

Mercury: Efficient On-Device Distributed DNN Training via Stochastic Importance Sampling

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SenSys 21

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Outline

- Motivation
- Mercury
- Implementation Setup
- Results
- Conclusion

Motivation

- Deep learning model training
- Smart phones, AR/VR headsets, Smart speakers, Robotics, Drones



Motivation

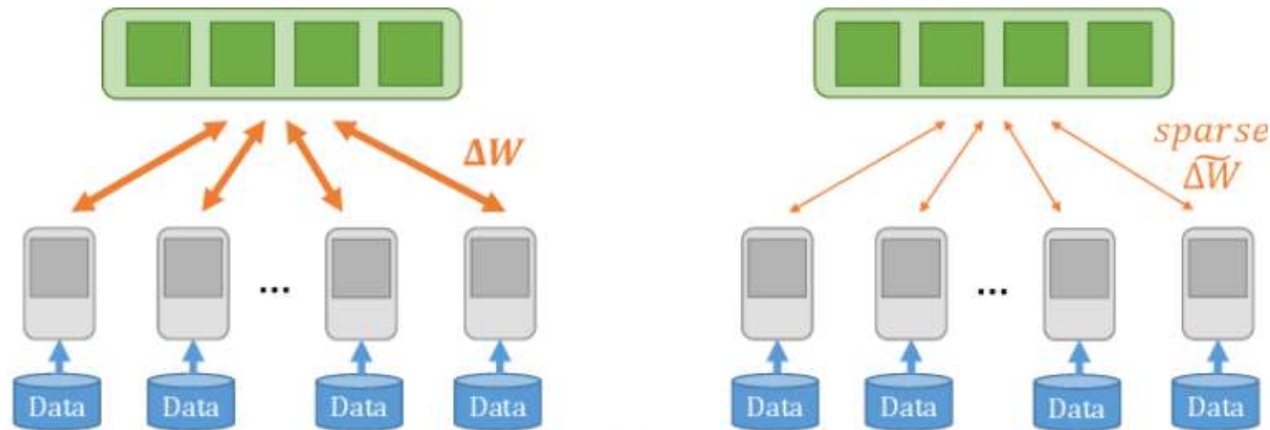
- Contribution: **On-device** distributed Training
- Limitation: **significant amount** of training time
- Limited bandwidth **slows down** communication

$$T = E \cdot (T_{cp} + T_{cm}).$$



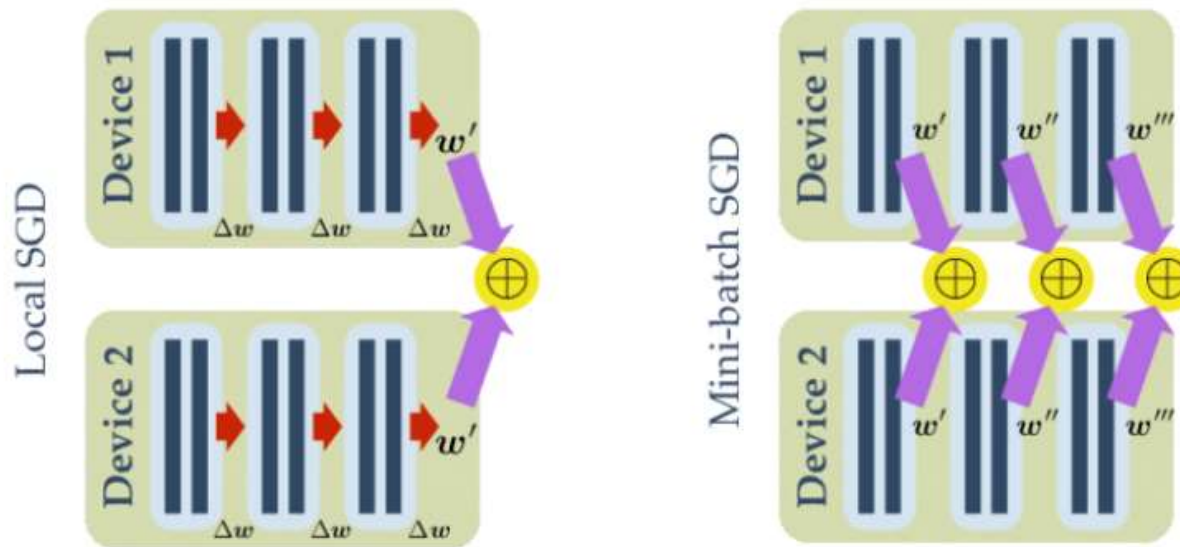
Motivation

- Solution 1: gradient compression
- **Quantizing gradients** (smaller number of bits)
- **Sparsification** (selecting important gradients)
- **Sacrifices the accuracy** of the trained model



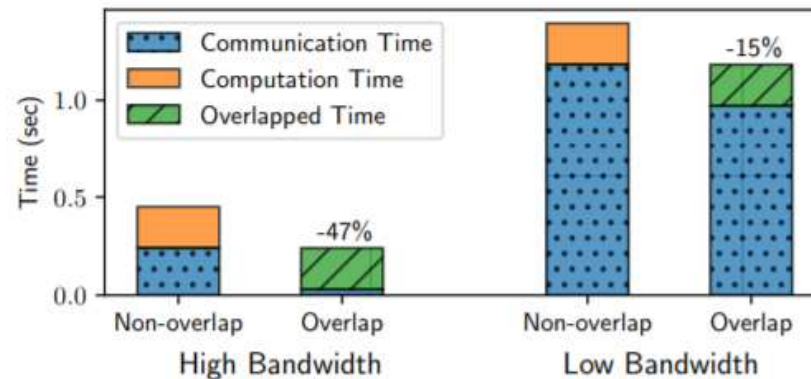
Motivation

- Solution 2: Local SGD
- Clients perform **multiple** local updates
- May **deviate from** global optimal model



Motivation

- Solution 3: Overlapping
- **Overlap communication** with gradient computation
- Can **mask out** the communication cost
- On-device communication is **way higher than** gradient computation

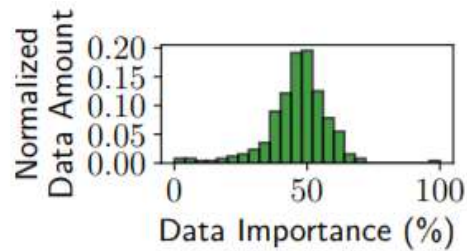


Mercury

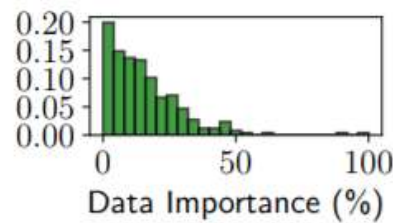
- Improve training efficiency
- Reduce the iterations for convergence
- Key concept: **importance sampling**

Mercury

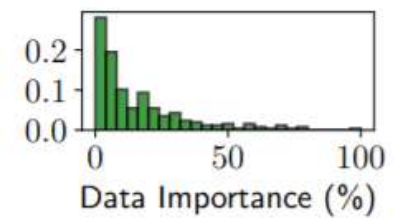
- Data importance distribution differs as the iteration goes up



