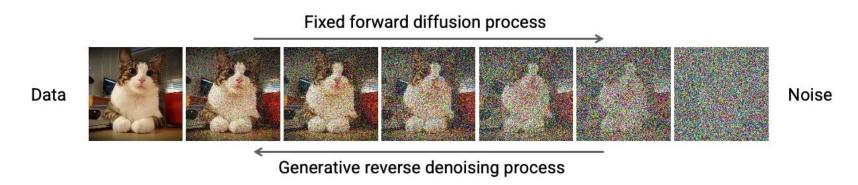
# Inversion for Generative Image Editing

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### Diffusion models

Let's add noise to images (forward process)



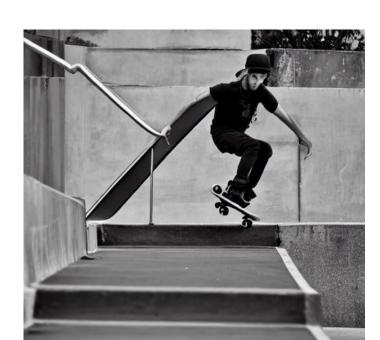
and train a model to reconstruct images from pure noise (reverse process)

# Classifier-free guidance

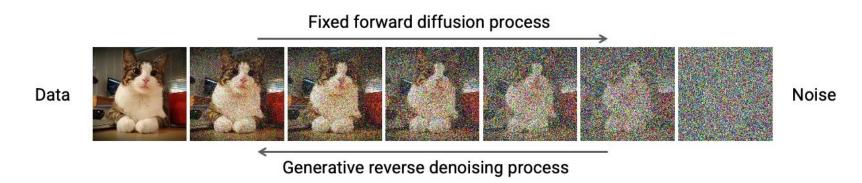
- We can use guidance to generate images:  $\tilde{\epsilon}_{\theta}(\mathbf{z}_{\lambda}, \mathbf{c}) = (1+w)\epsilon_{\theta}(\mathbf{z}_{\lambda}, \mathbf{c}) w\epsilon_{\theta}(\mathbf{z}_{\lambda})$
- Not applicable for editing



+ "...with a hat..." =



Let's try to reconstruct the noise that will generate the image we want

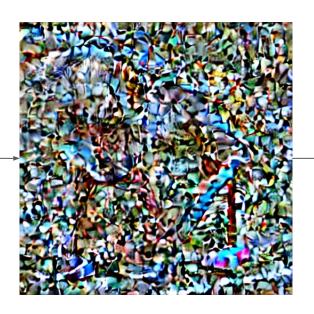


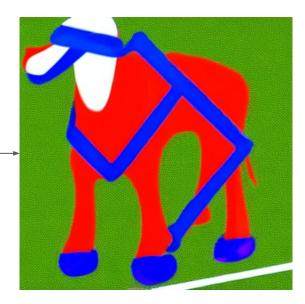
Here is the formula

$$z_{t+1} = \sqrt{\frac{\alpha_{t+1}}{\alpha_t}} z_t + \left(\sqrt{\frac{1}{\alpha_{t+1}} - 1} - \sqrt{\frac{1}{\alpha_t} - 1}\right) \cdot \varepsilon_{\theta}(z_t, t, \mathcal{C})$$

Let's see how it works in practice







Solution – use guidance\_scale=1 during inversion







# **DDIM-based editing**

Perform guided generation from the inverted latents







"...elk..."



"...chicken..."

Let's play and add more guidance during generation







"...elk..."



"...chicken..."

# **DDIM Inversion: Issues**

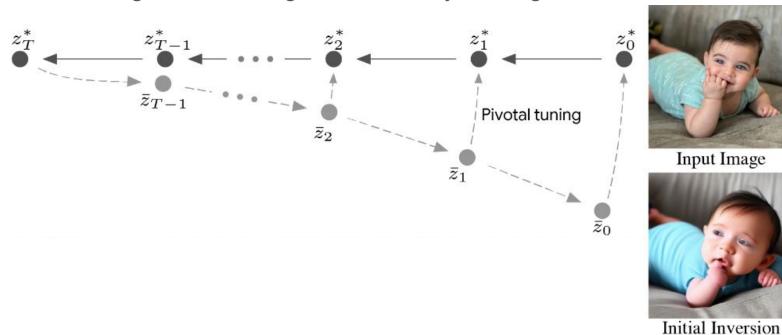
- For complex scenes: can't recover even the initial image, so result differs greatly from the source



