
MATLAB Session 2

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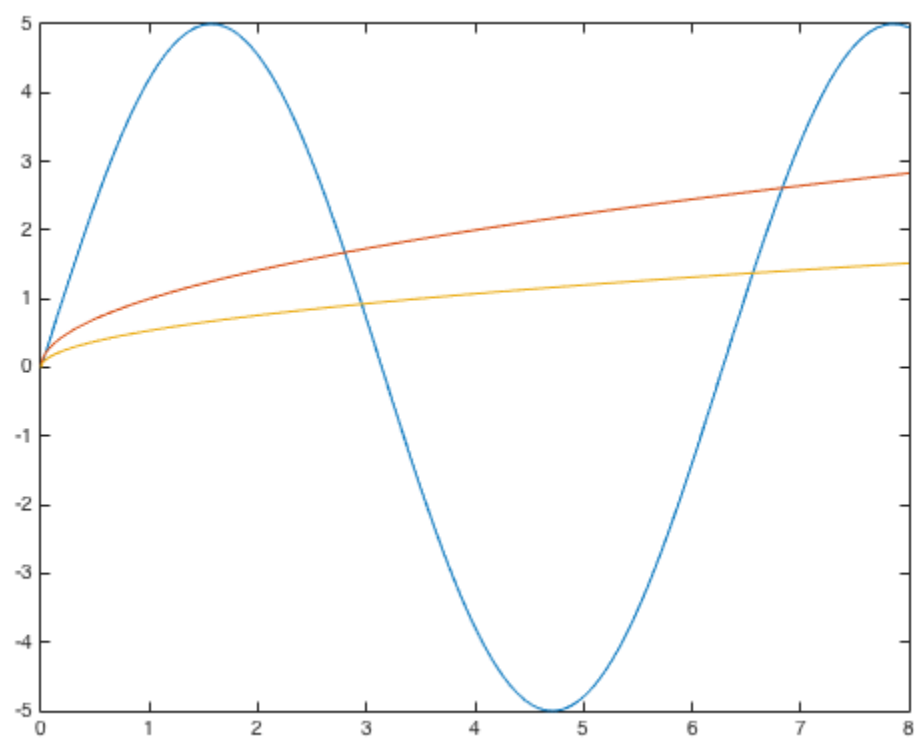
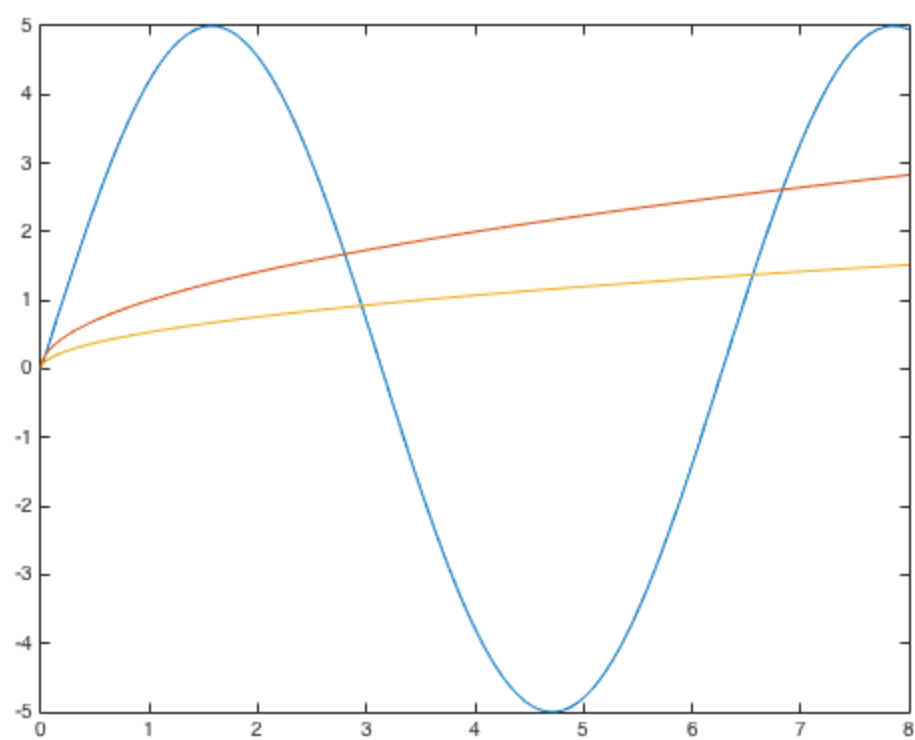
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Question 3