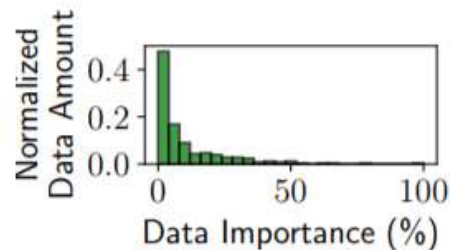
(a) #iterations=0



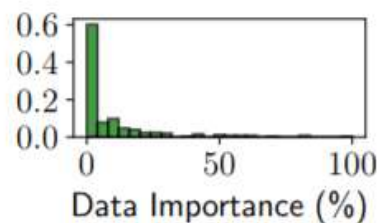
(b) #iterations=200



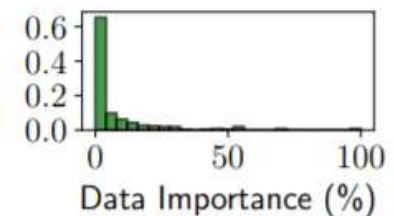
(c) #iterations=400



(d) #iterations=600

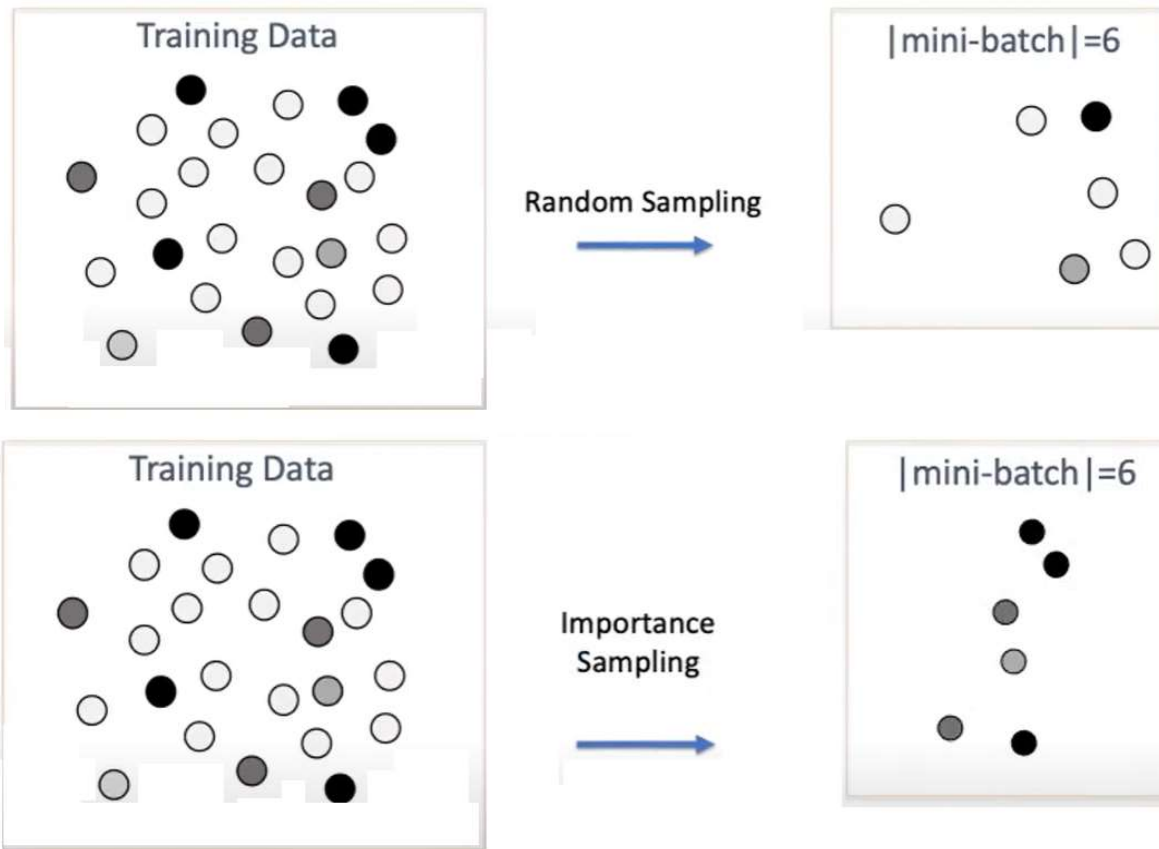


(e) #iteration=800



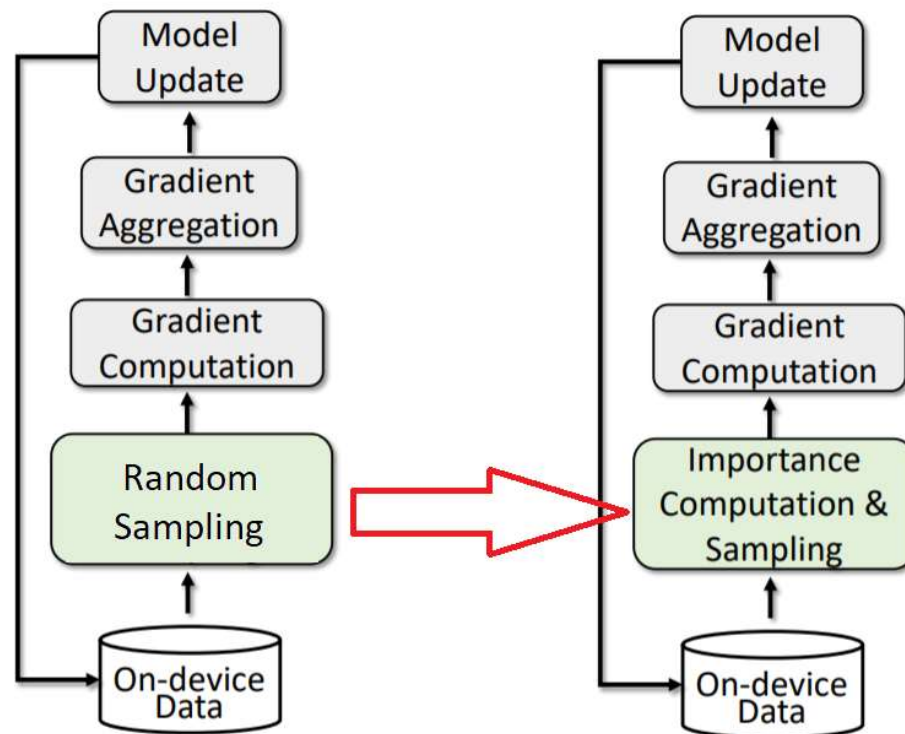
(f) #iteration=1000

Mercury



Mercury

- Framework



Mercury

- Challenge 1: importance sampling incurs computation cost

$$\begin{aligned} \text{Speedup} &= \frac{E \cdot (T_{cp} + T_{cm})}{E_{is} \cdot (T_{cp} + T_{cm} + T_{is})} \\ &= \frac{1}{\frac{E_{is}}{E} \cdot \left(1 + \frac{T_{is}}{T_{cp} + T_{cm}}\right)} \end{aligned}$$

