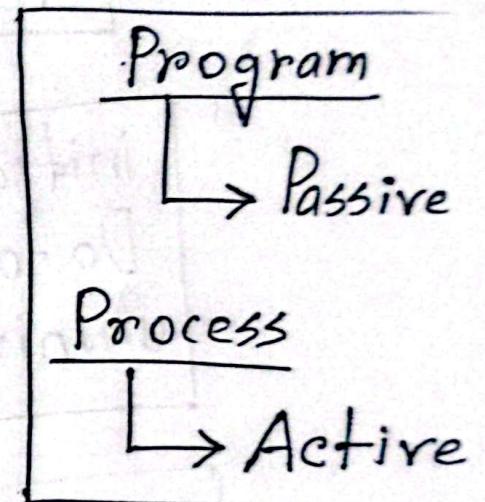
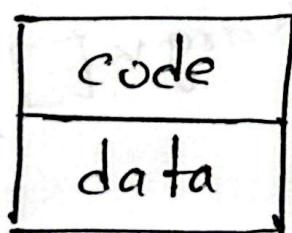


Process:

- program in execution
- CPU
- batch system → job
- unit of work of the OS.
- certain space occupied



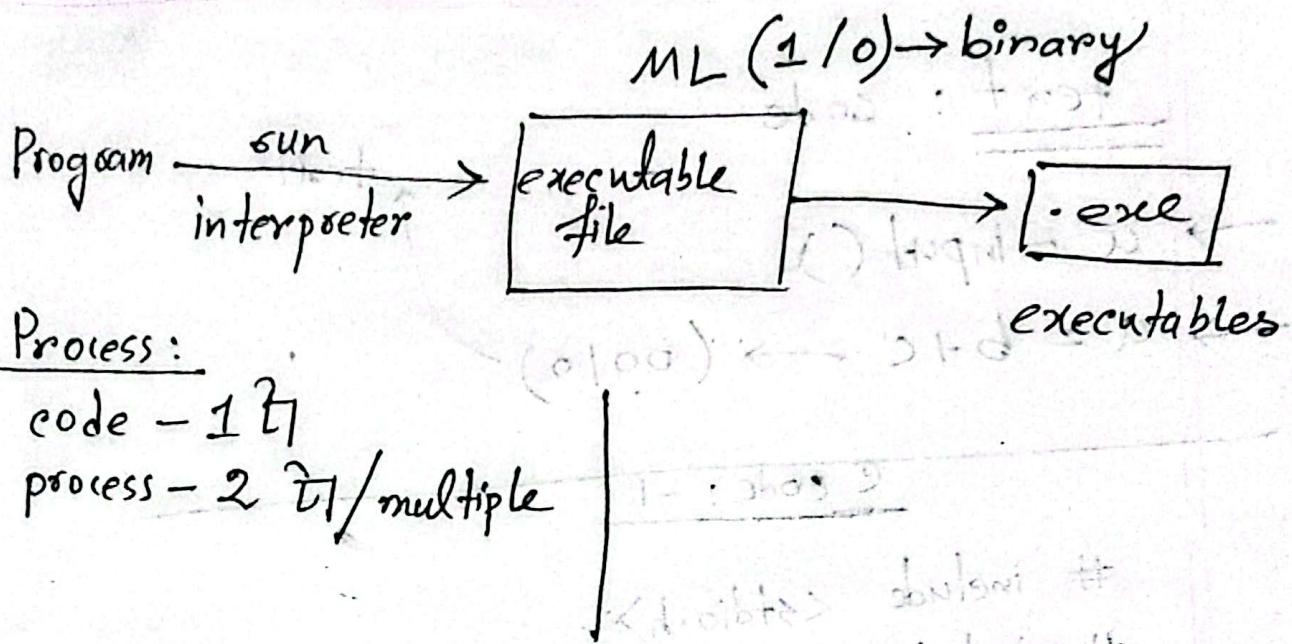
1) Program → Multiple process → certain address at the memory



