Field Storage 695

#### FIELD STORAGE

## **Purpose**

The classes of the menu *Field Storage* define the output points at which the field is calculated.

The output points may be grouped in a one-dimensional

Cut

or they may be grouped in a two-dimensional

Grid

Finally, field grids, irregular in two dimensions, may be defined in the class

Tabulated uv-Points

## **Command Types**

The calculation of the specified field is activated by one of the commands:

Get Field

Add Field

Subtract Field

Further, the following commands may be applied to interpolate, add and subtract already calculated fields.

Get Pattern

Add Pattern

Subtract Pattern

Replace Pattern

## Links

Classes→Electrical Objects→Field Storage

696 Cut

CUT

# **Purpose**

*Cut* is a menu which contains classes that define regular field cuts or pattern cuts.

Field upon a surface in space:

Spherical Cut (includes far-field cuts),

Planar Cut

Cylindrical Cut

Field at the surface of a scatterer:

Surface Cut

## Links

 $Classes \rightarrow Electrical\ Objects \rightarrow Field\ Storage \rightarrow Cut$ 

## SPHERICAL CUT (spherical\_cut)

## **Purpose**

The class *Spherical Cut* defines points in cuts on a sphere at which the field is to be calculated. Polar as well as conical cuts can be specified, both in the near-field and in the far-field region.

### Links

```
Classes \rightarrow Electrical\ Objects \rightarrow Field\ Storage \rightarrow Cut \rightarrow Spherical\ Cut Remarks
```

## Syntax

```
<object name> spherical cut
                                          : ref(<n>),
   coor_sys
   cut type
                                          : \langle si \rangle,
   theta range
                                         : struct(start:<r>, end:<r>, np:<i>),
   phi range
                                         : struct(start:<r>, end:<r>, np:<i>),
   e_h
                                         : <si>,
   polarisation
                                         : <si>,
   polarisation modification
                                         : struct(status:<si>, coor_sys:ref(<n>)),
   near_far
                                         : <si>,
   near dist
                                         : <rl>,
                                         : <f>.
   file name
   file format
                                          : \langle si \rangle,
   comment
                                         : <s>,
                                          : ref(<n>)
   frequency
)
where
\langle i \rangle = integer
\langle n \rangle = name of an object
\langle r \rangle = real number
<rl> = real number with unit of length
\langle s \rangle = character string
\langle f \rangle = file name
<si> = item from a list of character strings
```

### **Attributes**

Coordinate System (coor\_sys) [name of an object], default: **blank**.

Reference to an object of one of the classes in *Coordinate System* defining the coordinate system (the output coordinate system) in which the field points will be calculated. Further, the origin serves as the phase reference for far-fields. The field polarisation components will also be expressed in this coordinate system unless otherwise specified in the attribute *polarisation\_modification*.

Cut Type (cut type) [item from a list of character strings], default: polar.

Defines the direction of the cuts over the sphere. See also the remarks below.

polar

Polar cuts are cuts for which  $\phi$  is constant and  $\theta$  is varying. Polar cuts will pass through the pole of the sphere when  $\theta=0^\circ$  is within the  $\theta$ -range.

conical

Conical cuts are cuts for which  $\theta$  is constant and  $\phi$  is varying.

theta-Range (theta range) [struct].

Defines the range of the polar angle  $\theta$  (see the remarks below).

Start (start) [real number].

Start value of the polar coordinate  $\theta$ , in degrees.

End (end) [real number].

End value of the polar coordinate  $\theta$ , in degrees.

Np (np) [integer].

Number of  $\theta$ -values. When the  $cut\_type$  is specified to 'polar' np is the number of  $\theta$ -values in each polar cut. When the  $cut\_type$  is specified to 'conical' np is the number of conical cuts.

phi-Range (phi\_range) [struct].

Defines the range of the azimuthal angle  $\phi$  (see the remarks below).

Start (start) [real number].

Start value of the azimuthal coordinate  $\phi$ , in degrees.

End (end) [real number].

End value of the azimuthal coordinate  $\phi$ , in degrees.

Np (np) [integer].

Number of  $\phi$ -values. When the  $cut\_type$  is specified to 'polar' np is the number of polar cuts. When the  $cut\_type$  is specified to 'conical' np is the number of  $\phi$ -values in each conical cut.