E: iteration of standard SGD

E_{is}: iteration of importance sampling

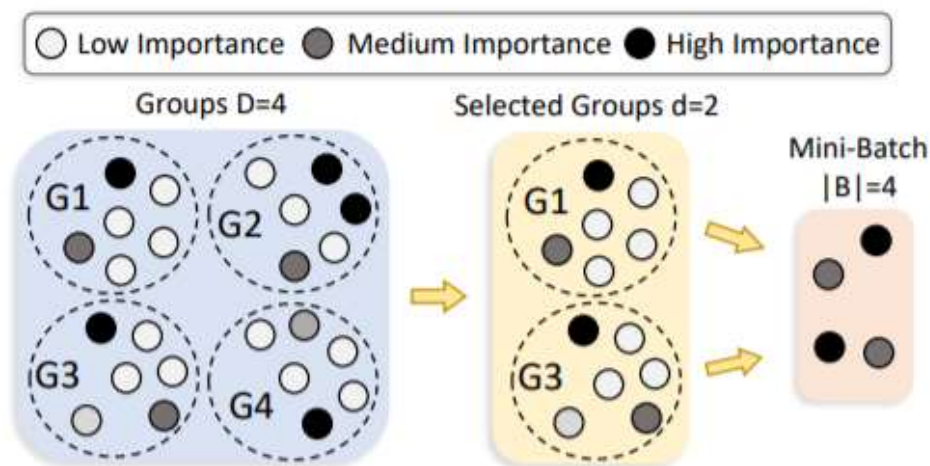
T_{cp}: computation time

T_{cm}: communication time

T_{is}: importance sampling computation time

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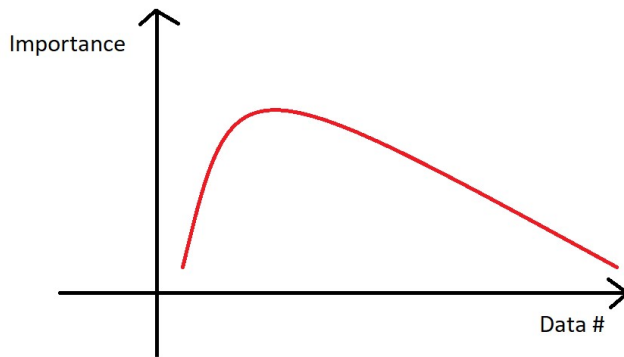
- Solution 1: Group-wise Importance Sampling
- **Divide** training data **into groups**
- Only **update** importance distribution **for one group**
- **Reuse** cached distribution **from other groups**



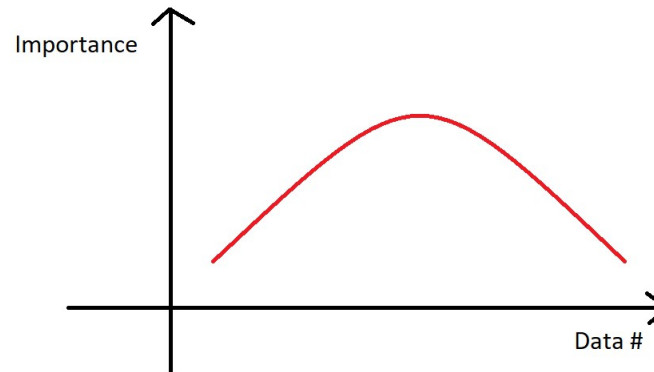
Mercury

- Challenge 2: Data importance is imbalanced
- A device may learn global trivial samples

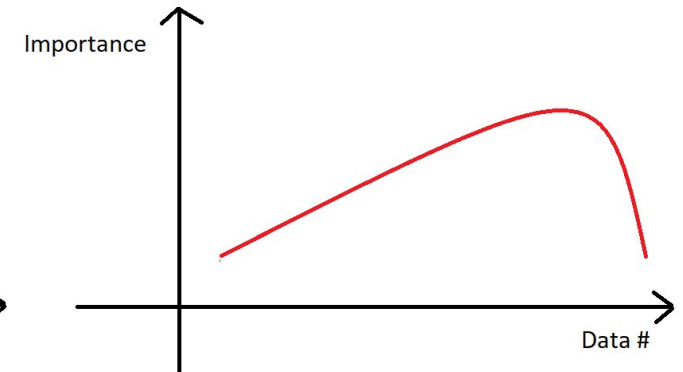
Device #1



Device #2

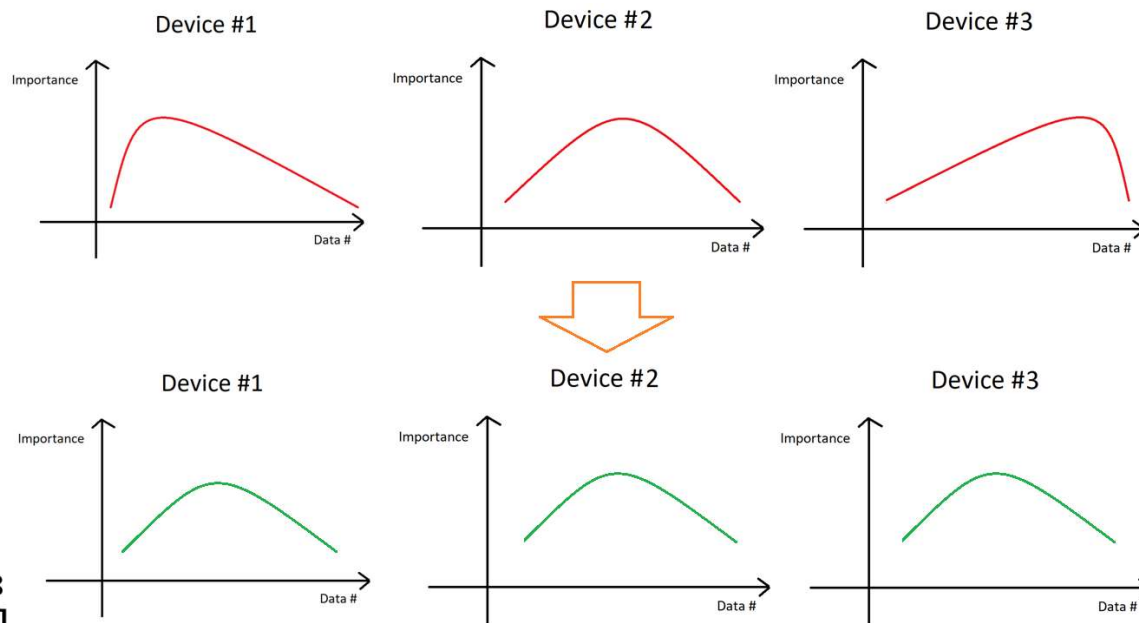


Device #3



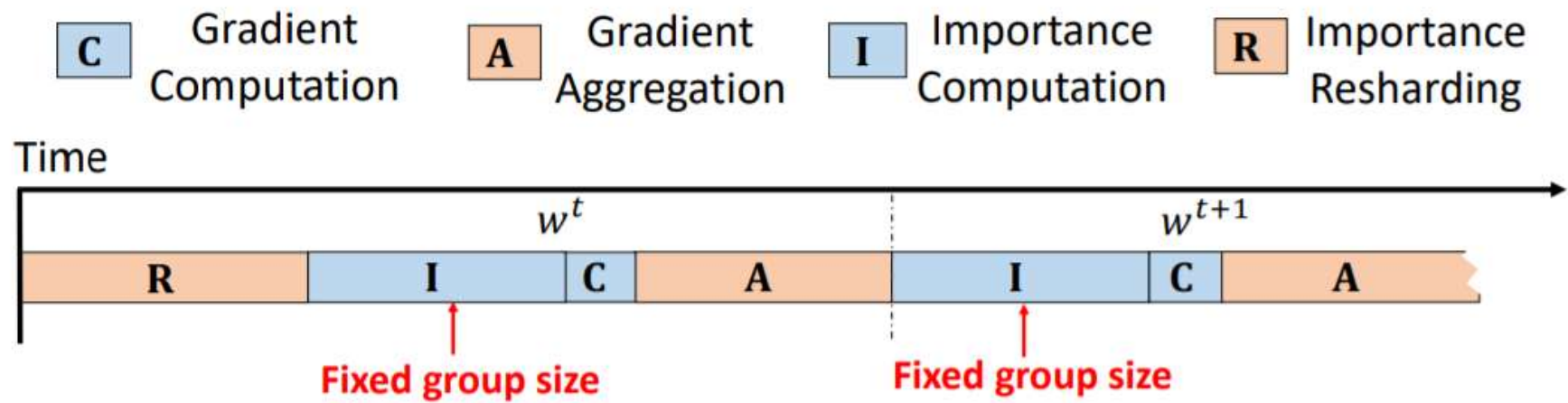
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- Solution 2: Importance-aware Data Resharding
- Redistribute samples among workers
- Select non-trivial samples to shuffle



