

# **STA 141A – Fundamentals of Statistical Data Science**

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## **Section 4: Basics in probability theory**

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## **SECTION 4: BASICS IN PROBABILITY THEORY**

## Section 1: Overview

### 1 Section 4: Basics in probability theory

- Section 4.1: Probability measure and random variables
- Section 4.2: PMF/PDF and CDF
- Section 4.3: Some distributions
- Section 4.4: Expected value
- Section 4.5: Variance and covariance
- Section 4.6: Conditional probability and independence

The prereq for this class is either STA 108 (regression) or STA 106 (ANOVA), so I expect you have already learned everything in this slide deck.

- If you need a refresher on probability, you can refer to this free textbook:  
<https://www.probabilitycourse.com/>

## **SECTION 4: BASICS IN PROBABILITY THEORY**

### **SECTION 4.1: PROBABILITY MEASURE AND RANDOM VARIABLES**

## Section 4.1 – Probability measure - Motivation

Probability is a way to quantify randomness and/or uncertainty.

- e.g., coin flips, dice rolls, stocks, weather.
- Rules of probability should be intuitive and self-consistent.
- Self-consistent: the rules shouldn't lead to contradictions.
- Thus these rules must be constructed in a certain way.
- Suppose we want to assign a probability to each event in a set of possible events.
- We would like, at the very least:
  - 1. each probability to be a value between 0 and 1 (inclusive)
  - 2. the probability assigned to the full set of events to be 1
  - 3. the probability assigned to the empty set to be 0
- We need more restrictions to ensure self-consistency.

The following definition will lead to intuitive and self-consistent rules of probability.

## Section 4.1 – Probability measure - Definition

### Definition 1: Probability measure $P(\cdot)$

For a nonempty set  $\Omega$ , the set function  $P: \Omega \rightarrow [0, 1]$  is a *probability measure*, if

- $P(\Omega) = 1$ , “Omega”
- for any pairwise disjoint sets  $A_1, A_2, \dots \subseteq \Omega$  (i.e.  $A_i \cap A_j = \emptyset$  for all  $i, j$  with  $i \neq j$ ), holds:

$$P\left(\bigcup_{i \in \mathbb{N}} A_i\right) = \sum_{i \in \mathbb{N}} P(A_i). \quad (1)$$

union  
empty set

This definition fulfills the three properties from the previous slide:

- $P(\Omega) = 1$ : the probability of the biggest possible set is equal to 1.
- Property (1) allows us to add probabilities of disjoint sets.
  - ▶ Disjoint means having no shared elements.
  - ▶ (Property (1) is called the *countable additivity* property.)

## Section 4.1 – Probability measure - Properties

Definition 1 implies the following additional properties:

### Properties of $P(\cdot)$

With  $\emptyset$  being the empty set, with some sets  $A, B \subset \Omega$ , and with  $A^c = \Omega \setminus A$  denoting the complement of  $A$ , holds,

- i)  $P(\emptyset) = 0;$
- ii)  $P(A \cup B) = P(A) + P(B)$  if  $A \cap B = \emptyset$ ;
- iii)  $P(A^c) = 1 - P(A);$
- iv)  $P(B \setminus A) = P(B) - P(A)$  if  $A \subseteq B$ ;
- v)  $P(A) \leq P(B)$  if  $A \subseteq B$ .

↑  
"A complement"

(Pictures)

iv)



## Section 4.1 – Random variables - Notion

Probability measures allow us to characterize the "randomness" of events.

- But we are often interested in more than just probabilities. For example:
  - ▶ the number of heads from three (independent) flips of some coin
  - ▶ the sum of the faces after throwing two dice
  - ▶ the lifetime of a battery
- We call each of these a *random variable* because they take on different values based on random events.
- The probability that a random variable is a certain value will depend on the probabilities of individual events.

## **SECTION 4: BASICS IN PROBABILITY THEORY**

### **SECTION 4.2: PMF/PDF AND CDF**

## Section 4.2 – Motivation

When doing probability calculations, rather than use probability measures (which are functions of sets), it is often easier to describe a probability distribution using functions of single variables

1. PMF/PDF
2. CDF

## Section 4.2 – PMF/PDF - concept

The idea behind a PMF/PDF is to assign probabilities to the possible values of a random variable.

- The concept is different for discrete and continuous random variables.

## Section 4.2 – PMF/PDF - discrete and continuous case

A random variable  $X$  is *discrete* if its range is finite or countably infinite.

