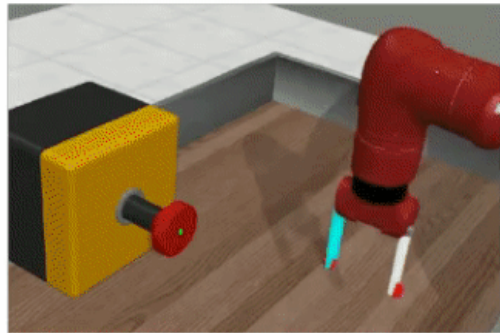


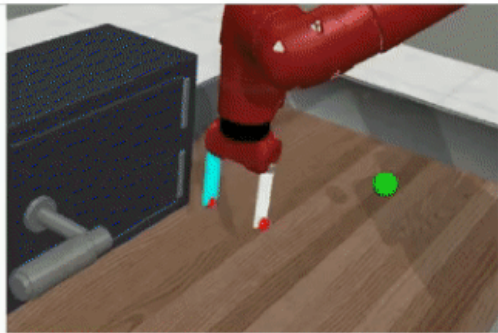
FCAI

fcai.fi

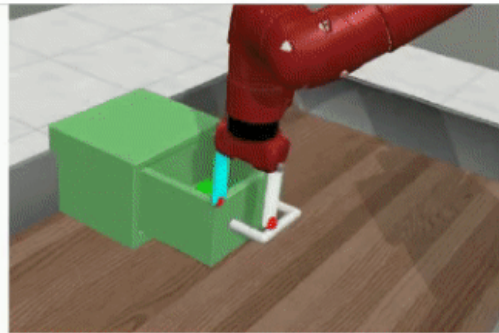
Train



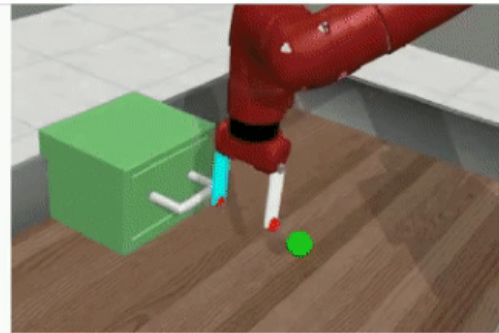
button press



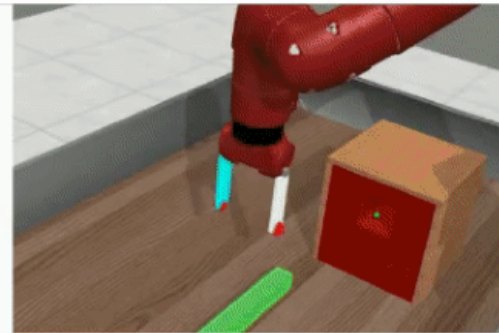
door open



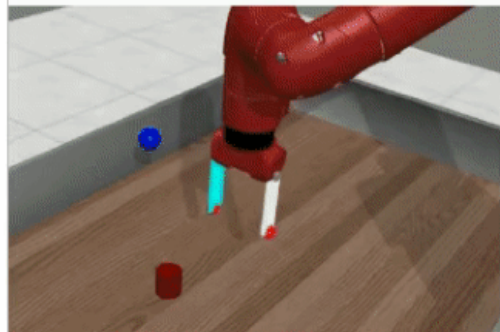
drawer close