E/H-Field (e h) [item from a list of character strings], default: **e field**.

Specifies whether the complex E-field or H-field shall be calculated.

e field

The complex E-field is calculated.

h field

The complex H-field is calculated.

Polarisation (*polarisation*) [item from a list of character strings], default: **linear**.

Defines how the calculated field shall be decomposed. All components refer to the polarisation coordinate system as defined under the attribute Polarisation Modification. In the near field the r-component of the field is calculated as a third component.

#### linear

Linear components are calculated according to Ludwig's  $3^{rd}$  definition, with the first component  $(E_{co})$  along x and the second component  $(E_{cx})$  along y (at  $\theta=0^{\circ}$ ). The notation implies that for a field, which is mainly y-polarised then the second component  $(E_{cx})$  represents the co-polar field component.

#### circular

Circular components are calculated based on the linear components defined above. The first component is the right hand circular ( $E_{rhc}$ ) and the second is left hand circular component ( $E_{lhc}$ ).

## theta phi

The field is decomposed along the  $\theta$ - and  $\phi$ -unit vectors with the  $\theta$ -component ( $E_{\theta}$ ) being the first component and the  $\phi$ -component being the second ( $E_{\phi}$ ).

## major\_minor

The field is de-composed along the major and minor axes of the polarisation ellipse. The first field component is parallel to the major axis  $(E_{maj})$  and the second to the minor axis  $(E_{min})$ .

#### linear xpd

The ratios  $E_{co}/E_{cx}$  and  $E_{cx}/E_{co}$ , where  $E_{co}$  and  $E_{cx}$  are the first and second components as defined for the 'polarisation: linear' above. This is the linear cross-polar discrimination ratio.

#### circular xpd

The ratios  $E_{rhc}/E_{lhc}$  and  $E_{lhc}/E_{rhc}$ , where  $E_{rhc}$  and  $E_{lhc}$  are the first and second components as defined for the 'polarisation: circular' above. This is the circular cross-polar discrimination ratio.

## theta\_phi\_xpd

The ratios  $E_{\theta}/E_{\phi}$  and  $E_{\phi}/E_{\theta}$ , where  $E_{\theta}$  and  $E_{\phi}$  are the first and second components as defined for the 'polarisation: theta\_phi' above.

#### major\_minor\_xpd

The ratios  $E_{maj}/E_{min}$  and  $E_{min}/E_{maj}$ , where  $E_{maj}$  and  $E_{min}$  are the first and second components as defined for the 'polarisation: major\_minor' above.

power

The first component is the amplitude of the field,  $\left| \vec{E} \right|$ , (i.e. the square root of the power) and the second component is the complex square root  $\sqrt{E_{rhc}/E_{lhc}}$ . The phase of the latter component is the rotation angle of the polarisation ellipse.

In the far field the square root of the power is determined from  $\left| \vec{E} \right| = \sqrt{\left| E_{co} \right|^2 + \left| E_{cx} \right|^2}$ 

and in the near field it is determined from all three field components:  $\left| \vec{E} \right| = \sqrt{\left| E_{co} \right|^2 + \left| E_{cx} \right|^2 + \left| E_r \right|^2}$ ,  $E_r$  being the r-component of the field.

Polarisation Modification (polarisation modification) [struct].

Defines a coordinate system in which the field polarisation components are determined (if different from the output coordinate system defined).

Status (status) [item from a list of character strings], default: off.

Determines if the polarisation modification shall be performed:

off

No polarisation modification, the polarisation is defined in the above defined output coordinate system and the polarisation coordinate system is identical to the output coordinate system.

on

The polarisation is defined in the coordinate system defined next.

Coordinate System (*coor sys*) [name of an object], default: **blank**.

Reference to an object of one of the classes in *Coordinate System* defining the coordinate system (the polarisation coordinate system) in which the polarisation components of the calculated field vectors will be expressed. Shall only be specified for *status*: on.

Near Far (near far) [item from a list of character strings], default: far.