Multiple plots, maxima, minima and comparators: For $t = 0$ to 8 and each each signal $s1 = 5\sin t$, $s2 = 2t$ and $s3 = 0.4\sqrt{1.8t}$

a) Plot the 3 signals on the same time axes, use: *figure*, *hold*, *plot(t, s# , 'colour letter')* and/or *plot(t, [s1; s2; s3])*

```
t = 0: .01 : 8; % t=linspace(0,8,1000)
y1 = 5*sin(t);
y2=sqrt(t); %y2=t^0.5;
y3=0.4*(1.8*t).^0.5; %y3=0.4*sqrt(1.8*t);
figure
plot(t,y1); hold on; plot(t,y2);
plot(t,y3)
figure
plot(t,[y1;y2;y3])
```

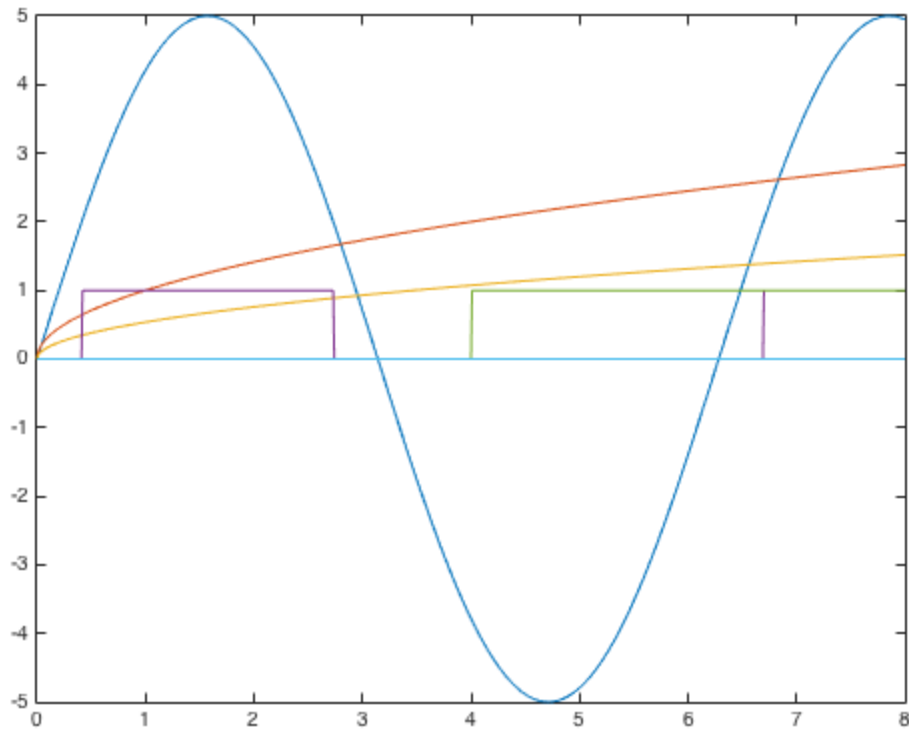


b) `>>max(s#) , min(s#)` % Confirm the maximum and minimum values

c) `>>plot(t , s#>=2)` and explain the output

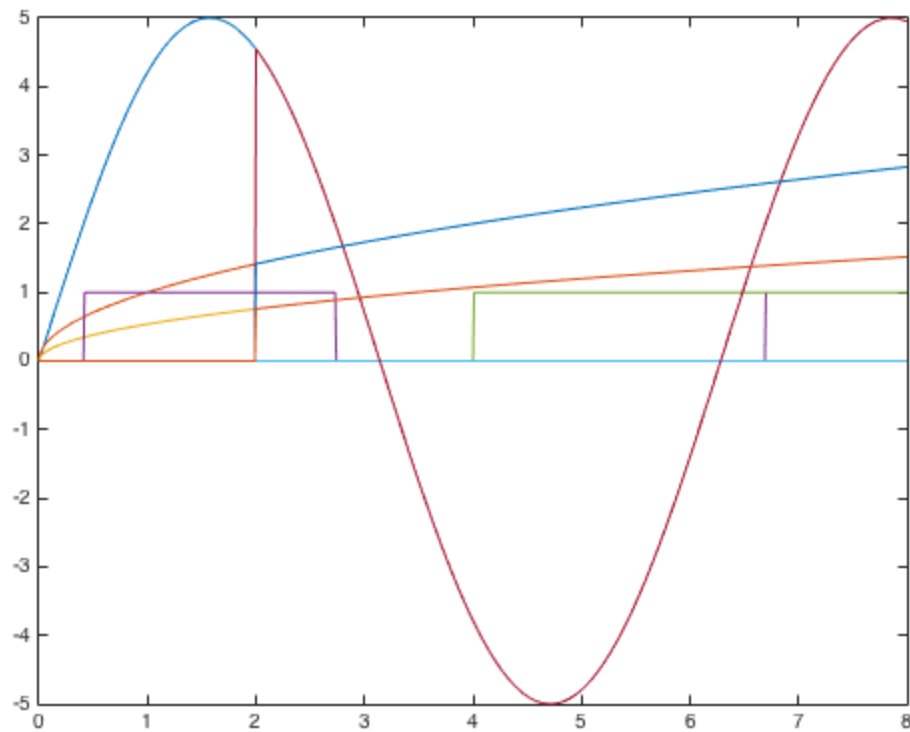
hold on

`plot(t,[y1;y2;y3]>2)% binary output 0 false, 1 true`



d) `>>plot(t , s#.*(t>=2))` and explain the output

