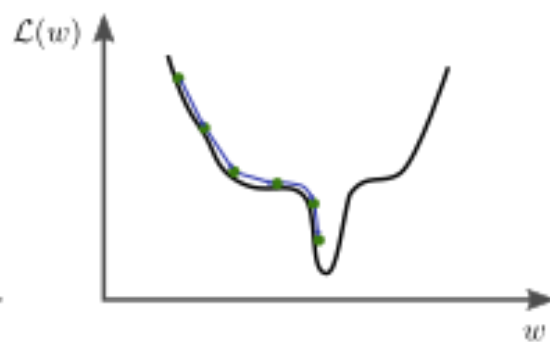




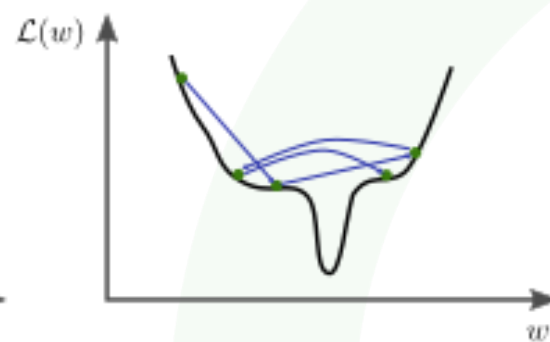
LEARNING RATE



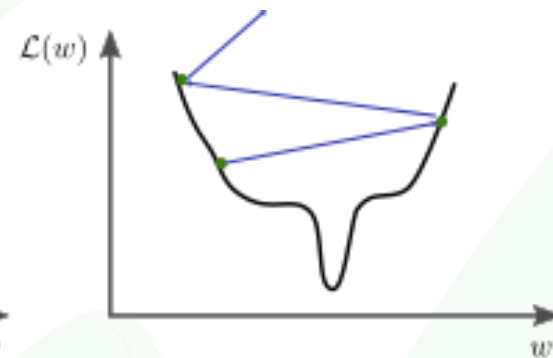
Learning rate too low



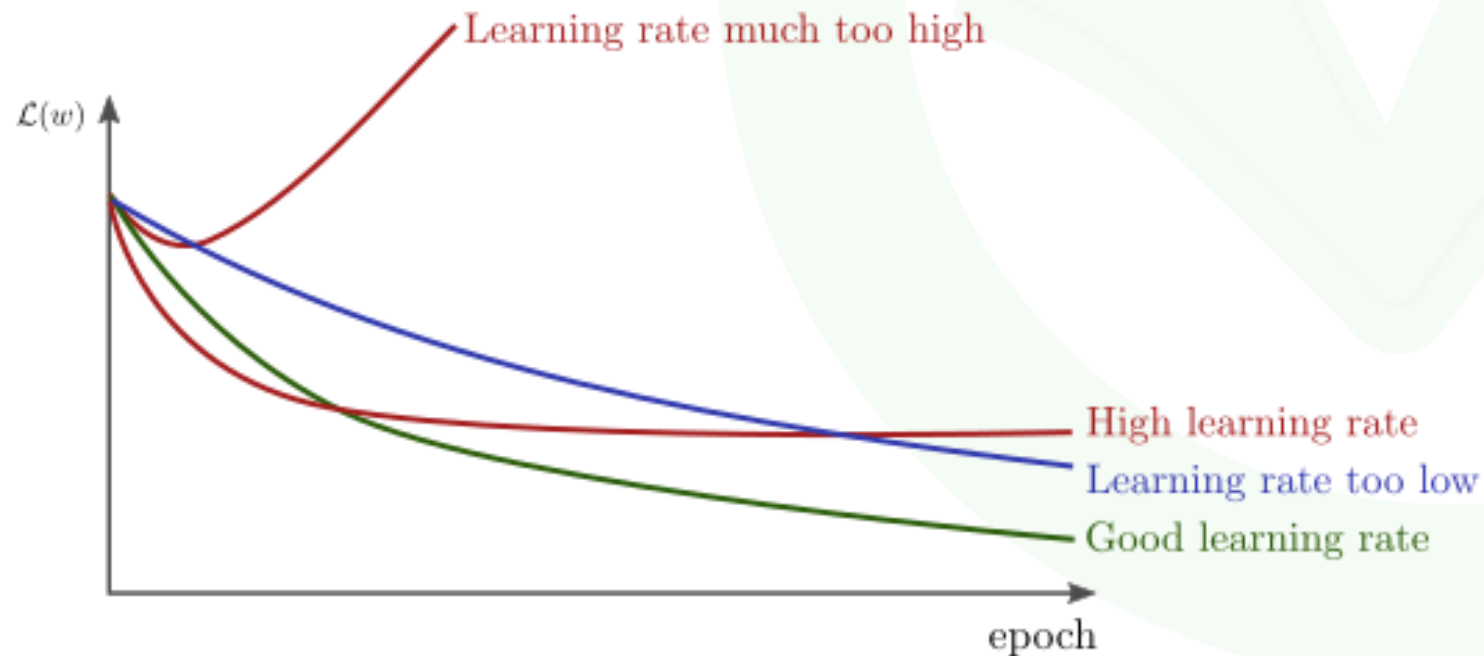
Good learning rate



High learning rate



Learning rate much too high





