

Problem (Problem 1): Prove that if $f: M \rightarrow N$ is smooth, and L is a k -codimensional submanifold of N that is transverse to f , then $f^{-1}(L)$ is either empty or a submanifold of M with codimension k .

Solution: If L is not contained in $f(M)$, then $f^{-1}(L)$ is clearly empty. Therefore, we focus on the case where $f^{-1}(L)$ is not empty.

Let L be transverse to f , $q \in L$, and $p \in M$ such that $f(p) = q$. We observe that $T_q L + D_p F(T_p M) = T_q N$, so any vector in $T_q N$ can be written (not necessarily uniquely) as an element of $D_p F(T_p M)$ and $T_q L$. Next, we observe that, if we take a coordinate chart for q in U such that $\varphi(U) \cong \mathbb{R}^k$, then by the Regular Value Theorem, we may select φ such that $L \cap U = \varphi^{-1}(0)$. This follows from the assumption that L has codimension k .

Now, if we can show that 0 is a regular value for $\varphi \circ f$, then $(\varphi \circ f)^{-1}(0) = f^{-1}(L) \cap f^{-1}(U)$, meaning that $f^{-1}(L)$ is a submanifold of M with codimension k . First, since 0 is a regular value for φ , it follows that if $v \in T_0 \mathbb{R}^k$, then there is some $w \in T_q N$ such that $D_q \varphi(w) = v$. Since f is transverse to L , there is $w_1 \in T_q L$ and $w_2 \in T_p M$ such that $w = w_1 + D_p F(w_2)$. We observe that, since φ is constant on L , we have $D_q \varphi(w_1) = 0$, so that

$$\begin{aligned} D_p(\varphi \circ f)(w_2) &= D_q \varphi \circ D_p F(w_2) \\ &= D_q \varphi(w_1 + D_p F(w_2)) \\ &= D_q \varphi(w) \\ &= v, \end{aligned}$$

so 0 is a regular value for $\varphi \circ f$.

Problem (Problem 2): Let $GL_n(\mathbb{R})$ denote the space of invertible $n \times n$ matrices over \mathbb{R} , let $SL_n(\mathbb{R})$ denote the matrices of determinant one, and let $O(n)$ be the orthogonal group.

- Prove that we may identify the tangent space of $GL_n(\mathbb{R})$ at the identity with $n \times n$ matrices over \mathbb{R} .
- Prove that the tangent space of $SL_n(\mathbb{R})$ at the identity consists of matrices of trace zero.
- Prove that the tangent space of $O(n)$ at the identity consists of skew-symmetric matrices. What is the dimension of $O(n)$?
- Show that $SL_n(\mathbb{R})$ and $O(n)$ do not intersect transversely at the identity.

Solution:

- Let $A \in Mat_n(\mathbb{R})$, and consider a path through the identity given by $\gamma(t) = I + tA$. Since the determinant is a smooth function, and $\det(I) = 1$, we have that for a small $\varepsilon > 0$ there is δ , such that $|\det(I + tA) - 1| < \varepsilon$ whenever $|t| < \delta$. In particular, this means that the tangent space at the identity of $GL_n(\mathbb{R})$ consists of all matrices.
- We let $\gamma(t) = I + tA$ be a curve in $SL_n(\mathbb{R})$, so that $\gamma'(0) = A$ is an element of the tangent space of $SL_n(\mathbb{R})$ at the identity. We observe that $\det(\gamma(t)) = 1$ for all (sufficiently small) t , so by chain rule, we find that

$$\begin{aligned} 0 &= \left. \frac{d}{dt} \right|_{t=0} \det(\gamma(t)) \\ &= D_{\gamma(0)} \det(\gamma'(0)) \\ &= D_I \det(A). \end{aligned}$$

Therefore, we must evaluate what $\det'(I)(A)$ yields. Toward this end, we see that

$$D_I \det(A) = \lim_{t \rightarrow 0} \frac{\det(I - tA) - 1}{t}$$

$$= \lim_{t \rightarrow 0} \frac{t^n \det\left(\frac{1}{t}I - A\right) - 1}{t}.$$

Observe that the expression $\det\left(\frac{1}{t}I - A\right)$ is the characteristic polynomial of A in $\frac{1}{t}$. This means that the $\left(\frac{1}{t}\right)^{n-1}$ term is equal to $\text{tr}(A)$, so that $D_I \det(A) = \text{tr}(A)$. Thus, we find that A is traceless.

