# Practice Set 4: Solutions

Problem 1:

- We saw in class that the run time of Counting sort on input of size n is O(n+m) where the numbers in the array are all at most m. If the numbers are less than  $n^3$ , the overall runtime is  $O(n^2+n) = O(n^2)$ .
- If the numbers are in the range 0 to  $n^2$  then the run time of Counting sort is  $O(n+n^2)=O(n^2)$ .
- If each number is in binary and less than  $2^n$ , then the number requires at most n digits. We saw that Radix sort runs in time O(d(n+r)) where d is the number of digits and r is the radix. Therefore Radix sort in this case runs in time  $O(n(n+2)) = O(n^2)$ .
- In this case, each binary number requires at most  $\log_2(n^2)$  digits, which is  $2\log_2(n)$ . Note that r=2. Therefore Radix sort runs in time  $O(2\log_2(n)(n+2)) = O(n\log n)$ .
- In this case, each decimal number requires at most  $\log_{10}(n)$  digits and r = 10. Therefore Radix sort runs in time  $O(\log_{10} n(n+10)) = O(n \log n)$ .

## Problem 2:

Design bucket sort with n buckets distributed over the range -10...0. Each bucket covers a range of length 10/n. The first bucket goes from -10...-10+10/n. Since the numbers are uniformly distributed, there is an equal chance that a number falls in any one bucket. Therefore the *expected* number of elements in each bucket is  $E(n_i) = n/n = 1$ . The expected time to sort each bucket is constant, and therefore the time to sort all n buckets is O(n). Bucket sort then performs a final pass through all n buckets, outputting the elements in sorted order. This takes time O(n). Therefore the overall **expected** runtime is O(n).

The worst-case runtime is when all numbers fall into one bucket, which could happen because the numbers are random. If this happens, insertion sort will take  $O(n^2)$  just to sort that one bucket. The overall runtime is then  $O(n^2)$ . MergeSort and Heapsort both have a worst-case runtime of  $O(n \log n)$ , which is a big improvement in the worst-case. Note that we could **not** use Counting sort or Radix sort here, because the numbers are not integers.

### Problem 3:

The expected runtime of bucket sort applies when the input is uniformly distributed over a range. It is very unlikely that class grades are uniform. There are probably a large number of grades around the average, and very few grades near 100 and 0. Therefore using Bucket sort is not a good idea, since we can't reasonably conclude that the expected runtime will be O(n), and instead it is reasonable to assume that many numbers would end up in just a few buckets.

Each number is of the form xxx.xx where each x represents a digit 0, 1, ... 9. If we multiply each number by 100, then the new grades are in the range 0 to 10,000, and they are now *integers*. Therefore we can use Counting sort, where m = 10,000. The runtime to sort the grades using Counting sort is O(n+m) = O(n+10,000) = O(n). Once the grades are sorted, we simply divide each number by 100 in order to reproduce the original grades. This does not affect the sorted order, and therefore the final result is the original grades in sorted order. Therefore it is possible to use Counting Sort to get a worst-case runtime of O(n). Similarly, we could use Radix sort on the grades. Once they have been multiplied by 100, each number is in the range 0 to 10,000 and therefore d = 5 and r = 10. Therefore the worst-case runtime of Radix sort is O(5(n+10)) = O(n).

#### Problem 4:

Since there are n fractions, we could use any comparison-based sort, such as Mergesort or Quicksort and sort the numbers in  $O(n \log n)$  time. However, since we have a bound on the denominator, we might be able to do better. If we could convert every fraction to a whole number, we could use Counting sort. Any

fraction in the list has a denominator  $\leq 1000$ . Thus multiplying each fraction by  $1000! = 1 \cdot 2 \cdot 3 \cdot \ldots \cdot 1000$  converts each fraction to a whole number. And since we multiplied each fraction by the same number, then the relative order of the input has not changed. Once the converted numbers are sorted, we simply divide each number by 1000! to restore the result.

Therefore we can use Counting sort to sort these new larger numbers. Note that the maximum value is 1000!. Thus the runtime will be O(n + 1000!) = O(n). Although the constant of the big-oh is huge, it is nevertheless still linear. Once the numbers have been sorted, we can simply divide each number by 1000! to reproduce the original values.

Similarly, we could use Radix sort to sort the converted numbers. In this case, r = 10 and  $d = \log_{10} 1000!$ . Therefore the runtime is  $O(d(n+r)) = O(\log_{10} 1000!(n+10)) = O(n)$ .

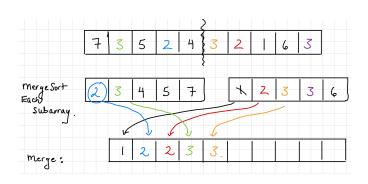
#### Problem 5:.