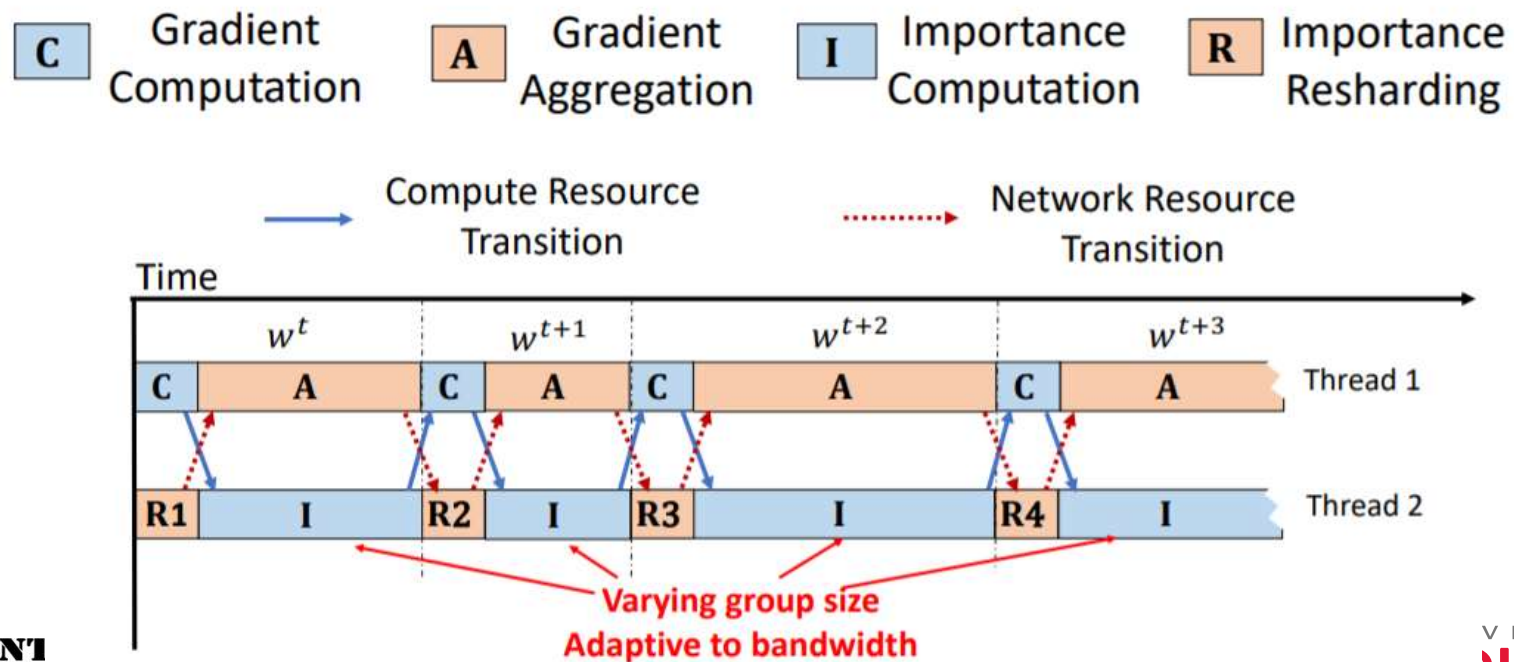
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- Challenge 3: Sequential implementation is inefficient