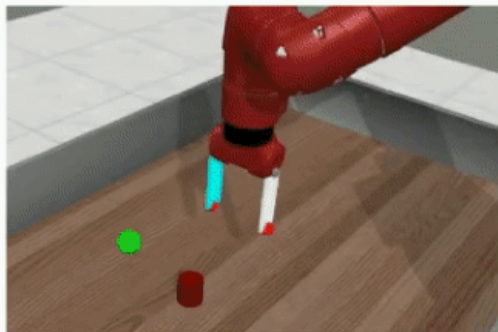
drawer open



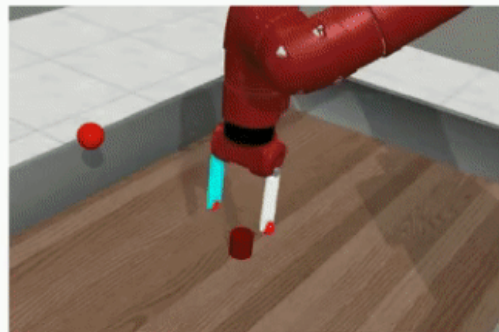
peg insert
side



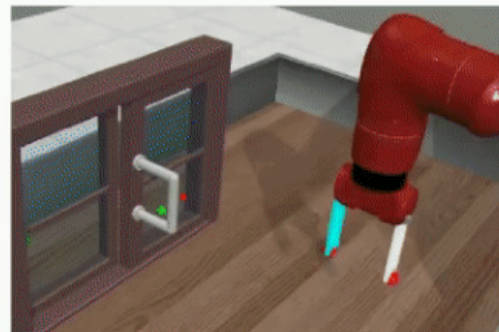
pick place



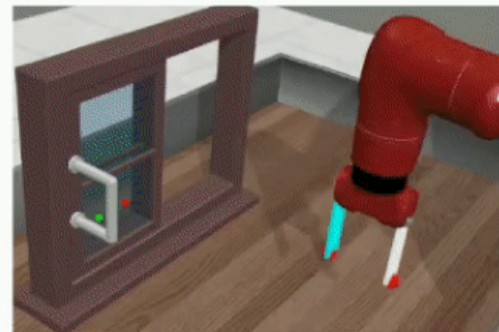
push



reach



window open

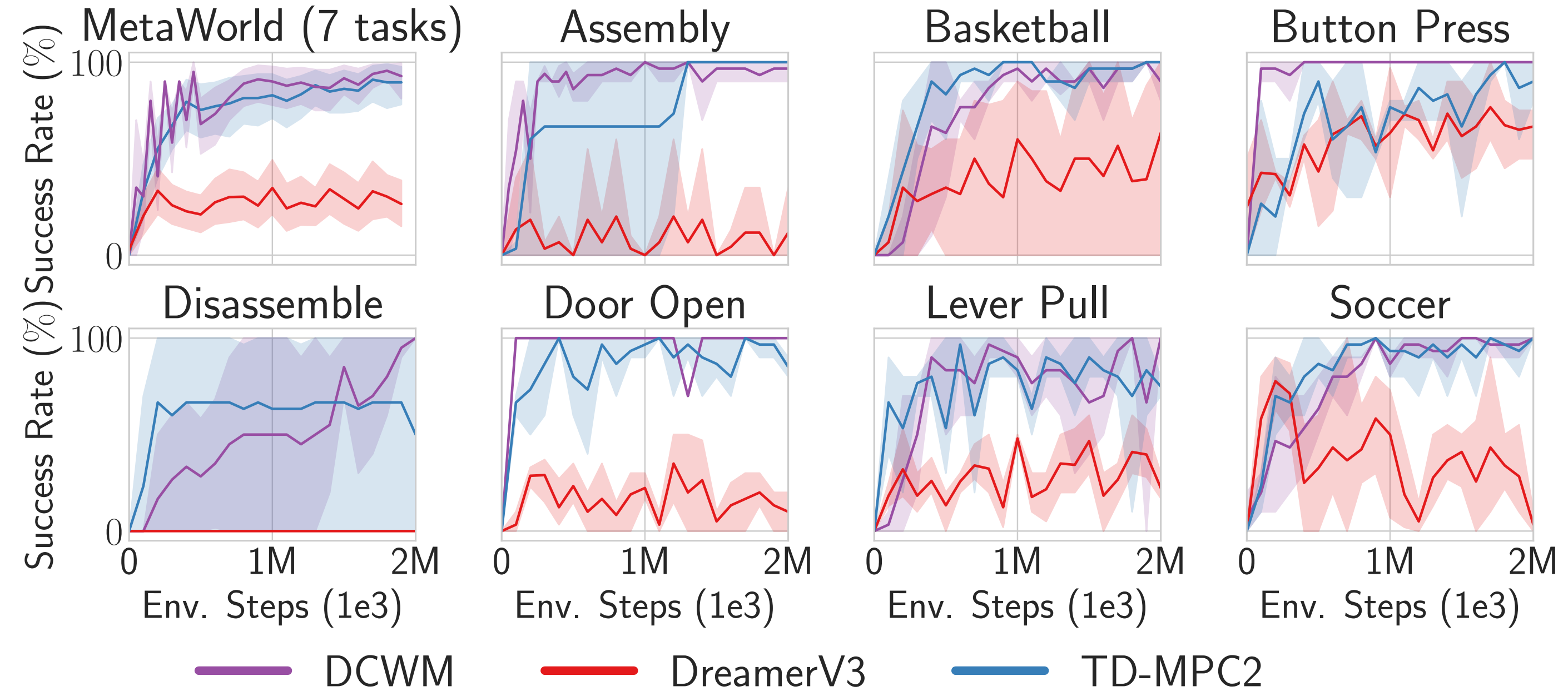


window close

Results: MetaWorld

