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## **Education** \_

#### The University Of Southern California

CA, U.S.A

M.S. IN COMPUTER SCIENCE, GPA: 3.5

Aug. 2018 - Present

Related Courses: Foundation of artificial intelligence | Analysis of Algorithms | Deep Learning and its Applications

#### The University Of Hong Kong

Hong Kong

B.S. IN COMPUTER SCIENCE, GPA: 3.6

Sep. 2013 - Jun. 2018

Related Courses: Functional Programming | Computer Vision | Computer and communication networks | Modern Technologies on World Wide Web | Artificial Intelligence | Design and analysis of algorithms | Principles of programming languages

#### The University of North Carolina at Chapel Hill

NC, U.S.A

ONE-YEAR EXCHANGE STUDENT, IN COMPUTER SCIENCE, GPA: 3.87

Aug. 2016 - May. 2017

Related Courses: Introduction to machine learning | Advanced machine learning | Algorithms of motion

## Skills \_\_\_

#### **Programming language**

Advanced: Python, Java, C#, C++ | Intermediate: Haskell, PHP, SQL, JavaScript, HTML, CSS

- Python, C++: Primary language, working in open source project.
- Java, C#: Familiar with OOP design, Used on several projects/coursework.

#### **Tools**

ROS, ROS2, TENSORFLOW, KERAS, GIT, DOCKER, PROTOCOL BUFFERS, GRPC

## Experience \_\_\_\_\_

#### Amazon - AWS Robotics

CA, U.S.A

SDE INTERN

Jun. 2019 - Aug. 2019

- Designed and implemented features in ROS2 for AWS RoboMaker.

#### **Robotic Embedded Systems Laboratory - USC Robotics Research Lab**

CA, U.S.A

Oct. 2018 - Present

RESEARCH ASSISTANT

Implements reinforcement learning algorithms in TensorFlow.

Actively working on an open source reinforcement learning framework called Garage.
URL: https://github.com/rlworkgroup/garage

# Undergraduate Research at The University Of North Carolina at Chapel Hill (Prof. Dinesh Manocha)

NC, U.S.A

Undergraduate Research Assistant, working on crowd simulation and robot navigation

Sep. 2016 - May. 2017

- Automated unannotated crowd videos generation. Built with synthetic agents and real-world background using simulation tool and unreal engine 4.
- Experiment obstacle avoidance policies on a turtlebot.
- Report: https://ahtsan.github.io/CAalgo.pdf

### Undergraduate Research at The University Of Hong Kong (Dr. Kenneth Wong)

Hong Kong

Mar. 2016 - May. 2016

STUDENT IN HKU COMPUTER VISION GROUP

- Visualizing learning performance of deep learning models.
- Dynamic generation of deep learning models with high-level parameters.

## Undergraduate Research at The University Of North Carolina at Chapel Hill (Prof. Dinesh Manocha)

NC, U.S.A

VISITING STUDENT

June. 2015 - Sep. 2015

- Synthetic crowd dataset generation using multi-agent simulation tool and unreal engine 4.
- URL: http://gamma.cs.unc.edu/LCrowdV/

#### **Fundroots Creative Software Ltd.**

Hong Kong

Aug. 2016 - Aug.2018

- SOFTWARE ENGINEER
- · Worked on a trading system backend.
- Developed an Android mobile application.

## Projects \_\_\_\_

# Training Collision Avoidance Policy in Simulation through Deep Reinforcement Learning

HKU CS FINAL YEAR PROJECT

- Using Unreal Engine 4 to train a collision avoidance policy using state-of-the-art Deep Reinforcement Learning algorithm and machine learning frameworks.
- URL: https://ahtsan.github.io/rlbot/

#### **Generating Images with Few Shot Meta-Learning**

USC Course Project

 $\bullet \ \, \mathsf{Blog:} \, \mathsf{https:} / \mathsf{medium.com/@utkarshjp7/generating-images-with-few-shot-meta-learning-25bf1d301ab0\#0ff9}$ 

## **Honors & Awards** \_

2016	Rosita King Ho Scholarship, (Support academic outstanding student in oversea exchange)	Hong Kong
2015	The Arthur and Louise May Memorial Fund Scholarship, (Support academic outstanding	Hong Kong
	student in oversea research)	Hong Kong
2013	Sir Edward Youde Memorial Prizes, (Support academic outstanding students)	Hong Kong
2012	Silver Award, Asia International Mathematical Olympiad	Hong Kong

#### 11th Annual Undergraduate Research Symposium at UNC-CH

NC, U.S.A

 $\label{thm:condition} \textbf{Presenting "Synthetic Data for Crowd and Human Understanding"}$ 

Apr. 2017

• Introduced the use of synthetic data in crowd understanding. Talked about the advantages over conventional human labelling and how it improved pedestrian detection accuracy.

### **Publication**

# MixedPeds: Pedestrian Detection in Unannotated Videos using Synthetically Generated Human-agents for Training

Paper

Coauthor

2017

• Published in AAAI 2018

• URL: https://arxiv.org/abs/1707.09100

### LCrowdV: Generating Labeled Videos for Simulation-based Crowd Behavior

Paper 2016

COAUTHOR

- Published in ECCVW 2016 and Neurocomputing Journal
- URL: http://gamma.cs.unc.edu/LCrowdV/, https://doi.org/10.1016/j.neucom.2018.08.085

## Extracurricular Activity \_\_\_\_\_

#### **DARPA Robotic Challenge**

CA, U S.A

STUDENT MEMBER FOR HKU TEAM

• Involved in robot operation.

Jun. 2015