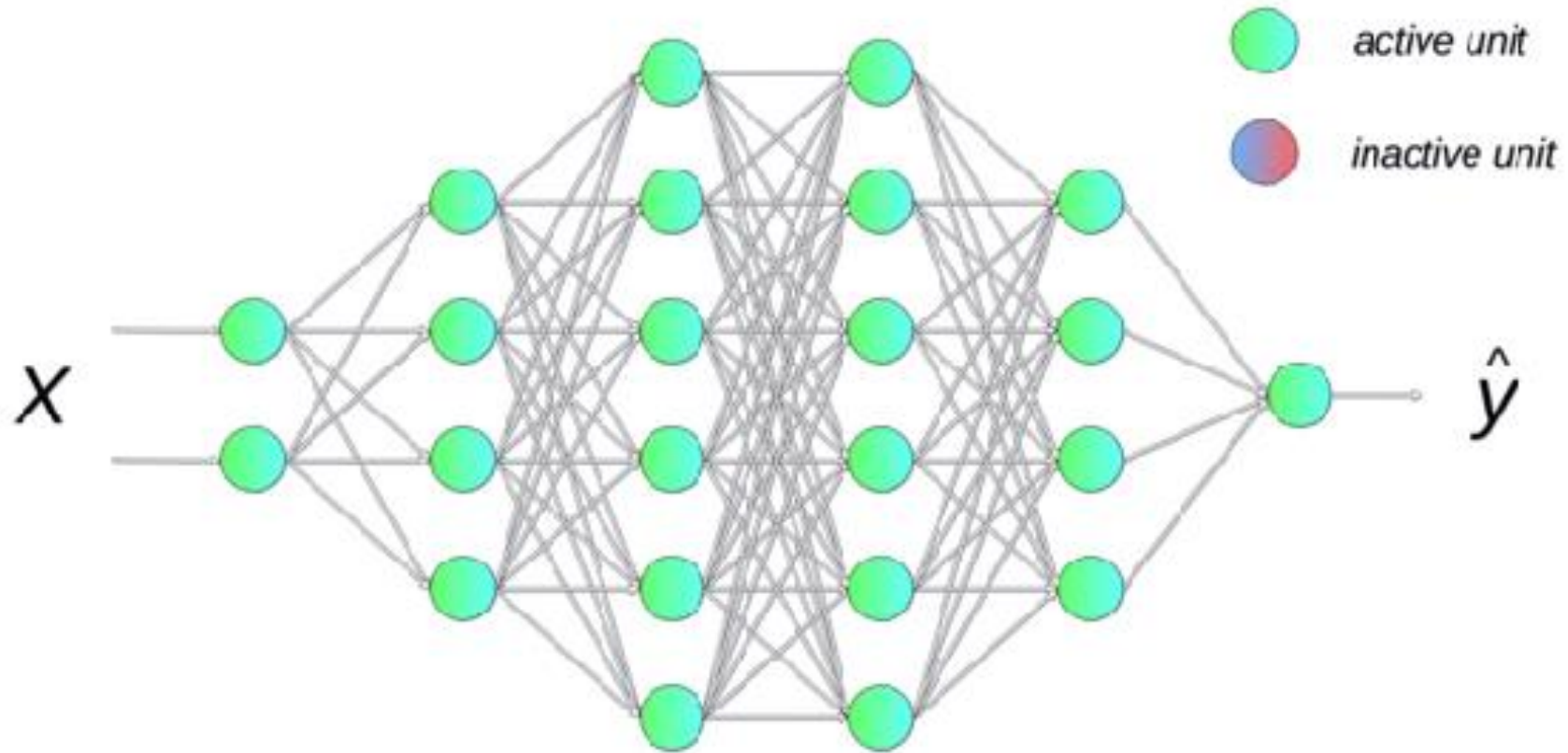
REGULARIZATION

DROPOUT
EARLYSTOPPING
BATCHNORMALIZATION

L1
L2



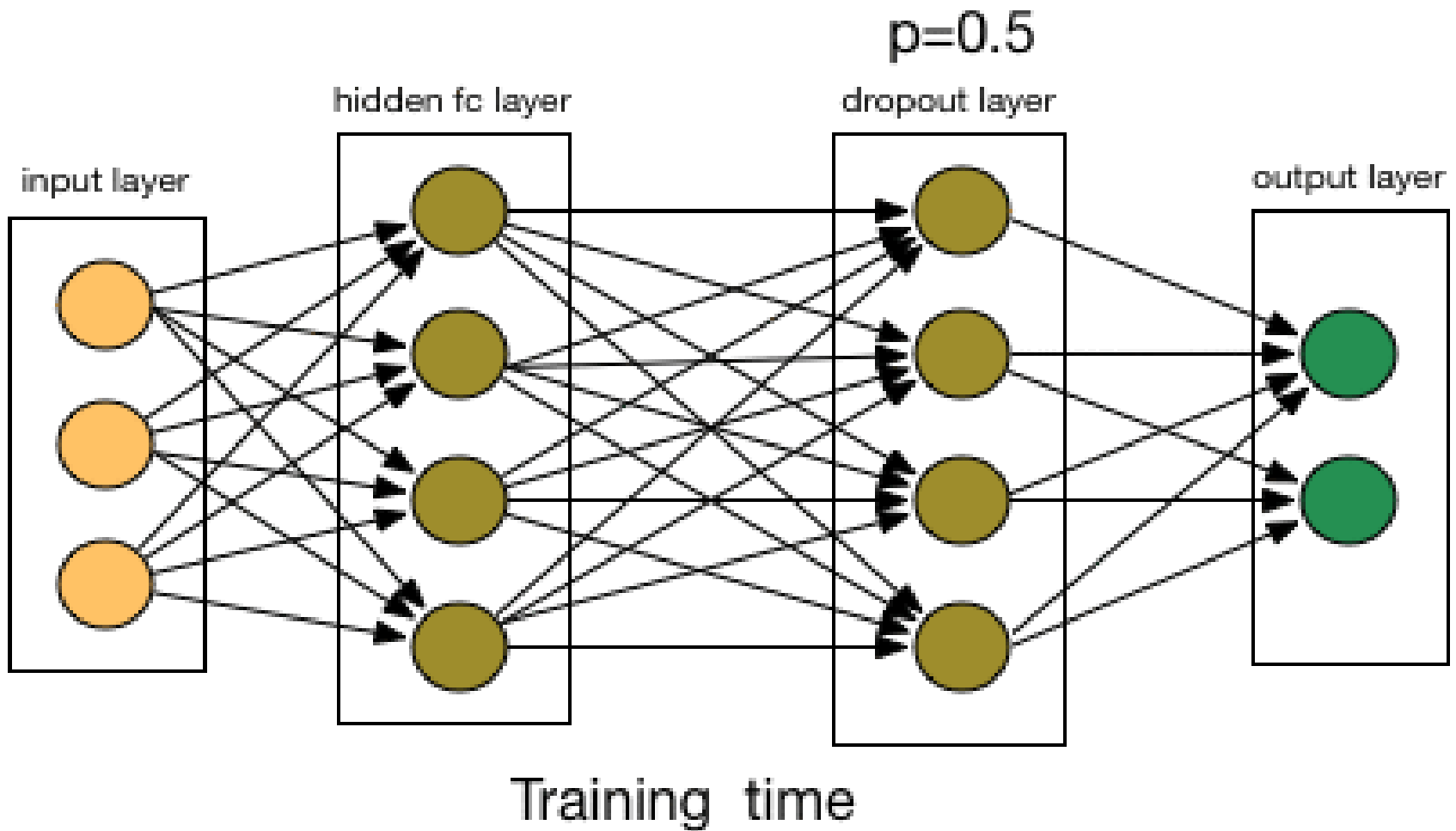
DROPOUT



$$p^{[0]} = 0.0 \quad p^{[1]} = 0.0 \quad p^{[2]} = 0.5 \quad p^{[3]} = 0.0 \quad p^{[4]} = 0.25$$

