Contest (1)

sol.cpp

```
#include <bits/stdc++.h>
using namespace std;

#define rep(i, a, b) for (int i = (a); i < (b); i++)
#define all(x) begin(x), end(x)
#define sz(x) int((x).size())
using ll = long long;
using pii = pair<int, int>;
using vi = vector<int>;

#ifdef LOCAL
auto& operator<<(auto&, pair<auto, auto>);
auto operator<<(auto& o, auto x) -> decltype(x.end(), o) {
  o << '{';
  for (int i = 0; auto y : x) o << ", " + !i++ * 2 << y;
  return o << '}';
}
auto& operator<<(auto& o, pair<auto, auto> x) {
  return o << '(' << x.first << ", " << x.second << ')';
}
void __print(auto... x) { ((cerr << ' ' << x), ...) << endl; }
#define debug(x...) cerr << "[" #x "]:", __print(x)
#else
#define debug(...) 2137
#endif

int main() {
  cin.tie(0)->sync_with_stdio(0);
}
```

.vimrc

```
set nu et ts=2 sw=2
filetype indent on
syntax on
colorscheme habamax
hi MatchParen ctermfg=66 ctermbg=234 cterm=underline
nnoremap ; :
nnoremap : ;
inoremap {<cr> {<cr>}<esc>O <bs>
```

Makefile

```
CXXFLAGS=-std=c++20 -Wall -Wextra -Wshadow
sol: sol.cpp
  g++ $(CXXFLAGS) -fsanitize=address,undefined -g -DLOCAL \
      sol.cpp -o sol
fast: sol.cpp
  g++ $(CXXFLAGS) -O2 sol.cpp -o fast
```

test.sh

```
#!/bin/bash
for((i=1;i>0;i++)) do
  echo "$i"
  echo "$i" | ./gen > int
  diff -w <(./sol < int) <(./slow < int) || break
done
```

hash.sh

```
#!/bin/bash
cpp -dD -P -fpreprocessed | tr -d '[:space:]'| md5sum |cut -c-6
```

.bashrc

```
alias rm='trash'
alias mv='mv -i'
alias cp='cp -i'
```

Grafy (2)

2.1 Przepływy

Dinic.h

Opis: Dinic ze skalowaniem. Należy ustawić zakres `it` w `flow` zgodnie z U.
Czas: $\mathcal{O}(nm \log U)$

```
struct dinic {
  struct edge {
    int to, rev;
    ll cap;
  };
  vi lvl, ptr, q;
  vector<vector<edge>> adj;
  dinic(int n) : lvl(n), ptr(n), q(n), adj(n) {}
  void add_edge(int u, int v, ll cap, ll rcap = 0) {
    int i = sz(adj[u]), j = sz(adj[v]);
    adj[u].push_back({v, j + (u == v), cap});
    adj[v].push_back({u, i, rcap});
  }
  ll dfs(int v, int t, ll f) {
    if (v == t || !f) return f;
    for (int& i = ptr[v]; i < sz(adj[v]); i++) {
      edge& e = adj[v][i];
      if (lvl[e.to] == lvl[v] + 1)
        if (ll p = dfs(e.to, t, min(f, e.cap))) {
          e.cap -= p, adj[e.to][e.rev].cap += p;
          return p;
        }
    }
    return 0;
  }
  ll flow(int s, int t) {
    ll f = 0; q[0] = s;
    for (int it = 29; it >= 0; it--) do {
      lvl = ptr = vi(sz(q));
      int qi = 0, qe = lvl[s] = 1;
      while (qi < qe && !lvl[t]) {
        int v = q[qi++];
        for (edge e : adj[v])
          if (!lvl[e.to] && e.cap >> it)
            q[qe++] = e.to, lvl[e.to] = lvl[v] + 1;
      }
      while (ll p = dfs(s, t, LLONG_MAX)) f += p;
    } while (lvl[t]);
    return f;
  }
};
```

GomoryHu.h

Opis: Tworzy drzewo gdzie min cut to minimum na ścieżce.
Czas: $\mathcal{O}(n)$ przepływów

```
struct edge { int u, v; ll w; };
vector<edge> gomory_hu(int n, const vector<edge>& ed) {
  vector<edge> t; vi p(n);
  rep(i, 1, n) {
    dinic d(n);
    for (edge e : ed) d.add_edge(e.u, e.v, e.w, e.w);
    t.push_back({i, p[i], d.flow(i, p[i])});
    rep(j, i + 1, n) if (p[j] == p[i] && d.lvl[j]) p[j] = i;
  }
  return t;
}
```