In the third step of counting sort, the elements of the array A are removed from back to front and placed in the output array in the position based on the number of elements that are smaller or equal to that element. For example, element 3 in the array below currently has rank 4 because there are 4 elements less than or equal to 3. It goes into position 4 in the output array (the orange step below). Because we process the input array from back to front, when the next 3 is encountered (in pink), it will be inserted to the left of the previous 3 in the output array.(the pink step below). The result is that counting sort is a stable sorting algorithm: duplicate items appear in the output array in their original order.

input:	3 2 4 2	3
	Step 4 V Step	1
Countria	0 2 43 3	
	1 2 3 4	
Ootput avray.	3 3	
	1 2 3 4	2

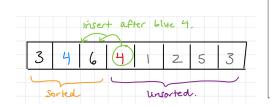
Mergesort and Insertion sort are not necessarily stable. We could update them slightly in order to make sure they produced stable output.

Mergesort: We could update the Merge step so that when it compares the front elements of each subarray, it breaks ties by selecting the element from the front of the left subarray first, as shown in the illustration on the left below. This only requires a small update to the pseudo-code of Merge, shown on the right below:



```
\begin{aligned} &\operatorname{Merge}(A,\,s,\,q,\,f) \\ &\operatorname{Let}\,L\,[] \text{ and } R\,[] \text{ be new arrays} \\ &\operatorname{Copy} \text{ elements from } A \text{ between } s \text{ and } q \text{ into array } L\,[] \\ &\operatorname{Set}\,L\,[q-s+2] = \infty \\ &\operatorname{Copy} \text{ elements from } A \text{ between } q+1 \text{ and } f \text{ into array } R\,[] \\ &\operatorname{Set}\,R\,[f-q+1] = \infty \\ &i=1,j=1 \\ &\operatorname{for}\,k=s \text{ to } f \text{ do:} \\ &\operatorname{if}\,L\,[i] \leq R\,[j] \\ &A\,[k] = L\,[i] \\ &i++ \\ &\operatorname{else}\,A\,[k] = R\,[j] \\ &j++ \end{aligned}
```

Insertion sort: If we were careful in the implementation of Insertion sort to ensure that when a duplicate element is encountered, that the new element is placed to its right, then the result will be a stable algorithm. Note that the original pseudo-code for insertion sort was already implemented in this way:



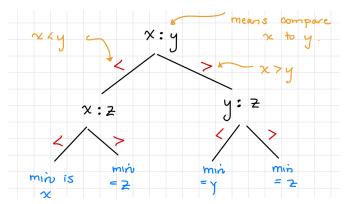
```
InsertionSort(A[1 \dots n])
for i = 2 to n:
j = i
for j = i down to 2:
if A[j] < A[j-1]
Swap A[j] and A[j-1]
else break
```

Bubble sort: The original implementation of bubble sort that we saw in class is shown below. Not that when duplicate elements are encountered, they are not swapped. Therefore a duplicate on the "right", stays on the right. Therefore Bubble sort is indeed stable.

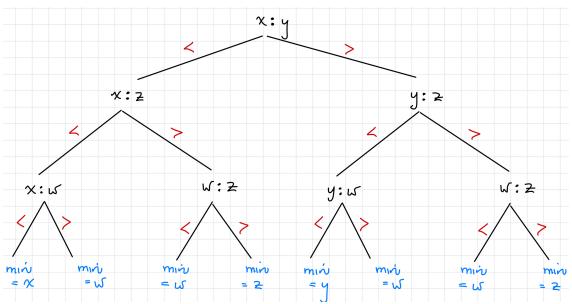
```
made-swap = true
while(made-swap)
    made-swap = false
    for i = 1 to n-1
        if A[i+1] < A[i]
            Swap A[i] and A[i+1]
            made-swap = true</pre>
```

## Problem 6:

Assume the three numbers are x, y, z and they are distinct. The decision tree for finding the min is shown below. Note that at each node in the tree, we simply compare the next element to the current min, and that the height of the tree is 2.



In order to find the min of x, y, z, w we use a similar approach. The decision tree is shown below. The height in this case is 3:



Given a set of n numbers, it not possible that there is a path in that tree that has length less than n-1. The argument is by contradiction. Since there are n numbers, we cannot conclude that any one number is the max unless it has at least been compared to all the other numbers. That would take at least n-1 comparisons. So all paths must have length at least n-1. This means that the height of the tree is at least n-1. Therefore any algorithm that finds the min in a set of n numbers must run have a run time of at least  $\Omega(n)$ .

In fact, it is possible to create a decision tree for finding the max that has height exactly n-1. The examples above demonstrate this fact.