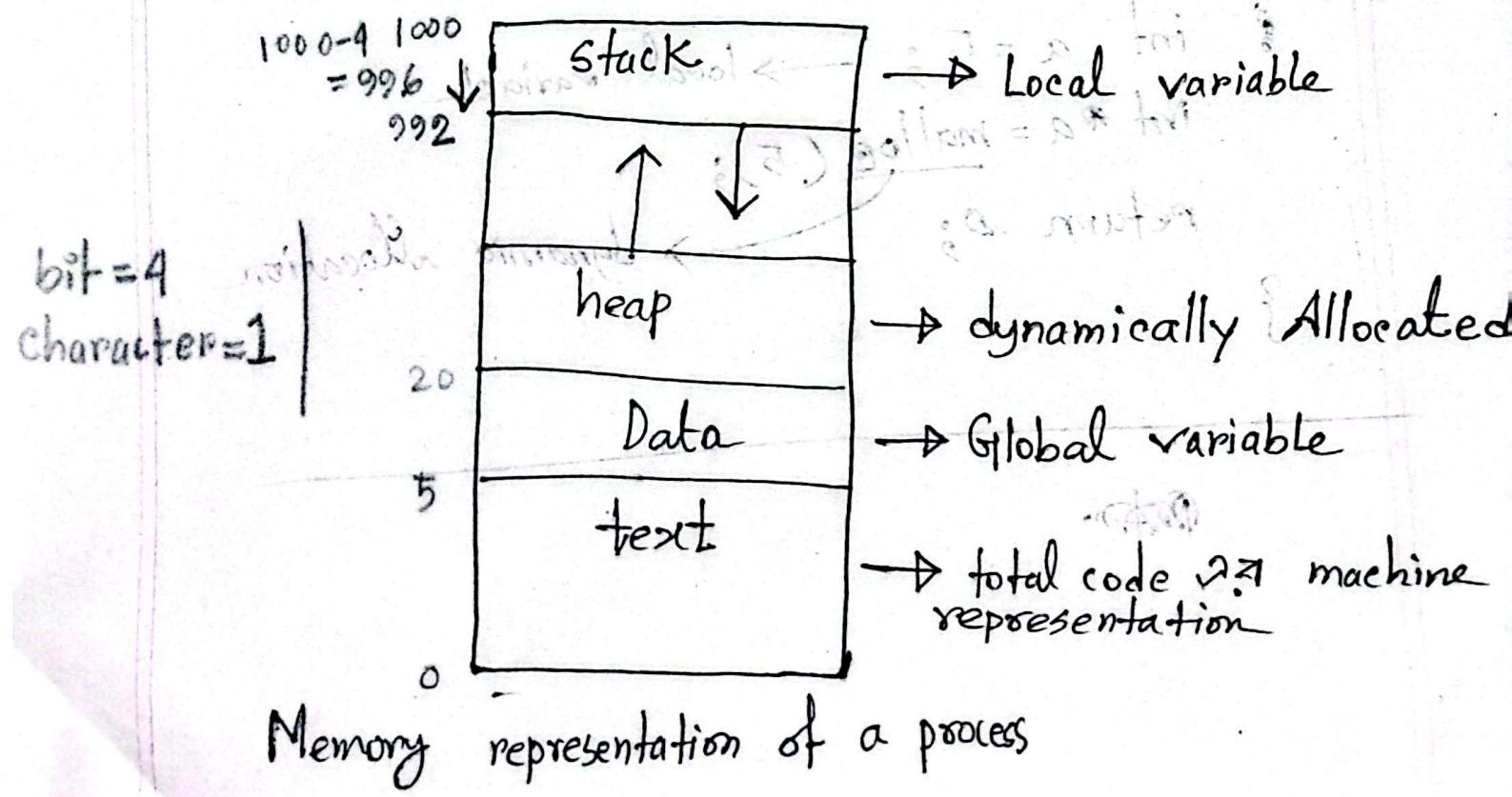
→ executable files

## Lecture-2

CSE-321:



- # A process is a program that is in execution.
- # Every process memory's certain space occupied.
- # memory's certain address ↗ 256(B)



## Process:

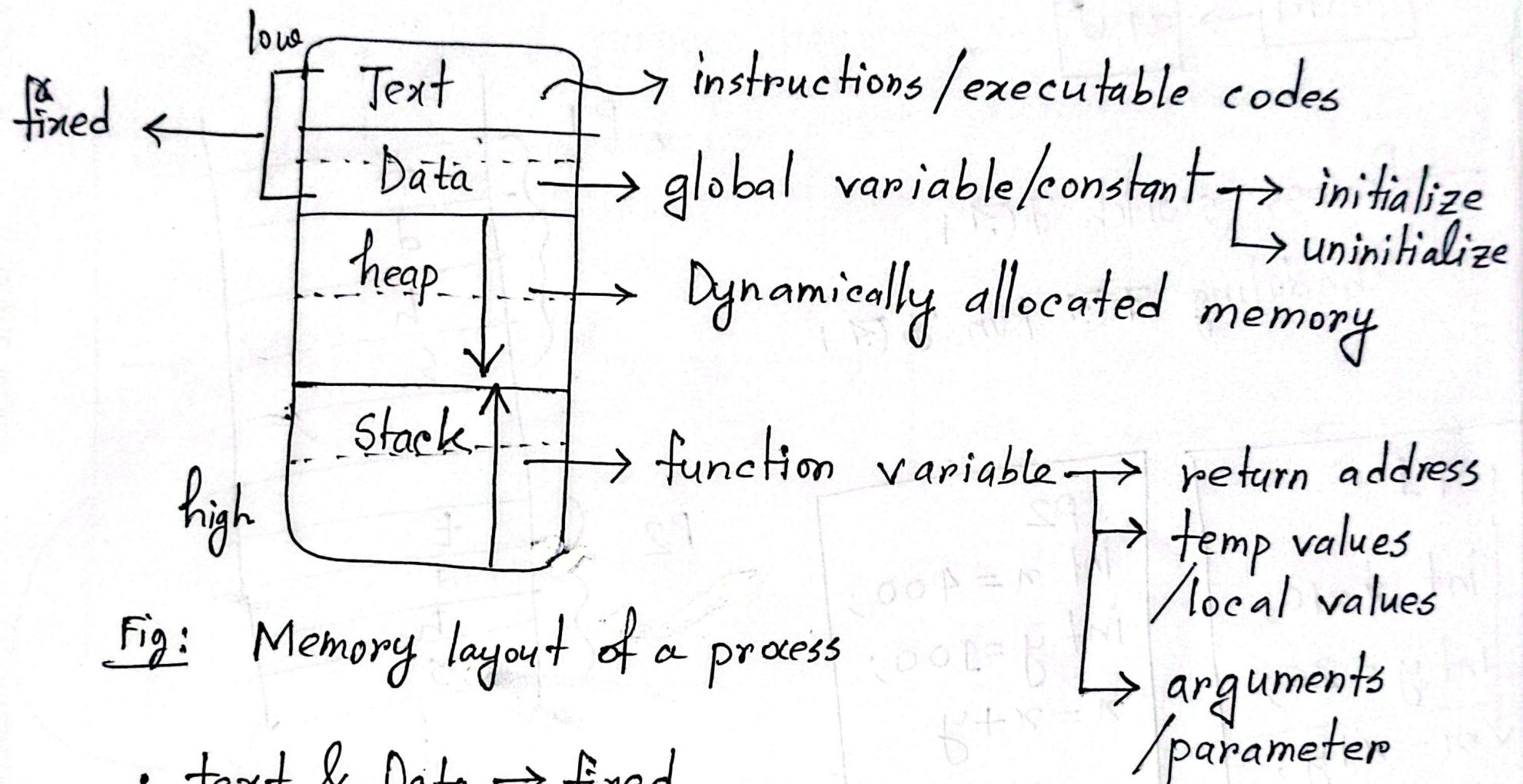


Fig: Memory layout of a process

- text & Data → fixed
- heap & stack → Shrink & Expand
- heap & stack → can't overlap

Structure

↳ PCB (Process Control Block)

- OS ৰাখা process কৰে store কৰিবলৈ (Data Structure)  
use কৰে এটি PCB

Process is represented in OS by Process Control Block (PCB)  
or Task Control Block.