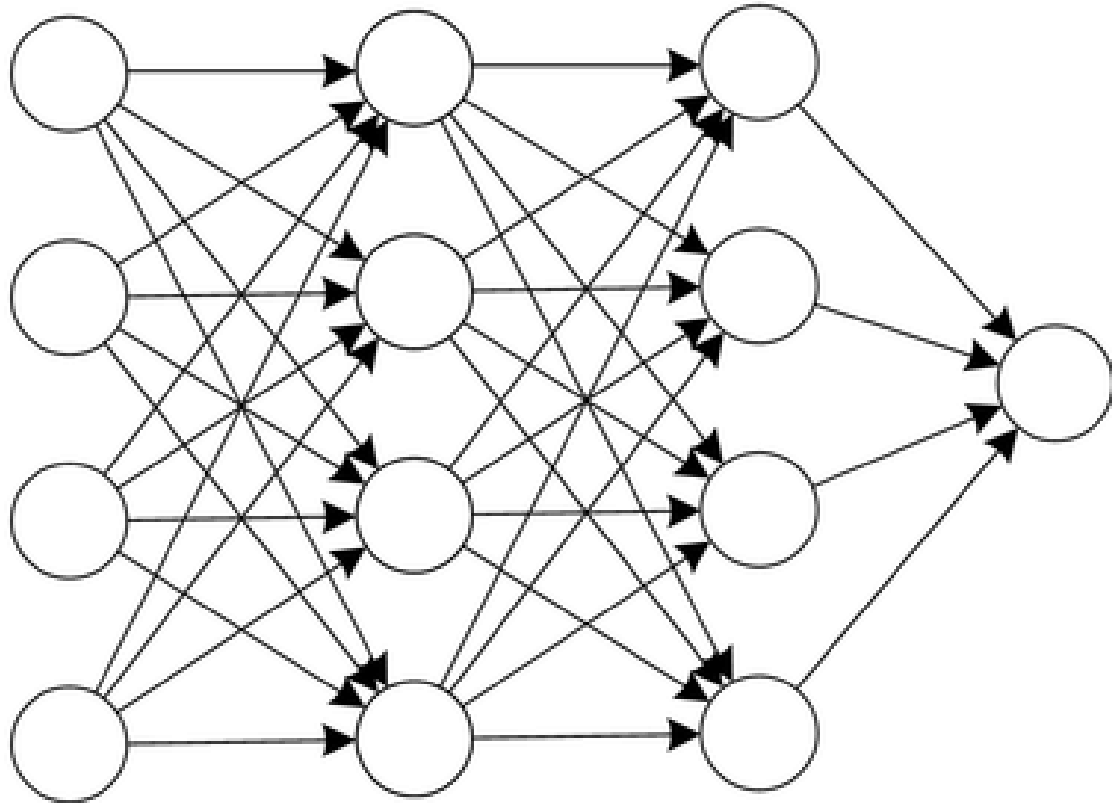


DROPOUT

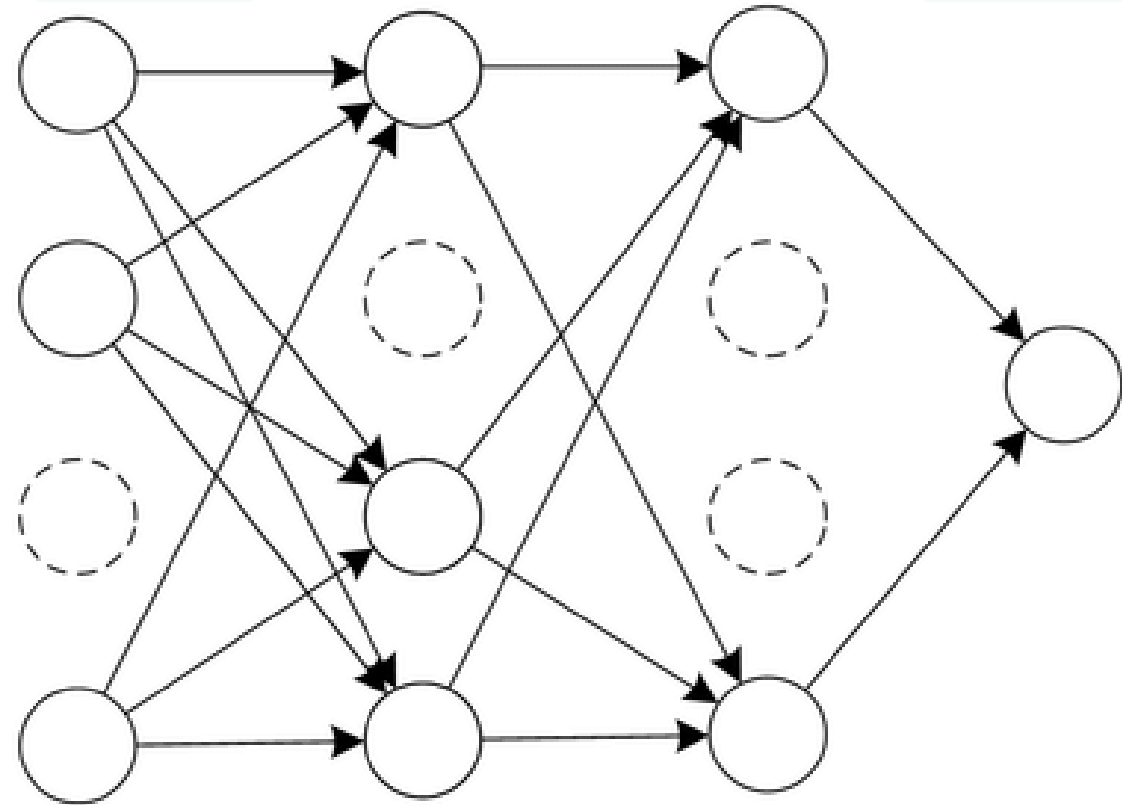




DROPOUT



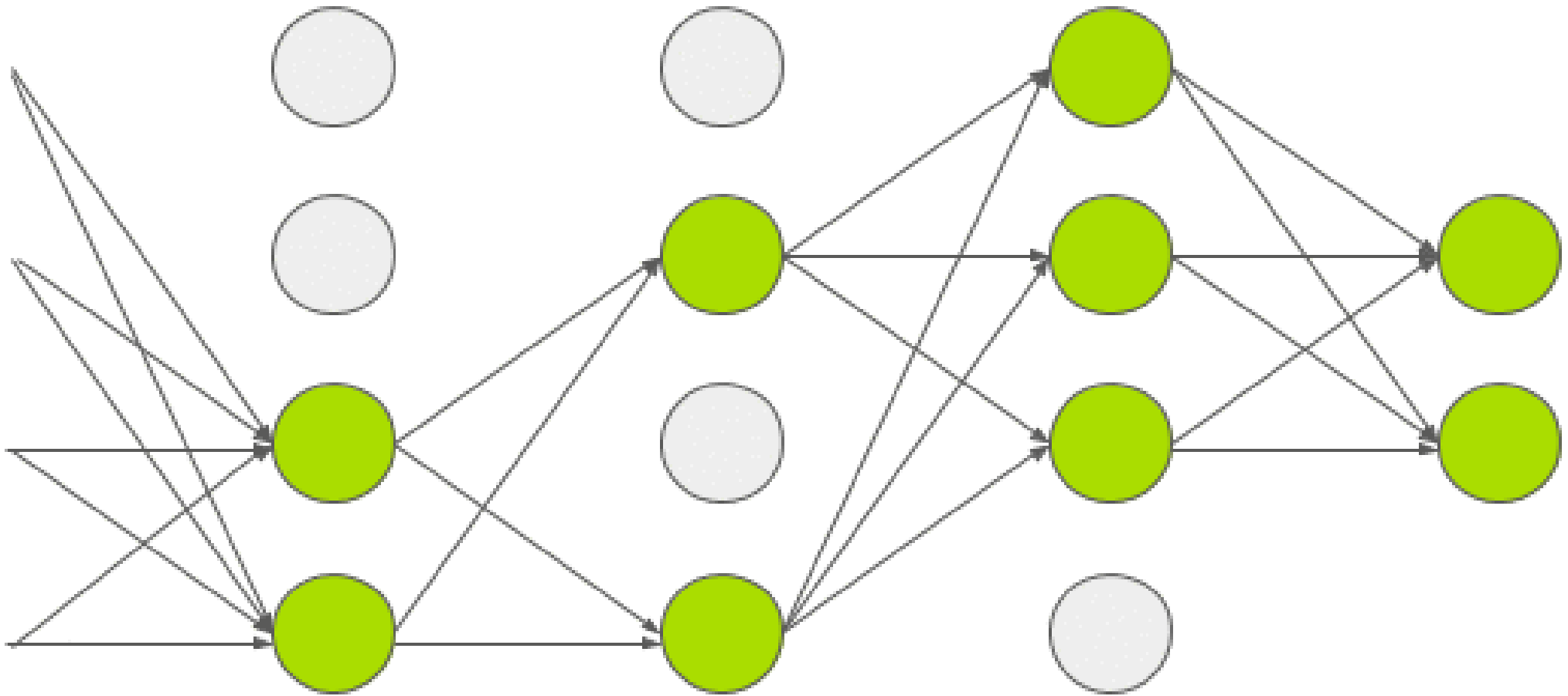
(a) Standard Neural Network



(b) Network after Dropout



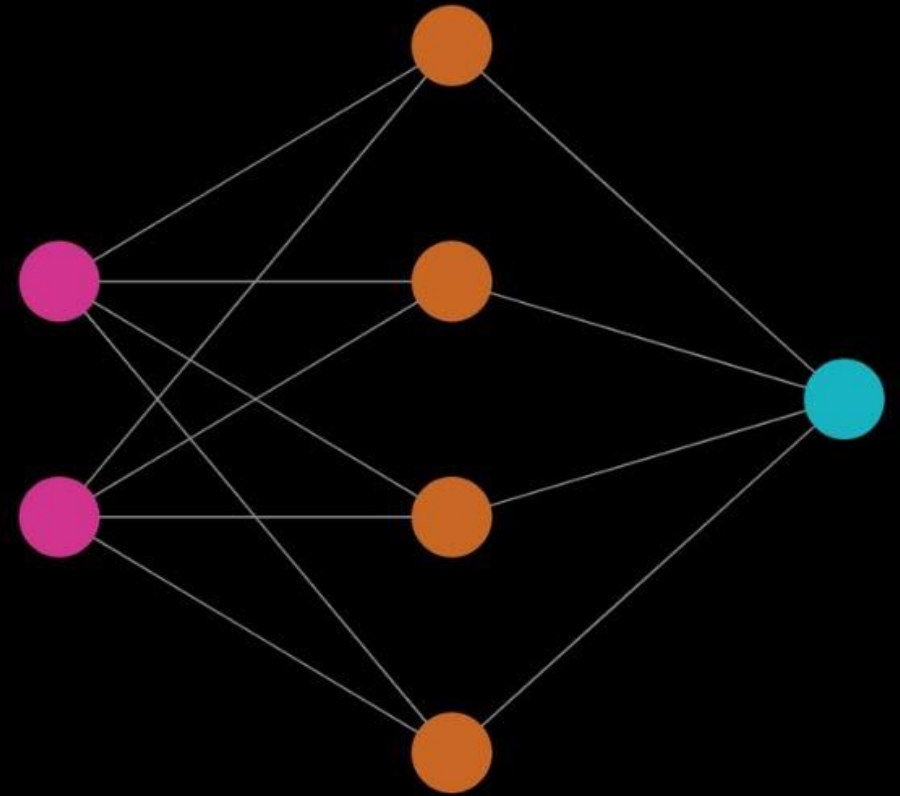
DROPOUT





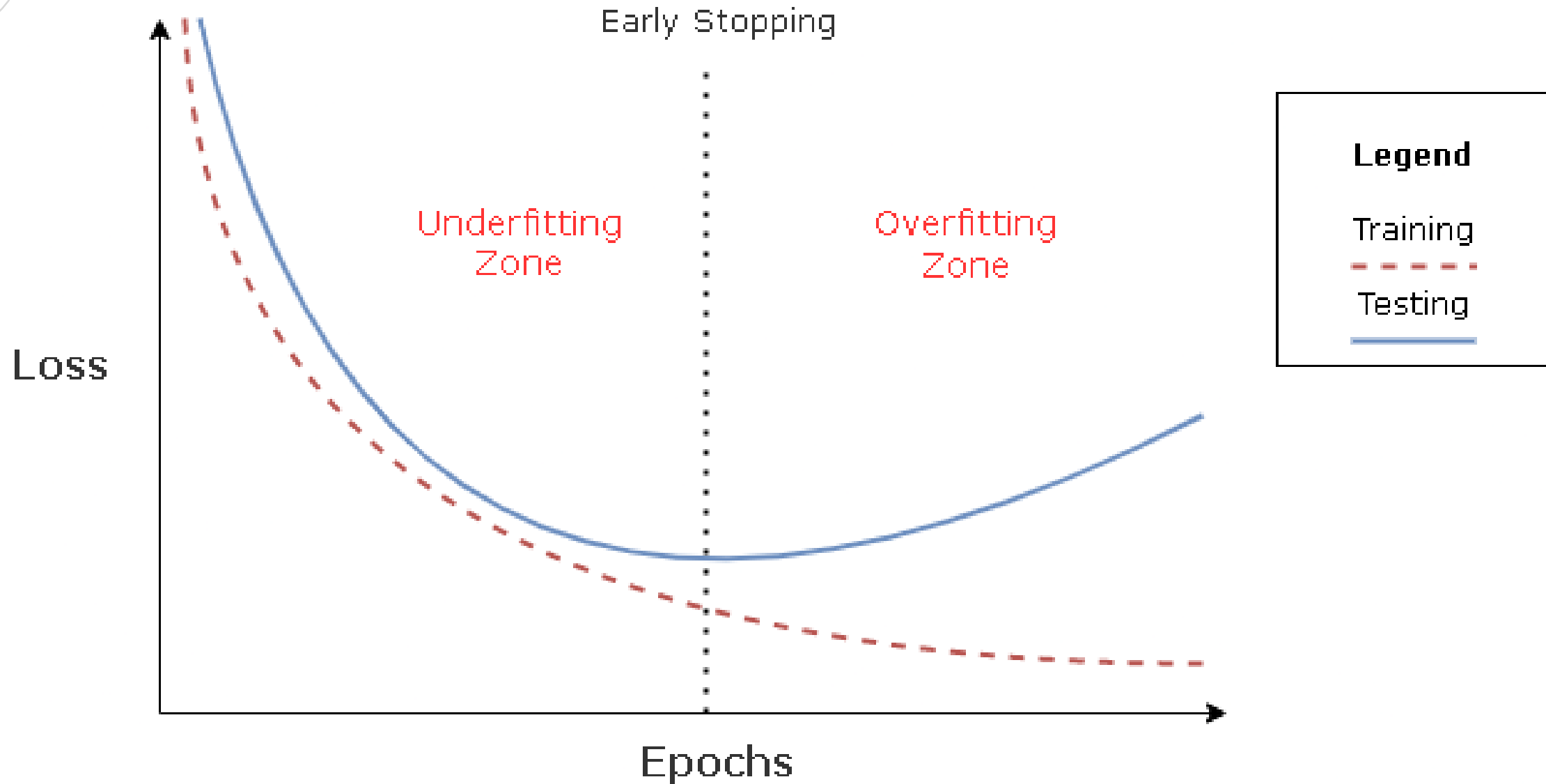
EARLY STOPPING

**EARLY
STOPPING TO
PREVENT
OVERFITTING**





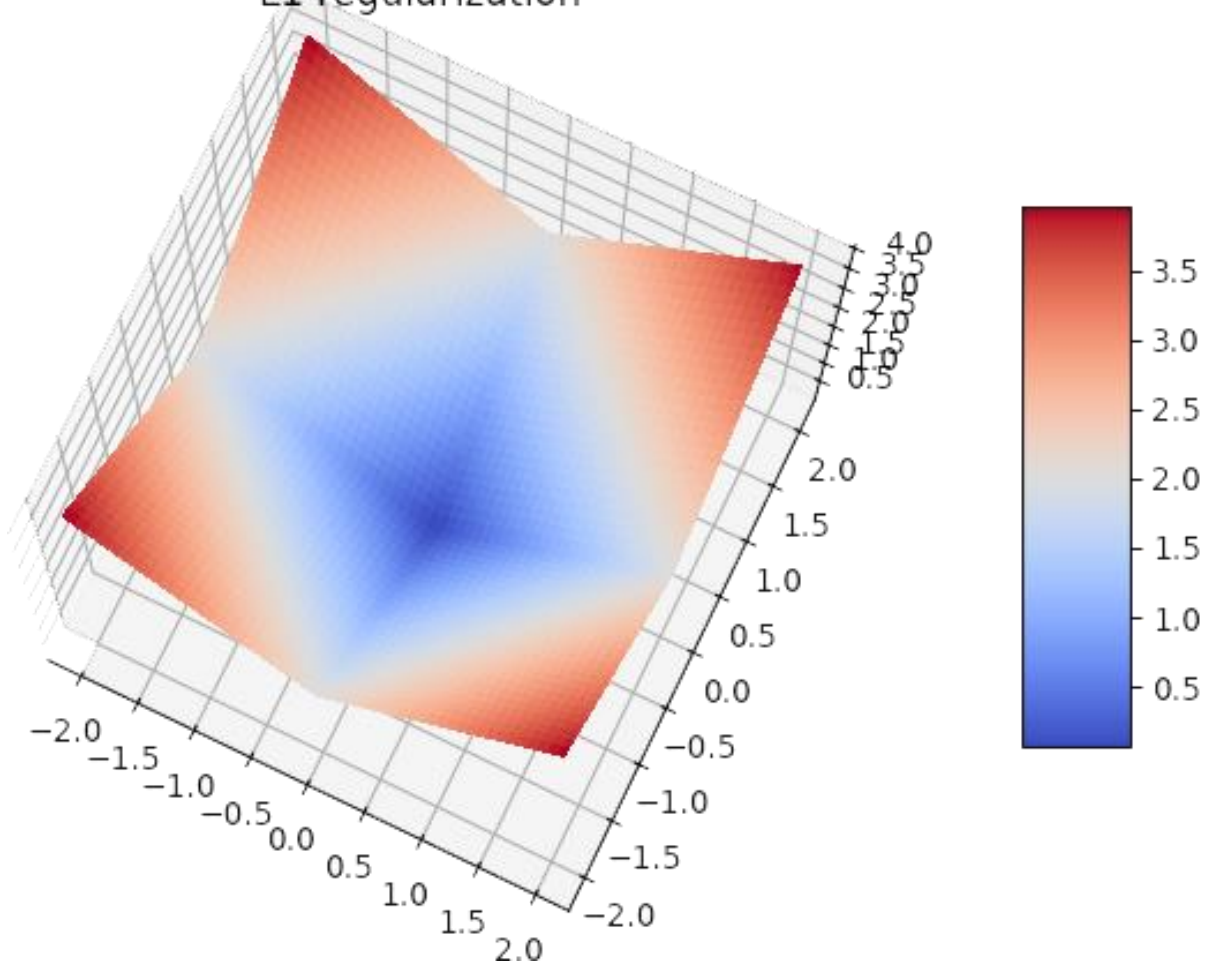
EARLY STOPPING



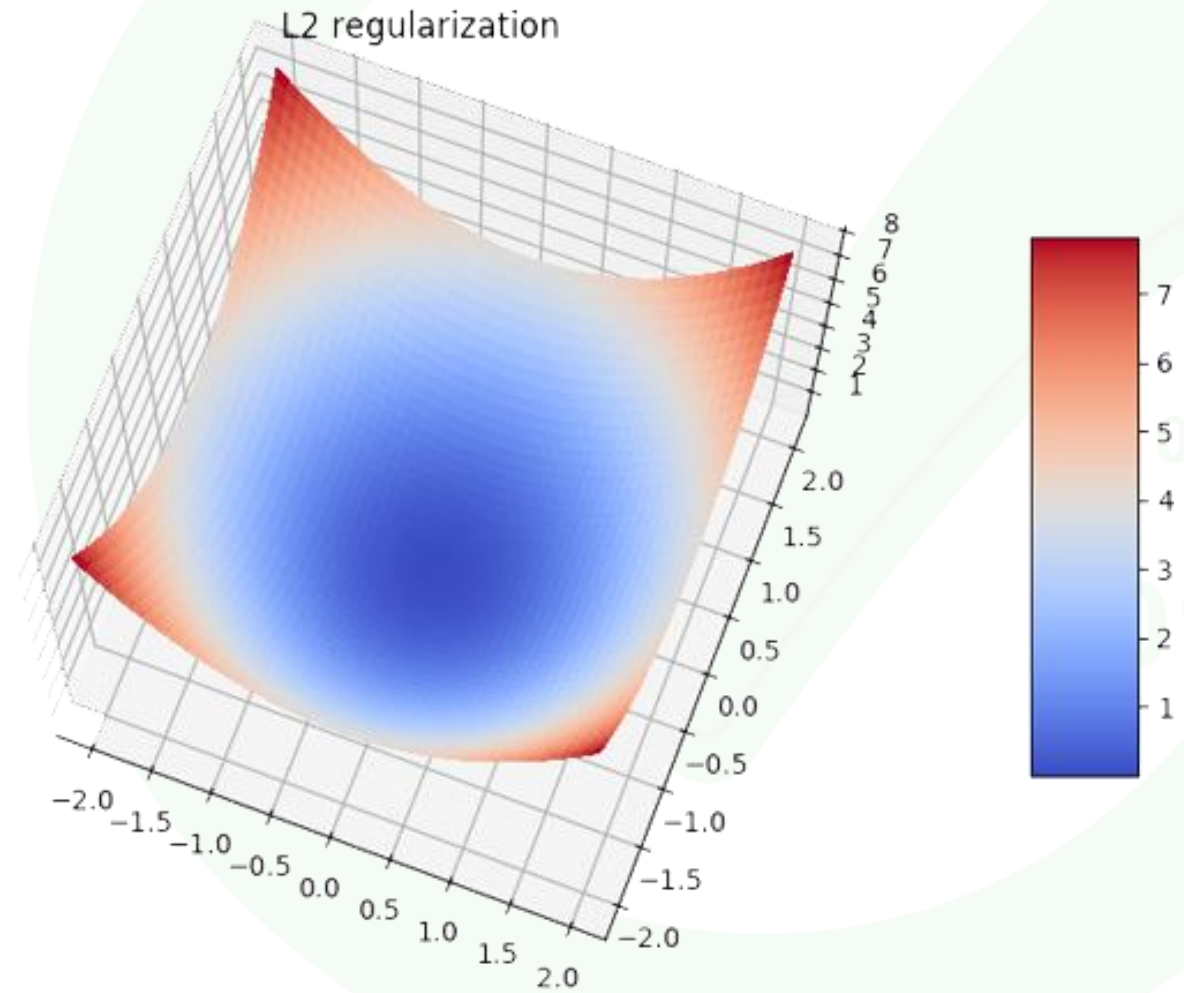


L1 and L2

L1 regularization

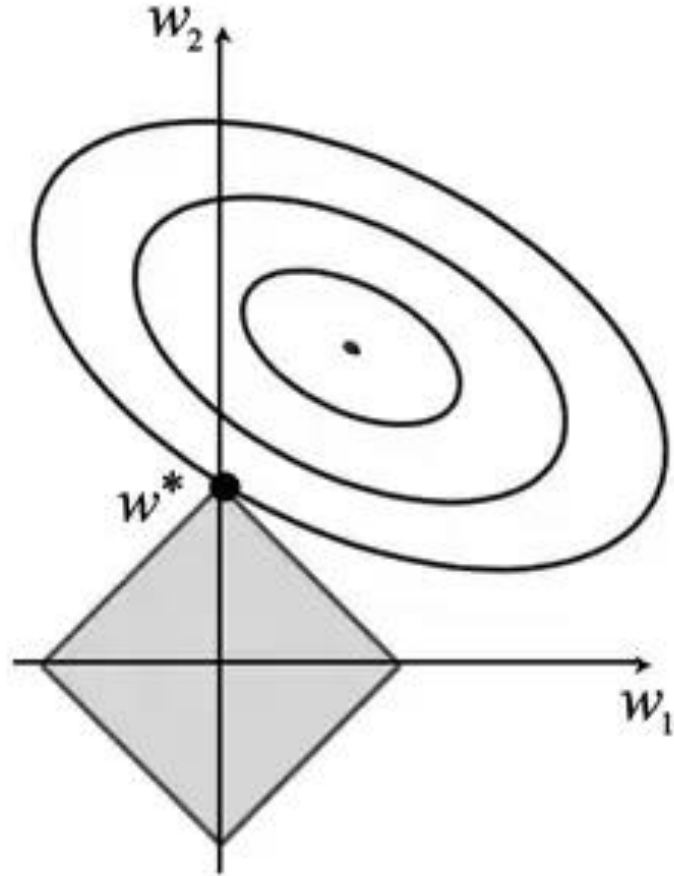


L2 regularization

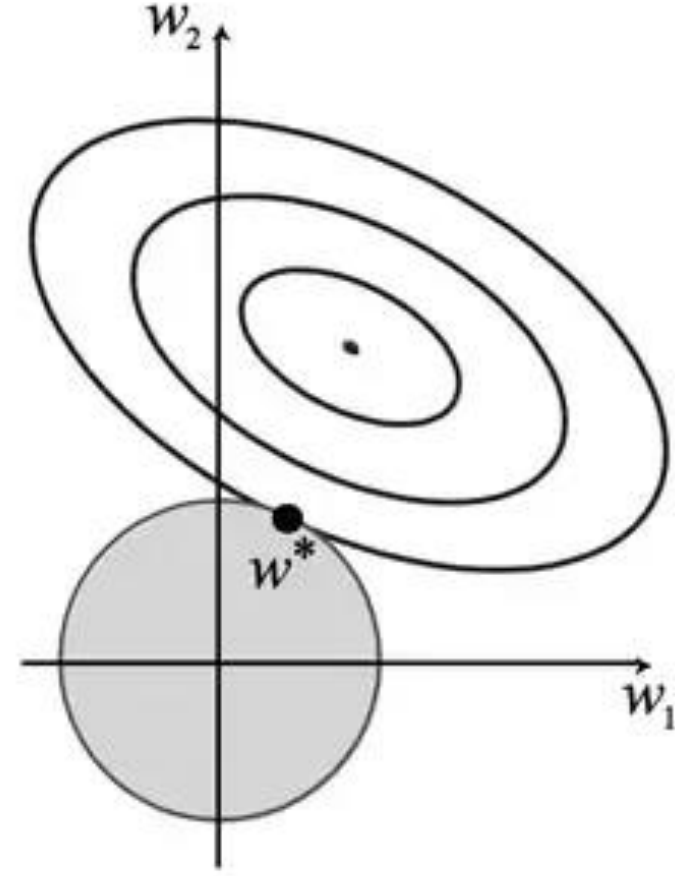




L1 and L2



L1



L2



L1 and L2

```
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense
from tensorflow.keras import regularizers
```

```
tf.random.set_seed(seed)
```

```
# Modeli oluştur
model = Sequential()
```

```
# Katmanları ekle ve sadece L1 düzenlemesini uygula
model.add(Dense(32, activation='relu', kernel_regularizer=regularizers.l1(0.01)))
