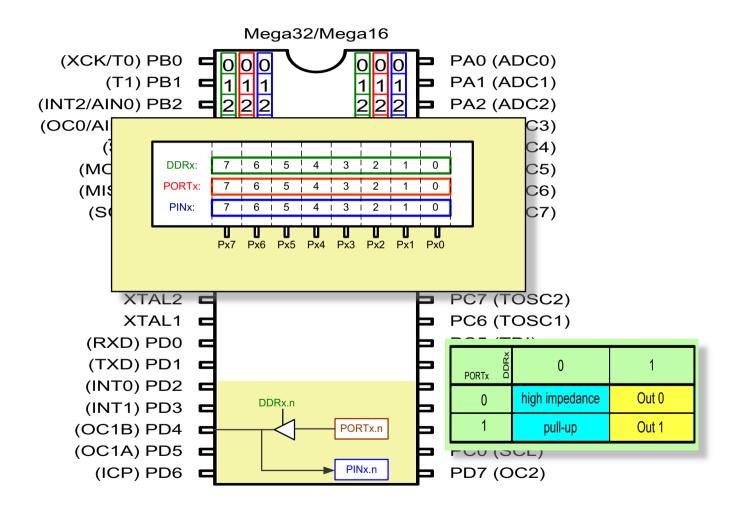
#### **Lecture 3 content**

- Ports
  - DDRx defining direction (input/output)
  - Read from ports (PINx) and Write to ports (PORTx),
     Config.
- Instructions related to Ports:
  - OUT/IN
  - SBI/CBI
  - SBIC/SBIS
- Boolean instructions
  - AND/ANDI, OR/ORI
  - LSL, LSR, ASR, ROL, ROR

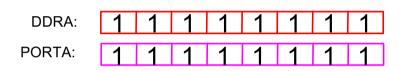
#### **Ports**

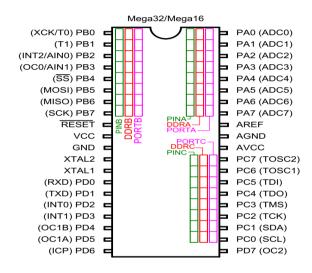
- I/O pins are generally grouped into ports of 8 pins, which can be accessed with a single byte access.
- Pins can either be input only, output only, or
  - most commonly,
  - bidirectional, that is, capable of both input and output. (not simultaneously!)

## The structure of IO pins (not the chip we have)



 Write a program that makes all the pins of PORTA one.





```
LDI R20,0xFF ;R20 = 0b11111111

OUT DDRA,R20 ;DDRA = R20

OUT PORTA,R20 ;PORTA = R20
```

PORTx O	0	1
0	high impedance	Out 0
1	pull-up	Out 1

The following code will toggle all 8 bits of Port B forever with some time delay between "on" and "off" states:

```
LDI
              R16,0xFF
                            :R16 = 0xFF = 0b111111111
              DDRB,R16
   OUT
                            ;make Port B an output port
              R16,0x55
L1: LDI
                            ;R16 = 0x55 = 0b01010101
              PORTB, R16
   OUT
                            ; put 0x55 on port B pins
   CALL
              DELAY
   LDI
              R16,0xAA
                            ;R16 = 0xAA = 0b10101010
   OUT
              PORTB, R16
                            ;put 0xAA on port B pins
   CALL
              DELAY
   RJMP
              L1
```

## **Example 5: Input**

 The following code indefinitely gets the data present at the pins of port C and sends it to port B, after adding the value 5 to it:

```
LDI
              R16,0x00
                            ;R16 = 00000000 (binary)
              DDRC,R16
       OUT
                            ;make Port C an input port
              R16,0xFF
                            ;R16 = 11111111 (binary)
       LDI
                            ;make Port B an output port(1 for Out)
       OUT
              DDRB,R16
12:
              R16, PINC
                            ;read data from Port C and put in R16
       IN
       LDI
              R17,5
              R16,R17
                            ;add 5 to it
       ADD
       OUT
              PORTB,R16
                            ;send it to Port B
       RJMP L2
                            ;continue forever
```

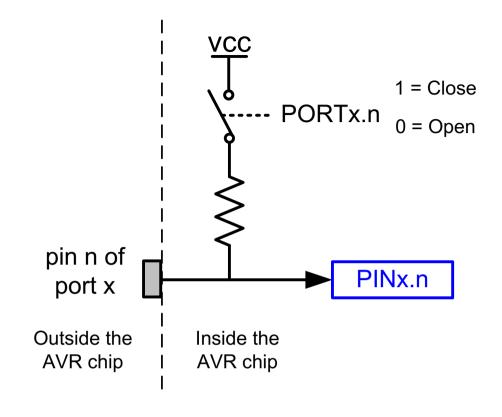
# **Pull-up resistor**

Note: You can also read

this value:

IN R16, PORTC

- A bug, if not intentional!