- 1) Process state: running, waiting etc
- 2) Prog counter - location of instruction to execute next?
- 3) CPU register - contents of all process-centric registers.
- 4) CPU scheduling information - priorities, scheduling queue.
- 5) Memory-management info - memory allocation.
- 6) Accounting info - CPU used, process ~~age~~ वायर्स (age)
- 7) I/O status info - Input/output ready? रियल?

## III States of Process

- 1) New
- 2) Running
- 3) Waiting
- 4) Ready
- 5) Terminated

Delay : Ready

## Process State :

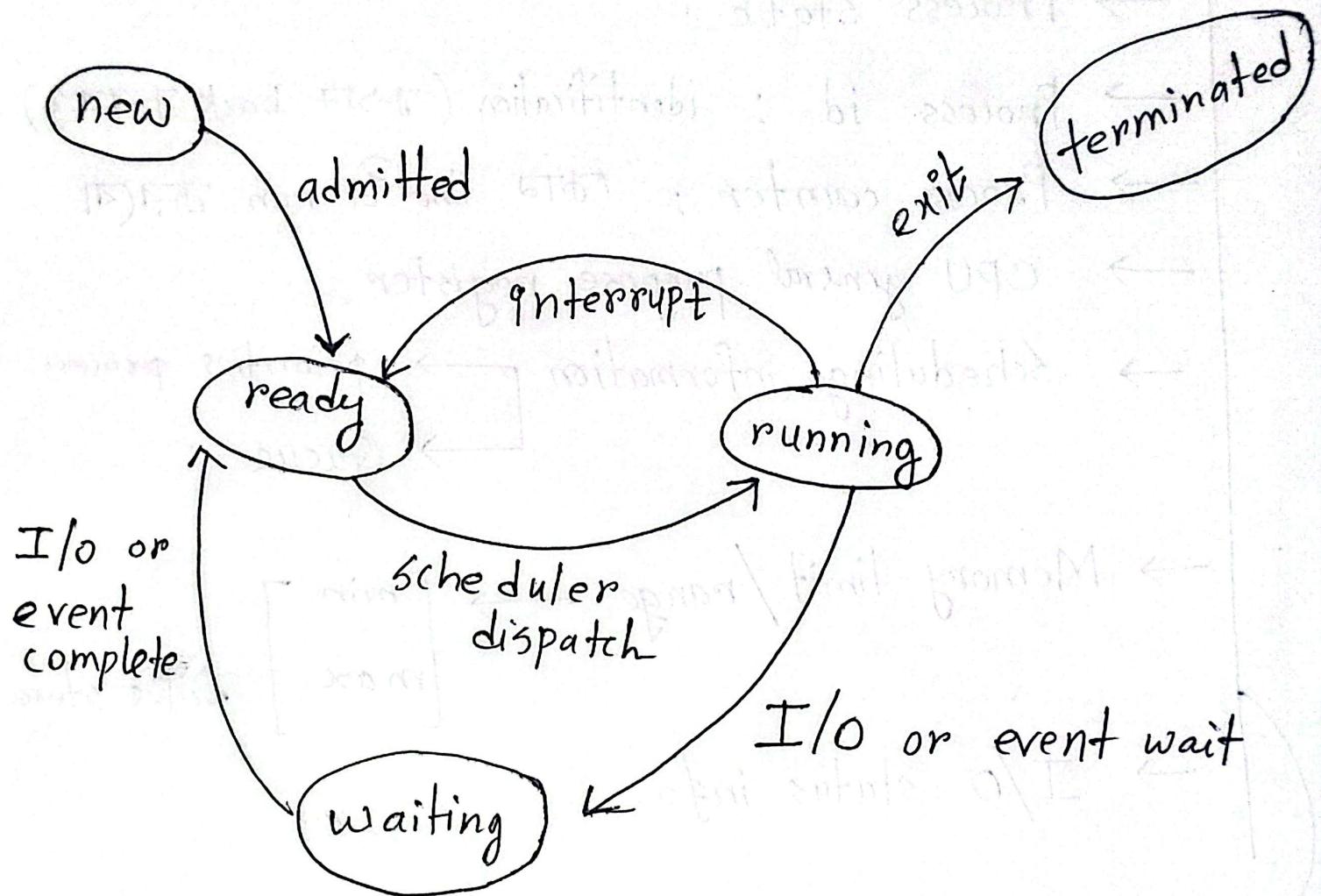
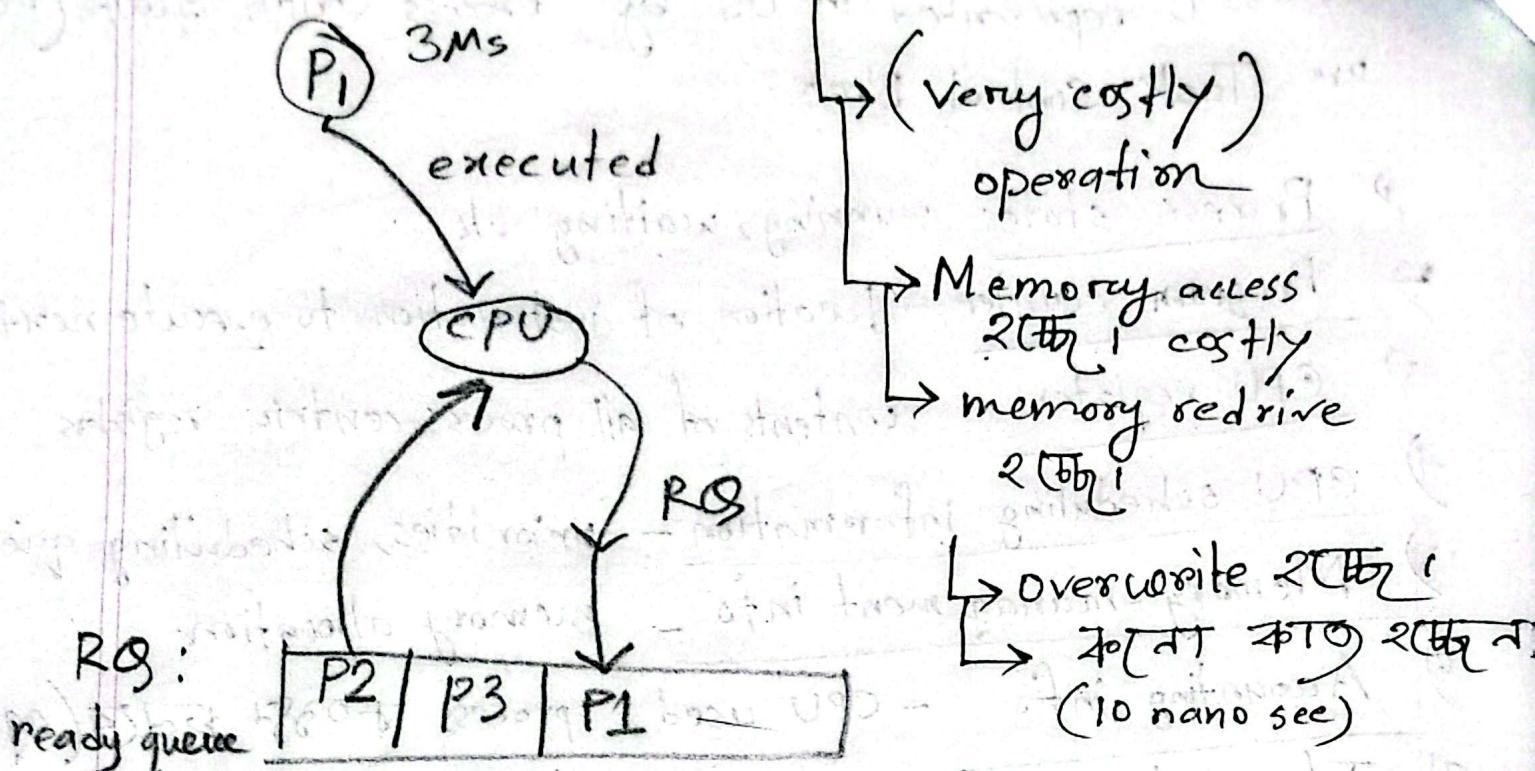