The value specifies if a near or a far field is to be calculated.

far

A far field is calculated. In this case only two field components are calculated according to the specified *polarisation* as described in the remarks below.

near

The three field components of a near field is calculated. These are the two components defined under the attribute *polarisation* below and the third component is the radial component.

Near Dist (near dist) [real number with unit of length], default: 0.

Defines the radius of a near-field sphere. For a far field this attribute has no effect and needs not to be specified.

File Name (file name) [file name].

Name of a file, to which the calculated field values shall be written.

File Format (*file\_format*) [item from a list of character strings], default: **TICRA**.

The file format used to store the field data:

**TICRA** 

The field is written in GRASP units and stored as an ASCII-file according to the TICRA-format described in *Field Data in Cuts*. The recommended file extension is .cut.

**EDX** 

The field is written in SI units in a format according to the Electromagnetic Data Exchange (EDX) standard. The recommended file extension is .cut.

Files in this format cannot be read by the PostProcessor.

EDI

Obsolete file format name. The same as EDX.

Comment (comment) [character string], default: Field data in cuts.

A line of text which will be written as a header in the file specified by file\_name above.

Frequency (frequency) [name of an object], default: **blank**.

Reference to a *Frequency* object, defining the frequencies for which the field is calculated. The reference must be to the same object as specified in the *frequency* attribute of the source generating the field. A *frequency* needs not to be specified. In that case, the frequencies in the *frequency* object of the source generating the field will be applied.

## **Command Types**

The *Spherical Cut* class is derived from the class *Field Storage*. See this class for available commands.

#### **Remarks**

The section introduces the position of the field points and the definition of a polarisation coordinate system.

## **Field Points**

Field points in a *Spherical Cut* are defined in usual spherical  $(\theta,\phi)$ -coordinates given in the output coordinate system. For far fields,  $(\theta,\phi)$  defines a direction

```
\hat{r} = \hat{x}\sin\theta\cos\phi + \hat{y}\sin\theta\sin\phi + \hat{z}\cos\theta
```

and for near fields,  $(\theta, \phi)$  defines a point

$$\bar{R} = R(\hat{x}\sin\theta\cos\phi + \hat{y}\sin\theta\sin\phi + \hat{z}\cos\theta)$$

where  $R=\left|\bar{R}\right|$  is the radius (given by Near Dist) of the near-field sphere. In a polar cut,  $\phi$  is fixed and  $\theta$  takes on the values

$$\theta_i = \theta_{start} + \Delta\theta \cdot (i-1), \qquad i = 1, 2, ..., n_{\theta}$$
(1)

with

$$\Delta\theta = (\theta_{end} - \theta_{start})/(n_{\theta} - 1)$$

where  $\theta_{start}$  and  $\theta_{end}$  are the members *start* and *end*, respectively, of the attribute *theta\_range*, and  $n_{\theta}$  is the member np of the same attribute.

The  $\phi$ -angle is increased equidistantly from one cut to the next by the values

$$\phi_j = \phi_{start} + \Delta\phi \cdot (j-1), \qquad j = 1, 2, ..., n_{\phi}$$
 (2)

with

$$\Delta \phi = (\phi_{end} - \phi_{start})/(n_{\phi} - 1)$$

where  $\phi_{start}$  and  $\phi_{end}$  are the members start and end, respectively, of the attribute  $phi\_range$ , and  $n_{\phi}$  is the member np of the same attribute.

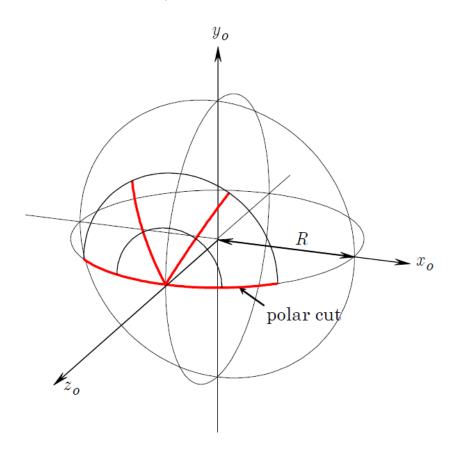


Figure 1 4 polar cuts for  $0^{\circ} \le \theta \le 45^{\circ}$ , and  $\phi = 0^{\circ}$ ,  $60^{\circ}$ ,  $120^{\circ}$  and  $180^{\circ}$ .