LDI R16, 0x00

OUT DDRC, R16

LDI R16, 0xFF

OUT PORTC, R16

. . . . . .

IN R16, PINC

. . . . .

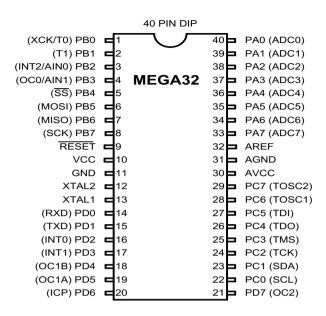
; Make all pins input

•

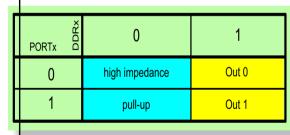
; enable pull-up on all pins

; read pins

 Write a program that reads from port A and writes it to port B.



```
LDI
         R20,0x0
                     ;R20 = 00000000
                                      (binary)
          DDRA,R20
                     ;DDRA = R20
    OUT
          R20,0xFF
                     ;R20 = 111111111
    LDI
                                       (binary)
    OUT
          DDRB,R20
                     ;DDRB = R20
L1:
    IN
          R20, PINA
                     ;R20 = PINA
    OUT
          PORTB, R20 ; PORTB = R20
    RJMP L1
```



#### **SBI** and **CBI** instructions

- SBI (Set Bit in IO register)
  - SBI ioReg, bit ;ioReg.bit = 1
  - Examples:
    - SBI PORTD,0 ;PORTD.0 = 1
    - SBI DDRC,5 ;DDRC.5 = 1
- CBI (Clear Bit in IO register)
  - CBI ioReg, bit ;ioReg.bit = 0
  - Examples:
    - CBI PORTD,0 ;PORTD.0 = 0
    - CBI DDRC,5 ;DDRC.5 = 0

Write a program that toggles PORTA.4 continuously.

```
SBI DDRA,4 ;PA4 output
L1: SBI PORTA,4 ;PA4=1
CBI PORTA,4 ;PA4=0
RJMP L1
```

An LED is connected to each pin of Port D. Write a program to turn on each LED from pin D0 to pin D7. Call a delay module before turning on the next LED.

LDI	R20, 0xFF	
OUT	DDRD, R20	;make PORTD
		;an output
		;port
SBI	PORTD, 0	;set bit PDO
CALL	DELAY	;delay
		;before next
SBI	PORTD, 1	;turn on PD1
CALL	DELAY	;delay
		;before next
SBI	PORTD, 2	;turn on PD2
CALL	DELAY	
SBI	PORTD, 3	
CALL	DELAY	
SBI	PORTD, 4	
CALL	DELAY	
SBI	, -	
CALL		
SBI	PORTD, 6	
CALL	DELAY	
SBI	PORTD,7	
CALL	DELAY	

#### **SBIC** and **SBIS**

- SBIC (Skip if Bit in IO register Cleared)
  - SBIC ioReg, bit ; if (ioReg.bit = 0) skip next instr
  - Example:

```
SBIC PIND,0 ;skip next instr if PIND.0=0
INC R20
LDI R19,0x23
```

SBIS (Skip if Bit in IO register Set)

```
SBIS ioReg, bit ; if (ioReg.bit = 1) skip next instr
```

– Example:

```
SBIS PIND,0 ;skip next instr if PIND.0=1
INC R20
LDI R19,0x23
```

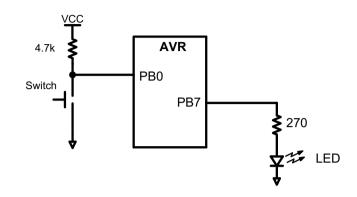
- Write a program to perform the following:
- (a) Keep monitoring the PB2 bit until it becomes HIGH;
- (b) When PB2 becomes HIGH, write value \$45 to Port C, and also send a HIGH-to-LOW pulse to PD3.

```
CBI DDRB, 2 ;make PB2 an input
SBI PORTB,2 ;enable pull-up on PB2
LDI R16, 0xFF
OUT DDRC, R16 ;make Port C an output port
SBI DDRD, 3 ;make PD3 an output

AGAIN: SBIS PINB, 2 ;Skip if Bit PB2 is HIGH
RJMP AGAIN ;keep checking if LOW
LDI R16, 0x45 ;$45 = 0x45!
OUT PORTC, R16;write 0x45 to port C
SBI PORTD, 3 ;set bit PD3 high (H-to-L)
CBI PORTD, 3 ;set bit PD3 low again (clear PD3)

HERE: RJMP HERE
```

