Problem (Problem 1): Let $f: M \to N$ be a smooth map of manifolds. Prove that the graph of f is a smooth submanifold of $M \times N$.

Solution: Let (U, φ) be a chart on M with $\varphi(U) \cong \mathbb{R}^m$, and (V, ψ) a chart on N with $\psi(V) \cong \mathbb{R}^n$ and $f(U) \subseteq V$.

Define a chart on $M \times N$ corresponding to $U \times V$, and notice that the graph of $f|_{U}$ is a subset of $U \times V$.

Problem (Problem 2): Let U(n) be the set of unitary complex $n \times N$ matrices. Write $SU(n) \le U(n)$ for the kernel of the determinant map.

- (a) Show that U(1) is diffeomorphic to the circle, so that SU(1) is a point.
- (b) Prove that U(n) is a smooth manifold.
- (c) Prove that SU(2) is diffeomorphic to S^3 , the three-sphere.
- (d) Prove that U(2) is diffeomorphic to $S^1 \times S^3$.

Solution:

- (a) Since complex 1×1 matrices are diffeomorphic to \mathbb{C} , we see that $x \in U(1)$ if and only if $|x|^2 = 1$, meaning |x| = 1, so $x = e^{i\theta}$ for some θ . In particular, this means that the assignment $x \mapsto e^{i\theta}$ gives a diffeomorphism between S^1 and U(1).
- (b) Consider the self-map $f \colon Mat_n(\mathbb{C}) \to Mat_n(\mathbb{C}) \cong \mathbb{C}^{n^2}$ given by $f(A) = A^*A$. Note that this maps $Mat_n(\mathbb{C})$ to positive semi-definite matrices $Mat_n(\mathbb{C})^+$.

We want to calculate the derivative of f by taking

$$f(A + H) - f(A) = (A + H)^{*}(A + H) - A^{*}A$$

$$= (A^{*} + H^{*})(A + H) - A^{*}A$$

$$= A^{*}A + H^{*}A + A^{*}H + H^{*}H - A^{*}A$$

$$= H^{*}A + A^{*}H + H^{*}H.$$

Dividing out by $\|H\|_{op}$, we find that $D_A(f) = A + A^*$. Now, since I is of full rank, so too is $\frac{1}{2}I$, meaning that $D_{\frac{1}{2}I}(f) = I$, and thus f has a locally defined inverse about I. In particular, this means that $f^{-1}(\{I\})$ consists entirely of regular points, or that I is a regular value for f. Thus, U(n) is a smooth manifold.

(c) We view S^3 as a subset of \mathbb{C}^2 , so that S^3 consists of all (z_1, z_2) such that

$$|z_1|^2 + |z_2|^2 = 1.$$

We claim that the matrix

$$A_{z_1, z_2} = \begin{pmatrix} z_1 & z_2 \\ -\overline{z_2} & \overline{z_1} \end{pmatrix}$$

is an element of SU(2). Since it is uniquely determined by z_1 and z_2 in S^3 , it follows that SU(2) is diffeomorphic to S^3 .

To see this, observe that

$$\begin{aligned} \det(A) &= 1 \\ A^*A &= \begin{pmatrix} \overline{z_1} & -z_2 \\ \overline{z_2} & z_1 \end{pmatrix} \begin{pmatrix} z_1 & z_2 \\ -\overline{z_2} & \overline{z_1} \end{pmatrix} \end{aligned}$$

$$= \begin{pmatrix} |z_1|^2 + |z_2|^2 & z_2\overline{z_1} - z_2\overline{z_1} \\ z_1\overline{z_2} - z_1\overline{z_2} & |z_1|^2 + |z_2|^2 \end{pmatrix}$$
$$= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

Therefore, SU(3) is diffeomorphic to S³, with the diffeomorphism given by coordinate assignment.

(d) Observe that if $(z_1, z_2) = z \in S^3 \subseteq \mathbb{C}^2$, then if $a \in U(2)$, we have $az \in S^3$. In particular, since unitary matrices are invertible, the operation of $a \in U(2)$ on $z \in S^3$ by multiplication is a group action.

We observe now that the action of U(2) on $S^3 \subseteq \mathbb{C}^2$ by matrix multiplication is transitive, since for any element $(w_1, w_2) \in S^3$, the matrix

$$\begin{pmatrix} w_1 & -\overline{w_2} \\ w_2 & \overline{w_1} \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix},$$

and

$$\begin{pmatrix} \overline{w_1} & \overline{w_2} \\ -w_2 & w_1 \end{pmatrix} \begin{pmatrix} w_1 & -\overline{w_2} \\ w_2 & \overline{w_1} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

Additionally, we observe that for any θ ,

$$\begin{pmatrix} 1 & 0 \\ 0 & e^{i\theta} \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix},$$

meaning

$$S^3 \cong U(2)/P$$
,

where P consists of all matrices of the form

$$Q = \begin{pmatrix} 1 & 0 \\ 0 & e^{i\theta} \end{pmatrix}.$$

We observe that P is diffeomorphic to S^1 via a coordinate assignment, so $U(2) \cong S^3 \times S^1$.

Problem (Problem 3): In this exercise, we will prove the Frobenius theorem.

Let M be a smooth manifold of dimension n, and let D be an r-dimensional distribution on M, where $r \le n$. That is, D picks out an r-dimensional D_p of T_pM for each $p \in M$. In other words, at every point, there are r distinguished, linearly independent vector fields defined in a neighborhood of the point.

A submanifold $N \subseteq M$ is called an *integral submanifold* for D if $T_pN = D_p$ for each $p \in M$. We say D is *completely integrable* if an integral submanifold exists through every point. Integral curves of a vector field are integral submanifolds of a vector field.

We call a distribution that is closed under taking Lie brackets involutive. That is, for any vector fields $X, Y \in D$ (i.e., local 1-distributions that lie in D), then $[X, Y] \in D$.

The Frobenius Theorem says that a distribution D on M is completely integrable if and only if it is involutive.