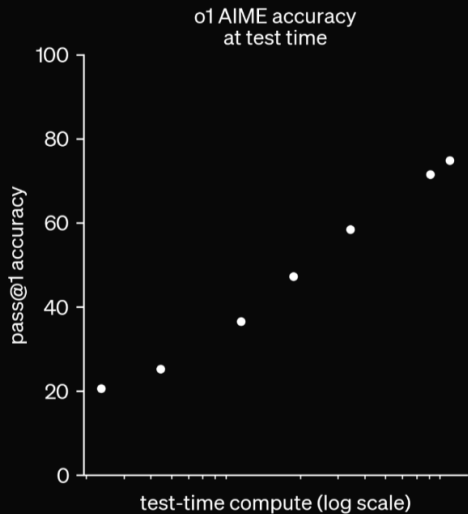
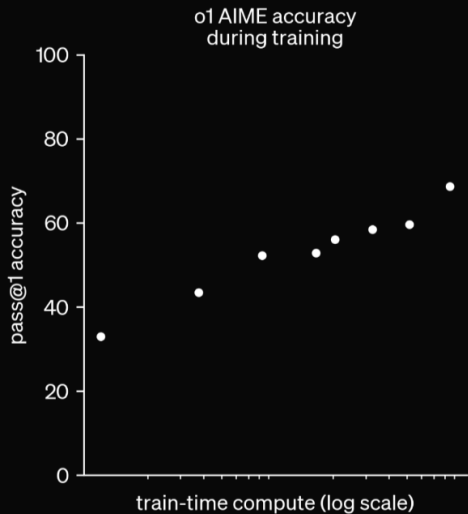


# **Speculations on Test-Time Scaling**

Sasha Rush Daniel Ritter

Cornell





# Importance of Search



# Bitter Lesson

The bitter lesson is based on the historical observations that 1) AI researchers have often tried to build knowledge into their agents, 2) this always helps in the short term, and is personally satisfying to the researcher, but 3) in the long run it plateaus and even inhibits further progress, and 4) breakthrough progress eventually arrives by an opposing approach based on scaling computation by **search and learning**.

# Example Problem

# This Talk

- Survey of the public literature
- Synthesis of discussions with experts (thx Lewis Tunstall, Edward Beeching, Aviral Kumar, Charlie Snell, Michael Hassid, Yoav Artzi, Rishabh Agarwal, Kanishk Gandhi, Wenting Zhao, Yuntian Deng, Nathan Lambert)
- Rumors

# Outline

Introduction

The Clues

Technical Background

The Suspects

What do we do now?



## o1 Description

Our large-scale **reinforcement learning algorithm** teaches the model how to think productively using its **chain of thought** in a highly **data-efficient** training process.

# Implication

- RL; Signal from verifiable problems
- CoT; Test-time occurs in token stream
- Data Efficient; Bounded set of problems

# Current Assumptions

- Single final language model
- Not following from expert examples
- Behavior is “learned”.

# Review: Chain of Thought

- In the process of answering a question, the model generates intermediate steps.
- These steps provide an scratchpad for hard technical problems.
- A limited number of examples provided.

# o1 Chain of Thought

o1 learns to hone its chain of thought and refine the strategies it uses. It learns to recognize and **correct its mistakes**. It learns to **break down tricky steps** into simpler ones. It learns to try a **different approach** when the current one isn't working.

## o1 CoT: Outlining

Implementation Outline:

1. Capture input string as argument.
2. Remove any spaces (if any).
3. Parse the input string to extract numbers into arrays.
  - Since the input is in the format '[1,2],[3,4],[5,6]', we can:
  - Remove outer brackets if necessary.
  - Split the string by '],' to get each row.
  - For each row, remove '[' and ']', then split by ',' to get elements.
4. Build a 2D array in bash (arrays containing arrays).

## o1 CoT: Planning

First, the cipher seems connected to the plaintext.

Given the time constraints, perhaps the easiest way is to try to see patterns.

