## **Click-Through Rate Prediction**





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#### Let's consider an automatic recommendation problem

- Given a set of restaurant indexed on a a web platform (think Tripadvisor)
- ...We want to estimate how likely a user is to actually open the restaurant card

This is know as click-through rate



This example (and the approach) is based on this TensorFlow Lattice Tutorail





## **Loading the Data**

#### Let's start by loading the dataset

- There are two numeric attributes, a categorical one, and a target
- Each row represents one visualization event, hence there might be duplicates

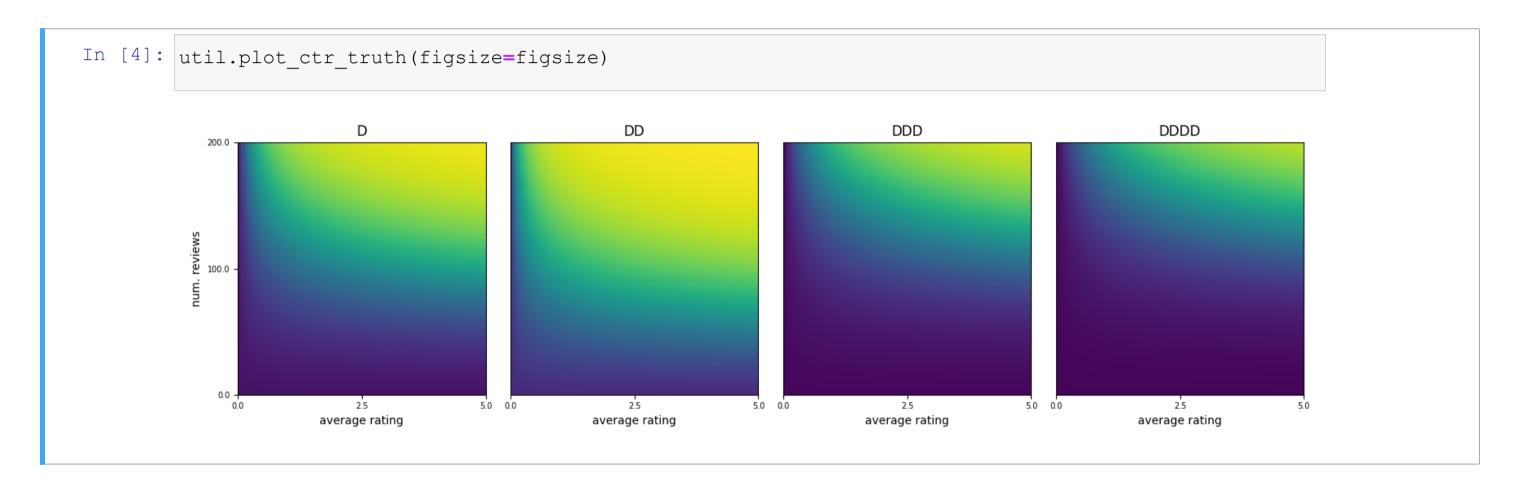
```
In [3]: dt_in = ['avg_rating', 'num_reviews', 'dollar_rating']
   ndup = np.sum(tr.duplicated(dt_in))
   print(f'#examples: {len(tr)}, #duplicated inputs {ndup}')

#examples: 835, #duplicated inputs 395
```