- Examples:

1. number of heads after two coin flips,
2. number of coin flips needed before a heads turns up.

- Here probabilities can be assigned to each realizable value. Examples:

1. For  $\{0, 1, 2\}$  (finite), we can assign probabilities  $1/4, 1/2$ , and  $1/4$ .
2. For  $\mathbb{N}$  (countably infinite), we can assign probabilities  $(1/2)^k$  to each  $k \in \mathbb{N}$ .

- The *probability mass function* (PMF)  $f_X$  of a discrete random variable  $X$  assigns probabilities to each realizable value of  $X$ . Examples:

1.  $f_X(0) = 1/4, f_X(1) = 1/2$ , and  $f_X(2) = 1/4$ .
2.  $f_X(k) = (1/2)^k$  for each  $k \in \mathbb{N}$ .

Here  $f_X(a)$  is “the probability that  $X$  equals  $a$ .”

- The probability  $P(X \in A)$  that  $X$  lies in a set  $A$  can be calculated by

$$P(X \in A) = \sum_{a \in A} f_X(a), \quad \text{with} \quad f_X(a) := P(X = a). \quad (2)$$

- It is common to plot the PMF.

## Section 4.2 – PMF/PDF - discrete and continuous case

A random variable  $X$  is *continuous* if its range is uncountably infinite.

- Examples: the lifetime of a battery, the lifetime of a person, the time it takes you to finish the first midterm exam
- For any value in the range of a continuous random variable  $X$ , the probability that  $X$  is that value must be zero. Why?
  - ▶ If uncountably many values are assigned positive probability, the sum of those values would then be infinity!
- For a continuous random variable  $X$ , at any value  $a$  we have  $\underline{P(X = a) = 0}$ .
- The *probability density function* (PDF)  $f_X$  of a continuous random variable  $X$  describes how likely it is for  $X$  to lie <sup>in</sup> ~~in~~ a set  $A$  of values:

$$\underline{P(X \in A)} = \int_A f_X(s) ds. \quad (3)$$

- It is common to plot the PDF.

## Section 4.2 – PMF/PDF - discrete and continuous case

From the properties of probability measures, it follows that any PMF  $f_X$  of a discrete random variable  $X$  must satisfy both

1.  $f_X(x) \geq 0$  for all  $x$ , and
- 2.  $\sum_{\text{all } x} f_X(x) = 1.$

Similarly, it follows that any PDF  $f_X$  of a continuous random variable  $X$  must satisfy both

1.  $f_X(x) \geq 0$  for all  $x$ , and
- 2.  $\int_{\text{all } x} f_X(x) dx = 1.$

## Section 4.2 – CDF

The *cumulative distribution function* (CDF) of a random variable  $X$  is the function  $F_X: \mathbb{R} \rightarrow [0, 1]$  defined by

$$F_X(a) := P(X \leq a), \quad a \in \mathbb{R}. \quad (4)$$

This is “the probability that  $X$  is less than or equal to  $a$ .”

- Definition holds regardless of whether  $X$  is continuous or discrete.
- In the discrete case – recall Eq. (2) – holds for any  $a \in \mathbb{R}$ ,

$$F_X(a) = \sum_{s \leq a} f_X(s).$$

- In the continuous case – recall Eq. (3) – holds for any  $a \in \mathbb{R}$ ,

$$F_X(a) = \int_{-\infty}^a f_X(s) \, ds.$$

- From the definition in Eq. (4) come the following properties:
  1. The function  $F_X$  is (right-continuous) and monotonically increasing,
  2.  $\lim_{a \rightarrow -\infty} F_X(a) = 0$ ,
  3.  $\lim_{a \rightarrow \infty} F_X(a) = 1$ .
- For any  $a, b \in \mathbb{R}$  with  $b > a$  holds,

