Chapter 2 Problems

2.3

Cylindrical Coordinates

Starting with our expression of r, we have

$$\mathbf{r} = \rho \cos \phi \hat{\mathbf{i}} + \rho \sin \phi \hat{\mathbf{j}} + z \hat{\mathbf{k}}$$
$$d\mathbf{r} = \frac{\partial \mathbf{r}}{\partial \rho} d\rho + \frac{\partial \mathbf{r}}{\partial \phi} d\phi + \frac{\partial \mathbf{r}}{\partial z} dz.$$

Calculating each partial derivative,

$$\begin{split} \frac{\partial \mathbf{r}}{\partial \rho} &= \cos \phi \hat{\mathbf{i}} + \sin \phi \hat{\mathbf{j}} \\ \hat{\rho} &= \frac{\frac{\partial \mathbf{r}}{\partial \rho}}{\left\| \frac{\partial \mathbf{r}}{\partial \rho} \right\|} \\ &= \cos \phi \hat{\mathbf{i}} + \sin \phi \hat{\mathbf{j}}, \\ \frac{\partial \mathbf{r}}{\partial \phi} &= \rho \left(-\sin \phi \hat{\mathbf{i}} + \cos \phi \hat{\mathbf{j}} \right) \\ \hat{\phi} &= \frac{\frac{\partial \mathbf{r}}{\partial \phi}}{\left\| \frac{\partial \mathbf{r}}{\partial \phi} \right\|} \\ &= -\sin \phi \hat{\mathbf{i}} + \cos \phi \hat{\mathbf{j}} \end{split}$$

implying

$$\frac{\partial \mathbf{r}}{\partial \boldsymbol{\varphi}} = \rho \hat{\boldsymbol{\varphi}},$$

and finally, we have

$$\frac{\partial \mathbf{r}}{\partial z} = \hat{\mathbf{k}}.$$

The above calculations yield

$$d\mathbf{r} = (d\rho)\,\hat{\rho} + (\rho\,d\phi)\,\hat{\phi} + (dz)\,\hat{k}.$$

Spherical Coordinates

Starting with our expression of x^{I}

$$\mathbf{x} = r \sin \phi \sin \theta \hat{\mathbf{i}} + r \cos \phi \sin \theta \hat{\mathbf{j}} + r \cos \theta \hat{\mathbf{k}}$$
$$d\mathbf{x} = \frac{\partial \mathbf{x}}{\partial r} dr + \frac{\partial \mathbf{x}}{\partial \phi} d\phi + \frac{\partial \mathbf{x}}{\partial \theta} d\theta,$$

Evaluating each partial derivative, we have

$$\begin{split} \frac{\partial x}{\partial r} &= \sin \varphi \sin \theta \hat{i} + \cos \varphi \sin \theta \hat{j} + \cos \theta \hat{k} \\ \hat{r} &= \frac{\frac{\partial x}{\partial r}}{\left\| \frac{\partial x}{\partial r} \right\|} \end{split}$$

 $^{^{\}mathrm{I}}$ I am using x instead of r because r is already used in the expression of the spherical coordinates.

$$= \sin \phi \sin \theta \hat{i} + \cos \phi \sin \theta \hat{j} + \cos \theta \hat{k},$$

$$\frac{\partial \mathbf{x}}{\partial \phi} = -r \sin \phi \sin \theta \hat{i} + r \cos \phi \sin \theta \hat{j}$$

$$\hat{\phi} = \frac{\frac{\partial \mathbf{x}}{\partial \phi}}{\left\|\frac{\partial \mathbf{x}}{\partial \phi}\right\|}$$