`plot(t,[y1;y2;y3].*([t;t;t]>=2))%turn on at t>=2;`



Question 4

The roots of a polynomial $f(x)$ are the values of x , such that $f(x) = 0$. Obtain the roots of the following polynomials:

a) $x^3 - 4.5x^2 + 5x - 1.5 = 0$

```
F1=[1 -4.5 5 -1.5];
root=roots(F1) %3 real roots (0.5, 1, 3)
```

root =

```
3.0000
1.0000
0.5000
```

b) $x^3 - 7x^2 + 40x - 34 = 0$

```
F2=[1 -7 40 -34];
root=roots(F2) %2 complex roots (1, 3+- 5i)
```

root =

```
3.0000 + 5.0000i
3.0000 - 5.0000i
1.0000 + 0.0000i
```

Question 5

Plot the above polynomials to confirm if the roots were located correctly by

a) calculating $f(x)$ using array operators for $x=[-10:0.2:10]$; then `plot(x,f)`

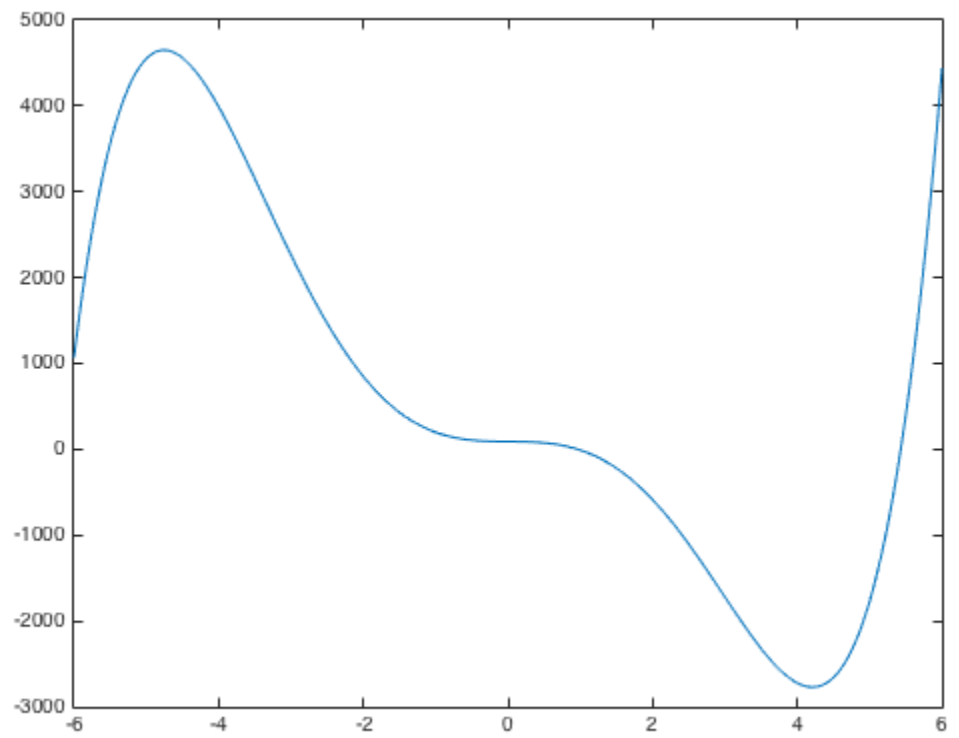
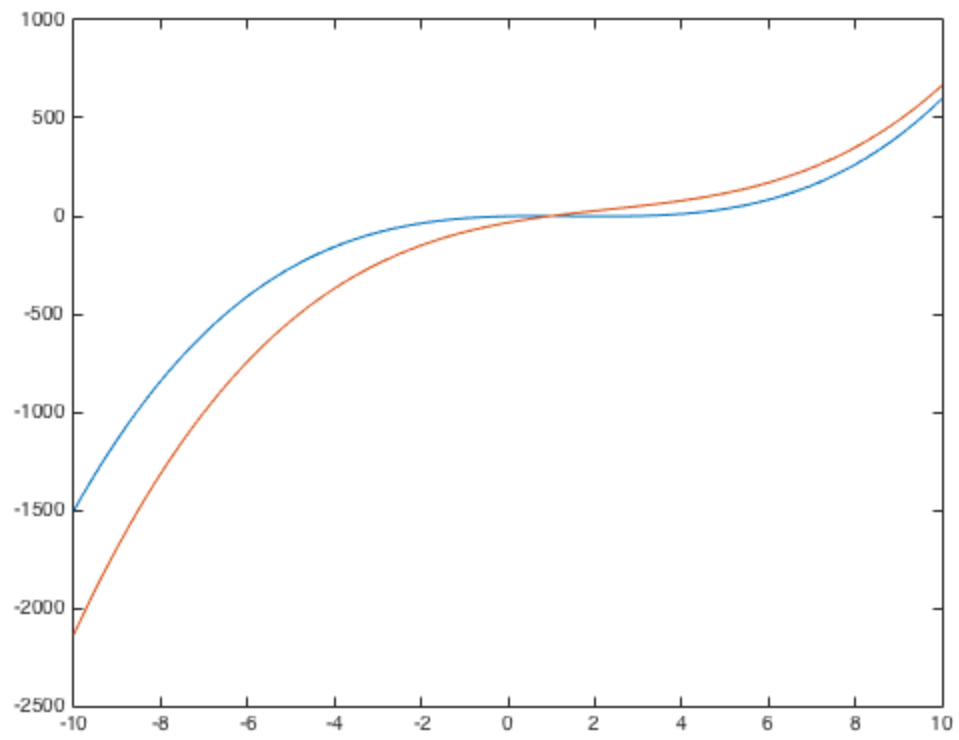
```
x= -10:.2:10 ;
f1=x.^3 - 4.5*x.^2 + 5*x -1.5;
f2=x.^3 - 7*x.^2 + 40*x -34;
```