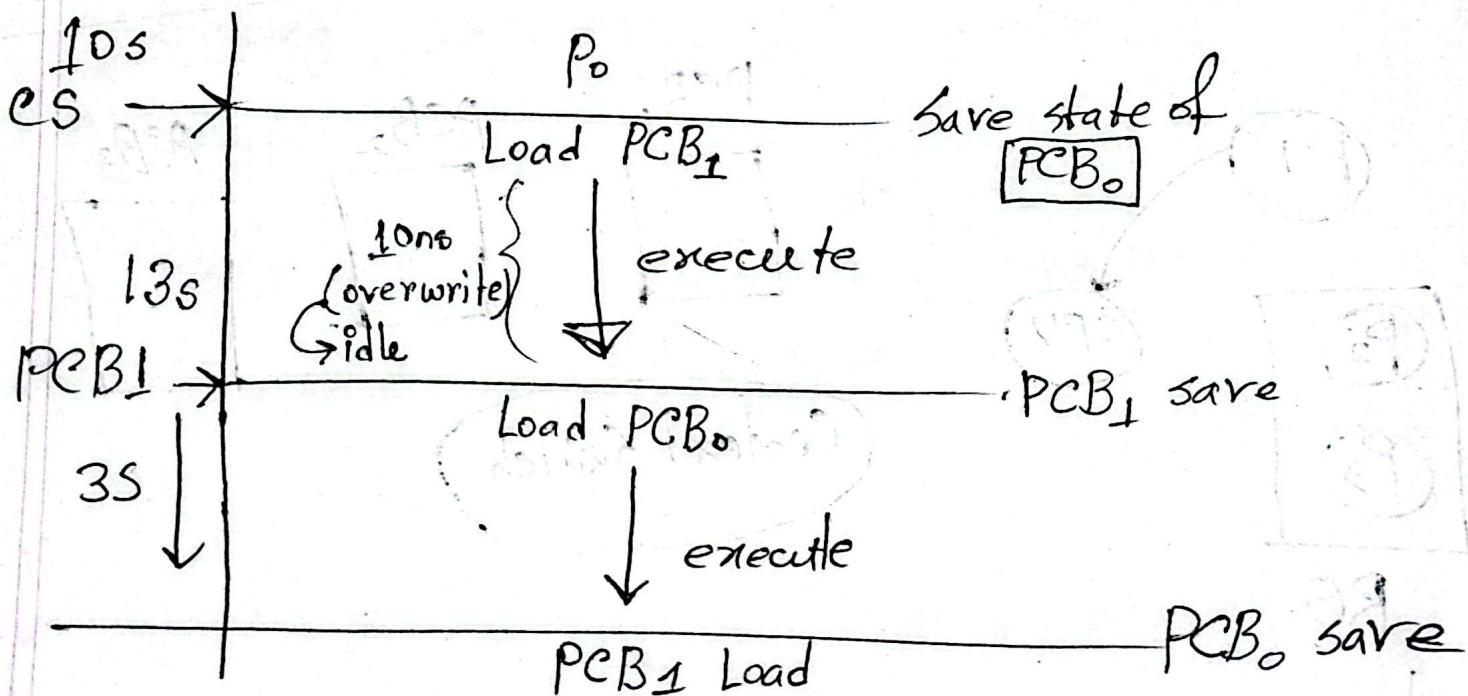
Fig: Diagram of Process State.