## **Target Function**

## This is a synthetic dataset, for which we know the target function



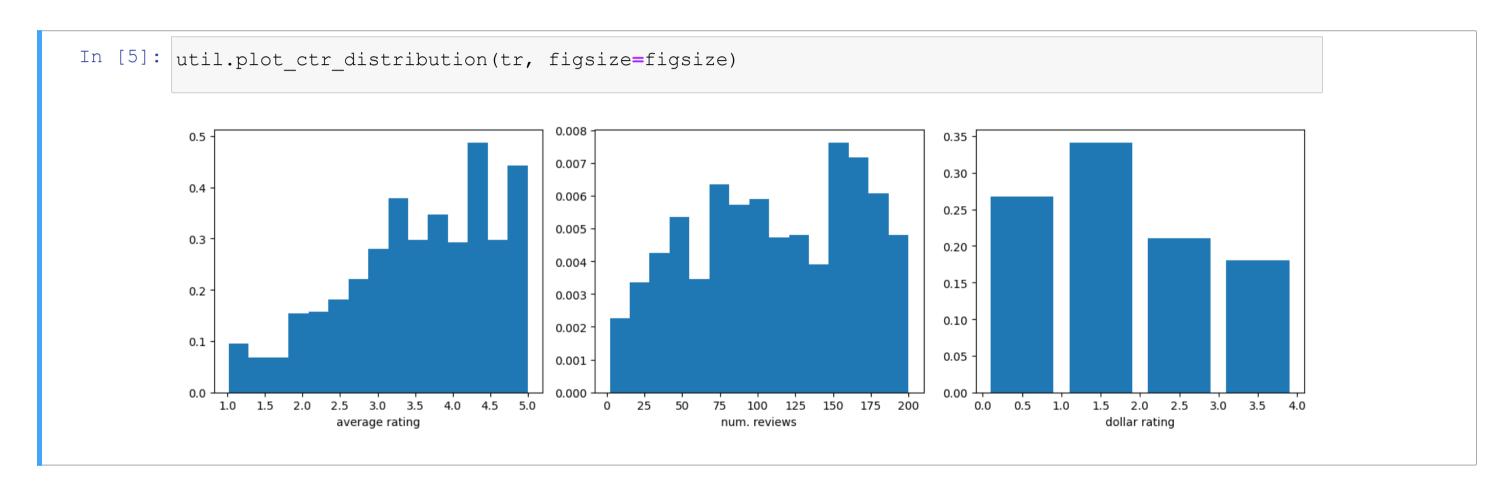
- The click rate grows with the average rating and the number of reviews
- Average priced restaurant are clicked the most