Competitive Performance in Robotic Manipulation

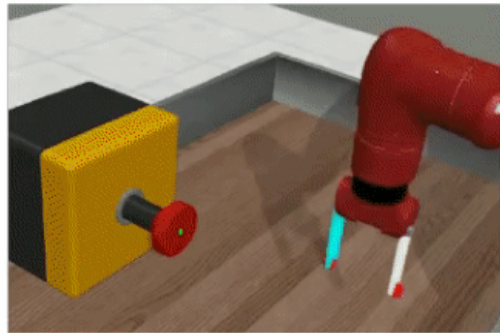




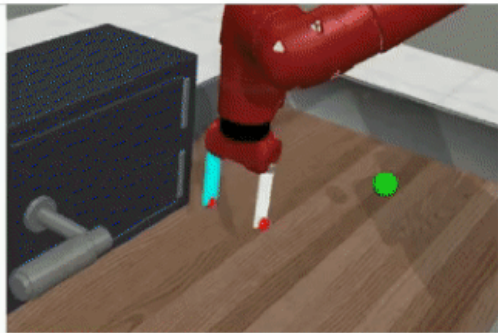




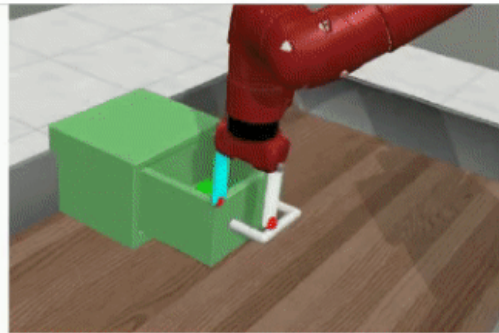
Train



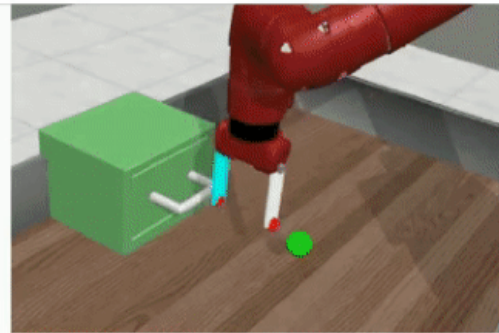
button press



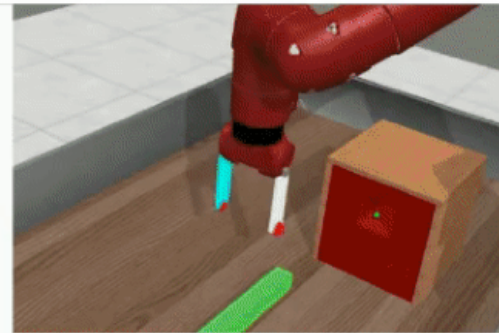
door open



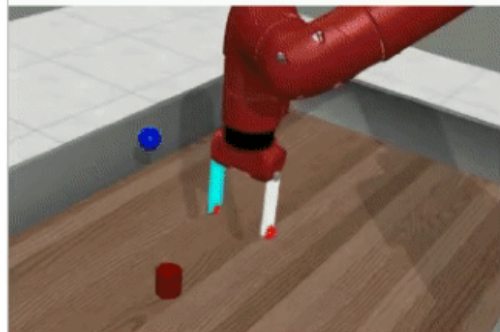