$$= -\sin \phi \sin \theta \hat{i} + \cos \phi \sin \theta \hat{j}$$

implying

$$\frac{\partial \mathbf{x}}{\partial \phi} = r \sin \theta \hat{\phi},$$

and finally, we have

$$\begin{split} \frac{\partial \mathbf{x}}{\partial \boldsymbol{\theta}} &= r \cos \varphi \cos \theta \hat{\mathbf{i}} + r \sin \varphi \cos \theta \hat{\mathbf{j}} - r \sin \theta \hat{\mathbf{k}} \\ \hat{\boldsymbol{\theta}} &= \frac{\frac{\partial \mathbf{x}}{\partial \boldsymbol{\theta}}}{\left\|\frac{\partial \mathbf{x}}{\partial \boldsymbol{\theta}}\right\|} \\ &= \cos \varphi \cos \theta \hat{\mathbf{i}} + \sin \varphi \cos \theta \hat{\mathbf{j}} - \sin \theta \hat{\mathbf{k}}, \end{split}$$

implying

$$\frac{\partial \mathbf{x}}{\partial \theta} = r\hat{\theta}.$$

The above calculations yield

$$dx = (dr)\hat{r} + (r\sin\theta d\phi)\hat{\phi} + (rd\theta)d\theta.$$

2.8

Let

$$\vec{a} = r_a \cos \phi_a \sin \theta_a \hat{i} + r_a \sin \phi_a \sin \theta_a \hat{j} + r_a \cos \theta_a \hat{k}$$

$$\vec{b} = r_b \cos \phi_b \sin \theta_b \hat{i} + r_b \sin \phi_b \sin \theta_b \hat{j} + r_b \cos \theta_b \hat{k}.$$

Then,

$$\begin{split} \cos \gamma &= \frac{\vec{a} \cdot \vec{b}}{\left\| \vec{a} \right\| \left\| \vec{b} \right\|} \\ &= \frac{1}{r_{\alpha} r_{b}} \left(r_{\alpha} r_{b} \left(\sin \theta_{\alpha} \sin \theta_{b} \left(\cos \varphi_{\alpha} \cos \varphi_{b} + \sin \varphi_{\alpha} \sin \varphi_{b} \right) + \cos \theta_{\alpha} \cos \theta_{b} \right) \\ &= \cos \theta_{\alpha} \cos \theta_{b} + \sin \theta_{\alpha} \sin \theta_{b} \cos \left(\varphi_{\alpha} - \varphi_{b} \right). \end{split}$$

2.9

$$\begin{split} \frac{d\vec{\nu}}{dt} &= \frac{d}{dt} \left(\dot{\rho} \dot{\hat{\rho}} \right) + \frac{d}{dt} \left(\rho \dot{\varphi} \dot{\hat{\varphi}} \right) \\ &= \hat{\rho} \ddot{\rho} + \dot{\rho} \frac{d\hat{\rho}}{dt} + \dot{\rho} \dot{\varphi} \dot{\hat{\varphi}} + \rho \ddot{\varphi} \dot{\hat{\varphi}} + \rho \dot{\varphi} \frac{d\hat{\varphi}}{dt} \\ &= \hat{\rho} \ddot{\rho} + \dot{\rho} \dot{\varphi} \dot{\hat{\varphi}} + \rho \ddot{\varphi} \dot{\hat{\varphi}} + \dot{\rho} \dot{\varphi} \dot{\hat{\varphi}} + \left(\frac{\partial \dot{\varphi}}{\partial \rho} \frac{d\rho}{dt} + \frac{\partial \dot{\varphi}}{\partial \varphi} \frac{d\varphi}{dt} \right) \\ &= \left(\ddot{\rho} - \rho \dot{\varphi}^2 \right) \hat{\rho} + \left(\rho \ddot{\varphi} + 2 \dot{\rho} \dot{\varphi} \right) \dot{\hat{\varphi}}. \end{split}$$

2.12

- (a)
- (i) $d\mathbf{a} = \rho d\phi dz$
- (ii) $d\mathbf{a} = d\rho dz$
- (iii) $d\mathbf{a} = \rho d\rho d\phi$
- (b)
- (i) $d\mathbf{a} = r^2 \sin \theta \ d\theta d\phi$
- (ii) $d\mathbf{a} = r \sin \theta \, dr d\phi$
- (iii) $d\mathbf{a} = r dr d\theta$

2.14

(a)

$$\begin{split} d\Phi &= \mathbf{E} \cdot \hat{\mathbf{n}} \; dA \\ &= \|\mathbf{E}\| \, \|\hat{\mathbf{n}}\| \cos \theta dA \\ &= \frac{q}{4\pi\varepsilon_0 r^2} \cos \theta dA. \end{split}$$

Chapter 3 Problems

For all problems involving arg z (or equivalents), I will be using the principle branch, arg $z \in (-\pi, \pi]$.