Option 1: Try to find mapping from letters to letters.

Do any letters match?

First, let's write down the ciphertext and plaintext letters on top of each other.

## o1 CoT: Backtracking

Similarly,  $m(x) \cdot (-x^2) = (-x^{2n+2} + m^{2n-2}x^{2n} + \text{lower terms})$   
 $m(x) \cdot (-x^2) = (-x^{2n+2} + m^{2n-2}x^{2n} + \text{lower terms})$ .  
Wait, actually, this may not help us directly without specific terms. An alternative is to consider the known polynomials.  
So  $m(x) = k \dots$



## o1 CoT: Self-Evaluation

*Let's analyze each option.*

*Option A: "because appetite regulation is a field of staggering complexity."*

*Is that a good explanation? Hmm.*

*Option B: "because researchers seldom ask the right questions."*

*Does this make sense with the main clause?*

# Summary

- CoT provides test-time scaling
- CoT looks like search / planning in a classical sense
- RL needed to induce this behavior

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# Technical Background

- Formalize sampling of latent reasoning
- Techniques from combinatorial sampling
- No learning yet.

# Stepwise LLM Sampling

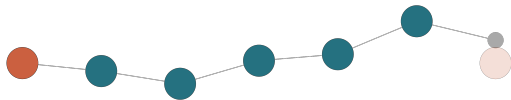
- $x$ ; problem specification
- $z_{1:T} \in \mathcal{S}^T$ ; chain of thought (CoT) steps
- $y \in \mathcal{Y}$ ; final answer

$$p(y|x) = \mathbb{E}_z p(y|x, z)$$

# Warm-up: Ancestral Sampling

$$z_{1:T} \sim p(\cdot | x)$$

$$y \sim p(\cdot | x, z_{1:T})$$



$T$  is the amount of test-time compute

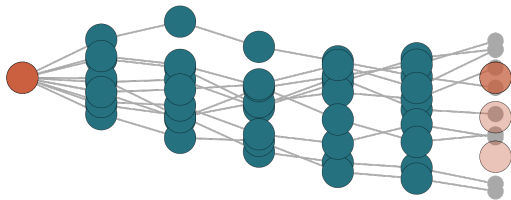
# Warm-up: Monte-Carlo (Self-Consistency)

For  $N$  samples,

$$z_{1:T} \sim p(\cdot | \mathbf{x})$$

$$y^n \sim p(\cdot | \mathbf{x}, z_{1:T})$$

Pick majority choice  $y^n$



# Assumption: Verifier

$$\text{Ver}_x : \mathcal{Y} \rightarrow \{0, 1\}$$

Examples:

- Regular expression for math
- Unit test for code
- Test questions for science



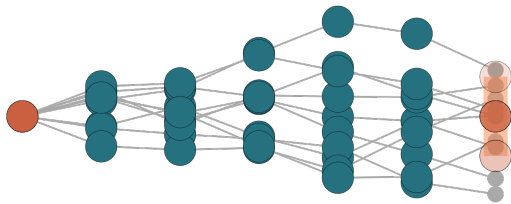
# Warm up: Rejection Sampling / Best-of-N

For  $n = 1$  to  $N$ :

$$z^n \sim p(z|x)$$

$$y^n \sim p(y|x, z^n)$$

Verified set  $\{y^n : \text{Ver}_x(y^n)\}$

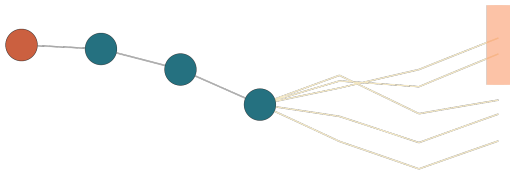


# Warm up: Monte-Carlo Roll-Outs

Given partial CoT  $z_{1:t}$ , expected value,

$$\mathbb{E}_{y \sim p(y|z, x), z_{t:T}} \text{Ver}_x(y)$$

Rollout = Monte Carlo for this expectation.