drawer close



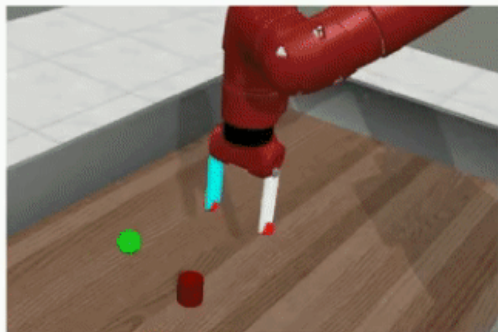
drawer open



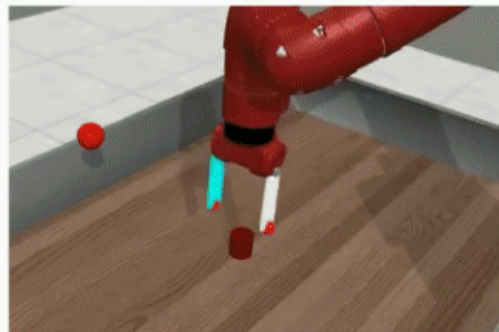
peg insert
side



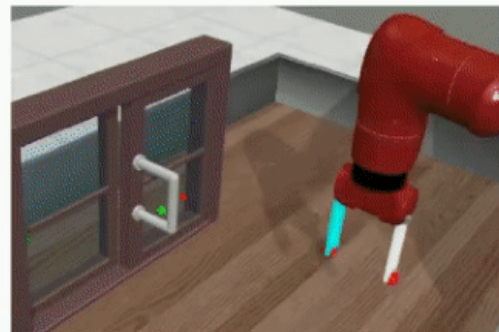
pick place



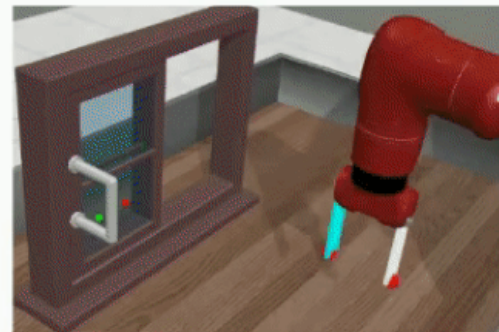
push



reach

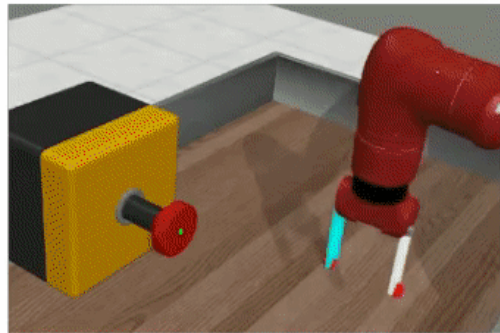


window open

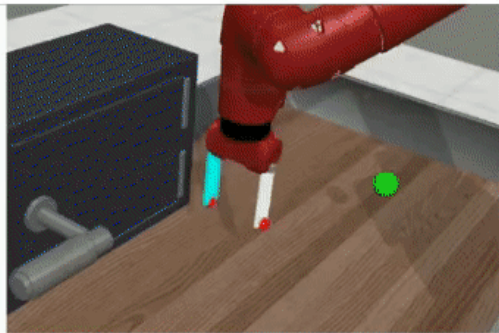