#### **Data Distribution**

## Let's check the attribute distribution on the training set

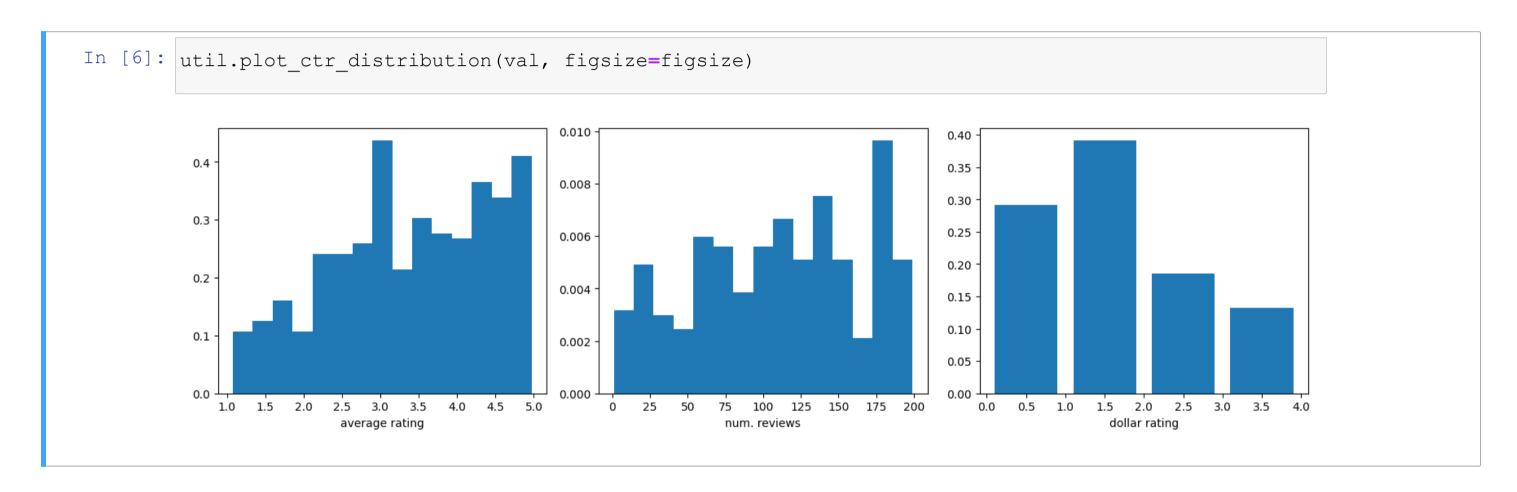






#### **Data Distribution**

#### ...Then on the validation set



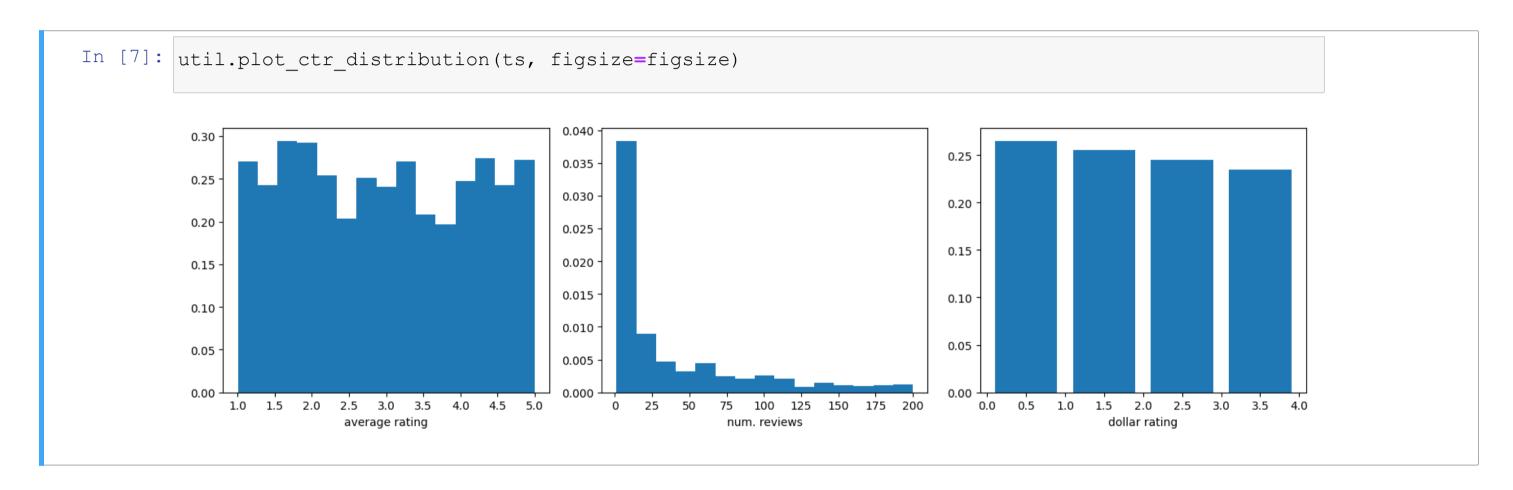
Not exactly the same, but it roughly matches





#### **Data Distribution**

## ...And finally on the test set



Here there is a strong discrepancy w.r.t. the training set





## **Distribution Discrepancy**

#### What is the reason for the discrepancy?

A training set for this kind of problem will come from app usage data

- Users seldom scroll through all search results
- ...So their clicks will be biased toward high ranked restaurant

Any training set obtained in this fashion will be strongly biased

#### However, click rate prediction is typically use for ranking search results

...Meaning that we will need to evaluate also less viewed restaurants

- In a practical problem, the test set would not even be available
- We have it just as a mean for validating our results

A bias in the training can be problematic: we will try to see that in action





# A Baseline Approach





## **Preparing the Data**

#### We will start by tackling the problem using a Multi Layer Perceptron

We normalize the numeric data:

We also adopt a one-hot encoding for the categorical data:

```
In [9]: tr_sc = pd.get_dummies(tr_s).astype(np.float32)
    val_sc = pd.get_dummies(val_s).astype(np.float32)
    ts_sc = pd.get_dummies(ts_s).astype(np.float32)
    dt_in_c = [c for c in tr_sc.columns if c != 'clicked']
```