$$P(a < X \leq b) = F_X(b) - F_X(a).$$

## Section 4.2 – CDF - relationship to PMFs

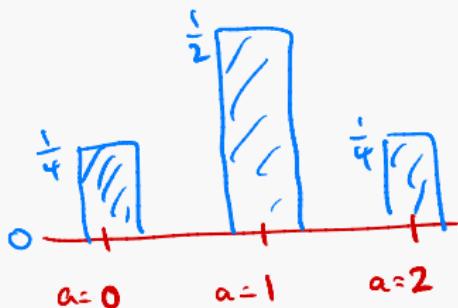
Discrete random variables

PMF

$P(X=a)$

CDF

$P(X \leq a)$

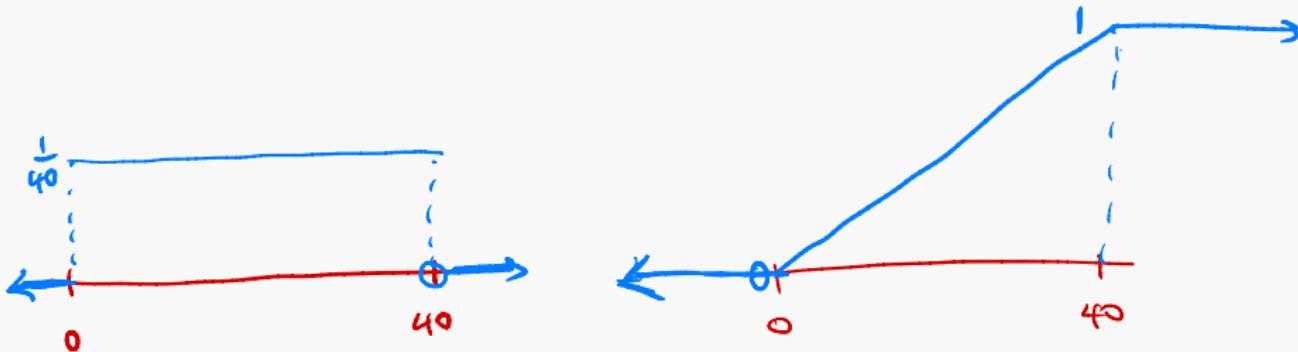


## Section 4.2 – CDF - relationship to PDFs

Continuous random variables

PDF  $f_x(a)$

CDF  $P(X \leq a) = \int_{-\infty}^a f_x(s)ds$



## **SECTION 4: BASICS IN PROBABILITY THEORY**

### **SECTION 4.3: SOME DISTRIBUTIONS**

## Section 4.3 – Discrete case - Uniform distr.

A random variable  $X$  with values in a finite set  $M$  is *uniformly distributed* if each element in  $M$  has the same probability:

$$P(X = k) = \frac{1}{\#M} \quad \text{for all } k \in M$$

- Such distributions occur when all possible outcomes are equally likely.
- We write  $X \sim U(M)$  or  $X \sim \text{Unif}(M)$ .
- Nine random draws in R:

```
sample(c(1,2,3,4,5,6), size=9, replace=TRUE)
```

## Section 4.3 – Discrete case - Bernoulli distr.

A random variable  $X$  is *Bernoulli* distributed with parameter  $p \in (0, 1)$ , if  $P(X = 1) = p$  and  $P(X = 0) = 1 - p$ .

- For when our random experiment has only two possible outcomes ("success" and "failure").
- Example: flip a coin with probability  $p$  of heads ("success"). Is it heads?
- We write  $X \sim Ber_p$  or  $X \sim Bern(p)$ .
- Nine random draws in R: `rbinom(n=9, size=1, prob=1/3)`

## Section 4.3 – Discrete case - Binomial distr.

A random variable  $X$  is *Binomial* distributed with parameters  $n \in \mathbb{N}$  and

$p \in (0, 1)$  if

$$P(X = k) = \binom{n}{k} p^k (1-p)^{n-k} \quad \text{for all } k = 0, \dots, n.$$

$\frac{n!}{k!(n-k)!}$  ↘  $\begin{matrix} \text{HTT} \\ \text{THT} \\ \text{TTH} \end{matrix}$   $\binom{n}{k} = \binom{3}{1} = \frac{3!}{(1)(2)} = 3$  outcomes with 1 success  
 $\binom{n}{k}$  ↘  $2^3$  total outcomes

- We think of  $n$  as the number of experiments and  $p$  the success probability.  
In the above equation,  $k$  is the number of successes.
- For measuring the probability of the number of successes of  $n$  independent Bernoulli experiments with parameter  $p$ .
- Example: flip a coin  $n$  times, each flip with probability  $p$  of heads ("success"). How many heads?
- We write  $X \sim \text{Bin}_{n,p}$  or  $X \sim \text{Bin}(n, p)$ .
- A random draw in R: **rbinom(n=3, size=1, prob=0.25) |> sum()**