# Goal: Learning with Latent CoTs

Maximum likelihood;

$$\max_{\theta} \sum \log p(y|x; \theta) = \\ \sum \log \mathbb{E}_z p(y|x, z; \theta)$$

Classic combinatorial  
expectation

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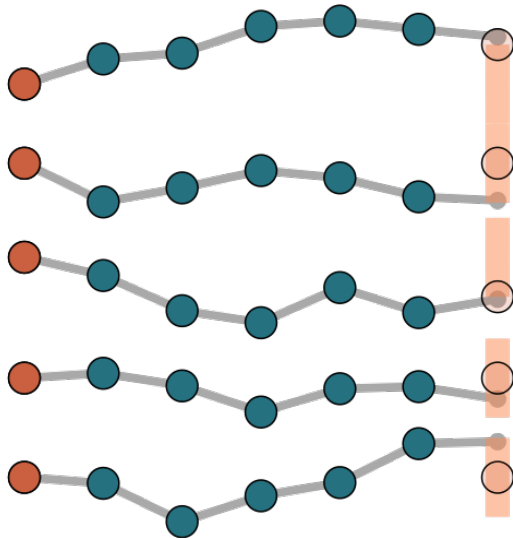
What do we do now?

# The Suspects

- Guess + Check
- Guided Search
- AlphaZero
- Learn to Search

# Suspect 1: Guess + Check

- 1) Sample  $N$  CoTs
- 2) Check if successful
- 3) Train on good ones



# G+C Formalization: Rejection Sampling EM

$$\max_{\theta} \sum \log E_{z \sim p(z|x; \theta)} p(y|x, z)$$

- E-Step: For  $n = 1$  to  $N$ :

$$z^n \sim p(\cdot|x)$$

$$y^n \sim p(\cdot|x, z^n)$$

Keep verified set  $\mathcal{Z} = \{z^n : \text{Ver}(y^n)\}$

- M-Step: Fit  $\theta' \leftarrow \arg \max_{\theta} \sum_{z \in \mathcal{Z}} \log p(z|x; \theta)$

# G+C Variants

- STaR
- ReST
- ReST-EM
- Filtered Rejection Sampling
- Best-of-N Training



## G+C Variants

- Batched -> Compute trajectories first, then train with behavioral cloning
- Online -> Use policy gradient-like steps to update after each example

# G+C Empirical Results

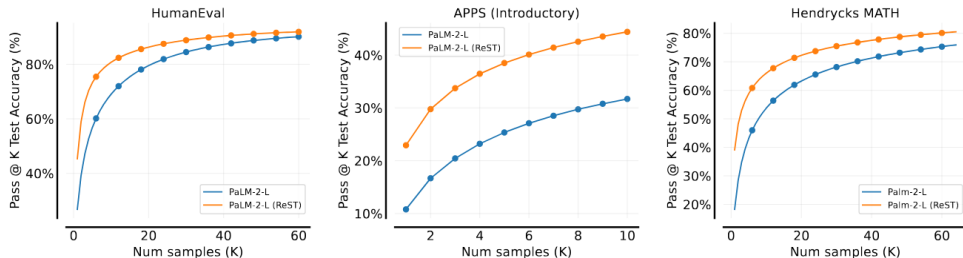


Figure 5 | **Pass@K results** for PaLM-2-L pretrained model as well as model fine-tuned with ReST<sup>EM</sup>. For a fixed number of samples K, fine-tuning with ReST<sup>EM</sup> substantially improves Pass@K performance. We set temperature to 1.0 and use nucleus sampling with  $p = 0.95$ .

