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Education _

The University Of Southern California

CA, U.S.A

M.S. IN COMPUTER SCIENCE

08/2018 - 05/2020

Related Courses: Machine Learning | Foundation of artificial intelligence | Analysis of Algorithms | Deep Learning and its Applications | Web Technologies | Robotics

The University Of Hong Kong

Hong Kong

B.S. IN COMPUTER SCIENCE

09/2013 - 05/2018

Related Courses: Machine Learning | Computer Vision | Computer and communication networks | Modern Technologies on World Wide Web | Artificial Intelligence | Design and analysis of algorithms | Principles of programming languages

The University of North Carolina at Chapel Hill

NC, U.S.A

ONE-YEAR VISITING STUDENT, COMPUTER SCIENCE

08/2016 - 05/2017

Related Courses: Introduction to machine learning | Advanced machine learning | Algorithms of motion

Skills

Programming language

 ${\tt Advanced: Python, C++ \, | \, Intermediate: \, Java, \, C, \, Haskell, \, SQL, \, JavaScript, \, HTML, \, CSS}$

Tools

ROS, ROS2, Unreal Engine 4, Kubernetes, TensorFlow, Git, Docker, Protocol Buffers, GRPC, AWS SERVICES

Experience _____

Cruise LLC CA, U.S.A

SENIOR SDE - SIMULATION

09/2024 - Present

Worked on Cruise's Scenario Generation toolkit, which the majority of the company has been using to create scenarios for validating
different autonomous driving behaviors and components.

Amazon Web Services CA, U.S.A

SDE | SDE II

06/2020 - 12/2021 | 12/2021 - 09/2024

- AWS RoboMaker 1) Contribute to the design and implementation of a feature that allows customers to manipulate physical simulation via ROS and Gazebo topics. Develop sample robot simulation applications for AWS RoboMaker demos in C++. 2) Worked on Github CI/CD integration with AWS, unit test, integration test and one-click installation scripts.
- AWS SageMaker Ground Truth synthetic data 1) Contribute to the design and implementation of multiple components for an AWS offering that procedural generates synthetic data for machine learning, with a cloud-based infrastructure that provides high availability and scalability. Involved Unreal Engine 4 and OpenCV post-processing. 2) Conduct internal proof-of-concept projects with internal and external customers, including Amazon Robin.
- AWS SimSpace Weaver 1) Expand the service to the GovCloud regions, involving infrastructural changes on the SDK packaging, publishing and testing workflow, as well as deployment pipeline.
 2) Deploy AWS CloudFront for service SDK artifacts and reduce deployment time by 94%.
- AWS Batch 1) Contribute to multi-container feature launch, allowing customers to efficiently process hundreds of thousands of batch and machine learning containerized computing jobs that consist of multiple containers on AWS, leveraging various kinds of scheduling and on-demand scaling mechanisms.
 2) Delivered an end-to-end AWS Batch security feature for AWS EKS, including design documentation, implementation, testing, and security review process.

Amazon Web Services CA, U.S.A

SDE INTERN 06/2019 - 09/2019

• AWS Robomaker — Contribute to the design and implementation of ROS2 topic statistics.

Robotic Embedded Systems Laboratory - USC Robotics Research Lab

CA, U.S.A

RESEARCH ASSISTANT 10/2018 - 05/2020

• Implement reinforcement learning algorithms in TensorFlow for an open source reinforcement learning framework – Garage (https://github.com/rlworkgroup/garage).

Undergraduate Research at The University Of North Carolina at Chapel Hill (Prof. Dinesh Manocha)

NC, U.S.A

Undergraduate Research Assistant, working on novel crowd simulation.

09/2016 - 05/2017

- Automated unannotated crowd videos generation. Built with synthetic agents and real-world background using simulation tool and unreal engine 4.
- Synthetic crowd dataset generation using multi-agent simulation tool and unreal engine 4.
- URL: http://gamma.cs.unc.edu/LCrowdV/

Projects _

Training Collision Avoidance Policy in Simulation through Deep Reinforcement Learning

HKU CS FINAL YEAR PROJECT

- Used Unreal Engine 4 to train a collision avoidance policy using state-of-the-art Deep Reinforcement Learning algorithm and machine learning frameworks.
- URL: https://ahtsan.github.io/rlbot/

Generating Images with Few Shot Meta-Learning

USC COURSE PROJECT

• Blog: https://medium.com/@utkarshjp7/generating-images-with-few-shot-meta-learning-25bf1d301ab0#0ff9

Honors & Awards ____

2016	Rosita King Ho Scholarship , (Support academic outstanding student in oversea exchange)	Hong Kong
2015	The Arthur and Louise May Memorial Fund Scholarship, (Support academic outstanding	Hong Kong
	student in oversea research)	
2013	Sir Edward Youde Memorial Prizes, (Support academic outstanding students)	Hong Kong
2012	Silver Award, Asia International Mathematical Olympiad	Hong Kong

11th Annual Undergraduate Research Symposium at UNC-CH

NC, U.S.A

Presenting "Synthetic Data for Crowd and Human Understanding"

2017

• Introduced the use of synthetic data in crowd understanding. Talked about the advantages over conventional human labelling and how it improved pedestrian detection accuracy.

Publication

MixedPeds: Pedestrian Detection in Unannotated Videos using Synthetically Generated Human-agents for Training

Paper

COAUTHOR

COAUTHOR

2017

- Published in AAAI 2018
- URL: https://arxiv.org/abs/1707.09100

LCrowdV: Generating Labeled Videos for Simulation-based Crowd Behavior

Paper

2016

- Published in ECCVW 2016 and Neurocomputing Journal
- URL: http://gamma.cs.unc.edu/LCrowdV/, https://doi.org/10.1016/j.neucom.2018.08.085

Extracurricular Activity _____

DARPA Robotic Challenge

CA, U S.A

STUDENT MEMBER FOR HKU TEAM

2015