## **Preparing the Data**

## Here is the result of our preparation

In [10]: tr\_sc

Out[10]:

	avg_rating	num_reviews	clicked	dollar_rating_D	dollar_rating_DD	dollar_rating_DDD	dollar_rating_DDDD
0	0.785773	0.610	1.0	0.0	0.0	0.0	1.0
1	0.785773	0.610	0.0	0.0	0.0	0.0	1.0
2	0.785773	0.610	0.0	0.0	0.0	0.0	1.0
3	0.866150	0.610	1.0	0.0	0.0	0.0	1.0
4	0.619945	0.590	0.0	0.0	1.0	0.0	0.0
•••	•••						
830	0.597304	0.055	1.0	0.0	1.0	0.0	0.0
831	0.783784	0.505	1.0	1.0	0.0	0.0	0.0
832	0.783784	0.505	1.0	1.0	0.0	0.0	0.0
833	0.688336	0.270	1.0	0.0	1.0	0.0	0.0
834	0.688336	0.270	0.0	0.0	1.0	0.0	0.0

835 rows × 7 columns

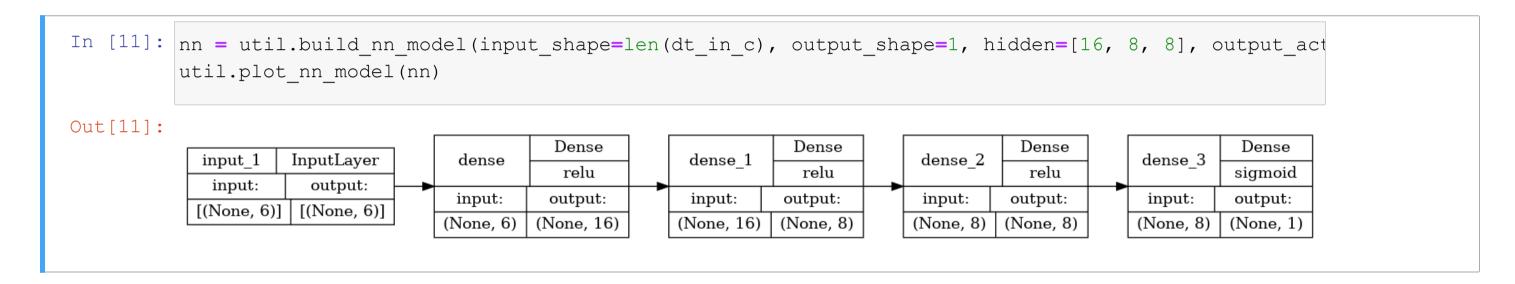




## **Building a Baseline Model**

#### Let's start by ignoring the issue

...And building as baseline model an MLP classifier



- Remember this is a stochastic prediction problem
- So, even if we train a classifier we are not interested in classes
- Rather, we care about estimated probabilities





## Training the Baseline Model

#### We can train the model as usual

```
In [12]: nn = util.build_nn_model(input_shape=len(dt_in_c), output_shape=1, hidden=[16, 8, 8], output_act
         history = util.train_nn_model(nn, tr_sc[dt_in_c], tr_sc['clicked'], loss='binary_crossentropy',
          util.plot training history(history, figsize=figsize)
           0.675
           0.650
           0.625
           0.600
           0.575
           0.550
           0.525
           0.500
                               20
                                                       60
                                                                               100
                                                                                            120
                                                                                                        140
                                                               epochs
          Final loss: 0.4921 (training)
```



#### **Loss Function**

#### What are we minimizing here?

Usually, ML introduction focus on two tasks

- Regression, where we need to estimate a numeric quantity
- Classification, where we need to predict a category

#### ...But both approaches are trained based on the same principle

- We want to choose the model parameters
- ...So that probability of the data, according to the ML model
- ...Is as large as possible

In fact, under certain conditions, most ML model can output probabilities





## **Evaluating the Predictions**

### This is not a classification problem, so accuracy is not a good metric

- The output of our system is meant to be interpreted as a probability
- ...So, rounding to obtain a deterministic prediction may be too restrictive