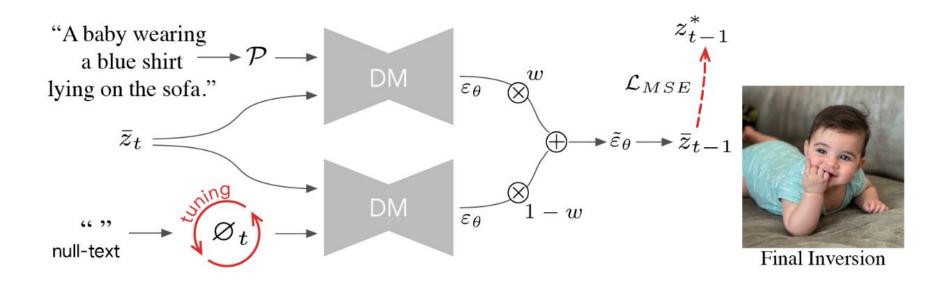




We see that the generated image is not exactly the original.



Let's **train** unconditional embeddings to fix it.



### Final pipeline is

- Perform DDIM inversion to get latents (with guidance\_scale = 1!)
- 2. Train unconditional embeddings
- Perform denoising process with new unconditional embeddings and target prompt

### **Algorithm 1:** Null-text inversion

- 1 **Input:** A source prompt embedding  $C = \psi(P)$  and input image  $\mathcal{I}$ .
- **2 Output:** Noise vector  $z_T$  and optimized embeddings  $\{\emptyset_t\}_{t=1}^T$ .
- 3 Set guidance scale w = 1;
- 4 Compute the intermediate results  $z_T^*, \ldots, z_0^*$  using DDIM inversion over  $\mathcal{I}$ :
- 5 Set guidance scale w = 7.5;
- 6 Initialize  $\bar{z_T} \leftarrow z_T^*, \varnothing_T \leftarrow \psi("");$
- 7 for  $t = T, T 1, \dots, 1$  do

for 
$$j = 0, \dots, N-1$$
 do

9 
$$\left\| \varnothing_t \leftarrow \varnothing_t - \eta \nabla_{\varnothing} \left\| z_{t-1}^* - z_{t-1}(\bar{z}_t, \varnothing_t, \mathcal{C}) \right\|_2^2; \right\|$$

- 10 end
- 11 Set  $\bar{z}_{t-1} \leftarrow z_{t-1}(\bar{z}_t, \varnothing_t, \mathcal{C}), \varnothing_{t-1} \leftarrow \varnothing_t;$
- 12 end
- 13 Return  $\bar{z_T}$ ,  $\{\emptyset_t\}_{t=1}^T$

First, let's compare the reconstruction abilities. These examples use w = 7.5



original



**DDIM** inversion



Null-text inversion

# Recovery of the initial image: sheep example







Now, let's compare actual editing abilities.







"...elk..."



"...chicken..."

Now, let's compare actual editing abilities.







"...horse..."



"...sheep..."

Let's compare DDIM and null-text inversion.



original



**DDIM** inversion



Null-text inversion

Let's compare DDIM and null-text inversion.



original



**DDIM** inversion



Null-text inversion

Let's compare DDIM and null-text inversion.



original



**DDIM** inversion



Null-text inversion

### Results & Conclusion

Metric	Generated	DDIM Inversion	Null-text inversion
SSIM	0.2151±0.0825	0.4644±0.1318	<b>0.4894</b> ±0.0971
CLIP Img2Img Target	0.7483±0.0997	0.7930±0.0960	0.7418±0.0835
CLIP Img2Img Source	0.6991±0.1061	<b>0.7509</b> ±0.1055	0.7060±0.1018
CLIP Img2Text Target	<b>0.3212</b> ±0.0288	0.3181±0.0318	0.3090±0.0218
CLIP Img2Text Source	<b>0.2911</b> ±0.0384	0.2906±0.0394	0.2643±0.0374
Generation time	30 seconds	60 seconds	7 minutes

- Comparison of DDIM, Null-text Inversion
  - Some tradeoff in quality vs structural similarity
  - Much better than generating everything from sampled noise!
- Hyperparameters matter a lot

Q&A

### References

- Mokady, R., Hertz, A., Aberman, K., Pritch, Y., & Cohen-Or, D. (2023). Null-text inversion for editing real images using guided diffusion models. In *Proceedings of the IEEE/CVF conference on computer vision and pattern recognition* (pp. 6038-6047).
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- Radford, A., Kim, J. W., Hallacy, C., Ramesh, A., Goh, G., Agarwal, S., ... & Sutskever, I. (2021, July). Learning transferable visual models from natural language supervision. In *International conference on machine learning* (pp. 8748-8763). PmLR.