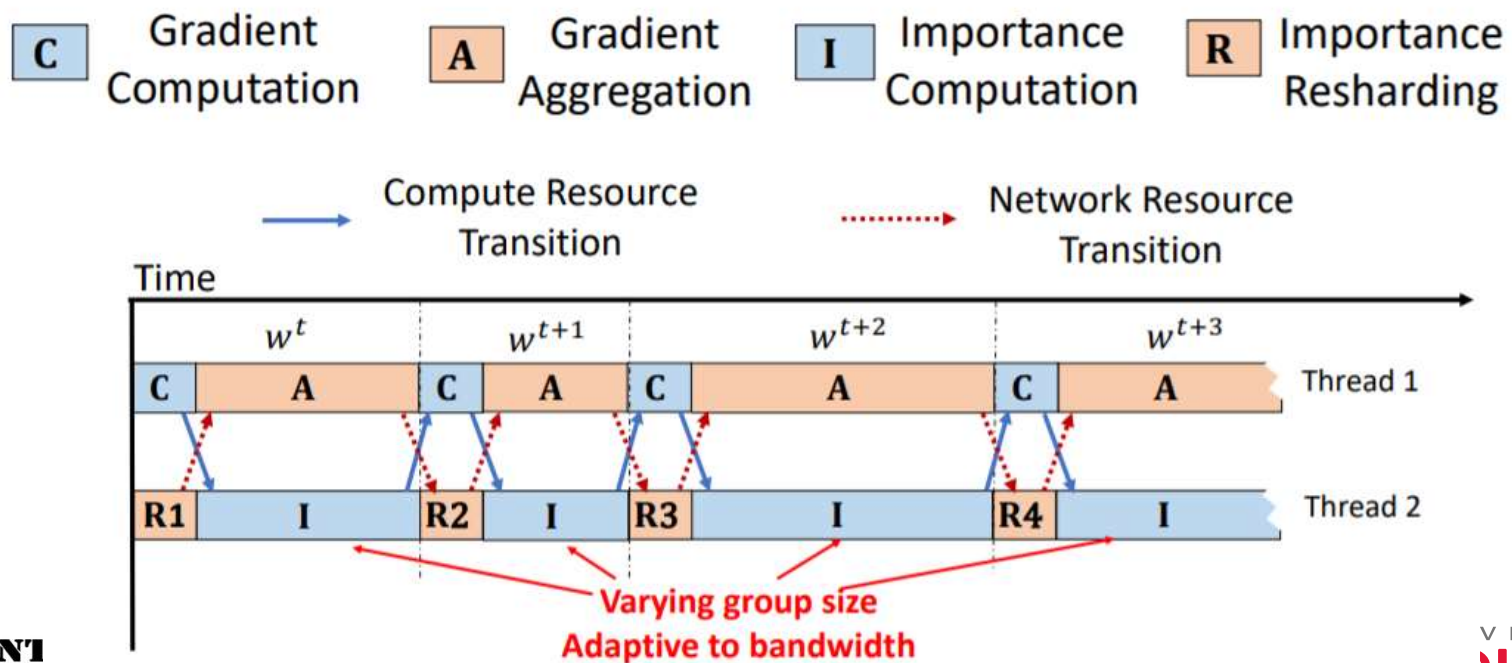
Mercury

- Solution 3: Bandwidth-adaptive computation-communication (BACC) scheduler



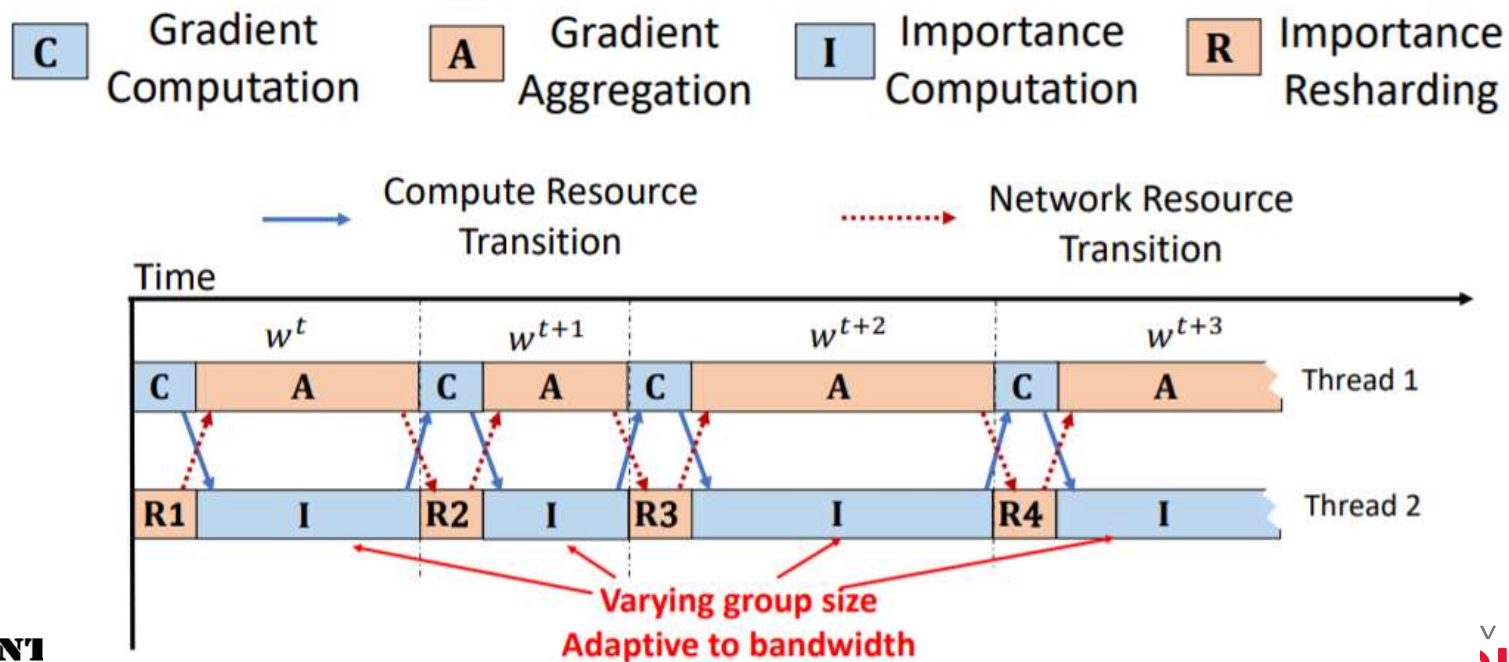
Mercury

- To fully overlap **I** with **A**: Adopt varying group sizes



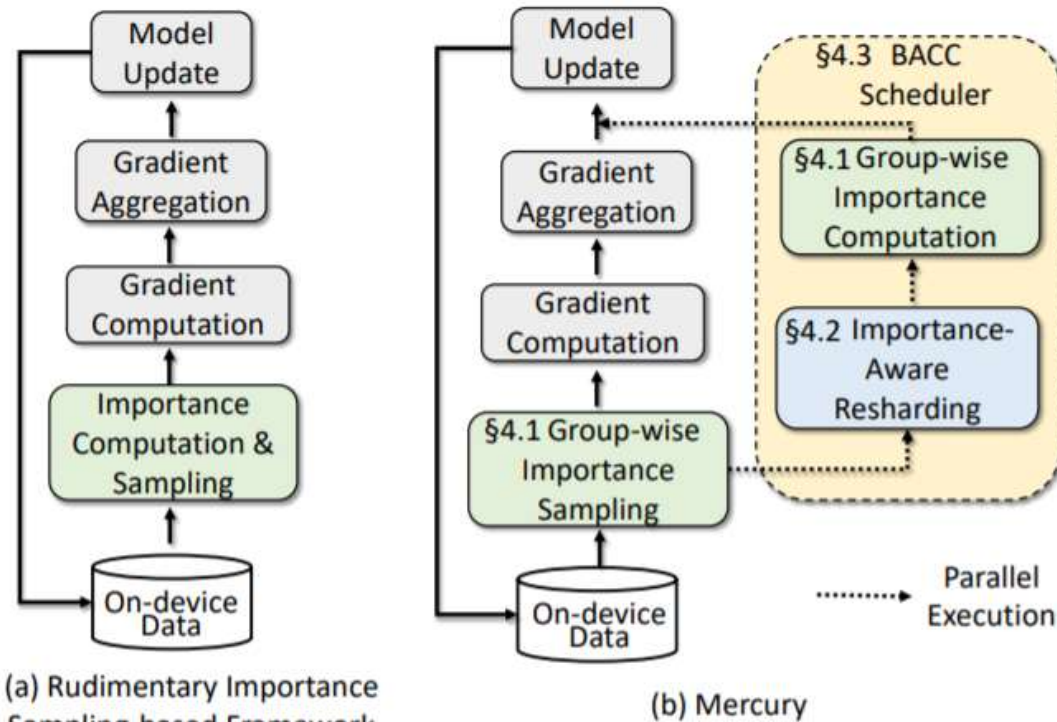
Mercury

- To fully overlap **R** with **C**: Resharding **pauses** when aggregation begins and **resumes** when it ends