#### Instead, we will make a first evaluation using a ROC curve

A Receiver Operating Characteristic curve is a type of plot

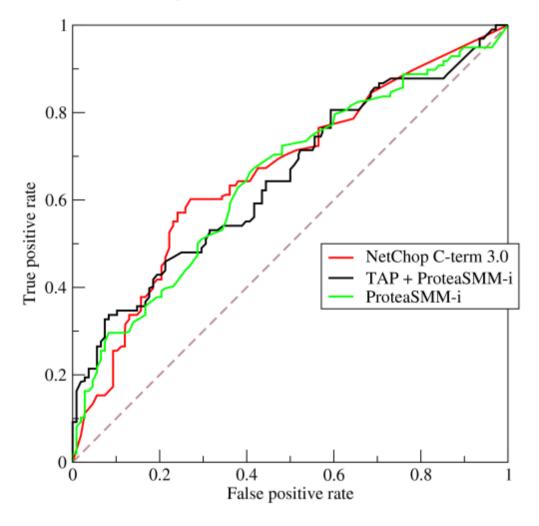
- We consider multiple threshold values
  - Each threshold is meant to be used for discriminating between classes
  - The usual rounding approach is equivalent to a 0.5 threshold
- $\blacksquare$  On the x axis, we report the false positive rate for each threshold
- lacksquare On the y axis, we report the true positive rate for each threshold





## **Evaluating the Predictions**

A ROC curve looks like this (image from wikipedia)



- The large the Area Under Curve (AUC), the better the performance
- $\blacksquare$  The AUC value is guaranteed to be in the [0, 1] interval





## **Evaluating the Predictions**

#### Let's compute the AUC values for all sets

```
In [13]: pred_tr = nn.predict(tr_sc[dt_in_c], verbose=0)
    pred_val = nn.predict(val_sc[dt_in_c], verbose=0)
    pred_ts = nn.predict(ts_sc[dt_in_c], verbose=0)
    auc_tr = roc_auc_score(tr_sc['clicked'], pred_tr)
    auc_val = roc_auc_score(val_sc['clicked'], pred_val)
    auc_ts = roc_auc_score(ts_sc['clicked'], pred_ts)
    print(f'AUC score: {auc_tr:.2f} (training), {auc_val:.2f} (validation), {auc_ts:.2f} (test)')
AUC score: 0.81 (training), 0.79 (validation), 0.76 (test)
```

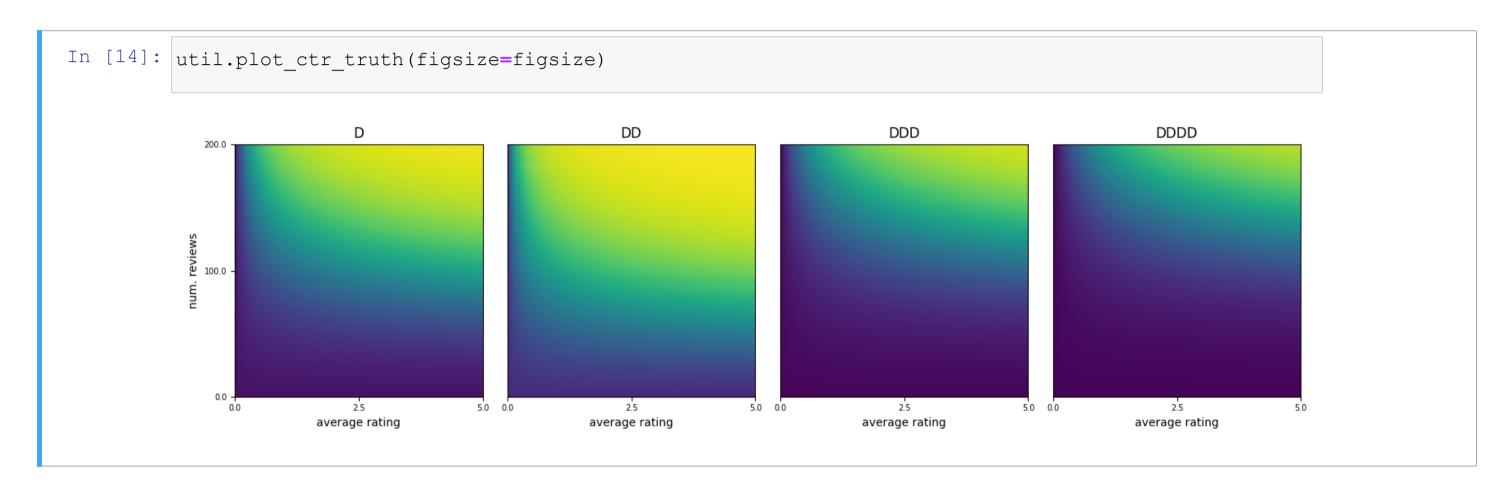
- The model works well on the training distribution
- But less well on the testing data (as expected)





