

How do you compute the PLS direction?

1) The first direction Z_1 is computed by setting each ϕ_{j1} equal to β_j from a simple linear regression of Y onto X_j . So

$$Z_1 = \sum_{j=1}^p \phi_{j1} X_j$$

is ~~the~~ strongly correlated with the response.

Okay, I don't understand this

2/21/23
Day 15

I'm gonna skip partial least squares for the time being.

6.4: Considerations in High Dimensions

6.4.1:
High dimensional data

In the low dimensional setting, $n \gg p$. But in modern problems $p \gg n$, the high dimensional setting

- The bias-variance tradeoff and overfitting become especially important in this setting.

6.4.2: What Goes Wrong in High Dimensions

Here, we discuss least squares regression, but this also applies to logistic regression, LDA, etc.

- Least squares produces a perfect fit when $p \geq n$, regardless of if there is really a linear relationship or not.
- A perfect fit almost certainly means overfitting to the data.
- If $p > n$ or $p \approx n$, then linear regression is too flexible.
- Including more predictors increases the variance of the coefficient estimates.

6.4.3: Regression in High Dimensions

The methods of Chapter 6 are useful in the high dimensional setting.

Can I use the lasso w/ Cox proportional hazards?

- 1) Regularization is important in high dimensional problems
- 2) Appropriate tuning parameter selection is crucial.
- 3) The test error tends to increase as the number of predictors increases, unless the additional features are truly associated with the response.

6.4.4: Interpreting Results in Higher Dimensions

- Multicollinearity is a huge problem in this setting - so you can end up with models w/ different predictors, (though it could be that both models produce accurate predictions).
- Be careful reporting errors. Since overfitting is so likely, NEVER use SSE, p-values, R^2 , or measures of fit to the training data.
- Use independent test set or cross validation errors instead.

Ch. 7: Moving Beyond Linearity

- Linear models are easily interpretable, but limited in predictive power.
 - In this chapter, we discuss simple model extensions such as
 - Polynomial regression
 - Step functions
 - Regression splines
 - Smoothing splines
 - Local regression
 - Generalized additive models
- } single predictors
- } multiple predictors

7.1: Polynomial Regression

$$y_i = \beta_0 + \beta_1 x_i + \dots + \beta_d x_i^d + \epsilon_i$$

In practice, $d \leq 4$ because otherwise it's too flexible, especially at the boundary of the X variable.

What is the variance of a fit i.e., $\text{Var} \hat{f}(x_0)$. We can use the reported variance/covariance matrix of the $\hat{\beta}_i$ to figure this out. If \hat{C} is the 5×5 covariance matrix and $\mathbf{l}_0^T = (1, x_0, x_0^2, x_0^3, x_0^4)$, then

$$\text{Var}[\hat{f}(x_0)] = \mathbf{l}_0^T \hat{C} \mathbf{l}_0$$

Can easily get 2*SE curves from this.

7.2: Step Functions

Polynomial functions impose a global structure on the non-linear function of X . We can use step functions to avoid imposing such a bias.

- Break X into bins
- Fit a different constant to each bin

This converts a continuous variable into an ordinal categorical variable.

Cutpoints c_1, \dots, c_k and then variables

$$c_0(X) = I(X < c_1)$$

$$c_1(X) = I(c_1 \leq X < c_2)$$

$$\vdots$$

$$c_{k-1}(X) = I(c_{k-1} \leq X < c_k)$$

$$c_k(X) = I(c_k \leq X)$$

Then fit the k model

$$y_i = \beta_0 + \sum_{j=1}^k \beta_j c_j(x_i) + \varepsilon_i$$

Unless the predictor has natural breakpoints, piecewise constant functions can miss the action.

7.3: Basis Functions

Polynomials & step functions are special examples of the basis function approach. Have

$$b_1(X), \dots, b_K(X)$$

and fit the linear model

$$y_i = \beta_0 + \sum_{j=1}^K \beta_j b_j(x_i) + \epsilon_i$$

All the tools of chapter 3 are available in this setting.

Other basis functions include:

- Wavelets
- Fourier series
- Regression splines