## Section 4.3 – Continuous case - Uniform distr.

A random variable  $X$  is *uniformly* distributed on an interval  $M = (a, b)$ , with  $b > a$ , if the PDF has the form

$$f_X(x) = \begin{cases} \frac{1}{b-a} & \text{for all } x \in (a, b), \\ 0 & \text{otherwise} \end{cases} \quad \int_a^b \frac{1}{b-a} dx = 1$$

- Such distributions occur when all (uncountably many) possible outcomes are equally likely.
- The interval  $M$  can also instead be  $[a, b]$ , or  $(a, b]$ , or  $[a, b]$ .
- Here we also write  $X \sim U(M)$  or  $X \sim \text{Unif}(M)$ .
- Nine random draws in  $(3, 5)$  in R: `runif(n=9, min=3, max=5)`

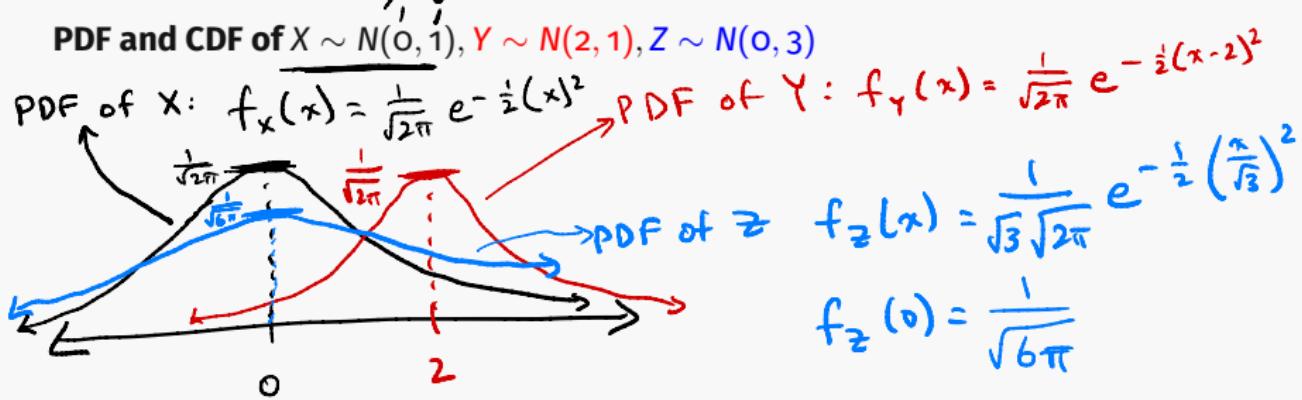
## Section 4.3 – Continuous case - Normal distr.

A random variable  $X$  is *normally* distributed with parameters  $\mu \in \mathbb{R}$  and  $\sigma^2 > 0$ , if the PDF has the form

$$f_X(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}(\frac{x-\mu}{\sigma})^2} \quad \text{for all } x \in \mathbb{R}. \quad \begin{matrix} \uparrow \\ \text{"mu"} \end{matrix} \quad \begin{matrix} \uparrow \\ \text{"sigma squared"} \end{matrix}$$

- This distribution appears often in this class, in future classes, and in life!
- We write  $X \sim N(\mu, \sigma^2)$ . We also call it *Gaussian* distributed.
- Thereby,  $E(X) = \mu$  (location parameter), and  $\text{Var}(X) = \sigma^2$  (squared scale).
- If  $X \sim N(0, 1)$ , the distribution of  $X$  is said to be *standard normal*.
- Nine random draws in R: `rnorm(n=9, mean=2, sd=1)`  $N(2, 1^2)$

PDF and CDF of  $X \sim N(0, 1)$ ,  $Y \sim N(2, 1)$ ,  $Z \sim N(0, 3)$



## **SECTION 4: BASICS IN PROBABILITY THEORY**

### **SECTION 4.4: EXPECTED VALUE**

## Section 4.4 – Expected value - Introduction

The expected value of a random variable is the weighted average of all of its values, where the weights are the probabilities that these values occur.