b) using `polyval()`, e.g. `plot(x,polyval([1 -4.5 5 -1.5], x))`

```
figure
plot(x,[f1 ; f2])
figure
plot(x,[polyval(F1,x);polyval(F2,x)])
F=[3 2 -100 2 -7 90];
root=roots(F)
x=linspace(-6,6,1000);
plot(x,polyval(F,x));
```

```
root =
```

```
-6.1423 + 0.0000i
 5.4298 + 0.0000i
 0.9630 + 0.0000i
-0.4586 + 0.8507i
-0.4586 - 0.8507i
```



Use Matlab to compute the roots of $3x^5 + 2x^4 + 100x^3 + 2x^2 + 7x + 90$ and plot the polynomial for $x = -6$ to 6 .

Question 6

Linear Algebraic Equations: Use the left-division method to solve the following set of linear, algebraic equations, i.e. find \mathbf{u} (i.e. $[x; y; z]$) when $\mathbf{A}\mathbf{u}=\mathbf{y}$, *Hint: A=3x3matrix, v=1x3, >> helpwin ops; >> helpwin mldivide; >> A*u* $3x + 2y - 9z = -65$ $-9x - 5y + 2z = 16$ $6x + 7y + 3z = 5$

```
A=[3 2 -9; -9 -5 2; 6 7 3]
y=[-65;16;5]
u=A\y %2 -4 -9
wrong=A/y' %note difference between this and above
check=A*u %check, e.g. 3*2 + 2*-4 + -9*7= 6-8-63=-65
check=A*wrong
```

A =

3	2	-9
-9	-5	2
6	7	3

y =

-65
16
5

u =

2.0000
-4.0000
7.0000

wrong =

-0.0462
0.1143
-0.0584

check =

-65.0000
16.0000
5.0000

check =

0.6154
-0.2727
0.3480

Question 7

An engineering system has a differential equation with the initial condition solution given by $y(t) = c_1 e^{d_1 t} + c_2 e^{d_2 t} + c_3 e^{d_3 t}$ where $c_1 = 0.3$, $c_2 = 0.35$, and $c_3 = 0.35$ weigh the effects of the roots of the characteristic equation $d_1 = -0.5$, $d_2 = -1 + 5i$, and $d_3 = -1 - 5i$. Using **MATLAB**, plot the initial condition response over the period from $t = 0$ to $t = 10$ seconds. Determine the maximum response amplitude between 1 and 2 seconds.

- *Extension ** (for later): you may like to learn to write a function with arguments to solve this for any parameters.

```
t=linspace(0,10,10001);
c1=0.3;c2=0.35;c3=0.35;
d1=-0.5;d2=-1+5i;d3=-1-5i;
y=c1*exp(d1.*t)+c2*exp(d2.*t)+c3*exp(d3.*t);
plot(t,y)
```