model.add(Dense(32, activation='relu', kernel_regularizer=regularizers.l1(0.01)))
model.add(Dense(32, activation='relu', kernel_regularizer=regularizers.l1(0.01)))
model.add(Dense(16, activation='relu', kernel_regularizer=regularizers.l1(0.01)))
model.add(Dense(8, activation='relu', kernel_regularizer=regularizers.l1(0.01)))
model.add(Dense(1)) # Düzenleme uygulanmadı
```



L1 and L2

```
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense
from tensorflow.keras import regularizers
```

```
tf.random.set_seed(seed)
```

```
# Modeli oluştur
model = Sequential()
```

```
# Katmanları ekle ve sadece L2 düzenlemesini uygula
model.add(Dense(32, activation='relu', kernel_regularizer=regularizers.l2(0.01)))
model.add(Dense(32, activation='relu', kernel_regularizer=regularizers.l2(0.01)))
model.add(Dense(32, activation='relu', kernel_regularizer=regularizers.l2(0.01)))
model.add(Dense(16, activation='relu', kernel_regularizer=regularizers.l2(0.01)))
model.add(Dense(8, activation='relu', kernel_regularizer=regularizers.l2(0.01)))
model.add(Dense(1)) # Düzenleme uygulanmadı
```

```
# Modeli derle
model.compile(optimizer='adam', loss='mse')
```



BATCH NORMALIZATION



Batch Normalization

Batch Normalization (BN), bir derin öğrenme modelinin her bir eğitim mini-batch'indeki verilerin istatistiksel özelliklerini normalleştiren bir tekniktir.

Daha basit bir şekilde, BN, eğitim sırasında her mini-batch verisinin ortalamasını ve varyansını hesaplar ve bu ortalamayı ve varyansı kullanarak verileri bir tür standart ölçekte yeniden ölçekler. Bu, ağıın daha hızlı ve daha istikrarlı bir şekilde öğrenmesine yardımcı olabilir.

Batch Normalization, ağıın daha hızlı ve daha güvenilir bir şekilde eğitilmesine yardımcı olan bir normalizasyon tekniğidir.

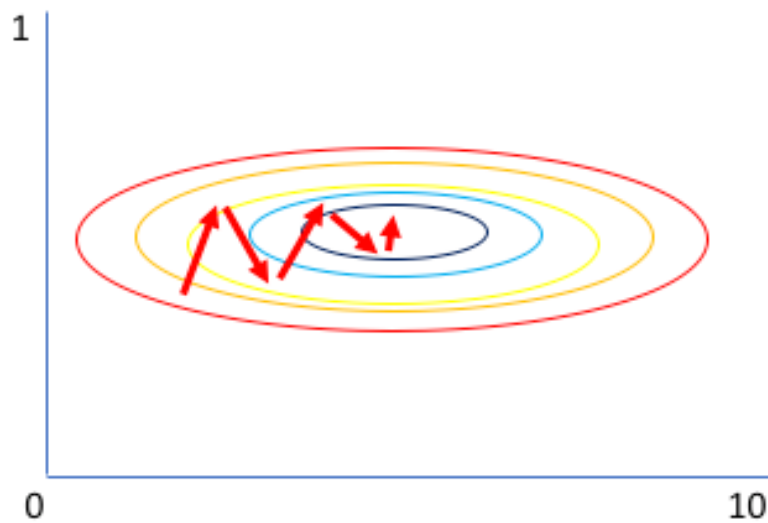


Kullanım Durumu	Açıklama
Derin Sinir Ağları (DNN)	DNN'lerde Batch Normalization, daha hızlı ve istikrarlı bir eğitim süreci sağlayabilir ve aşırı uyumu azaltabilir.
Evrişimli Sinir Ağları (CNN)	CNN'lerde özellikle büyük ve karmaşık modellerde kullanılabilir. Evreli ve tam bağlantılı katmanlar arasında eklenerek özellik haritalarının daha iyi öğrenilmesine yardımcı olabilir.
Rekürrent Sinir Ağları (RNN)	RNN'lerde Batch Normalization, özellikle büyük zaman serisi verileri işlerken kullanılabilir. Ancak, dikkatli bir şekilde yapılandırılması gerekebilir.
Uzun Kısa Süreli Bellek (LSTM) ve GRU	LSTM ve GRU gibi özel RNN türleri, Batch Normalization ile kullanılabilir. Özellikle bu hücre tiplerinin daha istikrarlı eğitim sağlamasına yardımcı olabilir.
Doğal Dil İşleme (NLP)	Metin verilerini işleyen NLP modellerinde özellik çıkarma veya tam bağlantılı katmanlar gibi yerlerde kullanılabilir.
Genel Veri Normalizasyonu	Veri normalizasyonu işlemini daha hızlı ve daha kararlı hale getirir. Bu, giriş verilerini aynı ölçekleme düzeyine getirerek eğitim sürecini iyileştirebilir.