MCMF.h

Opis: MCMF z Dijkstrą. Jeżeli są ujemne krawędzie to przed puszczeniem `flow` w `pi` trzeba policzyć najkrótsze ścieżki z `s`.
Czas: $\mathcal{O}(Fm \log n)$

```
#include <ext/pb_ds/priority_queue.hpp>
const ll INF = 2e18;
struct MCMF {
  struct edge {
    int from, to, rev;
    ll cap, cost;
  };
  int n;
  vector<vector<edge>> adj;
  vector<ll> dst, pi;
  __gnu_pbds::priority_queue<pair<ll, int>> q;
  vector<decltype(q)::point_iterator> it;
  vector<edge*> p;
  MCMF(int _n) : n(_n), adj(n), pi(n), p(n) {}
  void add_edge(int u, int v, ll cap, ll cost) {
    int i = sz(adj[u]), j = sz(adj[v]);
    adj[u].push_back({u, v, j + (u == v), cap, cost});
    adj[v].push_back({v, u, i, 0, -cost});
  }
  bool path(int s, int t) {
    dst.assign(n, INF); it.assign(n, q.end());
    q.push({dst[s] = 0, s});
    while (!q.empty()) {
      int u = q.top().second; q.pop();
      for (edge& e : adj[u]) {
        ll d = dst[u] + pi[u] + e.cost - pi[e.to];
        if (e.cap && d < dst[e.to]) {
          dst[e.to] = d, p[e.to] = &e;
          if (it[e.to] == q.end())
            it[e.to] = q.push({-dst[e.to], e.to});
          else
            q.modify(it[e.to], {-dst[e.to], e.to});
        }
      }
    }
    rep(i, 0, n) pi[i] = min(pi[i] + dst[i], INF);
    return pi[t] != INF;
  }
  pair<ll, ll> flow(int s, int t, ll cap) {
    ll f = 0, c = 0;
    while (f < cap && path(s, t)) {
      ll d = cap - f;
      for (edge* e = p[t]; e; e = p[e->from])
        d = min(d, e->cap);
      for (edge* e = p[t]; e; e = p[e->from])
```

```
      e->cap -= d, adj[e->to][e->rev].cap += d;
    f += d, c += d * pi[t];
  }
  return {f, c};
 }
};
```

2.2 Grafy skierowane

SCC.h

Opis: Znajduje SCC w kolejności topologicznej.
Czas: $\mathcal{O}(n+m)$

```
struct SCC {
  int n, t = 0, cnt = 0;
  vector<vi> adj;
  vi val, p, st;
  SCC(int _n) : n(_n), adj(n), val(n), p(n, -1) {}
  void add_edge(int u, int v) { adj[u].push_back(v); }
  int dfs(int u) {
    int low = val[u] = ++t; st.push_back(u);
    for (int v : adj[u]) if (p[v] == -1)
      low = min(low, val[v] ?: dfs(v));
    if (low == val[u]) {
      for (int x = -1; x != u;)
        p[x = st.back()] = cnt, st.pop_back();
      cnt++;
    }
    return low;
  }
  void build() {
    rep(i, 0, n) if (!val[i]) dfs(i);
    rep(i, 0, n) p[i] = cnt - 1 - p[i];
  }
};
```

Matma (3)

3.1 Arytmetyka modularna

GCD.h

Opis: Rozszerzony algorytm Euklidesa.
Czas: $\mathcal{O}(\log\min(a,b))$

```
ll gcd(ll a, ll b, ll &x, ll &y) {
  if (!b) return x = 1, y = 0, a;
  ll d = gcd(b, a % b, y, x);
  return y -= a / b * x, d;
}
```

CRT.h

Opis: Chińskie twierdzenie o resztach.
Czas: $\mathcal{O}(\log\min(m,n))$

```
ll crt(ll a, ll m, ll b, ll n) {
  if (n > m) swap(a, b), swap(m, n);
  ll x, y, g = gcd(m, n, x, y);
  assert((a - b) % g == 0); // no solution
  x = (b - a) % n * x % n / g * m + a;
  return x < 0 ? x + m * n / g : x;
}
```

ModMul.h

Opis: Mnożenie i potęgowanie dwóch long longów modulo. Jest to wyraźnie szybsze niż zamiana na __int128.

```
using ull = uint64_t;
ull modmul(ull a, ull b, ull M) {
  ll ret = a * b - M * ull(1.L / M * a * b);
  return ret + M * (ret < 0) - M * (ret >= (ll)M);
}
ull modpow(ull b, ull e, ull mod) {
  ull ans = 1;
  for (; e; b = modmul(b, b, mod), e /= 2)
    if (e & 1) ans = modmul(ans, b, mod);
  return ans;
}
```

