1/1 point

- 1. The Lunar Lander is a continuous state Markov Decision Process (MDP) because:
  - $\bigcirc$  The state-action value Q(s,a) function outputs continuous valued numbers
  - The state contains numbers such as position and velocity that are continuous valued.
  - The reward contains numbers that are continuous valued
  - igcup The state has multiple numbers rather than only a single number (such as position in the x-direction)

**⊘** Correct

That's right!

1/1 point

- 2. In the learning algorithm described in the videos, we repeatedly create an artificial training set to which we apply supervised learning where the input x=(s,a) and the target, constructed using Bellman's equations, is  $y = \underline{\hspace{1cm}}$ ?
  - $igotimes y = R(s) + \gamma \max_{a'} Q(s',a')$  where s' is the state you get to after taking action a in state s
  - igcirc  $y=\max_{a'}Q(s',a')$  where s' is the state you get to after taking action a in state s
  - $\bigcirc y = R(s)$
  - igcup y = R(s') where s' is the state you get to after taking action a in state s

**⊘** Correct

1/1 point

- 3. You have reached the final practice quiz of this class! What does that mean? (Please check all the answers, because all of them are correct!)
  - The DeepLearning.AI and Stanford Online teams would like to give you a round of applause!

**⊘** Correct

What an accomplishment -- you made it!

**⊘** Correct

Andrew sends his heartfelt congratulations to you!

**⊘** Correct

You deserve to celebrate!

**⊘** Correct