### Definition 2: Expected value $E(\cdot)$

Let  $X$  be a random variable. Then, the *expected value* of  $X$  is in the discrete case and in the continuous case (given the PDF  $f_X$ ) is defined as

$$E(X) = \sum_{\text{all } k} \underbrace{P(X = k)}_{\text{weight}} \cdot \underbrace{k}_{\text{value}} \quad \text{resp.} \quad E(X) = \int_{\text{all } s} \underbrace{f_X(s)}_{\text{weight}} \cdot \underbrace{s}_{\text{value}} ds. \quad (5)$$

*discrete*   *continuous*

- The expected value of a random variable sometimes does not exist if, for example, the random variable is continuous and the weights are "large" for large values of the random variable (e.g.  $E(X) = \int_1^\infty \frac{1}{s^2} \cdot s ds = \infty$ ).

## Section 4.4 – Expected value - Calculating expected value by hand

Calculate  $E(X)$  with PDF  $f_x(a) = \frac{3}{7}a^2$  where  $a \in [1, 2]$

$$E(X) = \int_1^2 f_x(a) a \ da$$

$$= \int_1^2 \frac{3}{7} a^2 a \ da$$

$$= \frac{3}{7} \int_1^2 a^3 da$$

$$= \frac{3}{7} \left. \frac{a^4}{4} \right|_{a=1}^{a=2}$$

$$= \frac{3}{7} \left[ \frac{2^4}{4} - \frac{1^4}{4} \right]$$

$$= \frac{3}{7} \frac{15}{4} = \boxed{\frac{45}{28}}$$

## Section 4.4 – Expected value - Calculation tools

### Properties of $E(\cdot)$

Let  $c \in \mathbb{R}$  be a constant, and let  $X, Y$  be random variables for which their expected values  $E(X)$  and  $E(Y)$  exists. Then, the following rules hold.

- i)  $E(c) = c;$
- ii)  $E(cX) = cE(X);$
- iii)  $E(X + Y) = E(X) + E(Y).$

**Example with**  $c = 2, E(X) = 1, E(Y) = 5$

i)  $E(2) = 2$

ii)  $E(2X) = 2E(X) = 2$

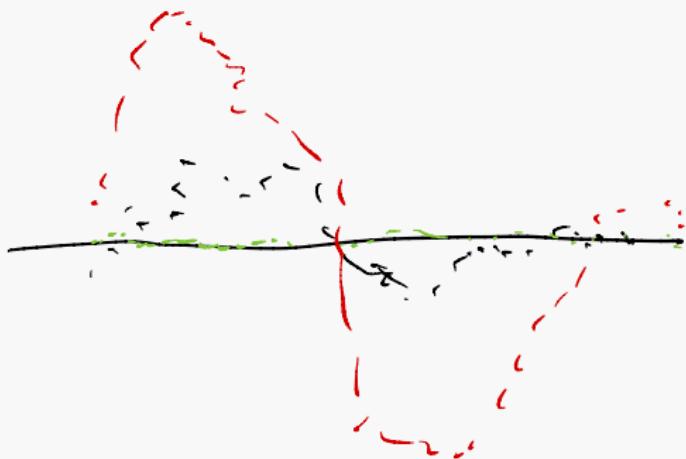
iii)  $E(X+Y) = E(X) + E(Y) = 1 + 5 = 6$   
 $E X + E Y$

## **SECTION 4: BASICS IN PROBABILITY THEORY**

### **SECTION 4.5: VARIANCE AND COVARIANCE**

## Section 4.5 – Variance - Introduction

**Heuristics** "How much values vary about their mean"

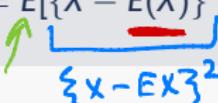


## Section 4.5 – Variance - Definition and properties

The variance of a random variable is the expected squared deviation of its values to its expected value.

### Definition 3: Variance $\text{Var}(\cdot)$

Let  $X$  be a random variable with  $E(X^2) < \infty$ . Then the *variance* of  $X$  is defined as

$$\text{Var}(X) := E[\{X - E(X)\}^2]. \quad (6)$$


Think of  $\text{Var}(X)$  as “how much  $X$  varies about its mean.” We can deduce:

- $\text{Var}(X) \geq 0$ .
- $\text{Var}(X) = 0 \Rightarrow X$  is constant.
- The variance of  $X$  can also be calculated as

$$\text{Var}(X) = E(X^2) - (E(X))^2. \quad (7)$$

## Section 4.5 – Variance - Calculation tools

### Properties of $\text{Var}(\cdot)$

Let  $c \in \mathbb{R}$  be a constant, and let  $X$  be a random variable with  $E(X^2) < \infty$ . Then

- i)  $\text{Var}(c) = 0$ ;
- ii)  $\text{Var}(X + c) = \text{Var}(X)$ ;
- iii)  $\text{Var}(cX) = c^2 \text{Var}(X)$ ;

Recall intuition:  $\text{Var}(X)$  is “how much  $X$  varies about its mean.”