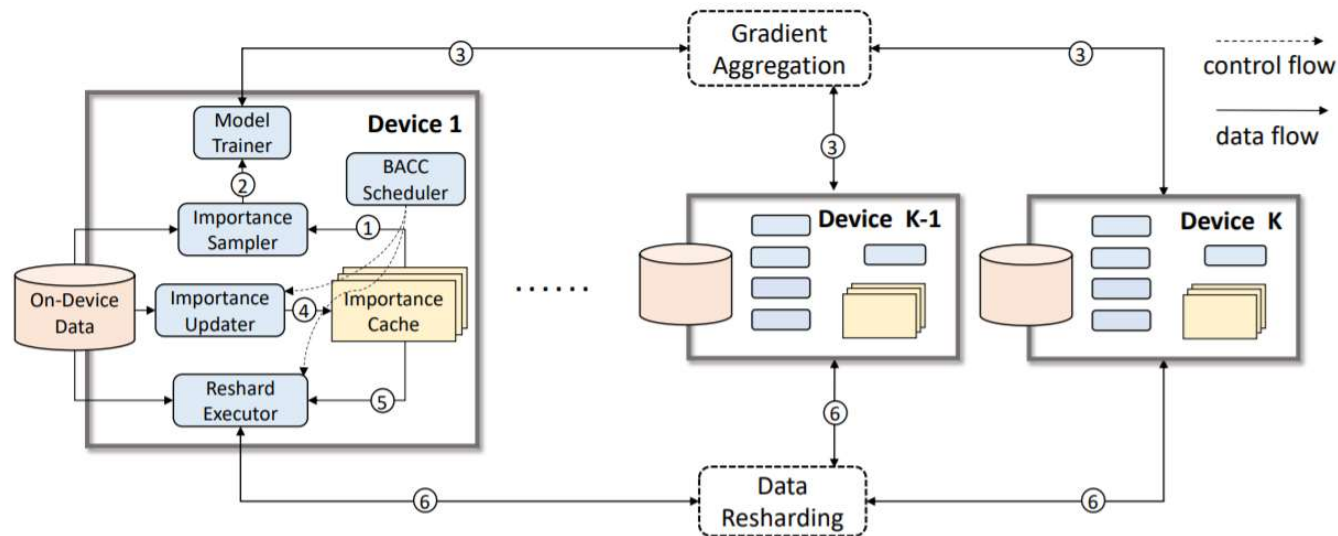
Mercury

- Framework



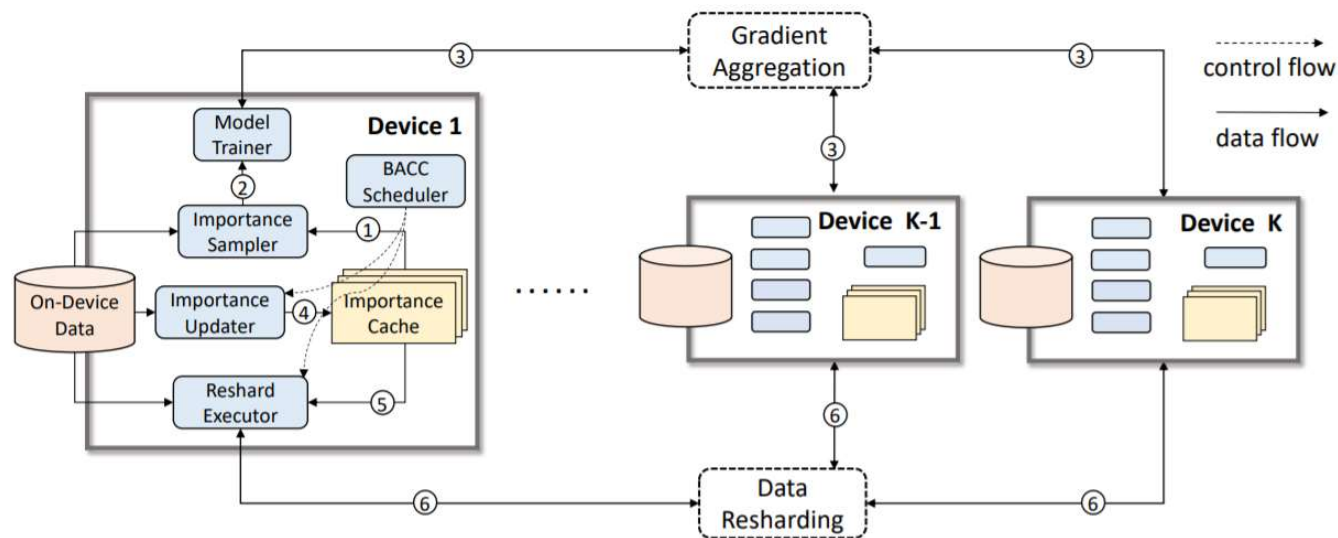
Mercury

- System architecture
- 1) Construct mini-batch from on-device data in importance cache



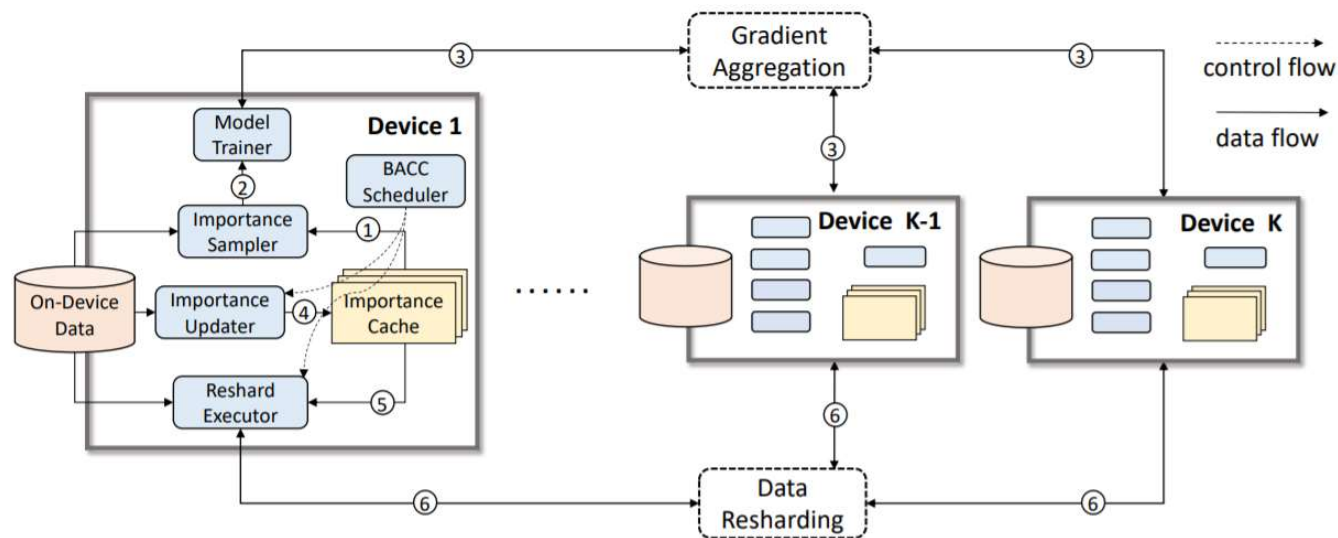
Mercury

- System architecture
- 2) Mini-batch is fed to model trainer to compute local gradient