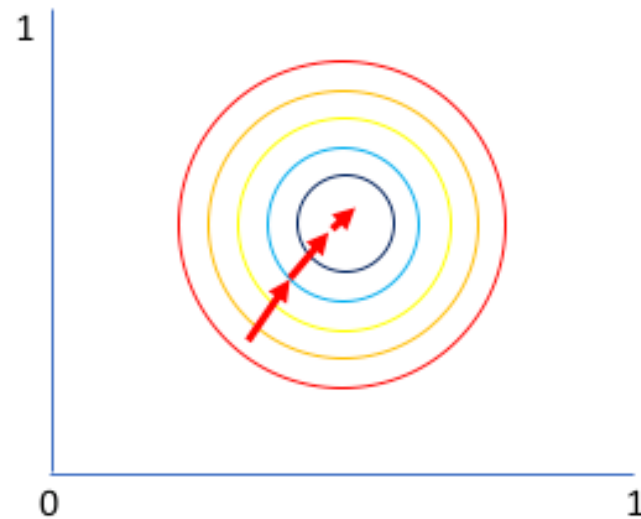


Batch Normalization

Why normalize?



Gradient of larger parameter
dominates the update



Both parameters can be
updated in equal proportions



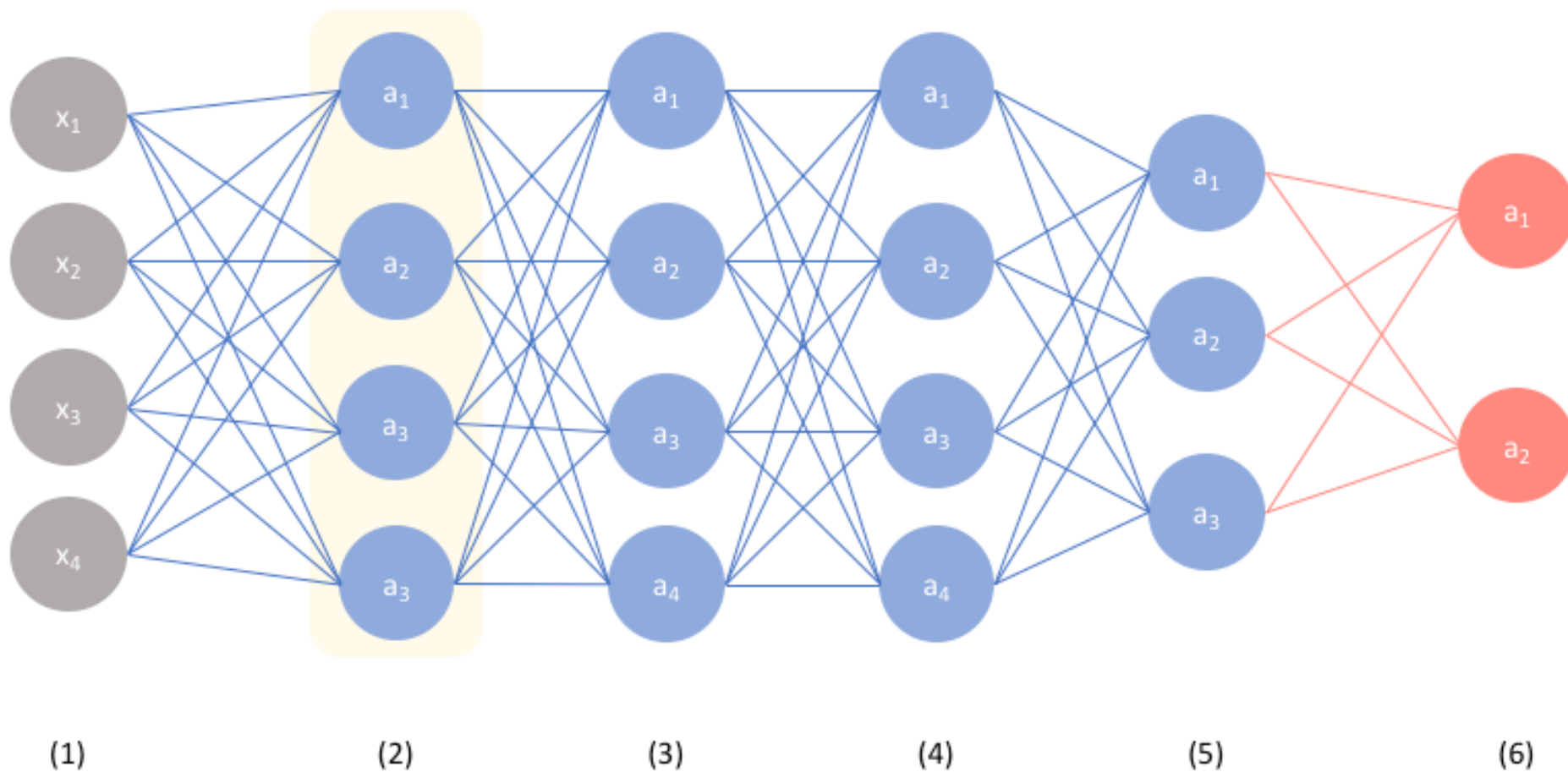
Batch Normalization

Input layer

Hidden layers

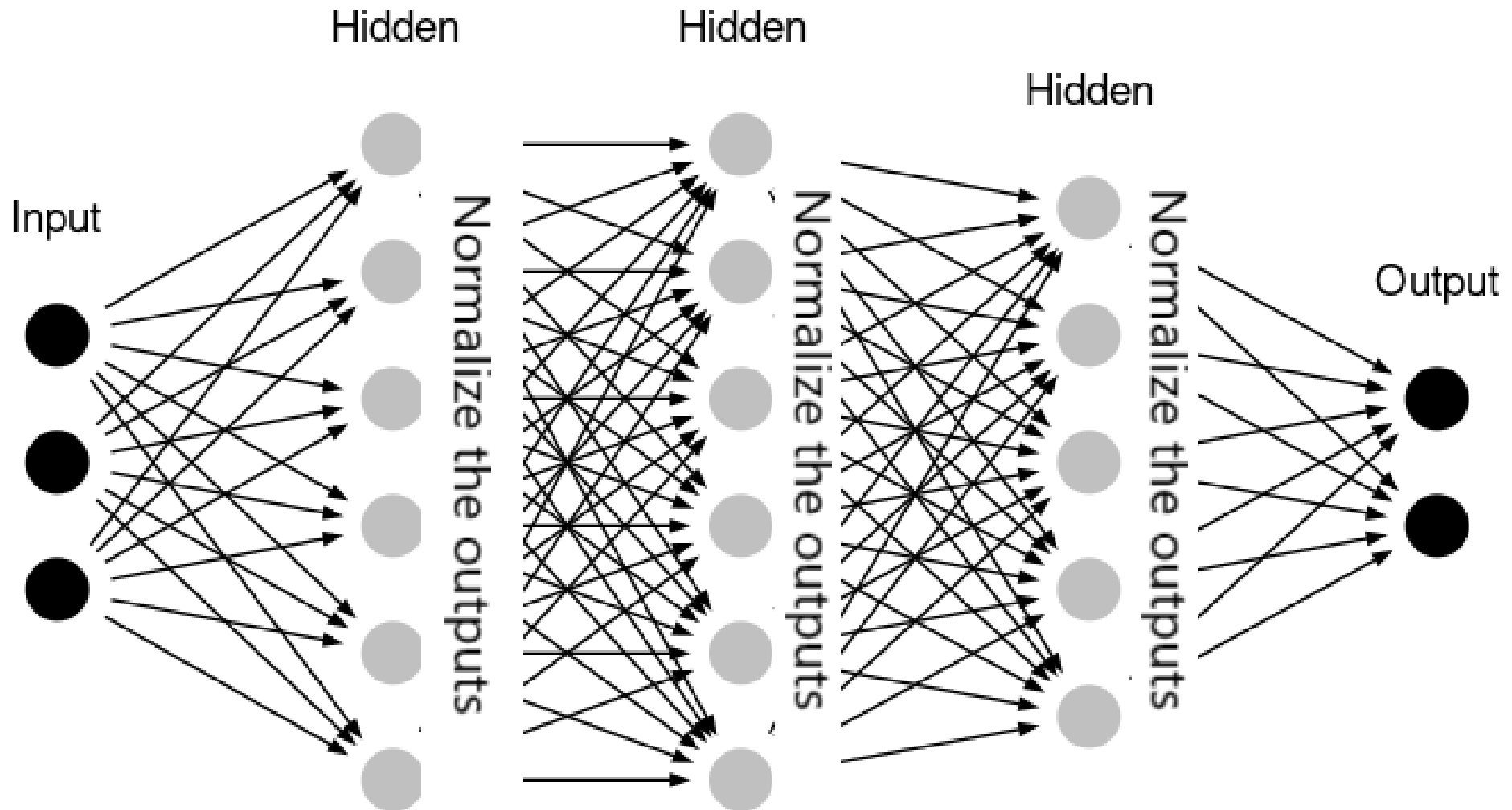
Output layer

These activations are essentially the inputs to the following layer, so why not normalize these values?





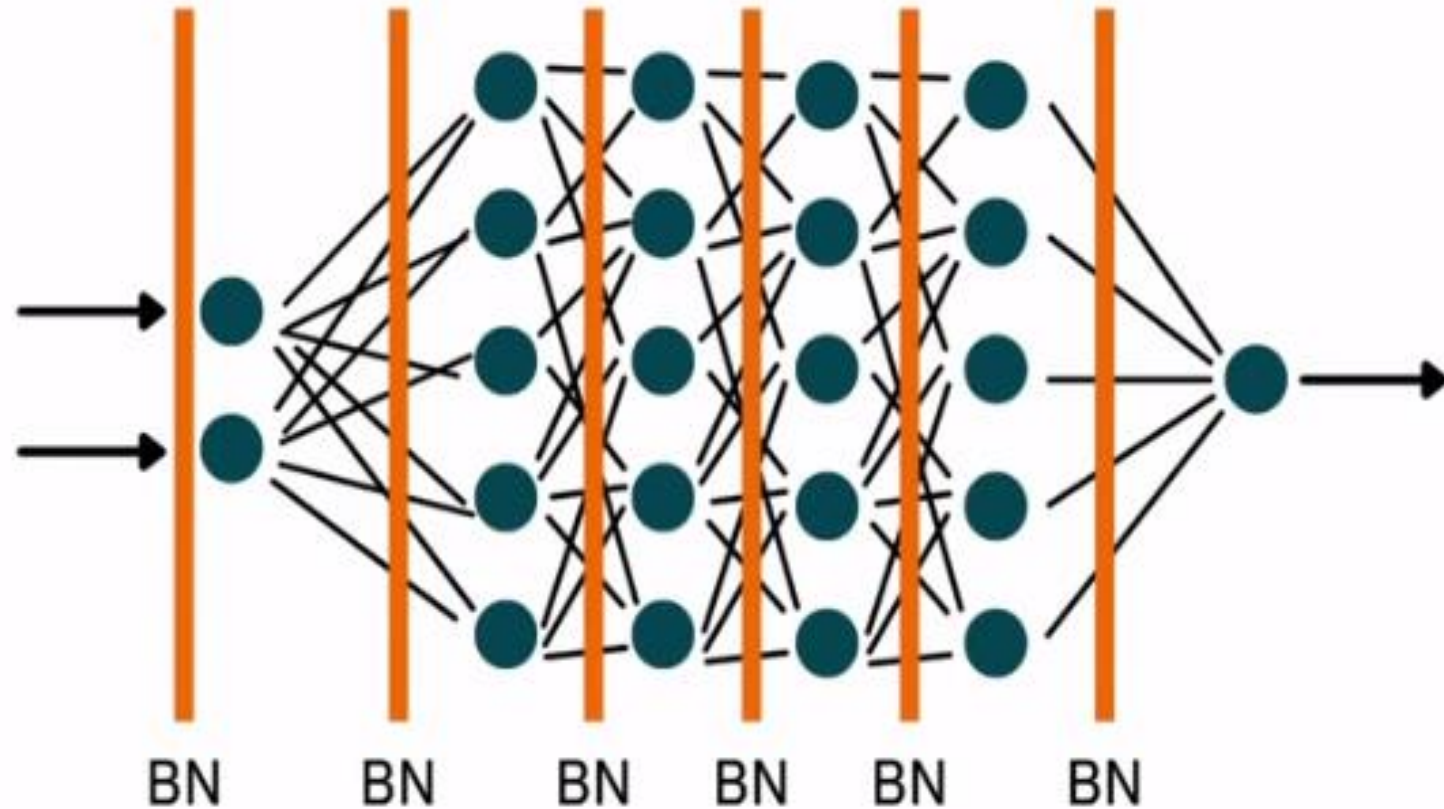
Batch Normalization





Batch Normalization

- Center around zero and normalize the inputs
- Achieves same accuracy faster
- Can lead to better performance
- No need to have a standardization layer
- Reduces the need for other regularization
- Epochs take longer due to the amount of computations but convergence will be faster





NOTEBOOK SAMPLES

```
import tensorflow as tf
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Conv2D, MaxPooling2D, Flatten, Dense,
BatchNormalization
```

Veri setini yüklemek ve hazırlamak için gerekli işlemleri yapabilirsiniz.

Örnek bir CNN modeli oluşturma
model = Sequential()

İlk evreli katman (Convolutional Layer)
model.add(Conv2D(32, (3, 3), activation='relu', input_shape=(64, 64, 3)))
model.add(BatchNormalization()) # Batch Normalization katmanı ekleniyor
