

**Problem (Problem 1):** A topological group is a group which is also a Hausdorff topological space where the group operations are continuous.

Recall the definition of the concatenation operation on the fundamental group. Now, let  $G$  be a path-connected topological group, and let  $\pi_1(G, e)$  be the fundamental group of  $G$  with base point  $e$ . Use the Hilton–Eckmann argument to prove that the concatenation operation on the fundamental group is commutative.

**Solution:** Define two operations,  $*$  and  $\cdot$ , on the homotopy-classes of functions  $f: S^1 \rightarrow (G, e)$ , where  $S^1 \cong [0, 1]/(\{0\} \sim \{1\})$  given by

$$f * g = \begin{cases} f(2t) & 0 \leq t \leq 1/2 \\ g(2t - 1) & 1/2 \leq t \leq 1 \end{cases}$$

$$f \cdot g = f(t)g(t),$$

where the latter is multiplication within the group and the former is concatenation. We see that the identity map

$$\begin{aligned} \text{id}: S^1 &\rightarrow (G, e) \\ t &\mapsto e \end{aligned}$$

is an identity for both  $*$  and  $\cdot$ . Our task now is to show that the Hilton–Eckmann condition holds. That is, let  $a, b, c, d: S^1 \rightarrow (G, e)$  be continuous maps with base point  $e$ . Then,

$$\begin{aligned} (a * b) \cdot (c * d) &= (a * b)(t) \cdot (c * d)(t) \\ &= \begin{cases} a(2t)c(2t) & 0 \leq t \leq 1/2 \\ b(2t - 1)d(2t - 1) & 1/2 \leq t \leq 1 \end{cases} \\ &= (a \cdot c) * (b \cdot d), \end{aligned}$$

whence  $\cdot = *$  and the concatenation operation is commutative.

**Problem (Problems 2–4):**

- (2) Let  $M$  and  $N$  be smooth, orientable, closed manifolds of the same dimension  $n$ , and let  $f: M \rightarrow N$  be a smooth function. Show that  $f$  induces a map  $f^*: H_{DR}^n(N) \rightarrow H_{DR}^n(M)$  which is multiplication by an integer. This is called the degree of  $f$  and is written  $\deg(f)$ .
- (3) Recall the definition of the degree of  $f$  from one of the previous problem sets, counting the sums of signs of determinants of the derivative of  $f$  over the preimage of a regular value of  $f$ . Prove that the two definitions of the degree agree.
- (4) With the setup of the previous exercises, prove that if  $\omega$  is an arbitrary  $n$ -form on  $N$ , then

$$\int_M f^* \omega = \deg(f) \int_N \omega.$$

**Solution:** Letting  $\omega \in H_{DR}^n(N)$  be a nonvanishing top-dimensional form. By the naturality of the de Rham isomorphism, it follows that there is some  $\delta \in \mathbb{R}$  such that

$$\int_M f^* \omega = \delta \int_N \omega$$

Our task now is to show that  $\delta \in \mathbb{Z}$ . In particular, we will show that  $\delta = \deg(f)$ , where  $\deg(f)$  is defined as before.

Toward this end, let  $q$  be a regular value of  $f$ . We may use a smooth bump function to restrict  $\omega$  to a

small open neighborhood  $V$  of  $q$ . It follows then that  $f^{-1}(q) = \{p_1, \dots, p_\ell\}$  for some  $\ell$ , with corresponding disjoint open neighborhoods  $U_1, \dots, U_\ell$  locally diffeomorphic to  $V$ , whence the support of  $f^*\omega$  is contained in the union of  $U_1, \dots, U_\ell$ . If  $f^{-1}(q) = \emptyset$ , then

$$\begin{aligned}\int_M f^*\omega &= \int_{\emptyset} f^*\omega \\ &= \delta \int_N \omega \\ &= 0,\end{aligned}$$

whence  $\delta = 0$ . If  $f^{-1}(q) \neq \emptyset$ , then we see that

$$\int_M f^*\omega = \sum_{k=1}^{\ell} \int_{U_k} f^*\omega.$$

Now, since  $f$  is a local diffeomorphism on each of the  $U_k$ , it follows that

$$\begin{aligned}\int_{U_k} f^*\omega &= \text{sgn}(\det(D_{p_k} f)) \int_V \omega \\ &= \text{sgn}(\det(D_{p_k} f)) \int_N \omega.\end{aligned}$$

Therefore, we find that

$$\begin{aligned}\int_M f^*\omega &= \sum_{k=1}^{\ell} \text{sgn}(\det(D_{p_k} f)) \int_N \omega \\ &= \deg(f) \int_N \omega,\end{aligned}$$

giving that  $\deg(f)$  as defined via cohomology and as defined via summation over neighborhoods of preimages of a regular value are equal to each other.

**Problem (Problem 5):** Prove that for all  $d \in \mathbb{Z}$  and all  $n$ , there exists a smooth map  $S^n \rightarrow S^n$  with degree  $d$ .

**Solution:** If  $d = 0$ , then we may take a constant map to have degree  $d$ .

If  $d > 0$ , select  $d$  points,  $p_1, \dots, p_d \in S^n$  and corresponding disjoint open neighborhoods  $U_1, \dots, U_d$ . We define  $f: S^n \rightarrow S^n$  to be a map that takes  $p_i$  to the north pole, a diffeomorphism between  $U_i$  and  $S^n \setminus \{s\}$  (which follows from the coordinate map for  $U_i$  composed with the (inverse) south pole stereographic projection), where  $s$  is the south pole, and everything outside of  $U_1 \cup \dots \cup U_d$  to the south pole.