A switch is connected to pin PB0 and an LED to pin PB7. Write a program to get the status of Switch and send it to the LED.



```
CBI DDRB,0 ;make PB0 an input
SBI DDRB,7 ;make PB7 an output
AGAIN: SBIS PINB,0 ;skip next if PB0 is =1
RJMP OVER ;if PB7 = 0, jump to OVER
CBI PORTB,7 ;LED = OFF
RJMP AGAIN
OVER: SBI PORTB,7 ;LED = ON
RJMP AGAIN
```

## Logic instructions - Setting and Clearing bits

```
;Rd = Rd AND Rr
AND
        Rd,Rr
ANDI
       RD, k
                        Rd = Rd AND k
OR
       Rd,Rr
                       :Rd = Rd OR Rr
ORI
       Rd, k
                       Rd = Rd OR k
EOR
       Rd,Rr
                        ;Rd = Rd XOR Rr (immediate is not supported)
COM
                        Rd = 1' Complement of Rd (111111111 - Rd)
        Rd
NEG
                        Rd = 2 Complement of Rd (100000000 – Rd)
        Rd
                        ;Swap the 2 nibbles (e.g 0x0F \rightarrow 0xF0)
SWAP
       Rd
```

AND is used to clear an specific bit/s of a byte

```
LDI R20, 0x35; R20 = 0011 0101
ANDI R20, 0x0F; AND 0000 1111
; R20 = 0000 0101
```

# Logic instructions - Setting and Clearing bits

```
;Rd = Rd AND Rr
AND
        Rd,Rr
ANDI
        RD, k
                        Rd = Rd AND k
OR
        Rd,Rr
                       :Rd = Rd OR Rr
ORI
        Rd, k
                        Rd = Rd OR k
EOR
        Rd,Rr
                        ;Rd = Rd XOR Rr (immediate is not supported)
COM
                        Rd = 1' Complement of Rd (111111111 - Rd)
        Rd
NEG
                        Rd = 2 Complement of Rd (100000000 – Rd)
        Rd
SWAP
        Rd
                        ;Swap the 2 nibbles (e.g 0x0F \rightarrow 0xF0)
```

OR is used to set an specific bit/s of a byte

```
LDI R20, 0x35 ; R20 = 0011 0101
ORI R20, 0xC0 ; OR 1100 0000
; R20 = 1111 0101
```

# Setting only a few bits in DDRx (1/3)

Sometimes we only want to use a few bits in a Port. We then need to set those bits in the DDRx. 3 ways:

- 1. Assume that the remaining bits are not used.
  - 1. Either set them to output (but what happens if something is connected to that bit?)
  - 2. Or, set them to input (without pullup, which means they are high impedance)

Example:

LDI	R16, 0b00010000	; C4 out, C5 in
OUT	DDRC, R16	

# Setting only a few bits in DDRx (2/3)

2. Read current value of DDRx, adjust the interesting bits and write back the updated values. Other bits are not affected. Example:

LDS	R16, DDRC	; read DDRC
ORI	R16, 0b00010000	; bit 4 = 1. PC4 is output
STS	DDRC, R16	; store DDRC
LDS	R16, DDRC	; read DDRC
ANDI	R16, 0b11011111	; bit 5 = 0. PC5 is input
STS	DDRC, R16	; store DDRC

# Setting only a few bits in DDRx (3/3)

#### Alternative:

```
LDS R16, DDRC ; read DDRC
ANDI R16, 0b11011111 ; bit 5 = 0. PC5 is input
OUT DDRC, R16
```

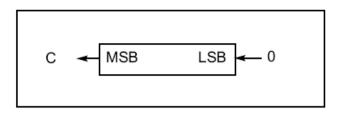
**OUT** is equivalent to STS!

3. Use the instructions SBI/CBI to set the individual bits in the DDRx. Example:

```
SBI DDRC, 4 ; PC4 is defined as output CBI DDRC, 5 ; PC5 is defined as input SBI PORTC, 5 ; set pullup on PC5
```

### LSL instruction

LSL Rd ;logical shift left



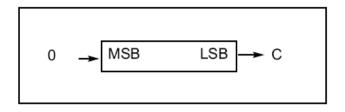
In LSL, as bits are shifted from right to left, 0 enters the LSB and the MSB exits to the carry flag. In other words, in LSL 0 is moved to the LSB, and the MSB is moved to the C. This instruction multiplies content of the register by 2 assuming that after LSL the carry flag is not set.

In the next code you can see what happens to 00100110 after running 3 LSL instructions.

```
CLC ;make C = 0 (carry is 0 ) 
LDI R20 , 0x26 ;R20 = 0010 0110(38 – dec...) C = 0 
LSL R20 ;R20 = 0100 1100(76) C = 0 
LSL R20 ;R20 = 1001 1000(152) C = 0 
LSL R20 ;R20 = 0011 0000(48) C = 1
```

;content of R20 is not multiplied by 2

### LSR instruction



LSR Rd ;Logical shift right

In LSR, as bits are shifted from left to right, 0 enters the MSB and the LSB exits to the carry flag. In other words, in LSR 0 is moved to the MSB, and the LSB is moved to the C. This instruction divides content of the register by 2 and carry flag contains the remainder of division.