# G+C Why might this be right?

## Pro

- Extremely simple and scalable
- Good baseline in past work

## Con

- No evidence this learns to correct, plan
- Well-explored in literature with marginal gains

# More Structure?

- Rejection sampling may be really inefficient.
- Particularly on hard problems, may get no signal

## Suspect 2: Guided Search

- During CoT sampling, use a heuristic to improve trajectories
- Check if final versions are successful
- Train on good ones

# GS: Beam Search with Guide

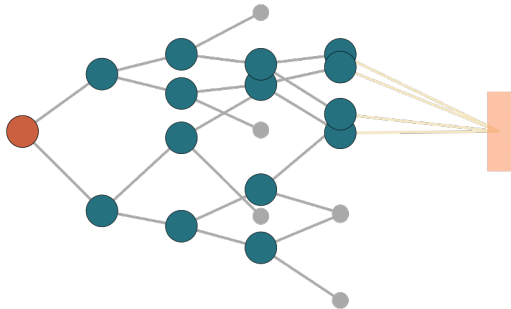
$r : \mathcal{S}^t \rightarrow \mathbb{R}$ ; Guide function

For each step  $t$

1. Sample next step,

$$z_t \sim p(\cdot | \mathbf{x}, z_{1:t-1}^i)$$

2. Keep the top  $N$  samples, ordered by  $r(z_t)$



# What to use as Guide?

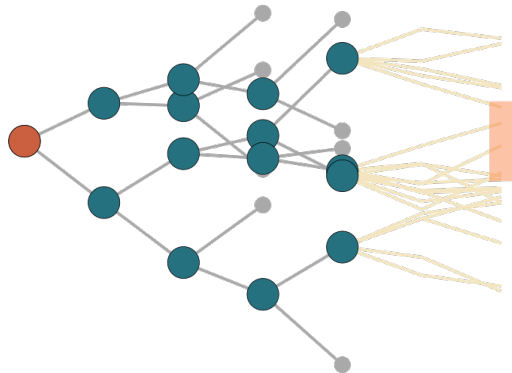
- Monte Carlo Roll-outs
- Learned Value Function
- Interleaved Value Function

# Beam Search with Roll-Outs

For a  $z_t$ , sample answers

$$y^n \sim p(\cdot | x, z_{1:t-1})$$

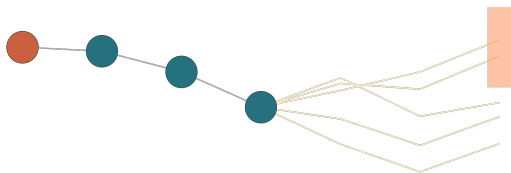
$$r_{MC}(z_t) = \frac{1}{N} \sum_{i=1}^N \text{Ver}(y^i)$$





# Amortized Roll-Outs

- Rollouts are costly, so instead learn a model  $r_\psi(z_t)$  to approximate rollouts
- Use  $r_{MC}$  to determine labels to train  $r_\psi$



# Interleaved

- Combine  $r_{MC}$  and  $r_{\psi}$
- $r_{Inter}(z_t) = (1 - \alpha)r_{MC}(z_t) + \alpha r_{\psi}(z_t)$

# What about test time?

- Learned rewards can improve test-time without verifier.
-

# Test-time Guides Outperform Self-consistency

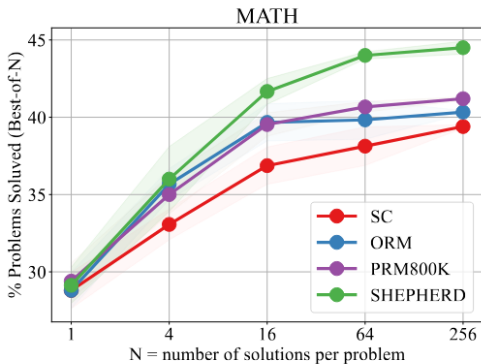
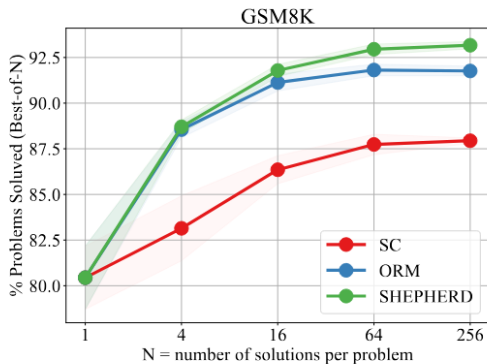


Figure 3: Performance of LLaMA2-70B using different verification strategies across different numbers of solution candidates on GSM8K and MATH.