3.5

(a)

$$\sqrt{3} + i = 2e^{i\frac{\pi}{3}}$$
$$-\sqrt{3} + i = 2e^{i\frac{2\pi}{3}}$$

(b)

$$\sqrt{2i} = \sqrt{2}e^{i\frac{\pi}{4}}$$

$$\sqrt{2 + 2\sqrt{3}i} = 2e^{i\frac{\pi}{6}}$$

3.6

(a) Real:

$$(-1)^{1/i} = \left(e^{i\pi}\right)^{-i}$$
$$= e^{\pi}.$$

(b) Real:

$$\left(\frac{z}{z^*}\right)^{i} = \left(e^{2i \arg z}\right)^{i}$$
$$= e^{-2 \arg z}.$$

(c) Imaginary:

$$(z_1 z_2^* - z_1^* z_2)^* = z_1^* z_2 - z_1 z_2^*$$

= $-(z_1 z_2^* - z_1^* z_2)$.

(d) Complex:

$$\sum_{n=0}^{N} e^{in\theta} = \frac{1 - e^{iN\theta}}{1 - e^{i\theta}}.$$

(e) Real: for each $a \in \{1, 2, ..., N\}$, $e^{ia\theta} + e^{-ia\theta} \in \mathbb{R}$.

3.9

(a)

$$\begin{split} \cos{(\alpha + b)} + \cos{(\alpha - b)} &= \frac{1}{2} \left(e^{i(\alpha + b)} + e^{-i(\alpha + b)} \right) + \frac{1}{2} \left(e^{i(\alpha - b)} + e^{-i(\alpha - b)} \right) \\ &= \frac{1}{2} \left(e^{i\alpha} \left(e^{ib} + e^{-ib} \right) + e^{-i\alpha} \left(e^{ib} + e^{-ib} \right) \right) \\ &= \frac{1}{2} \left(e^{i\alpha} + e^{-i\alpha} \right) \left(e^{ib} + e^{-ib} \right) \\ &= 2 \cos{\alpha} \cos{b}. \end{split}$$

(b)

$$\sin(a + b) + \sin(a - b) = \frac{1}{2i} \left(e^{i(a+b)} - e^{-i(a+b)} \right) + \frac{1}{2} \left(e^{i(a-b)} - e^{-i(a-b)} \right)$$

$$= \frac{1}{2i} \left(e^{ia} \left(e^{ib} + e^{-ib} \right) - e^{-ia} \left(e^{ib} + e^{-ib} \right) \right)$$

$$= \frac{1}{2i} \left(e^{ia} - e^{-ia} \right) \left(e^{ib} + e^{-ib} \right)$$

$$= 2 \sin a \cos b.$$

3.10

(a)

$$\begin{split} e^{i\alpha} + e^{i\beta} &= e^{i\left(\frac{\alpha+\beta}{2} + \frac{\alpha-\beta}{2}\right)} + e^{i\left(\frac{\alpha+\beta}{2} - \frac{\alpha-\beta}{2}\right)} \\ &= e^{i\frac{\alpha+\beta}{2}} \left(e^{i\frac{\alpha-\beta}{2}} + e^{-i\frac{\alpha-\beta}{2}} \right) \\ &= 2\cos\left(\frac{\alpha-\beta}{2}\right) e^{i\frac{\alpha+\beta}{2}}. \end{split}$$