(c) If $\gamma(t) = I + tA$ is a curve in $O(n)$, then then we have that

$$\begin{aligned} (I + tA)^T(I + tA) &= I \\ I + t(A^T + A) + t^2(A^T A) &= I, \end{aligned}$$

meaning that by taking an equivalence class of this tangent curve, we have

$$I + t(A^T + A) = I,$$

so that $A^T = -A$.

We observe that the function $f: \text{Mat}_n(\mathbb{R}) \rightarrow \text{Mat}_n(\mathbb{R})_{\text{s.a.}}$, given by

$$f(A) = A^T A,$$

has I_n as a regular value. To see this, observe that curves in $T_I \text{Mat}_n(\mathbb{R})_{\text{s.a.}}$ are of the form $\gamma(t) = I + tK$, where K is a self-adjoint(/symmetric) matrix. Similarly, $T_A \text{Mat}_n(\mathbb{R})$ is of the form $\varepsilon(t) = A + tB$, where $B \in \text{Mat}_n(\mathbb{R})$ and $t \in \mathbb{R}$. Both of these follow from the fact that $\text{Mat}_n(\mathbb{R})$ and $\text{Mat}_n(\mathbb{R})_{\text{s.a.}}$ are isomorphic to Euclidean spaces. Therefore, we see that the image of $\delta(t)$ is of the form $A^T A + t(A^T B + B^T A)$; if A satisfies $A^T A = I$, we can put this in the form of $I + tK$ by taking $\delta(t) = A + \frac{1}{2}tAK$. Therefore, by the Regular Value Theorem, the dimension of $O(n)$ is $n^2 - \frac{n(n-1)}{2} = \frac{n(n+1)}{2}$.

(d) Since both skew-symmetric and traceless matrices have trace zero, it follows that the tangent spaces of $SL_n(\mathbb{R})$ and $O(n)$ cannot span the tangent space of $GL_n(\mathbb{R})$, as there are matrices with nonzero trace.

Problem (Problem 4): Let D be a distribution on a smooth manifold of dimension n . We write $I(D)$ for the ideal of D , which consists of graded pieces $I^k(D) \subseteq \mathcal{A}^k(M)$, where $I^k(D)$ consists of forms ω such that $\omega(X_1, \dots, X_k) = 0$ for all $X_i \in D$, and

$$I(D) = \bigoplus_{k=0}^n I^k(D).$$

The Frobenius Theorem says that D is involutive if and only if I is *differential* — i.e., $d(I) \subseteq I$, where d is the exterior derivative.

- (a) Prove that $I(D)$ is an ideal — i.e., if $\omega \in I(D)$ and η is arbitrary, then $\omega \wedge \eta \in I(D)$.
- (b) Prove that $I(D)$ is locally generated by $s = n - r$ linearly independent 1-forms $\omega_1, \dots, \omega_s$, in the sense that for every point $p \in M$, there is a neighborhood U of p such that for any $\omega \in I^k(D)$ with k arbitrary, we may write

$$\omega = \sum_{i=1}^s \theta_i \wedge \omega_i$$

for suitable forms $\theta_1, \dots, \theta_s$.

- (c) Prove that if D is involutive, then for all $\omega \in I(D)$, we have $d\omega \in I(D)$.

(d) Use this to show that if ω is a 1-form, and X, Y are vector fields, then

$$d\omega(X, Y) = \frac{1}{2}(X(\omega(Y)) - Y(\omega(X)) - \omega([X, Y])).$$

Conclude that if $\omega \in I^1(D)$, and $X, Y \in D$, then $\omega([X, Y]) = 0$. Thus, if I is a differential ideal, then D is involutive.