window close

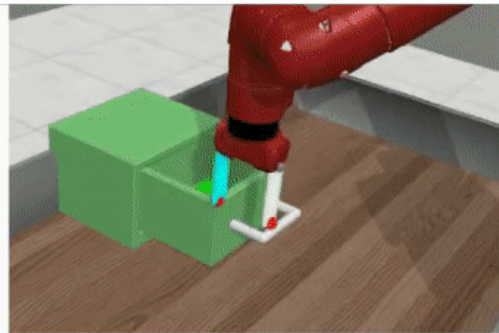
Train



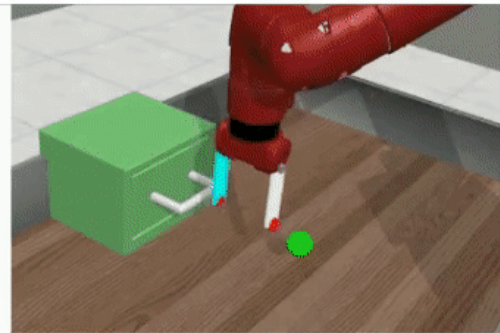
button press



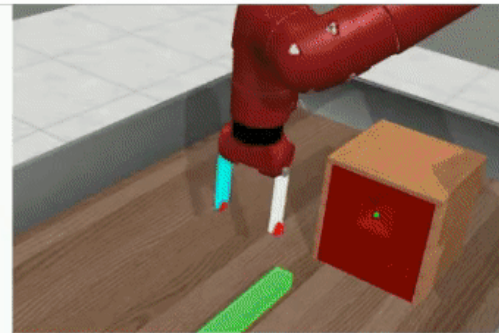
door open



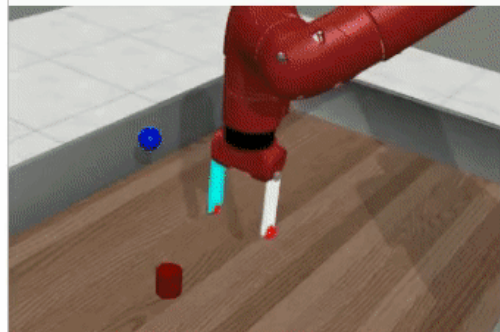
drawer close



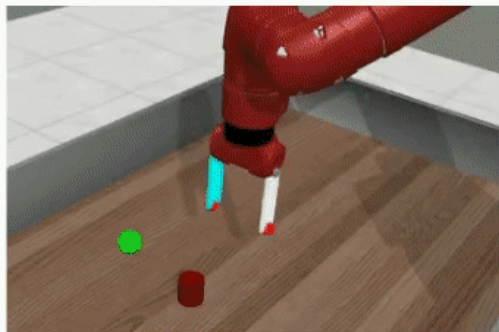
drawer open



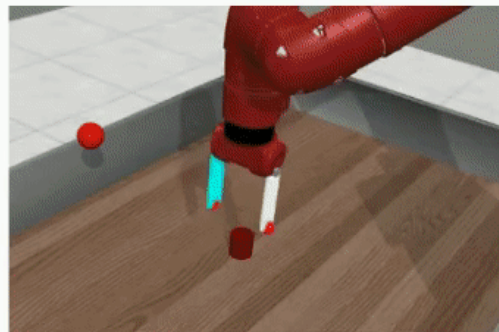