# Terminology

[Uesato et al., 2022, Setlur et al., 2024,  
Wang et al., 2023, Lightman et al., 2023,  
Snell et al., 2024]

- Value
- PRM
- PAV
- Math Shepard.
- snell.

# Why might this be right?

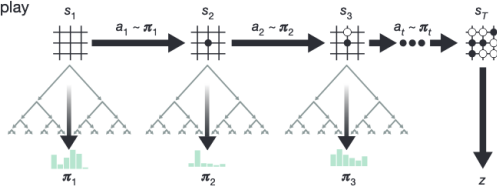
- OpenAI is exploring
- Makes RS more efficient.
- Learned rewards are effective
- Assumption: o1 is a single test-time model (although could train or distill-in)
- Not clear if it learns planning.

# More Structure

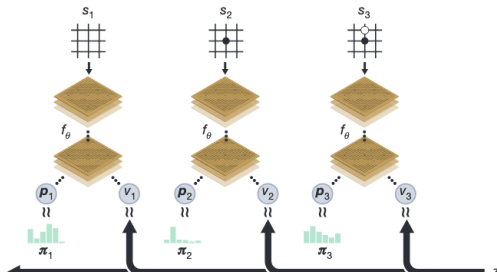
- Improving search seems critical.

# Reminder: AlphaZero

**a** Self-play



**b** Neural network training





## Suspect 3: AlphaZero

- Self-play using guided-search with exploration
- Label final outcomes of self-play games
- Train guide and generator

# Formalized: Expert Iteration

- Iterative algorithm combining learned model + expert search with a verifier.
- Generate samples using  $p(y, z|x)$ , reward model  $r(z_t)$ , and search algorithm (e.g. beam search)
- Label samples using  $Ver_x(y)$
- Train  $p(y, z|x)$ ,  $r(z_t)$  on the labeled samples, and repeat

# MCTS exploration

# UCB for Language

- Selection: Walk down tree to leaf  $z_{t-1}$
- Expand: Sample  $K$  next steps  $z_t^i$ , pick one at random
- Rollouts: Sample  $z_{t+1} \dots z_T$
- Backprop: Update nodes counts  $z_{1:t}$  based on results

# Compared with Search

## Pro

- System builds in exploration
- Scales to more train-time search

## Con

- Costly to maintain open states
- More complex algorithmically

# Empirical Results

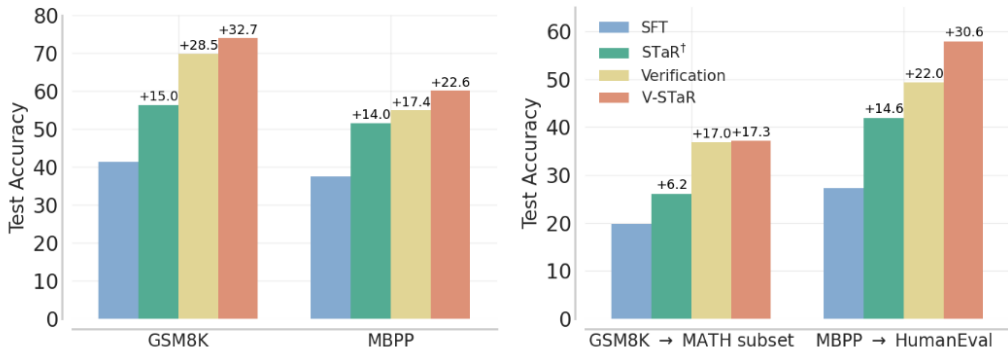


Figure 8: Test accuracy of 13B V-STaR compared to baselines. We report Best-of-64 for verification-based methods and Pass@1 for others. **(Left)** Test accuracy for training tasks. **(Right)** Transfer evaluation of GSM8K and MBPP trained models on MATH subset and HumanEval respectively.