#### Issues with the MLP

## Here we have again the ground truth for our click rate

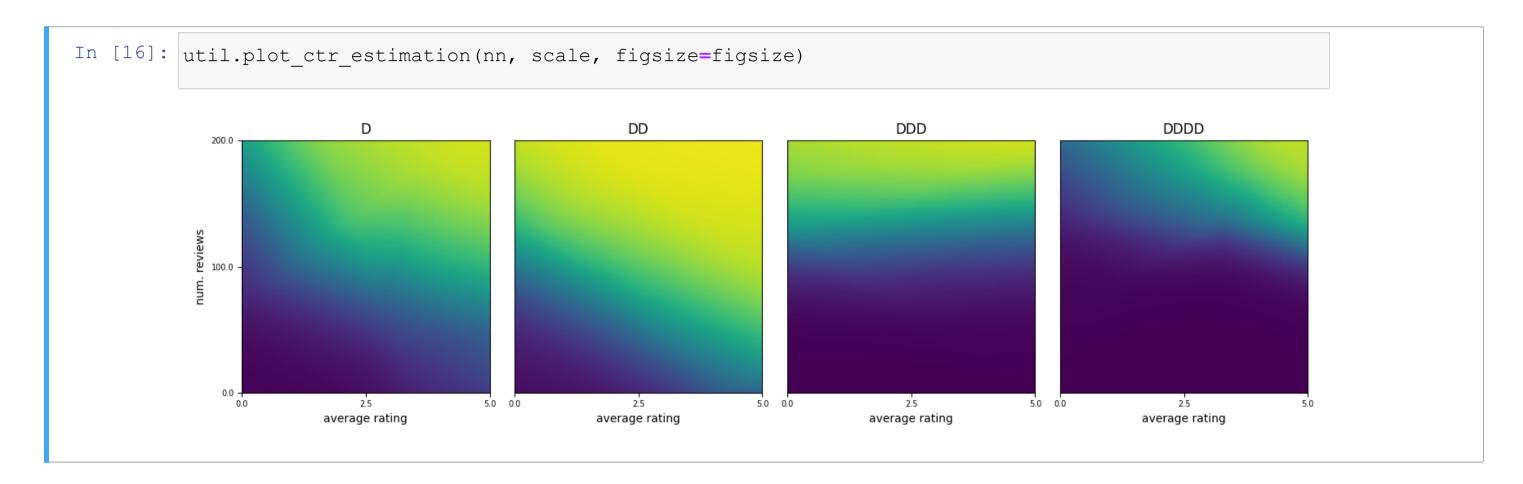






#### Issues with the MLP

### ...And here is the full (prediction) output space for the MLP



Something odd is happening here: can you tell what?





#### **Constraint Violations**

In some areas, increasing an attribute has the opposite of the expected effect

Our problem has natural monotonicities, which are may not hold for the MLP

- The motivation is that poor data for some region of the input space
- ...And ML models often have poor out-of-distribution behavior

#### This is a significant issue in practice

- In many domains a statistically representative training set is a luxury
- E.g. time series, organ trasplants programs, promo sales...

If we give up on those problem, we loose a lot of potential

#### More in general

■ In fact, most ML models are naturally incapable of enforcing constraints