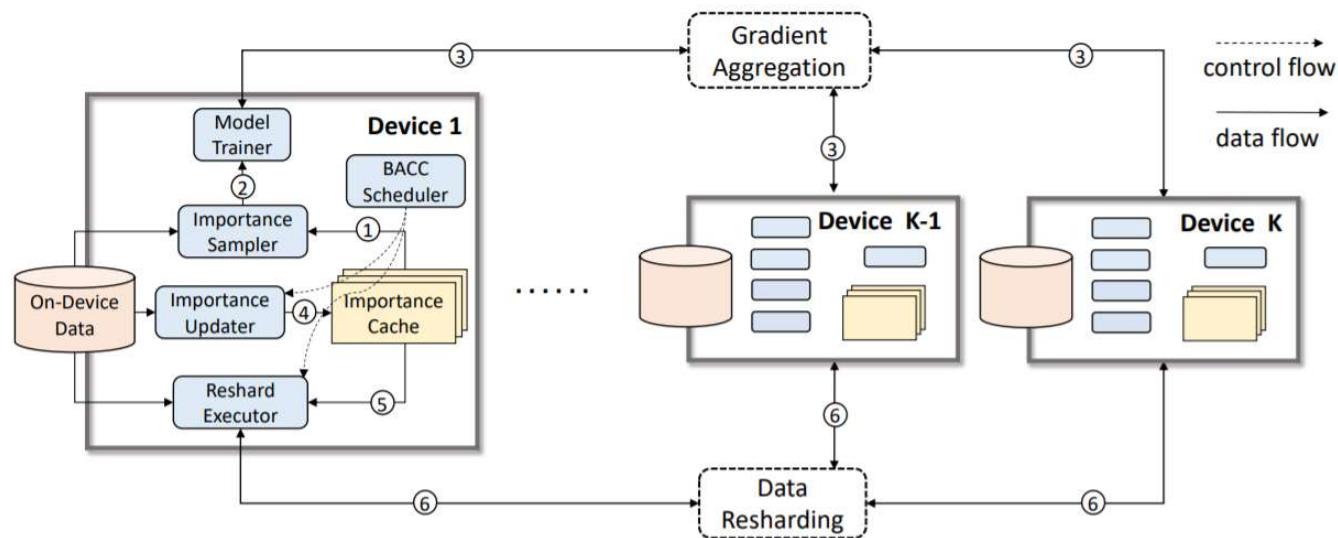
Mercury

- System architecture
- 3) Gradients aggregated, model updated



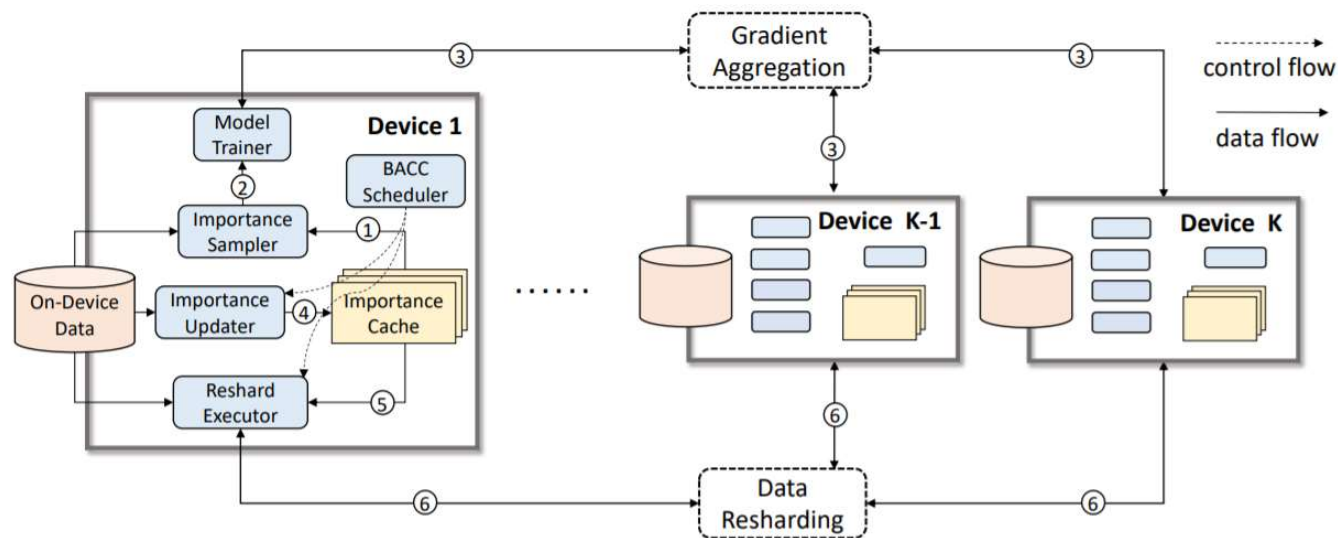
Mercury

- System architecture
- 4) Re-compute the data importance and update the Importance Cache



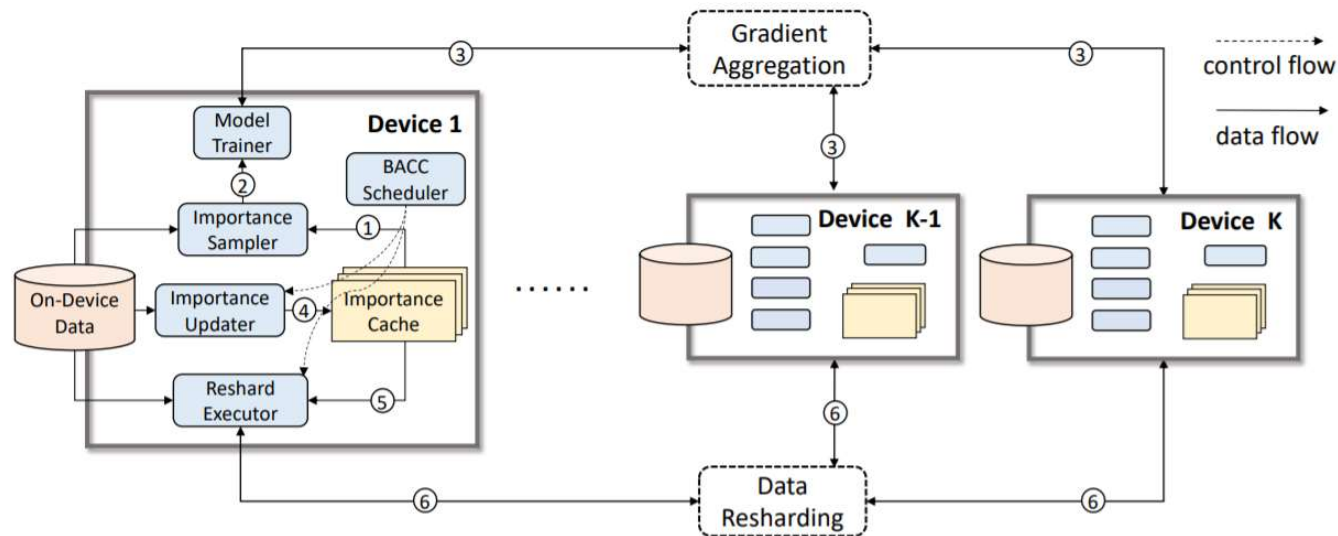
Mercury

- System architecture
- 5) Identify important data samples from Importance Cache



Mercury

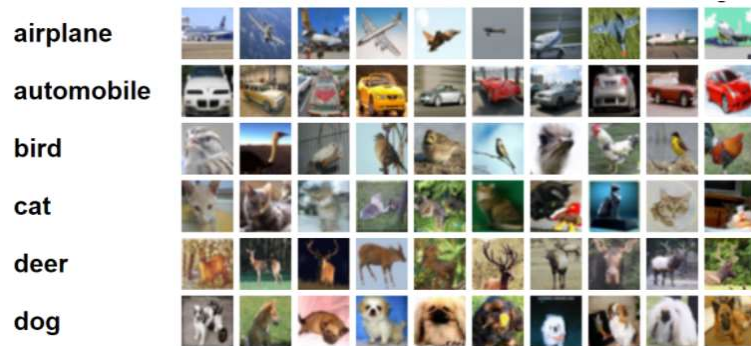
- System architecture
- 6) Communicate with other devices to perform importance-aware data resharding



Implementation Setup

Applications & models

- Image Classification (ResNet)
- Speech Recognition (VGG)
- Next Language Processing (LSTM)



Implementation Setup

Datasets:

- Image Classification
Cifar10, Cifar100, SVHN, Aerial Image Dataset
- Speech Recognition
Tensorflow Speech Command Dataset
- Next Language Processing
AG News Corpus

Implementation Setup

Devices:

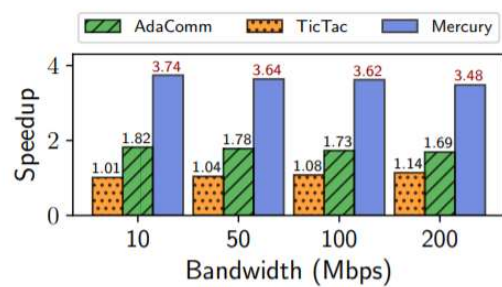
- 12 NVIDIA Jetson TX1
- Wifi routers to connect all TX1

Baselines:

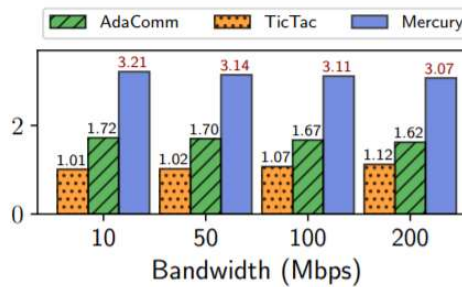
- TicTac (overlapping communication & computation)
- Adacomm (Local SGD)