In the next code you can see what happens to 0010 0110 after running 3 LSL instructions.

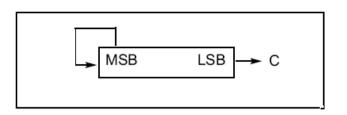
LDI R20,0x26 ;  $R20 = 0010 \ 0110 \ (38)$ 

LSR R20 ;  $R20 = 0001\ 0011\ (19)\ C = 0$ 

LSR R20 ;  $R20 = 0000 \ 1001 \ (9) \ C = 1$ 

LSR R20 ;  $R20 = 0000 \ 0100 \ (4) \ C = 1$ 

### **ASR** Instruction



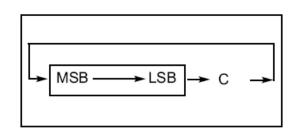
ASR Rd ;Arithmetic shift right

The ASR instruction can divide a signed number by 2. In ASR, as bits are shifted from left to right, MSB is held constant and the LSB exits to the carry flag. In other words MSB is not changed but is copied to D6, D6 is moved to D5, D5 is moved to D4 and so on.

In the next code you can see what happens to 0010 0110 after running 5 ASL instructions.

LDI R20, 0xD60 ;R20 = 1101 0000(-48) c = 0 ASR R20 ;R20 = 1110 1000(-24) C = 0 ASR R20 ;R20 = 1111 0100(-12) C = 0 ASR R20 ;R20 = 1111 1010(-6) C = 0 ASR R20 ;R20 = 1111 1101(-3) C = 0 ASR R20 ;R20 = 1111 1110(-2!) C = 1

#### **ROR** instruction



ROR Rd ;Rotate right

In ROR, as bits are rotated from left to right, the carry flag enters the MSB and the LSB exits to the carry flag. In other words, in ROR the C is moved to the MSB, and the LSB is moved to the C.

See what happens to 0010 0110 after running 3 ROR instructions:

CLC ;CLear Carry, make C = 0 (carry is 0)

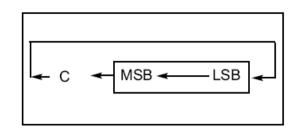
LDI R20, 0x26; R20 = 0010 0110

ROR R20 ;  $R20 = 0001 \ 0011 \ C = 0$ 

ROR R20 ; R20 = 0000 1001 C = 1

ROR R20 ; R20 = 1000 0100 C = 1

#### **ROL** instruction



ROL Rd ;Rotate left

In ROL, as bits are shifted from right to left, the carry flag enters the LSB and the MSB exits to the carry flag. In other words, in ROL the C is moved to the LSB, and the MSB is moved to the C.

See what happens to 0001 0101 after running 4 ROL instructions:

SEC ;Set Carry, make C = 1 (carry is 1)

LDI R20,0x15 ;R20 =  $0001 \ 0101$ 

ROL R20 ;  $R20 = 0010 \ 1011 \ C = 0$ 

ROL R20 ;R20 =  $0101\ 0110\ C = 0$ 

ROL R20 ;R20 =  $1010 \ 1100 \ C = 0$ 

ROL R20 ;  $R20 = 0101 \ 1000 \ C = 1$ 

#### Some other instructions...

...that appear in Lab 1 and that you may need to understand (we will cover this in Lecture 4):

. . .

CPI R18, 12; Compare content of R18

; to the value 12 (decimal)

BRNE scan\_key; if not equal, jump to

; label "scan\_key"

; if equal, continue here

**IS2.25** 

## **Assembly coding practice**

It is a good practice to organize your code in four columns as shown in the code below. Your program being easier to read/debug by you and others.

;Col_1	Col_2	Col_3	Col_4
	ADD	R16, R17	; Comment
	DEC	R17	// Comment
	MOV	R18, R16	; ;
END:	R <b>JMP</b>	END	/* Comment
			*/

- Column 1 (Col\_1) is used for labels.
- Column 2 (Col\_2) is used for the microcontroller instructions.
- Column 3 (Col\_3) is used for arguments operated on
- Column 4 (Col\_4) is used for comments.

**IS2.26** 

Column width is not equal or fixed, but be consistent in the program!

### "Include-files"

- When programs grow, it is practical to divide the program into separate files, where each file contains the implementation of a single logical part of the program. (= SW engineering...)
- Many programming languages (e.g. C) support this concept (we will cover to <file>.h and <file>.c later)
- Assembler does not!
- However, AVR Assembler support the concept of "Include-files"!
- The syntax is .INCLUDE <file-name>
- NOTE! The pre-processor includes all content from the included file at the position of the .INCLUDE statement IS2.27