#### Problem 7:

Suppose we use n/2 buckets in bucket-sort instead of n. Since the numbers are over the range  $0 \le x \le 1$ , each bucket has "size"  $\frac{1}{n/2} = 2/n$ . Since the data is uniformly distributed, the *expected* number of elements in each bucket is 2 (instead of 1). Nevertheless, this is still a constant. Thus we expect  $n_i$  to be a constant, in other words  $E(n_i) = constant$  As mentioned in class, this means  $E(n_i^2) = constant$ . So the runtime for insertion sort on *each* bucket is expected to be a constant. There are n/2 buckets and so the total runtime to sort them all is O(n/2) = O(n). The last step of bucket sort is to loop through all the buckets and output the sorted numbers. Since there are n/2 buckets, this last step also runs in time O(n). Therefore the entire algorithm runs in time O(n).

Next, suppose we have  $\sqrt{n}$  buckets. Then each bucket has "size"  $\frac{1}{\sqrt{n}}$ . For uniformly distributed numbers, the expected number of elements in each bucket is  $\frac{n}{\sqrt{n}} = \sqrt{n}$ . Insertion sort on each bucket is not expected to be a constant, since there are not a constant number of elements per bucket. In fact one can show that the expected runtime of insertion sort is O(n) when there are expected be be  $\sqrt{n}$  elements. Since there are  $\sqrt{n}$  buckets in total, sorting all buckets takes time  $O(n^{1.5})$ . The last step of bucket sorts loops through the  $\sqrt{n}$  buckets, taking time  $O(n^{0.5})$ . Nevertheless, the overall runtime is  $O(n^{1.5})$ .

Suppose we have  $n^2$  buckets. Then each bucket has "size"  $\frac{1}{n^2}$ . For uniformly distributed numbers, the expected number of elements in each bucket is  $\frac{n}{n^2} = \frac{1}{n}$ . Insertion sort on each bucket is expected to be less than 1. Therefore the expected time of insertion sort on each bucket is constant. Since there are  $n^2$  buckets, sorting *all* buckets takes time  $O(n^2)$ . The last step of bucket sorts loops through the  $n^2$  buckets, taking time  $O(n^2)$ . Therefore the overall runtime is  $O(n^2)$ .

### Problem 8:

```
First we find the maximum value:

m = A[1]

for i = 2 to n
```

m = max(m, A[i])

Next we count the number of occurrences of each element. In the solution below, we assume the input consists of numbers  $\geq 1$ , so the array C starts at 1.

```
Initialize array C[1, ..., m] = 0

for i = 1 to n

C[A[i]] = C[A[i]] + 1

Next we finalize the array C:

for i = 2 to m

C[i] = C[i] + C[i-1]

Next we fill in an output array B:

Initialize output array B[1, ..., n]

for i = n down to 1

index = C[A[i]]

B[index] = A[i]

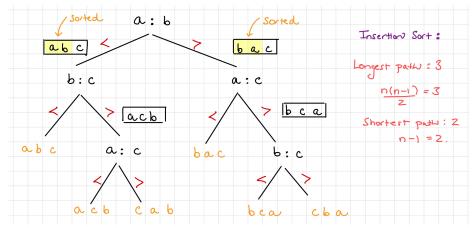
C[A[i]] = C[A[i]] - 1

Copy Result back into A:

ArrayCopy(A,B)
```

### Problem 9

• Below is the decision tree that represents the execution of insertion sort on  $\{a, b, c\}$ . The shortest path in the above tree is 2 and the longest path is 3.



- If the input is already sorted, we know that insertion sort only performs n-1 comparisons. Therefore the decision tree for insertion sort will have a path of length n-1, representing the best-case scenario. We also saw that the *exact* number of comparisons in the worst case is n(n-1)/2. Therefore the longest path of the decision tree for insertion sort has length n(n-1)/2.
- Selection sort on the other hand, always performs the same number of comparisons, regardless of input. We saw in week 1 that the number of comparisons performed by selection sort is always  $(n-1) + (n-2) + \ldots + 1 = n(n-1)/2$ . Therefore all paths in the decision tree for Selection sort will have length n(n-1)/2.
- In comparison-based sorting, we need at least n-1 comparisons to determine the sorted list. This can be argued by contradiction. If in fact we used less than n-1 comparisons, there there is at least one pair  $x_i, x_j$  that was never compared. So we cannot be certain of the final sorted order. This means that any sorting algorithm will never have a path that is shorter than n-1. But that does not mean that the height of the tree is n-1 (recall that we showed the height is  $\Omega(n \log n)$ ). Instead, it just means there is no path in the tree that is shorter than n-1.