**Example with**  $c = 5$ ,  $\text{Var}(X) = 1$ ,  $\text{Var}(Y) = 2$ .

i)  $\text{Var}(5) = 0$

ii)  $\text{Var}(X+5) = \text{Var}(X) = 1$

iii)  $\text{Var}(5X) = 25 \text{Var}(X) = 25$

## Section 4.5 – Covariance and correlation - Motivation

Expected value and variance help characterize the distribution of a single random variable  $X$ .

Now suppose we want to characterize the relationship between two random variables  $X$  and  $Y$ .

- A complete characterization requires assigning probabilities to every possible pair of values that  $(X, Y)$  could be.
- Simpler characterizations are the *covariance* and *correlation* of  $X$  and  $Y$ .

## Section 4.5 – Covariance - Introduction

### Heuristics

## Section 4.5 – Covariance - Definition and properties

### Definition 4: Covariance $\text{Cov}(\cdot, \cdot)$

Let  $X, Y$  be random variables with  $E(X^2), E(Y^2) < \infty$ . Then the covariance between  $X$  and  $Y$  is defined as

$$\text{Cov}(X, Y) := E\left\{ [X - E(X)][Y - E(Y)] \right\}. \quad (8)$$

*"centered Y"*  
*"centered X"*

- The covariance between  $X$  and  $Y$  can also be calculated as

$$\underline{\text{Cov}(X, Y) = E(XY) - E(X)E(Y)}. \quad (9)$$

- We say  $X$  and  $Y$  are *uncorrelated* if  $\text{Cov}(X, Y) = 0$ . Then  $X$  and  $Y$  have no linear relationship, and  $\boxed{E(XY) = E(X)E(Y)}$ .
- $\text{Cov}(X, Y) > 0$  indicate a positive linear relationship between  $X$  and  $Y$ .
- $\text{Cov}(X, Y) < 0$  indicate a negative linear relationship between  $X$  and  $Y$ .
- Covariance is symmetric:  $\text{Cov}(X, Y) = \text{Cov}(Y, X)$ .

## Section 4.5 – Correlation coefficient

$$X \sim N(0,1) \quad \rho(X,Y) = -1$$
$$Y = -X$$

$$X \sim \text{Unif}(0,1) \quad \rho(X,Y) = 1$$
$$Y = 2X$$

### Definition 5: Correlation coefficient $\rho(\cdot, \cdot)$

Let  $X, Y$  be random variables with  $E(X^2), E(Y^2) < \infty$ . Then, the *correlation coefficient* between  $X$  and  $Y$  is defined as, provided  $\text{Var}(X) > 0$  and  $\text{Var}(Y) > 0$ ,

$$\rho(X, Y) := \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}(X)} \sqrt{\text{Var}(Y)}} \in [-1, 1]. \quad (10)$$

- $\rho(X, Y) = 0 \Rightarrow$  between  $X$  and  $Y$  is no linear relationship.
- $\rho(X, Y) = -1 (1) \Rightarrow$  all values of  $X$  and  $Y$  lie on a line with negative (positive) slope.
- If  $\rho(X, Y)$  is close to  $-1 (1)$ , there is a strong negative (positive) linear relationship between  $X$  and  $Y$ .

## Section 4.5 – Variance and covariance - More calculation tools

### Properties of $\text{Var}(\cdot)$ and $\text{Cov}(\cdot, \cdot)$

Let  $c \in \mathbb{R}$  be a constant, and let  $X, Y, Z$  be random variables with  $E(X^2) < \infty$ ,  $E(Y^2) < \infty$ , and  $E(Z^2) < \infty$ . Then

iv)  $\text{Var}(X) = \text{Cov}(X, X)$

v)  $\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y) + 2\text{Cov}(X, Y)$

vi)  $\text{Cov}(X, Y) = \text{Cov}(Y, X)$

vii)  $\text{Cov}(X + Y, Z) = \text{Cov}(X, Z) + \text{Cov}(Y, Z)$  and  $\text{Cov}(cX, Z) = c\text{Cov}(X, Z)$

(Property vii says  $\text{Cov}(\cdot, \cdot)$  is linear in its first argument. Because  $\text{Cov}(\cdot, \cdot)$  is symmetric, it is also linear in its second argument. Thus we call it *bilinear*.)

