Problem (Problem 1): Let $T: V \to W$ be a linear transformation between \mathbb{F} -vector spaces. Show that T is injective if and only if T maps \mathbb{F} -linearly independent subsets of V to \mathbb{F} -linearly independent subsets of W.

Solution: Let T be injective. We claim that if $\{v_1, ..., v_n\}$ is linearly independent in V, then $\{Tv_1, ..., Tv_n\}$ is linearly independent in W. We see that if

$$\sum_{j=1}^{n} a_j \mathsf{T} v_j = 0_W,$$

then

$$T\left(\sum_{j=1}^{n} a_{j} v_{j}\right) = 0_{W},$$

meaning that

$$\sum_{j=1}^n \alpha_j \nu_j \in \ker(T).$$

Now, since T is injective, $\ker(T) = \{0_V\}$, meaning that $\sum_{j=1}^n a_j v_j = 0_V$. Yet, since $\{v_1, \dots, v_n\}$ is linearly independent, this means $a_j = 0$ for each j, so $\{Tv_1, \dots, Tv_n\}$ is linearly independent in W.

Now, let T map linearly independent subsets of V to linearly independent subsets of W. If $\mathcal{B}_V = \{v_i\}_{i \in I}$ is a basis for V, then since \mathcal{B}_V is linearly independent, $C = \{Tv_i\}_{i \in I}$ is a linearly independent subset of W, which can be extended to a basis \mathcal{B}_W . Since $C \subseteq \mathcal{B}_W$, we see that any linear combination in \mathcal{B}_W yields 0 if and only if every coefficient is zero, meaning that $\ker(T) = \{0_V\}$, so T is injective.

Problem (Problem 2): Let $P_{n+1}(\mathbb{R})$ be the space of polynomials with real coefficients of degree $\leq n+1$. Prove that for any n points $a_1, \ldots, a_n \in \mathbb{R}$, there exists a nonzero polynomial $f \in P_{n+1}(\mathbb{R})$ such that $f(a_j) = 0$ for each j, and $\sum_{j=1}^{n} f'(a_j) = 0$.

Solution: Based on the first condition, we see that the product $\prod_{j=1}^{n} (x - a_j)$ must divide the polynomial f, and since f has degree at most n + 1, we must have $f(x) = (x - L) \prod_{j=1}^{n} (x - a_j)$ for some $a, b \in \mathbb{R}$. Writing f'(x), we see that

$$f'(x) = \prod_{j=1}^{n} (x - a_j) + (x - L) \sum_{i=1}^{n} \prod_{j \neq i} (x - a_j),$$

implying that

$$\sum_{i=1}^n f'(\alpha_i) = \sum_{i=1}^n (\alpha_i - L) \prod_{j \neq i} (\alpha_i - \alpha_j).$$

By setting

$$0 = \sum_{i=1}^{n} (\alpha_i - L) \prod_{j \neq i} (\alpha_i - \alpha_j),$$

we get

$$L = \frac{1}{\sum_{i=1}^{n} \prod_{j \neq i} (\alpha_i - \alpha_j)} \sum_{i=1}^{n} \alpha_i \prod_{j \neq i} (\alpha_i - \alpha_j),$$

which is well-defined whenever the a_i are distinct.

Problem (Problem 3): Let T: V \rightarrow W be a linear map of finite-dimensional vector spaces, and let $W_0 \subseteq W$ be a subspace.

- (a) Show that $T^{-1}(W_0) = \{ v \in V \mid Tv \in W_0 \}$ is a subspace of V.
- (b) Assuming T is surjective, express $\dim(T^{-1}(W_0))$ in terms of $\dim(W_0)$ and $\dim(\ker(T))$.

Solution:

- (a) We see that if $v_1, v_2 \in T^{-1}(W_0)$ and $\alpha \in \mathbb{R}$, then since $Tv_1, \alpha Tv_2 \in W_0$, we have $Tv_1 + \alpha Tv_2 \in W_0$, so by linearity, $T(v_1 + \alpha v_2) \in W_0$, meaning $v_1 + \alpha v_2 \in T^{-1}(W_0)$, so $T^{-1}(W_0)$ is a subspace of V.
- (b) First, since T is surjective, $T(T^{-1}(W_0)) = W_0$. Therefore, by restricting the map T, we get the surjective map T': $T^{-1}(W_0) \to W_0$, and since $\ker(T) \subseteq T^{-1}(W_0)$, the First Isomorphism Theorem gives $T^{-1}(W_0)/\ker(T) \cong W_0$, so by rank-nullity (as each of W_0 and $T^{-1}(W_0)$ are finite-dimensional), $\dim(T^{-1}(W_0)) = \dim(\ker(T)) + \dim(W_0)$.