# Why might this be right?

- Major demonstrated RL result
- 
- 
-

# More Structure

- Can we force the model to search?



## Suspect 4: Learning to Correct

- Sample  $N$  Successful CoTs
- Edit to inject incorrect expansions before correct ones.
- Train on correcting trajectories

# Self-Correction

- Argument: Training on  $x, z_1^*, y$  is too easy.
- Train instead on  $x, z', z_1^*, y$
- Model should learn to self-correct

# Score

- Positive rewards

# Challenge: Collapse

- Model may learn to just ignore negative
- 
-

# Generalized: Stream of Search

- Find  $z_{1:T}^*$  as optimal length CoT
- Find  $z'_{1:T'}$  with  $T' > T$  through backtracking tree search
- Train model on  $z'_{1:T'}$

# From Tree to Stream



# Empirical Results

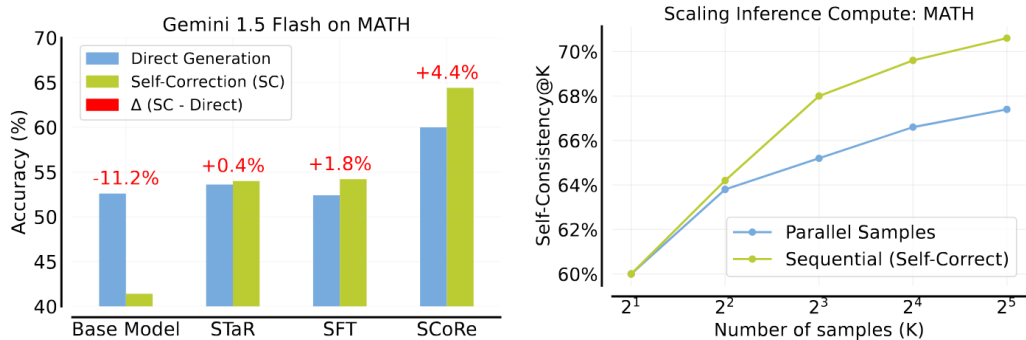


Figure 1 | **Left:** *SCoRe* achieves state-of-the-art self-correction performance on MATH; **Right:** *SCoRe* inference-time scaling: spending samples on *sequential* self-correction becomes more effective than only on *parallel* direct samples (Section 6.2).

# Empirical Results

Table 2 | Performance of *SCoRe* on MATH. *SCoRe* not only attains a higher accuracy at both attempts, but also provides the most positive self-correction performance  $\Delta(\mathbf{t1}, \mathbf{t2})$ .

Approach	Acc.@t1	Acc.@t2	$\Delta(\mathbf{t1}, \mathbf{t2})$	$\Delta^{i \rightarrow c}(\mathbf{t1}, \mathbf{t2})$	$\Delta^{c \rightarrow i}(\mathbf{t1}, \mathbf{t2})$
Base model	52.6%	41.4%	-11.2%	4.6%	15.8%
Self-Refine (Madaan et al., 2023)	52.8%	51.8%	-1.0%	3.2%	4.2%
STaR w/ $\mathcal{D}_{\text{StaR}}^+$ (Zelikman et al., 2022)	53.6%	54.0%	0.4%	2.6%	2.2%
Pair-SFT w/ $\mathcal{D}_{\text{SFT}}$ (Welleck et al., 2023)	52.4%	54.2%	1.8%	5.4%	3.6%
<b><i>SCoRe</i> (Ours)</b>	<b>60.0%</b>	<b>64.4%</b>	<b>4.4%</b>	<b>5.8%</b>	<b>1.4%</b>



## Why might this be right?

- 

- 

- 

-

# Less Structure?

- Maybe this is all too much...
- Could this be done without a verifier?

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# Replication

**Does it need to be the same?**



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