Similarly, if  $d < 0$ , perform the same process, but  $f$  should be orientation-reversing on each of the  $U_i$ .

**Problem (Problem 6):** Let  $K$  and  $L$  be smooth knots in  $\mathbb{R}^3$ , which is to say smooth embeddings of  $S^1$  into  $\mathbb{R}^3$ . Assume that  $K$  and  $L$  are disjoint subsets of  $\mathbb{R}^3$ . Choosing an orientation on  $S^1$  orients  $K$  and  $L$ . Write  $K = f(s)$  and  $L = g(t)$ , where  $t, s \in S^1$ , and let  $F(s, t) = g(t) - f(s)$  as a difference of vectors in  $\mathbb{R}^3$ . Notice that  $F$  never takes on the value 0. Renormalizing the vectors in  $\mathbb{R}^3 \setminus \{0\}$  gives a map  $\pi: \mathbb{R}^3 \setminus \{0\} \rightarrow S^2$ . Write  $G = \pi \circ F$ . Notice that  $G: S^1 \times S^1 \rightarrow S^2$  is a smooth map.

Define the linking number  $\text{lk}(K, L) \equiv \deg(G)$ . Now, let

$$\omega = \frac{1}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} (x_1 dx_2 \wedge dx_3 - x_2 dx_1 \wedge dx_3 + x_3 dx_1 \wedge dx_2),$$

where  $x_1, x_2, x_3$  are (Cartesian) coordinates on  $\mathbb{R}^3$ .

- (a) Show that  $d\omega = 0$ .
- (b) Let  $\eta = \omega|_{S^2}$ . Prove that

$$\int_{S^2} \eta = 4\pi.$$

Conclude that

$$\text{lk}(K, L) = \frac{1}{4\pi} \int_{S^1 \times S^1} F^* \omega.$$

- (c) Compute  $F^* dx_i$  for  $i = 1, 2, 3$ .
- (d) Find an explicit expression for  $\text{lk}(K, L)$  as an integral over  $S^1 \times S^1$ , in terms of  $f$  and  $g$ .

**Solution:**

- (a) We compute

$$d\omega = \left( \frac{\partial}{\partial x_1} \left( \frac{x_1}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} \right) + \frac{\partial}{\partial x_2} \left( \frac{x_2}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} \right) + \frac{\partial}{\partial x_3} \left( \frac{x_3}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} \right) \right) dx_1 \wedge dx_2 \wedge dx_3.$$

Symmetrically, we observe that

$$\begin{aligned} \frac{\partial}{\partial x_1} \left( \frac{x_1}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} \right) &= \frac{1}{(x_1^2 + x_2^2 + x_3^2)^{3/2}} - \frac{3}{2} \frac{2x_1(x_1)}{(x_1^2 + x_2^2 + x_3^2)^{5/2}} \\ &= \frac{-2x_1^2 + x_2^2 + x_3^2}{(x_1^2 + x_2^2 + x_3^2)^{5/2}}, \end{aligned}$$

whence their sum is zero.

- (b) We observe that the restriction to  $S^1$  yields  $x_1^2 + x_2^2 + x_3^2 = 1$ , meaning that the restriction is

$$\iota^* \omega = x_1 dx_2 \wedge dx_3 + x_2 dx_3 \wedge dx_1 + x_3 dx_1 \wedge dx_2,$$

where  $\iota: S^2 \hookrightarrow \mathbb{R}^3$  is inclusion. In particular, we observe that this is precisely the area form on  $\mathbb{R}^3$  with respect to the vector

$$v = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix},$$

whence

$$\int_{S^2} \iota^* \omega = 4\pi.$$

Now, since  $G^* = F^* \circ \pi^*$ , we see that

$$\begin{aligned} \deg(G) \int_{S^2} \omega &= \int_{S^1 \times S^1} G^* \omega \\ &= \int_{S^1 \times S^1} F^*(\pi^* \omega) \\ &= \int_{S^1 \times S^1} F^* \omega, \end{aligned}$$

where the latter equality emerges from the fact that  $\pi|_{S^2} = \text{id}$ .

(c) We write

$$\mathbf{F}(t, s) = \begin{pmatrix} f_1(t) - g_1(s) \\ f_2(t) - g_2(s) \\ f_3(t) - g_3(s) \end{pmatrix}.$$

Then,

$$\begin{aligned} F^* dx_i &= d(x_i \circ F) \\ &= d(f_i(t) - g_i(s)) \\ &= \frac{df_i}{dt} dt - \frac{dg_i}{ds} ds. \end{aligned}$$

(d) Inserting these expressions into  $\omega$  and using the natural symmetry therein, we find

$$\begin{aligned} F^* \omega &= \frac{1}{\|\mathbf{F}\|^3} (f_1(t) - g_1(s)) \left( \frac{df_3}{dt} \frac{dg_2}{ds} - \frac{df_2}{dt} \frac{dg_3}{ds} \right) \\ &\quad + \frac{1}{\|\mathbf{F}\|^3} (f_2(t) - g_2(s)) \left( \frac{df_1}{dt} \frac{dg_3}{ds} - \frac{df_3}{dt} \frac{dg_1}{ds} \right) \\ &\quad + \frac{1}{\|\mathbf{F}\|^3} (f_3(t) - g_3(s)) \left( \frac{df_2}{dt} \frac{dg_1}{ds} - \frac{df_1}{dt} \frac{dg_2}{ds} \right) \end{aligned}$$