In a conical cut  $\theta$  is fixed and  $\phi$  runs through the values given by Eq. (2). From one conical cut to the next, the  $\theta$ -angle is increased according to Eq. (1).

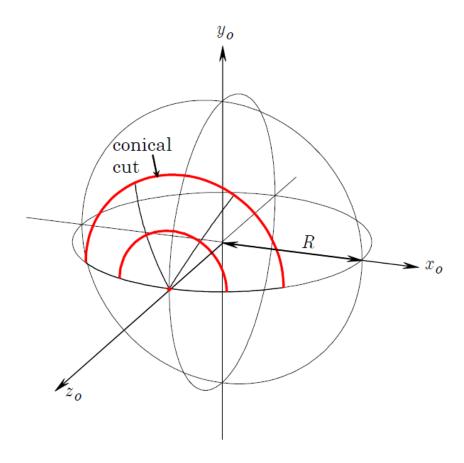


Figure 2 3 conical cuts for  $\theta=0^\circ$ ,  $22.5^\circ$  and  $45^\circ$ , and  $0^\circ \leq \phi \leq 180^\circ$ .

# The Polarisation Coordinate System

When the field polarisation is requested in another coordinate system than the output coordinate system then the attribute *polarisation\_modification* shall be applied with 'status: on' followed by a reference to the polarisation coordinate system.

The attribute *polarisation* may be specified as 'linear' ( $E_{co}$ - and  $E_{cx}$ -components), 'circular' ( $E_{rhc}$ - and  $E_{lhc}$ -components) or 'theta\_phi' ( $E_{\theta}$ - and  $E_{\phi}$ -components). In the near field also an  $E_r$ -component will be present. In case of 'theta\_phi' polarisation the electric field is given by

$$\bar{E} = E_r \hat{r} + E_\theta \hat{\theta} + E_\phi \hat{\phi}$$

where  $\widehat{r}$ ,  $\widehat{\theta}$  and  $\widehat{\phi}$  are the polarisation vectors in the polarisation coordinate system. The spherical cut in which the field is determined is always given in the output coordinate system.

An example is shown in Figure 3, the cut is the polar cut shown in red and the field shall be determined at one of the output points, P. The output coordinate system is denoted  $x_0y_0z_0$  and the polarisation coordinate system is  $x_py_pz_p$ . In the figure the latter is a simple rotation of the former around the y-axis but any coordinate system may be chosen as polarisation coordinate system.

Internally in GRASP the field is calculated in Cartesian components in the output coordinate system

$$\bar{E} = E_{ox}\widehat{x}_0 + E_{oy}\widehat{y}_0 + E_{oz}\widehat{z}_0$$

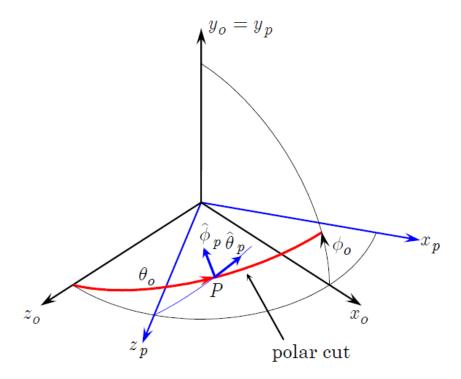


Figure 3 In red is shown a single polar cut in the output coordinate system given by  $x_0y_0z_0$ . A field point P at the direction  $(\theta_0,\phi_0)$  is illustrated. The polarisation is expressed in  $\theta\phi$ -components (polarisation: theta\_phi) along  $\hat{\theta}_p$  and  $\hat{\phi}_p$  in the polarisation coordinate system  $x_py_pz_p$ .

The field is then converted to the new components

$$\bar{E} = E_{px}\hat{x}_p + E_{py}\hat{y}_p + E_{pz}\hat{z}_p$$

before the Cartesian components are converted to (in this case) the polar components in the usual way.

The resulting  $\theta_p$ -component (shown in blue) is pointing away from the  $z_p$ -axis in the same way as the standard  $\theta_0$ -component will point away from the  $z_0$ -axis (along  $\theta_0$ ).