→ occurs when CPU switches from one process to another

### Context Switch:-

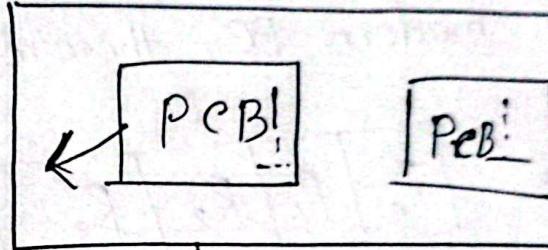
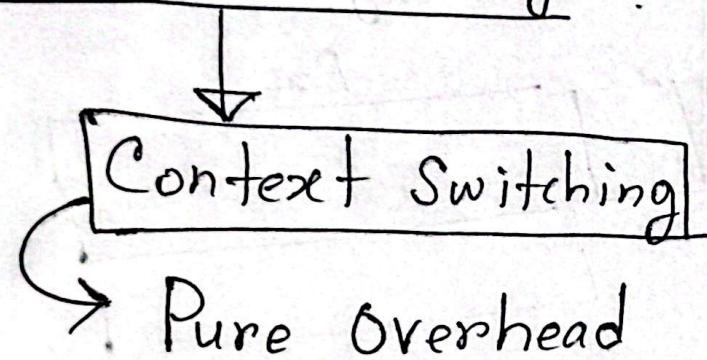


### Context switch



②

## Process Switching :



ଫିକ୍ଟୁ Process ରାତ୍ରି  
ଚାଲି ଭାବାୟ ଦିଅ  
ନୋଯାର New Process

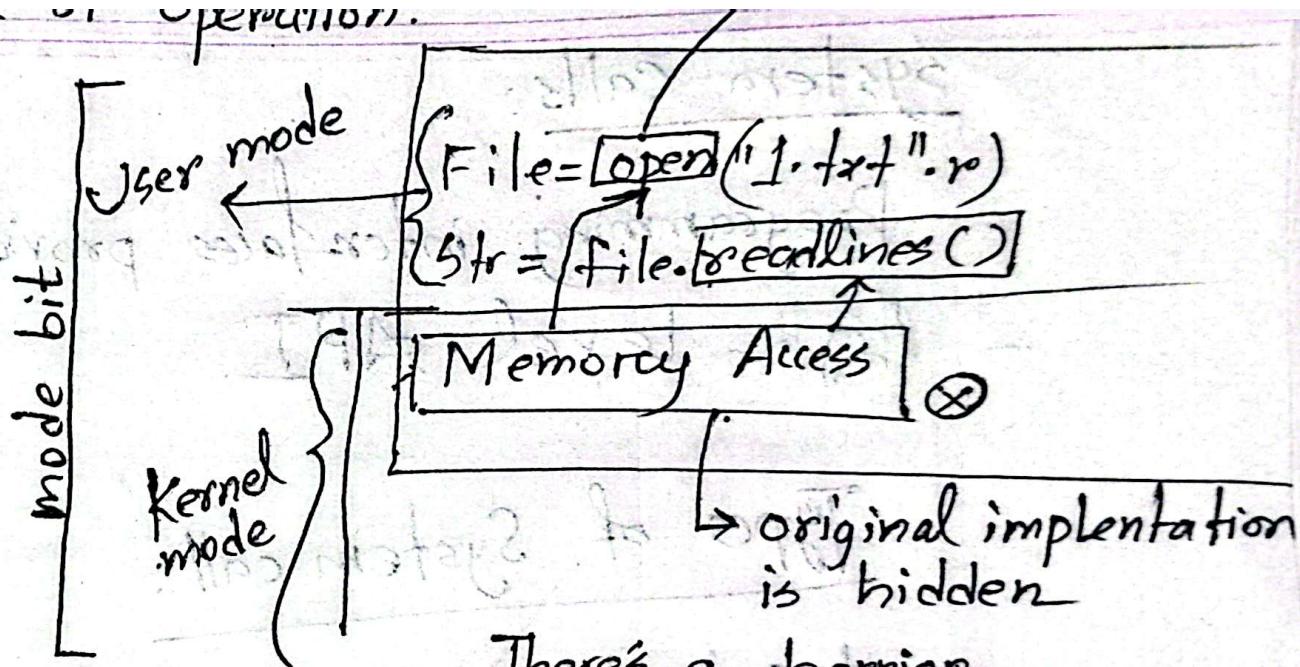
C Pure overhead  $\Rightarrow$  CPU idly ରମ୍ବ ଥାଏ । କାହାର କଂଟେ ।

→ Pure overhead ହଜାରେ, CPU ତମ ଉଲ୍ଲେଖ କାହାରେ ।

Two modes:

- 1) User mode
- 2) Kernel mode

User: bit (1)



Kernel mode: bit (0)

mode bit define is it in user or kernel?

→ System call করলে kernel → যাব। (mode.bit 1)  
এবং আবার Back করলে (mode change) change কো