Results

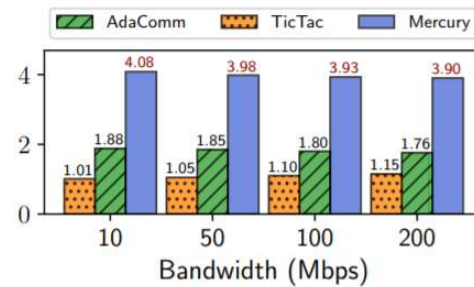
- End-to-end performance



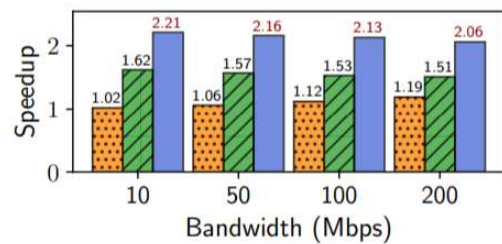
(a) CIFAR-10



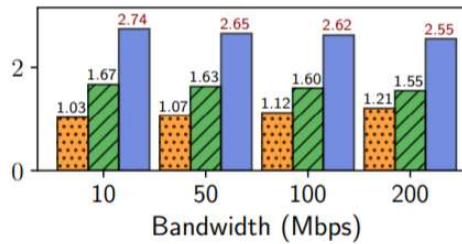
(b) CIFAR-100



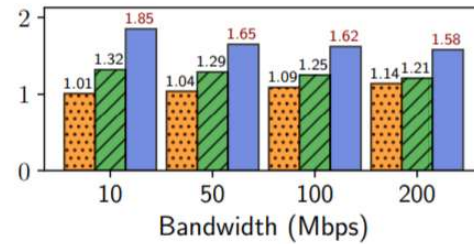
(c) SVHN



(d) AID



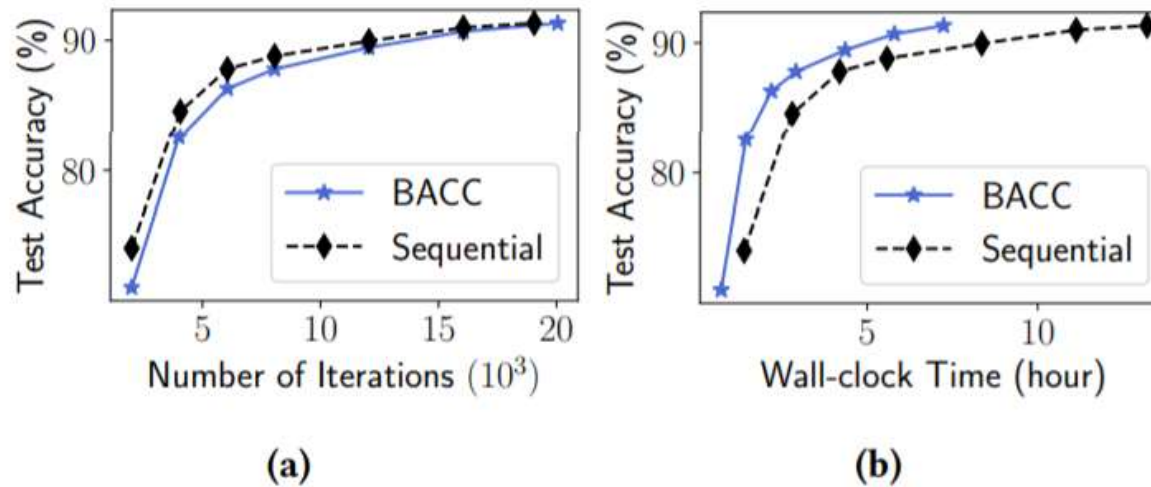
(e) Tensorflow Speech Command



(f) AGNews

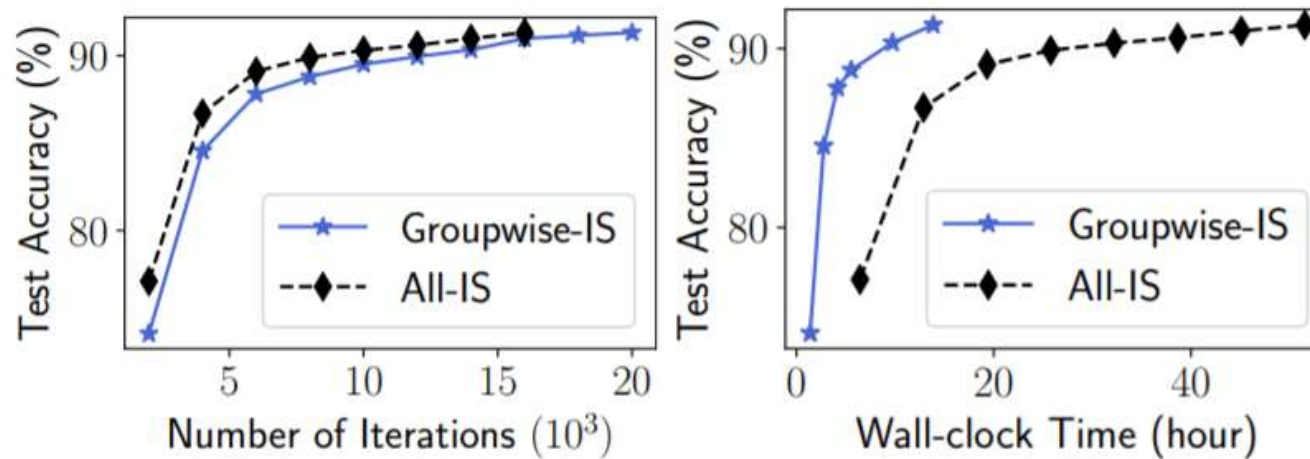
Results

- Sequential implementation & BACC scheduler



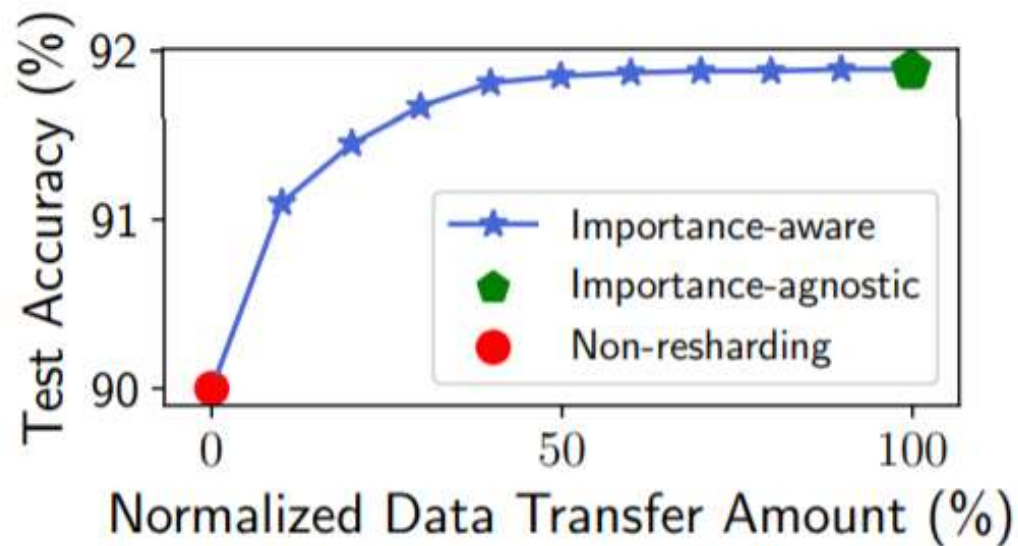
Results

- Group importance & All-inclusive



Results

- Importance-Aware & Importance-Agnostic



Conclusion

- Mercury enables efficient training
- Mercury doesn't damage accuracy too much
- Mercury addresses challenges using
 - 1) Group-wise importance sampling
 - 2) Importance-aware resharding
 - 3) BACC scheduler

An aerial photograph of the University of Houston campus at dusk. The foreground shows several large, modern university buildings with flat roofs and some with glass facades. A central green lawn with winding paths is visible. In the background, the Houston city skyline is silhouetted against a twilight sky with soft orange and blue hues. A large, semi-transparent red rectangle is superimposed over the upper half of the image, containing the text "THANK YOU" in white, bold, sans-serif capital letters.

THANK YOU

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