**Problem** (Problem 1): Prove that if  $f: M \to N$  is smooth, and L is a k-codimensional submanifold of N that is transverse to f, then  $f^{-1}(L)$  is either empty or a submanifold of M with codimension k.

**Solution:** If L is not contained in f(M), then  $f^{-1}(L)$  is clearly empty. Therefore, we focus on the case where  $f^{-1}(L)$  is not empty.

Let L be transverse to f,  $q \in L$ , and  $p \in M$  such that f(p) = q. We observe that  $T_qL + D_pF(T_pM) = T_qN$ , so any vector in  $T_qN$  can be written (not necessarily uniquely) as an element of  $D_pF(T_pM)$  and  $T_qL$ . Next, we observe that, if we take a coordinate chart for q in U such that  $\phi(U) \cong \mathbb{R}^k$ , then by the Regular Value Theorem, we may select  $\phi$  such that  $L \cap U = \phi^{-1}(0)$ . This follows from the assumption that L has codimension k.

Now, if we can show that 0 is a regular value for  $\varphi \circ f$ , then  $(\varphi \circ f)^{-1}(0) = f^{-1}(L) \cap f^{-1}(U)$ , meaning that  $f^{-1}(L)$  is a submanifold of M with codimension k. First, since 0 is a regular value for  $\varphi$ , it follows that if  $v \in T_0\mathbb{R}^k$ , then there is some  $w \in T_q\mathbb{N}$  such that  $D_q\varphi(w) = v$ . Since f is transverse to L, there is  $w_1 \in T_qL$  and  $w_2 \in T_p\mathbb{N}$  such that  $w = w_1 + D_pF(w_2)$ . We observe that, since  $\varphi$  is constant on L, we have  $D_q\varphi(w_1) = 0$ , so that

$$D_{p}(\phi \circ f)(w_{2}) = D_{q}\phi \circ D_{p}F(w_{2})$$

$$= D_{q}\phi(w_{1} + D_{p}F(w_{2}))$$

$$= D_{q}\phi(w)$$

$$= v,$$

so 0 is a regular value for  $\varphi \circ F$ .

**Problem** (Problem 2): Let  $GL_n(\mathbb{R})$  denote the space of invertible  $n \times n$  matrices over  $\mathbb{R}$ , let  $SL_n(\mathbb{R})$  denote the matrices of determinant one, and let O(n) be the orthogonal group.

- (a) Prove that we may identify the tangent space of  $GL_n(\mathbb{R})$  at the identity with  $n \times n$  matrices over  $\mathbb{R}$ .
- (b) Prove that the tangent space of  $SL_n(\mathbb{R})$  at the identity consists of matrices of trace zero.
- (c) Prove that the tangent space of O(n) at the identity consists of skew-symmetric matrices. What is the dimension of O(n)?
- (d) Show that  $SL_n(\mathbb{R})$  and O(n) do not intersect transversely at the identity.

## **Solution:**

- (a) Let  $A \in Mat_n(\mathbb{R})$ , and consider a path through the identity given by  $\gamma(t) = I + tA$ . Since the determinant is a smooth function, and det(I) = 1, we have that for a small  $\epsilon > 0$  there is  $\delta$ , such that  $|det(I+tA)-1| < \epsilon$  whenever  $|t| < \delta$ . In particular, this means that the tangent space at the identity of  $GL_n(\mathbb{R})$  consists of all matrices.
- (b) We let  $\gamma(t) = I + tA$  be a curve in  $SL_n(\mathbb{R})$ , so that  $\gamma'(0) = A$  is an element of the tangent space of  $SL_n(\mathbb{R})$  at the identity. We observe that  $det(\gamma(t)) = 1$  for all (sufficiently small) t, so we see that

$$0 = \frac{d}{dt} \Big|_{t=0} \det(\gamma(t))$$
$$= D_{\gamma(0)} \det(\gamma'(0))$$
$$= D_{I} \det(A).$$

Therefore, we must evaluate what det'(I)(A) yields. Toward this end, we compute the derivative directly from the definition, yielding

$$D_{I} \det(A) = \lim_{t \to 0} \frac{\det(I + tA) - 1}{t}.$$

The expression det(I + tA) is a polynomial in t where the constant term is 1 and the term in t is tr(A). Thus, we find that 0 = tr(A), so A is traceless.

(c) If  $\gamma(t) = I + tA$  is a curve in O(n), then then we have that

$$(I + tA)^{T}(I + tA) = I$$
  
 $I + t(A^{T} + A) + t^{2}(A^{T}A) = I$ ,

meaning that by taking an equivalence class of this tangent curve, we have

$$I + t(A^{\mathsf{T}} + A) = I,$$

so that  $A^{T} = -A$ .

We observe that the function  $f \colon Mat_n(\mathbb{R}) \to Mat_n(\mathbb{R})_{s.a.}$ , given by

$$f(A) = A^{T}A$$

has  $I_n$  as a regular value. To see this, observe that curves in  $T_I \operatorname{Mat}_n(\mathbb{R})_{s.a.}$  are of the form  $\gamma(t) = I + tK$ , where K is a self-adjoint(/symmetric) matrix. Similarly,  $T_A \operatorname{Mat}_n(\mathbb{R})$  is of the form  $\epsilon(t) = A + tB$ , where  $B \in \operatorname{Mat}_n(\mathbb{R})$  and  $t \in \mathbb{R}$ . Both of these follow from the fact that  $\operatorname{Mat}_n(\mathbb{R})$  and  $\operatorname{Mat}_n(\mathbb{R})_{s.a.}$  are isomorphic to Euclidean spaces. Therefore, we see that the image of  $\delta(t)$  is of the form  $A^TA + t(A^TB + B^TA)$ ; if A satisfies  $A^TA = I$ , we can put this in the form of I + tK by taking  $\delta(t) = A + \frac{1}{2}tAK$ . Therefore, by the Regular Value Theorem, the dimension of O(n) is  $n^2 - \frac{n(n-1)}{2} = \frac{n(n+1)}{2}$ 

(d) Since both skew-symmetric and traceless matrices have trace zero, it follows that the tangent spaces of  $SL_n(\mathbb{R})$  and O(n) cannot span the tangent space of  $GL_n(\mathbb{R})$ , as there are matrices with nonzero trace.