3.2 Liczby pierwsze

MillerRabin.h

Opis: Test pierwszości Millera-Rabina.

```
bool prime(ull n) {
  if (n < 2 || n % 6 % 4 != 1) return (n | 1) == 3;
  ull A[] = {2, 325, 9375, 28178, 450775, 9780504, 1795265022},
      s = __builtin_ctzll(n - 1), d = n >> s;
  for (ull a : A) {
    ull p = modpow(a % n, d, n), i = s;
    while (p != 1 && p != n - 1 && a % n && i--)
      p = modmul(p, p, n);
    if (p != n - 1 && i != s) return 0;
  }
  return 1;
}
```

PollardRho.h

Opis: Algorytm faktoryzacji rho Pollarda.
Czas: $\mathcal{O}(n^{1/4})$

```
ull pollard(ull n) {
  ull x = 0, y = 0, t = 30, prd = 2, i = 1, q;
  auto f = [&](ull x) { return modmul(x, x, n) + i; };
  while (t++ % 40 || __gcd(prd, n) == 1) {
    if (x == y) x = ++i, y = f(x);
    if ((q = modmul(prd, max(x, y) - min(x, y), n))) prd = q;
    x = f(x), y = f(f(y));
  }
  return __gcd(prd, n);
}
void factor(ull n, map<ull, int>& cnt) {
  if (n == 1) return;
  if (prime(n)) { cnt[n]++; return; }
  ull x = pollard(n);
  factor(x, cnt); factor(n / x, cnt);
}
```

Geometria (4)

4.1 Podstawy

Point.h

Opis: Podstawowy szablon do geometrii.

```
template<class T> int sgn(T x) { return (x > 0) - (x < 0); }
template<class T>
struct pt {
  T x, y;
  pt operator+(pt o) const { return {x + o.x, y + o.y}; }
  pt operator-(pt o) const { return {x - o.x, y - o.y}; }
  pt operator*(T a) const { return {x * a, y * a}; }
  pt operator/(T a) const { return {x / a, y / a}; }
  friend T cross(pt a, pt b) { return a.x * b.y - a.y * b.x; }
  friend T cross(pt p, pt a, pt b) {
    return cross(a - p, b - p); }
  friend T dot(pt a, pt b) { return a.x * b.x + a.y * b.y; }
  friend T dot(pt p, pt a, pt b) {
    return dot(a - p, b - p); }
  friend T abs2(pt a) { return a.x * a.x + a.y * a.y; }
  friend T abs(pt a) { return sqrt(abs2(a)); }
  auto operator<=>(pt o) const {
    return pair(sgn(x - o.x), sgn(y - o.y)) <=> pair(0, 0); }
  bool operator==(pt o) const {
    return sgn(x - o.x) == 0 && sgn(y - o.y) == 0; }
  friend auto& operator<<(auto& o, pt a) {
    return o << '(' << a.x << ", " << a.y << ')'; }
};
using P = pt<ll>;
```

AngleCmp.h

Opis: Sortuje punkty rosnąco po kącie z przedziału $(-\pi,\pi]$. Punkt $(0,0)$ ma kąt 0.

```
bool angle_cmp(P a, P b) {
  auto half = [](P p) { return sgn(p.y) ?: -sgn(p.x); };
  int A = half(a), B = half(b);
  return A == B ? sgn(cross(a, b)) > 0 : A < B;
}
```

LineDist.h

Opis: Najkrótsza odległość między punktem i prostą/odcinkiem.

```
auto line_dist(P p, P a, P b) {
  return abs(cross(p, a, b)) / abs(b - a);
}
auto seg_dist(P p, P a, P b) {
  if (sgn(dot(a, p, b)) <= 0) return abs(p - a);
  if (sgn(dot(b, p, a)) <= 0) return abs(p - b);
  return line_dist(p, a, b);
}
```

4.2 Wielokąty

ConvexHull.h

Opis: Otoczka wypukła w kierunku CCW.
Czas: $\mathcal{O}(n\log n)$

```
vector<P> convex_hull(vector<P> pts) {
  if (sz(pts) <= 1) return pts;
  sort(all(pts));
  vector<P> h(sz(pts) + 1);
  int s = 0, t = 0;
  for (int it = 2; it--; s = --t, reverse(all(pts)))
    for (P p : pts) {
      while (t >= s + 2 &&
          sgn(cross(h[t - 2], h[t - 1], p)) <= 0) t--;
      h[t++] = p;
    }
  return {h.begin(), h.begin() + t - (t == 2 && h[0] == h[1])};
}
```