ectly can't  
hardware

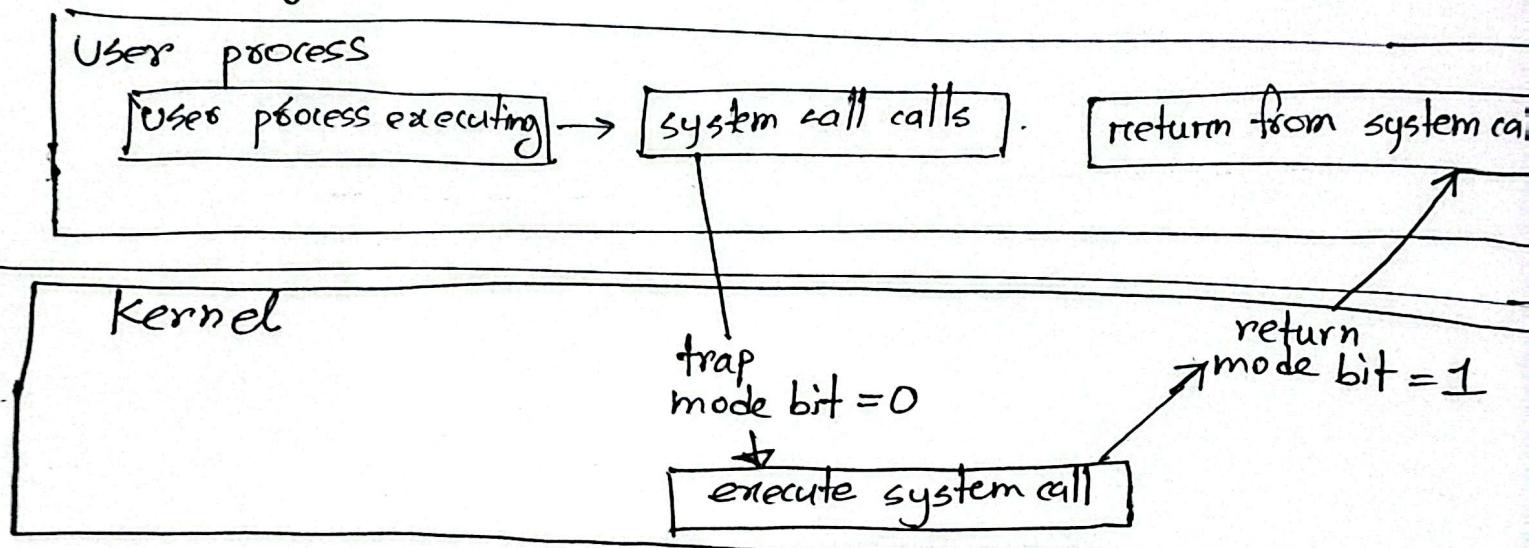
so that user directly can't access memory / hardware

so that one program can't effect another program.

### Dual Mode operation :

- Distinguish between [OS code and user defined code]
  - ↓  
system
  - ↓  
application/web-browser  
/ docs/spreadsheet
- **Mode bit**
  - Kernel mode (0) :- bit = 0
  - User mode (1) :- bit = 1
- Provides protection of the OS from errant users
- ~~Programs~~ Program  $\geq 20$  lines of codes (sensitive code) that can change behavior of system. That lines of codes are (privileged instructions) → executed only in kernel mode

figure:



## System calls:

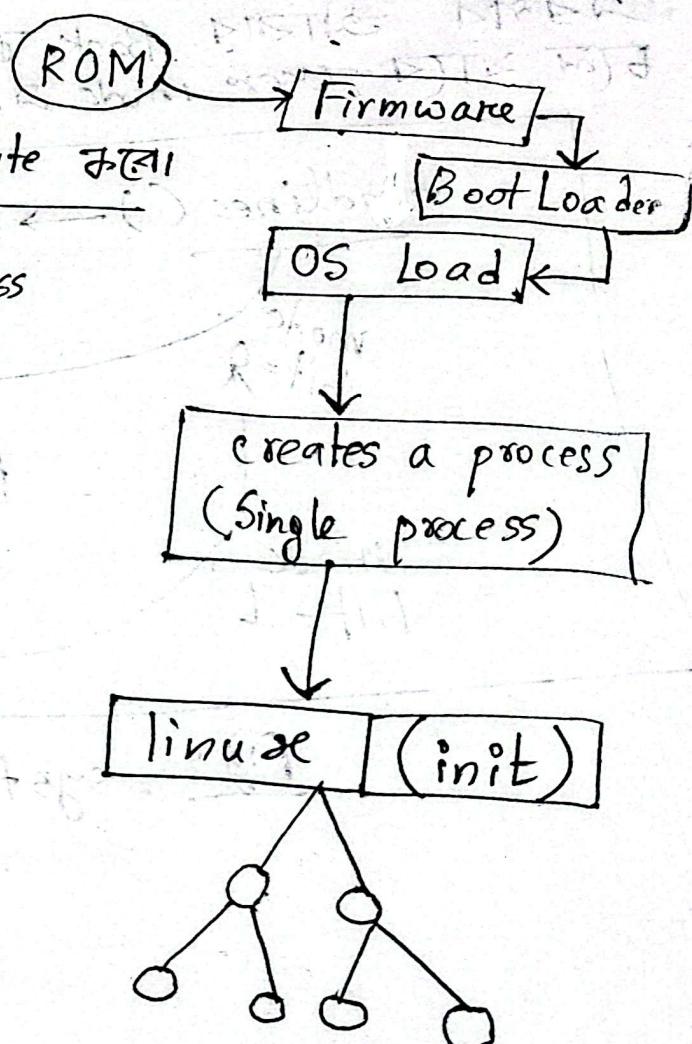
- Programming interfaces provided by OS
- High level API

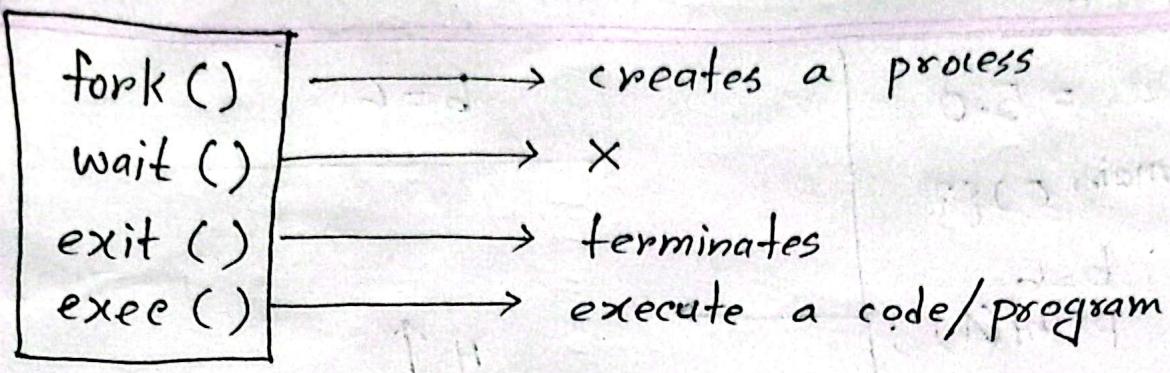
## Types of System call:

# getpid → process id

## Operations on Process:

- pc start करते हैं → ROM
- init → Multiple process create करता है।
  - Creates more process
- Firmware: check everything.  
if my mouse, keyboard all  
are working or not.