**Example with**  $c = 5, \text{Var}(X) = 1, \text{Var}(Y) = 2, \text{Cov}(X, Y) = 1/3$

a bilinear function

$$\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y) + 2 \cdot \text{Cov}(X, Y) = 1 + 2 + 2 \cdot \frac{1}{3} = 3 \frac{2}{3} = \frac{11}{3}$$

$$\begin{aligned}\text{Var}(2X + Y) &\stackrel{?}{=} \text{Var}(2X) + \text{Var}(Y) + 2 \cdot \text{Cov}(2X, Y) \\ &= 4\text{Var}(X) + 2 + 4 \cdot \text{Cov}(X, Y) \\ &= 4 \cdot 1 + 2 + 4 \cdot \frac{1}{3} = 6 + \frac{4}{3} = \frac{22}{3}\end{aligned}$$

more examples

## SECTION 4: BASICS IN PROBABILITY THEORY

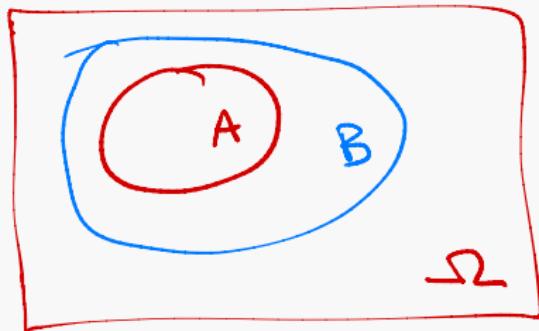
### SECTION 4.6: CONDITIONAL PROBABILITY AND INDEPENDENCE

$$\begin{aligned}\text{Var}(X - 2Y) &= \text{Var}(X) + \underbrace{\text{Var}(-2Y)}_{(-2)^2 \text{Var}(Y)} + \underbrace{\text{Cov}(X, -2Y)}_{-2 \text{Cov}(X, Y)} \\ &= 1 + 4 \cdot 2 - 2 \cdot 1_3 = 9 - \frac{2}{3} = \boxed{\frac{25}{3}}\end{aligned}$$

$$\begin{aligned}\text{Cov}(X+Y, Z+Y) &= \underbrace{\text{Cov}(X, Z+Y)}_{\text{Cov}(X, Z) + \text{Cov}(X, Y)} + \underbrace{\text{Cov}(Y, Z+Y)}_{\text{Cov}(Y, Z) + \underbrace{\text{Cov}(Y, Y)}_{\text{Var}(Y)}}\end{aligned}$$

## Section 4.6 – Conditional probability - Introduction

Heuristics



$$X \in \{0, 1, 2\}$$

$$P(X=0) = \frac{1}{4}$$

$$P(X=1) = \frac{1}{2}$$

$$P(X=2) = \frac{1}{4}$$

$$P(X=0 \mid X < 2) = P(X=0) \mid X=0 \text{ or } X=1)$$

$$= \frac{P(X=0)}{P(X=0 \text{ or } X=1)} = \frac{\frac{1}{4}}{\frac{1}{4} + \frac{1}{2}} = \frac{1}{3}$$

## Section 4.6 – Definition and properties

An event is a subset of the sample space  $\Omega$ . *“Omega”*

### Definition 6: Conditional probability

For events  $A, B \subseteq \Omega$ , the *conditional probability* of  $A$  given  $B$  is defined by

$$P(A|B) = \begin{cases} \frac{P(A \cap B)}{P(B)}, & \text{if } P(B) > 0, \\ 0, & \text{if } P(B) = 0. \end{cases} \quad (11)$$

- Events  $A$  and  $B$  are called *independent* if

$$\underline{P(A \cap B)} = \underline{P(A)} \underline{P(B)}. \quad (12)$$

Here knowing  $B$  provides no information about  $A$ , and vice versa.

- Equivalently, events  $A$  and  $B$  are independent if  $P(A|B) = P(A)$ .
- Random variables  $X$  and  $Y$  are called *independent* if for all sets  $A, B$  holds,

$$\underline{P(X \in A, Y \in B)} = \underline{P(X \in A)} \underline{P(Y \in B)}. \quad (13)$$

- Independent random variables are uncorrelated.
- But uncorrelated random variables are not necessarily independent!