Problem (Problem 4):

(a) Do there exist invertible matrices $A, B \in Mat_2(\mathbb{R})$ such that

$$ABA^{-1}B^{-1} = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}?$$

(b) Do there exist matrices $A, B \in Mat_2(\mathbb{R})$ such that

$$AB - BA = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}?$$

Solution:

(a) There do not. This follows from the fact that $det(ABA^{-1}B^{-1}) = 1$, while the determinant of the latter matrix is 2.

Problem (Problem 5):

(a) Find the inverse matrix A^{-1} for the matrix

$$A = \begin{pmatrix} \alpha + 1 & \alpha & \alpha \\ \alpha & \alpha + 1 & \alpha \\ \alpha & \alpha & \alpha + 1 \end{pmatrix}.$$

(b) Prove that

$$\begin{vmatrix} a + x_1 & a & \cdots & a \\ a & a + x_2 & \cdots & a \\ \vdots & \vdots & \ddots & \vdots \\ a & a & \cdots & a + x_n \end{vmatrix} = x_1 x_2 \cdots x_n \left(1 + \frac{a}{x_1} + \cdots + \frac{a}{x_n} \right).$$

Solution:

(a) We may find A^{-1} by trying to find the sequence of elementary matrices E_1, \ldots, E_n such that

$$E_n E_{n-1} \cdots E_2 E_1 A = I$$
.

First, we do row reduction on A, yielding

$$\begin{pmatrix} a+1 & a & a \\ a & a+1 & a \\ a & a & a+1 \end{pmatrix} \xrightarrow{R_1 \leftarrow R_1 - R_2} \begin{pmatrix} 1 & -1 & 0 \\ a & a+1 & a \\ a & a & a+1 \end{pmatrix}$$

$$\frac{R_{2} \leftarrow R_{3} - R_{2}}{\longrightarrow} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ \alpha & \alpha & \alpha + 1 \end{pmatrix}$$

$$\frac{R_{3} \leftarrow R_{3} - \alpha R_{1}}{\longrightarrow} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 2\alpha & \alpha + 1 \end{pmatrix}$$

$$\frac{R_{3} \leftarrow R_{3} - 2\alpha R_{2}}{\longrightarrow} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 3\alpha + 1 \end{pmatrix}$$

$$\frac{R_{3} \leftarrow R_{3}/(3\alpha+1)}{\longrightarrow} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\frac{R_{2} \leftarrow R_{3} + R_{2}}{\longrightarrow} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\frac{R_{1} \leftarrow R_{1} + R_{2}}{\longrightarrow} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

Thus, the product $E_n E_{n-1} \cdots E_2 E_1$ is our desired inverse, which we find by applying the elementary row operations to the identity matrix I, yielding

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_1 \leftarrow R_1 - R_2} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\xrightarrow{R_2 \leftarrow R_3 - R_2} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\xrightarrow{R_3 \leftarrow R_3 - \alpha R_1} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ -\alpha & \alpha & 1 \end{pmatrix}$$

$$\xrightarrow{R_3 \leftarrow R_3 - 2\alpha R_2} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ -\alpha & -\alpha & 2\alpha + 1 \end{pmatrix}$$

$$\xrightarrow{R_3 \leftarrow R_3/(3\alpha+1)} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ -\alpha/(3\alpha+1) & -\alpha/(3\alpha+1) & (2\alpha+1)/(3\alpha+1) \end{pmatrix}$$

$$\xrightarrow{R_2 \leftarrow R_3 + R_2} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ -\alpha/(3\alpha+1) & 1 - (\alpha/(3\alpha+1)) & -1 + ((2\alpha+1)/(3\alpha+1)) \\ -(\alpha/(3\alpha+1)) & -\alpha/(3\alpha+1) & (2\alpha+1)/(3\alpha+1) \end{pmatrix}$$

$$\xrightarrow{R_1 \leftarrow R_1 + R_2} \begin{pmatrix} 1 - \alpha/(3\alpha+1) & -\alpha/(3\alpha+1) & -1 + (2\alpha+1)/(3\alpha+1) \\ -\alpha/(3\alpha+1) & 1 - (\alpha/(3\alpha+1)) & -1 + ((2\alpha+1)/(3\alpha+1)) \\ -\alpha/(3\alpha+1) & -\alpha/(3\alpha+1) & -1 + ((2\alpha+1)/(3\alpha+1)) \\ -\alpha/(3\alpha+1) & -\alpha/(3\alpha+1) & (2\alpha+1)/(3\alpha+1) \end{pmatrix},$$

which is our desired inverse.