### process creation:

- parent process
  - child process
- } tree like structure

### process identifier (pid)

#### Sharing options:

- i) parent & child share all resources
- ii) child share subset of parent's resources
- iii) Parent & child share no resources

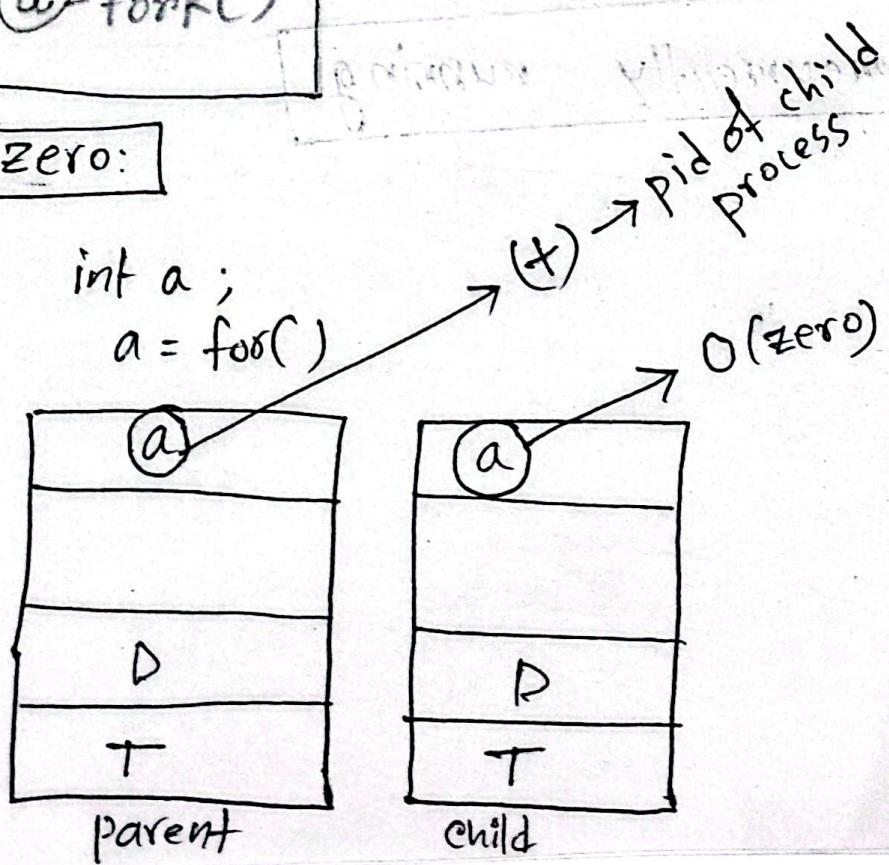
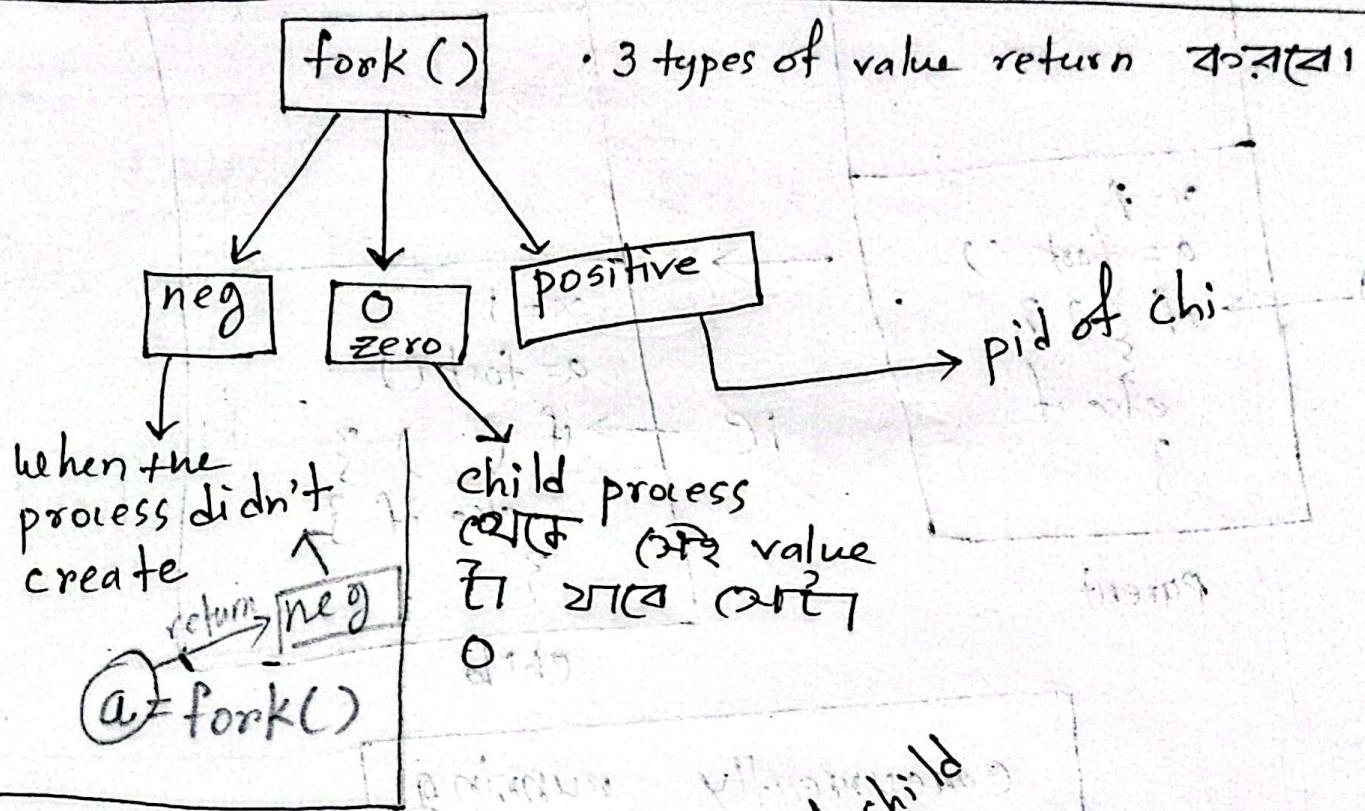
#### Execution option:

- i) Parent & children execute concurrently
- ii) Parents wait until children terminates

\* a process (কোর্স আবেক্ষণ্য) process create execute ২২৫, scheduler fn (ঘৃত)

(PC): program counter: points to the next line to execute

fork() → এখন অন্য একটা child create হচ্ছে।  
Parent process সব copy করছে।



concurrently running

wait() → ଏହି Parent ନାହିଁ under ଏହାକୁଣ୍ଡଳୀ- child ସ୍ଟର୍ଟ୍‌ପାର୍ଟ୍  
ଅବଶ୍ୟଳୀ ଚାଲିବାରେ execute କରିବାରେ ତାଙ୍କୁ ବାଧ୍ୟତା  
wait କରିବାରେ ହେଁ । (Forcefully stop କରି, ହାରିବାର)

## wait() recap:

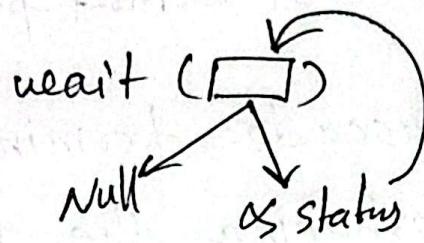
Parent waits until all of its children complete execution.

### ↳ Parameters:

① wait() → Null

② wait(&a) → address(status)

\* Cache: store the temporary data.



→ child

## Process Termination :

① exit() → when process executes its last statement it asks the operating system to delete it using exit()

↓  
i) Returns [status] → wait()

↳ status data from child to parent

↓  
ii) Resources → release.

↳ deallocated by OS.

## ② Abort() :

↳ Parent might terminate the execution of child process.

why abort is used?

- Child has exceeded resources allocation.
- Task assigned to child no longer needed.
- Parent is exiting. (OS will not allow to continue child without parent)

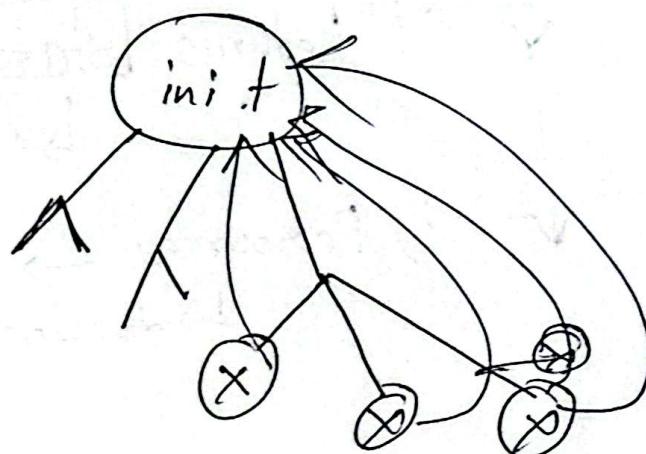
## ③ Abort():

↳ i) Cascade termination } if a process terminates  
} children must be terminated  
} ii) Reshaping the head }

i) Cascading : All process & subsequent process gets terminated → (child/grandchild) etc.

ii) Reshaping the head :

↳ 250 8(?) child 20  
Parent on(?) , 2STAT child  
↳ 254T intit (root)  
→ reach T?D,  
ie. it gets reshaped.



Parent → wait for child to terminate soon, the call returns status info and id of the terminated process.  
A pid = wait(& status)

⑤ if no parent waiting (no wait())

↳ process is a zombie

⑥ if parent is terminated without wait(),

↳ process is an orphan

↳ Parent done but didn't wait for child.

Zombie situation remedy: wait() should be in parent.

## IPC: (Interprocess Communication)

How two process communicate with each other?

↳ a shared memory or buffer.

1) Independent: [cannot affect/affect other process]  
[doesn't share data]

2) cooperating: [can affect/affected by other process]  
[Share data]

2) Process cooperation:

i) Information sharing: share data

ii) Computation speedup: for faster comm, breaks into subtask

iii) Modularity: separate process or threads

iv) Convenience.

→ IPC is a mechanism to exchange data & info among other processes.

Two fundamental model of IPC

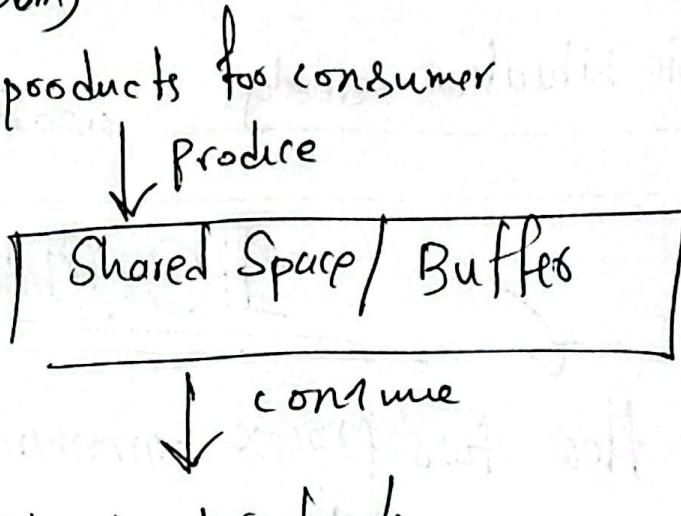
1) Shared Memory

2) Message passing

1) Shared memory:

(Producer - Consumer problem)

Producer: produces products for consumer



Consumer: consumes products.

Message passing system:

→ If P & Q wants to communicate, they must send messages to & receive messages from each other.

→ A communication link must exist b/w P & Q.