peg insert
side



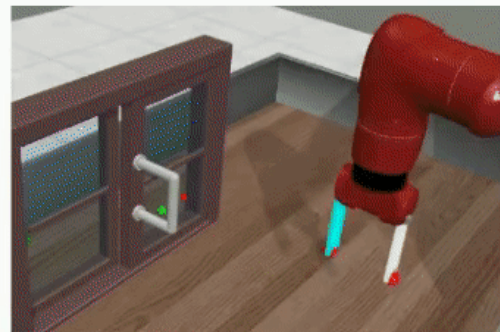
pick place



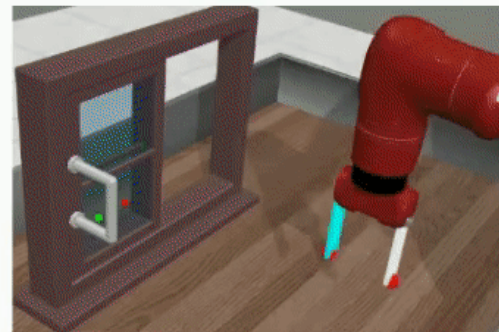
push



reach



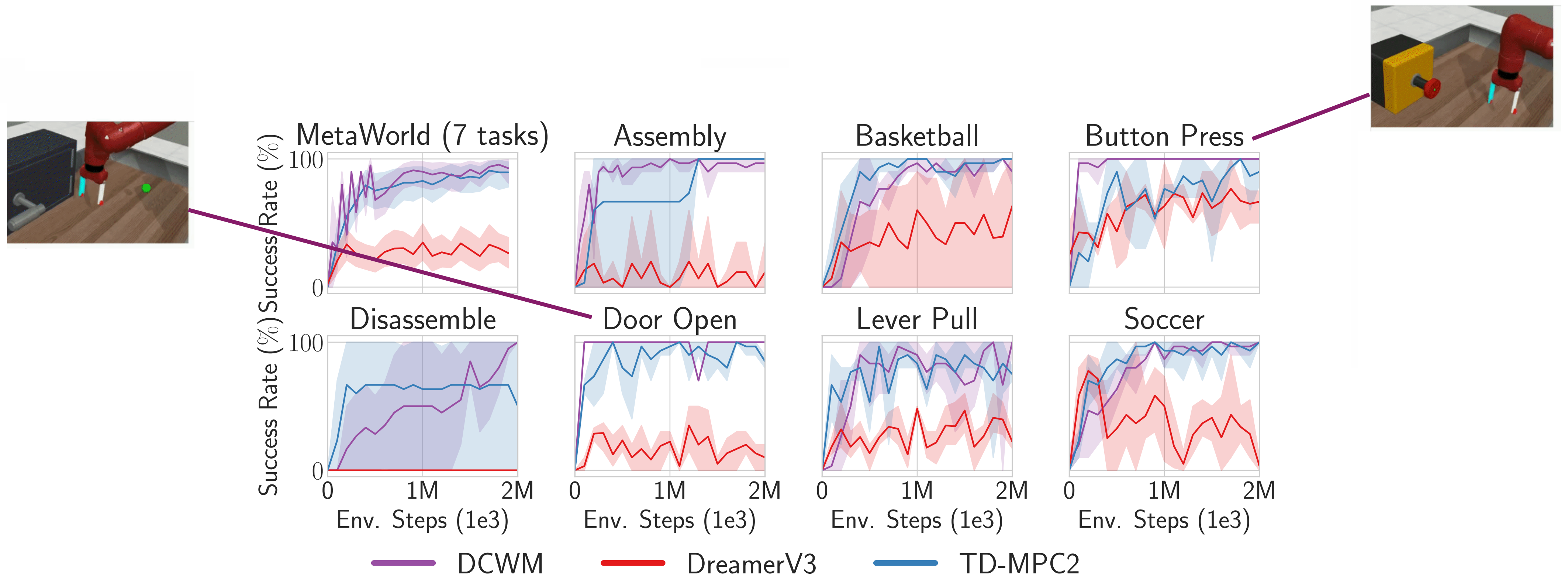
window open



window close

Results: MetaWorld

Competitive Performance in Robotic Manipulation



Comparison of Different Discrete Encodings