(b)

$$\begin{split} e^{i\alpha} - e^{i\beta} &= e^{i\left(\frac{\alpha+\beta}{2} + \frac{\alpha-\beta}{2}\right)} - e^{i\left(\frac{\alpha+\beta}{2} - \frac{\alpha-\beta}{2}\right)} \\ &= e^{i\frac{\alpha+\beta}{2}} \left(e^{i\frac{\alpha-\beta}{2}} - e^{-i\frac{\alpha-\beta}{2}}\right) \\ &= 2i\sin\left(\frac{\alpha-\beta}{2}\right) e^{i\frac{\alpha+\beta}{2}} \end{split}$$

3.12

$$\begin{split} \frac{1}{2i} \ln \left(\frac{a + ib}{a - ib} \right) &= \frac{1}{2i} \left(\ln \left(a + ib \right) - \ln \left(a - ib \right) \right) \\ &= \frac{1}{2i} \left(\ln \left| a + ib \right| + i \arctan \left(\frac{b}{a} \right) - \left(\ln \left| a + ib \right| + i \arctan \left(-\frac{b}{a} \right) \right) \right) \\ &= \arctan \left(\frac{b}{a} \right). \end{split}$$

3.13

$$\begin{split} \frac{d^n}{dt^n} \left(e^{\alpha t} \sin b t \right) &= \frac{1}{2i} \frac{d^n}{dt^n} \left(e^{(\alpha + ib)t} - e^{(\alpha - ib)t} \right) \\ &= \frac{1}{2i} \left((\alpha + ib)^n e^{(\alpha + ib)t} - (\alpha - ib)^n e^{(\alpha - ib)t} \right) \\ &= \frac{1}{2i} e^{\alpha t} \left(\left(\left(\alpha^2 + b^2 \right)^{n/2} e^{in \arctan\left(\frac{b}{\alpha}\right)} \right) e^{ibt} - \left(\left(\alpha^2 + b^2 \right)^{n/2} e^{-in \arctan\left(\frac{b}{\alpha}\right)} \right) e^{-ibt} \right) \\ &= e^{\alpha t} \frac{1}{2i} \left(\alpha^2 + b^2 \right)^{n/2} \left(e^{i \left(b + n \arctan\left(\frac{b}{\alpha}\right) \right)t} - e^{i \left(b + n \arctan\left(\frac{b}{\alpha}\right) \right)} \right) \\ &= e^{\alpha t} \left(\alpha^2 + b^2 \right)^{n/2} \sin\left(bt + n \arctan\left(\frac{b}{\alpha}\right) \right) \end{split}$$

3.20

Showing the equivalence between $C_1 \cos kx + C_2 \sin kx$ and $A \cos (kx + \alpha)$ and $B \sin (kx + \beta)$, we have

$$A\cos(kx + \alpha) = A\cos kx \cos \alpha - A\sin kx \sin \alpha$$
$$B\sin(kx + \beta) = B\cos kx \sin \beta + B\sin kx \cos \beta$$

meaning (assuming α , $\beta \neq \pi n$, $\pi/2 + \pi n$)

$$A = \frac{C_1}{\cos \alpha}$$
$$= -\frac{C_2}{\sin \alpha}$$
$$B = \frac{C_1}{\sin \beta}$$
$$= \frac{C_2}{\cos \beta}.$$

Now, we show the equivalence between $C_1 \cos kx + C_2 \sin kx$ and $D_1 e^{ikx} + D_2 e^{-ikx}$.

$$D_1 e^{ikx} + D_2 e^{-ikx} = \frac{D_1 + D_2}{2} \left(e^{ikx} + e^{-ikx} \right) + \frac{D_1 + D_2}{2} \left(e^{ikx} - e^{-ikx} \right)$$
$$= (D_1 + D_2) \cos kx + i (D_1 - D_2) \sin kx.$$

meaning

$$C_1 = D_1 + D_2$$

 $C_2 = i(D_1 - D_2)$.

Finally, we show the equivalence between Re (Fe^{ikx}) and $C_1 \cos kx + C_2 \sin kx$.

$$Re\left((a+ib)e^{ikx}\right) = Re\left(a\cos kx + ia\sin kx + ib\cos kx - b\sin kx\right)$$
$$= a\cos kx - b\sin kx,$$

meaning

$$C_1 = a$$

$$C_2 = -b.$$