(e) Show that if D is defined by the vanishing of linearly independent forms $\omega_1, \dots, \omega_s$ near a point p , then D is involutive if and only if for each i there are 1-forms $\omega_{i,j}$ such that

$$d\omega_i = \sum_{j=1}^s \omega_{i,j} \wedge \omega_j.$$

Solution:

(a) Write

$$\omega = \alpha_1 \wedge \dots \wedge \alpha_k$$

so that

$$\begin{aligned} \omega(X_1, \dots, X_k) &= \det\left((\alpha_i(X_j))_{i,j}\right) \\ &= 0. \end{aligned}$$

for $X_1, \dots, X_k \in D$. Then, if

$$\eta = \beta_1 \wedge \dots \wedge \beta_\ell,$$

we have the determinant of the block matrices

$$\begin{aligned} \omega \wedge \eta(X_1, \dots, X_k, \dots, X_{k+\ell}) &= \det\begin{pmatrix} \alpha_i(X_j) & \alpha_i(X_{\ell+j}) \\ \beta_i(X_j) & \beta_i(X_{\ell+j}) \end{pmatrix} \\ &= 0, \end{aligned}$$

so that $\omega \wedge \eta$ is contained in $I(D)$.

(b) Let $p \in U \subseteq M$ be such that $T_p M$ is spanned by $\left\{ \frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n} \right\}$. Without loss of generality, the distribution may be defined to be the subset of $T_p M$ spanned by $\left\{ \frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_r} \right\}$. Then, we observe that the ideal $I^1(D)$ is then spanned by the differential forms dx_{r+1}, \dots, dx_n . Since $I(D)$ is an ideal, we observe that an arbitrary element of $I^k(D)$ can then be written as

$$\omega = \sum_{j=r+1}^s \theta_j \wedge dx_j,$$

where the θ_j are elements of $\mathcal{A}^{k-1}(M)$.

(c) Let D be involutive.

The evaluation of $d\omega$ on vector fields (X_1, \dots, X_{k+1}) is given by

$$d\omega(X_1, \dots, X_{k+1}) = \frac{1}{k+1} \sum_{i=1}^{k+1} (-1)^{i+1} X_i \left(\omega(X_1, \dots, \widehat{X_i}, \dots, X_{k+1}) \right)$$

$$+ \frac{1}{k+1} \sum_{j=1}^n \sum_{i=1}^{j-1} (-1)^{i+j} \omega \left([X_i, X_j], X_1, \dots, \widehat{X_i}, \dots, \widehat{X_j}, \dots, X_{k+1} \right).$$

We verify this for the case that D is involutive, so that D may be assumed to locally be given by $(X_1, \dots, X_r) = \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_r} \right)$. Writing $\omega \in I(D)$ as

$$\omega = \sum_{i=r+1}^n \theta_i \wedge dx_i,$$

where the θ_i are $(k-1)$ -forms, we may then find that, by using the formula for evaluation of the derivative on k -forms that

$$\begin{aligned} d\omega(X_1, \dots, X_{k+1}) &= \frac{1}{k+1} \sum_{i=1}^{k+1} (-1)^{i+1} \frac{\partial}{\partial x_i} \left(\omega(X_1, \dots, \widehat{X_i}, \dots, X_{k+1}) \right) \\ &= 0, \end{aligned}$$

where we see that ω evaluates to zero on each of the X_i when $1 \leq i \leq r$, and $k, k+1 \leq r$.

(d) If we write $X = \frac{\partial}{\partial x}$ and $Y = \frac{\partial}{\partial y}$, and

$$\omega = f dx + g dy,$$

then

$$\begin{aligned} d\omega &= \frac{\partial f}{\partial x} dx \wedge dx + \frac{\partial f}{\partial y} dy \wedge dx + \frac{\partial g}{\partial x} dx \wedge dy + \frac{\partial g}{\partial y} dy \wedge dy \\ &= \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dx \wedge dy. \end{aligned}$$

Then, we see that

$$\begin{aligned} d\omega(X, Y) &= \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dx \wedge dy \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right) \\ &= \frac{1}{2} \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dx \wedge dy \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right) \\ &= \frac{1}{2} \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) \\ &= \frac{1}{2} \left(\frac{\partial}{\partial x} \left(\omega \left(\frac{\partial}{\partial y} \right) \right) - \frac{\partial}{\partial y} \left(\omega \left(\frac{\partial}{\partial x} \right) \right) - \omega \left(\left[\frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right] \right) \right). \end{aligned}$$

In particular, we observe that if $\omega \in I^1(D)$, and $d\omega \in I^2(D)$, then since we may locally write $X, Y \in D$ such that $X = \frac{\partial}{\partial x}$ and $Y = \frac{\partial}{\partial y}$, we find that $\omega([X, Y]) = 0$, so that if I is differential, then D is involutive.