(b) We show the case for n = 2, then use induction from then on. By raw calculation, we see that

$$\begin{vmatrix} a + x_1 & a \\ a & a + x_2 \end{vmatrix} = (a + x_1)(a + x_2) - a^2$$
$$= x_1x_2 + ax_1 + ax_2$$

$$=x_1x_2\bigg(1+\frac{a}{x_1}+\frac{a}{x_2}\bigg).$$

Now, for the general n case, we see that since determinants are multilinear,

$$\begin{vmatrix} a + x_1 & a & \cdots & a \\ a & a + x_2 & \cdots & a \\ \vdots & \vdots & \ddots & \vdots \\ a & a & \cdots & a + x_n \end{vmatrix} = \begin{vmatrix} a + x_1 & a & \cdots & a \\ a & a + x_2 & \cdots & a \\ \vdots & \vdots & \ddots & \vdots \\ a & a & \cdots & a \end{vmatrix} + \begin{vmatrix} a + x_1 & a & \cdots & 0 \\ a & a + x_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ a & a & \cdots & x_n \end{vmatrix}$$
$$= a \begin{vmatrix} a + x_1 & a & \cdots & 1 \\ a & a + x_2 & \cdots & 1 \\ \vdots & \vdots & \ddots & \vdots \\ a & a & \cdots & x_n \end{vmatrix} + \begin{vmatrix} a + x_1 & a & \cdots & 0 \\ a & a + x_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ a & a & \cdots & x_n \end{vmatrix}$$

and since determinants are alternating,

$$= a \begin{vmatrix} x_1 & 0 & \cdots & 1 \\ 0 & x_2 & \cdots & 1 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{vmatrix} + \begin{vmatrix} a + x_1 & a & \cdots & 0 \\ a & a + x_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ a & a & \cdots & x_n \end{vmatrix}$$

and by the cofactor expansion,

$$= a(x_1x_2\cdots x_{n-1}) + x_n \begin{vmatrix} a + x_1 & a & \cdots & a \\ a & a + x_2 & \cdots & a \\ \vdots & \vdots & \ddots & \vdots \\ a & a & \cdots & x_{n-1} \end{vmatrix}$$

and by the induction hypothesis,

$$\begin{split} &= \alpha(x_1x_2\cdots x_{n-1}) + x_n(x_1x_2\cdots x_{n-1}) \left(1 + \frac{\alpha}{x_1} + \cdots + \frac{\alpha}{x_{n-1}}\right) \\ &= x_1x_2\cdots x_n \left(1 + \frac{\alpha}{x_1} + \cdots + \frac{\alpha}{x_{n-1}} + \frac{\alpha}{x_n}\right), \end{split}$$

we obtain our desired result.

Problem (Problem 6): Let $A \in \operatorname{Mat}_n(\mathbb{R})$, and $(a_{ij})_{ij}$ such that $|a_{ij}| < \frac{1}{n}$ for each i, j. Show that $\det(I_n - A) \neq 0$.

Solution: Let $||x|| = \max_{i=1}^{n} |x_i|$. Let x_j be the component of x such that $|x_j| = ||x||$. Then, we see that

$$|(Ax)_{j}| = \left| \sum_{i=1}^{n} a_{ij} x_{i} \right|$$

$$\leq \sum_{i=1}^{n} |a_{ij}| |x_{i}|$$

$$< \sum_{i=1}^{n} \frac{1}{n} |x_{i}|$$

$$\leq \sum_{i=1}^{n} \frac{1}{n} ||x||$$

$$= |x_j|,$$

which means that $Ax \neq x$ at the component x_i , meaning $(I_n - A)x \neq 0$.

Problem (Problem 7):

- (a) Let $A \in Mat_n(\mathbb{C})$ be a matrix such that $A^2 = I_n$. Show that A is diagonalizable.
- (b) Give an example of of $A \in Mat_2(\mathbb{C})$ satisfying $A^2 = \mathbf{0}_2$ (the zero matrix) which is not diagonalizable.

Solution:

- (a) Since $A^2 I_n = \mathbf{0}_n$, we see that the minimal polynomial of A is $m_A(t) = t^2 1$, which splits over $\mathbb C$ to yield $m_A(t) = (t-1)(t+1)$. In particular, since the minimal polynomial splits into a product of distinct linear factors, A is diagonalizable.
- (b) The matrix

$$A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

satisfies $A^2 = \mathbf{0}_2$, but since $A \neq \mathbf{0}_2$, we see that $m_A(t) = t^2$. Since $m_A(t)$ does not split into distinct linear factors over \mathbb{C} , we see that A is necessarily not diagonalizable.

Problem (Problem 8): Let $A \in \operatorname{Mat}_n(\mathbb{C})$ be a matrix such that A^2 has n distinct eigenvalues. Show that A is diagonalizable.