model.add(MaxPooling2D((2, 2)))

İkinci evreli katman
model.add(Conv2D(64, (3, 3), activation='relu'))
model.add(BatchNormalization())
model.add(MaxPooling2D((2, 2)))

Düzleştirme katmanı
model.add(Flatten())

Tam bağlantılı katmanlar
model.add(Dense(128, activation='relu'))
model.add(BatchNormalization())
model.add(Dense(10, activation='softmax')) # Örnek bir çıkış katmanı

Modeli derleme
model.compile(optimizer='adam',
loss='categorical_crossentropy',
metrics=['accuracy'])

Modeli öğrenme verileriyle eğitme
model.fit(x_train, y_train, epochs=10, batch_size=32)

```
import tensorflow as tf
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense, BatchNormalization
```

Veri setini yüklemek ve hazırlamak için gerekli işlemleri yapabilirsiniz.

Örnek bir ANN modeli oluşturma
model = Sequential()

model.add(Dense(64, input_dim=input_dim, activation='relu'))
model.add(BatchNormalization()) # Batch Normalization katmanı ekleniyor
model.add(Dense(32, activation='relu'))
model.add(BatchNormalization())
model.add(Dense(output_dim, activation='softmax'))

Modeli derleme
model.compile(optimizer='adam',
loss='categorical_crossentropy',
metrics=['accuracy'])

Modeli öğrenme verileriyle eğitme
model.fit(x_train, y_train, epochs=10, batch_size=32)