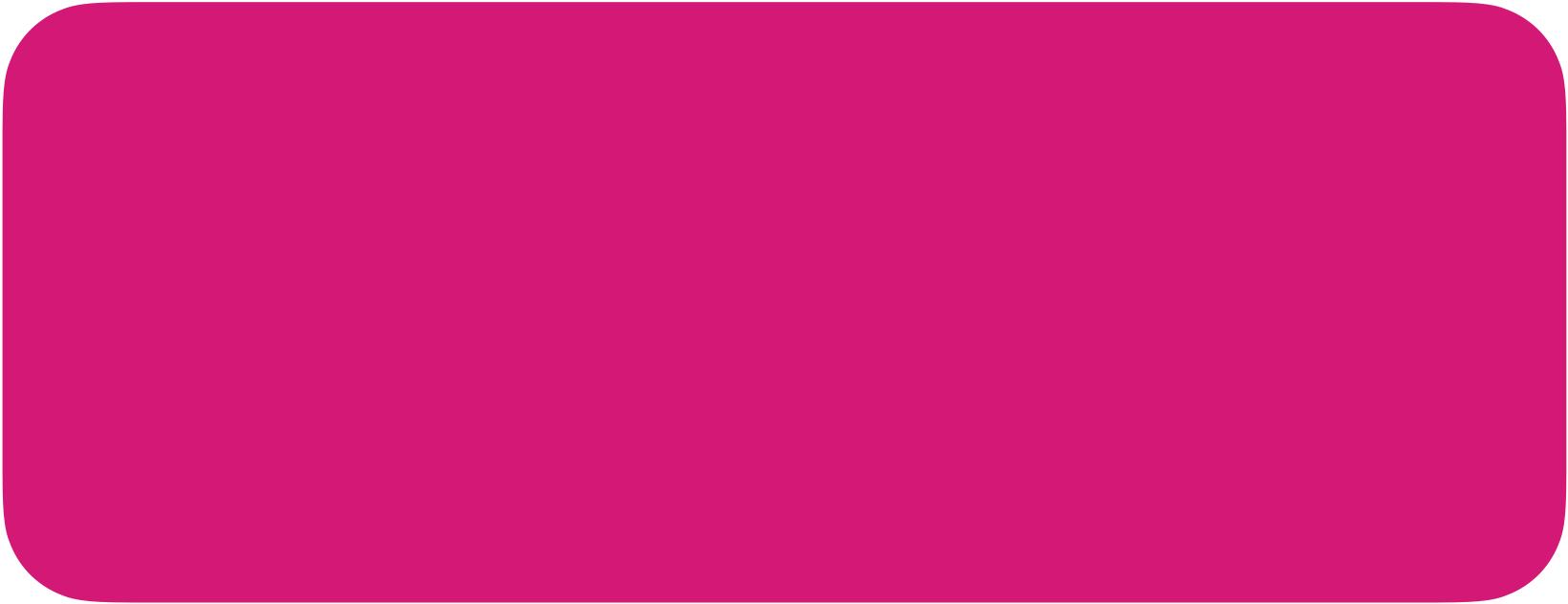
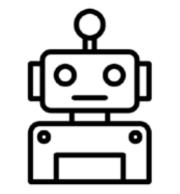
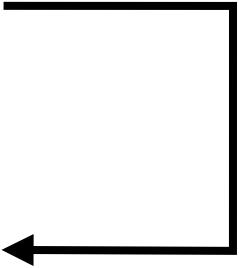
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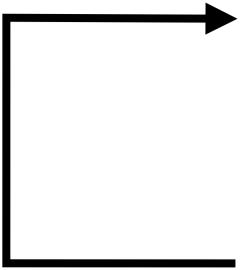


Reinforcement Learning





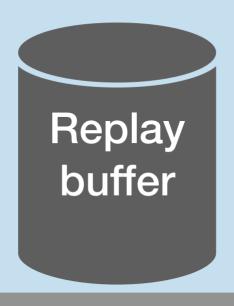




$a = \pi(s)$ **Actions**

$s' \sim P(\cdot \mid s, a)$ Transition function

r(s,a)S'State, Reward

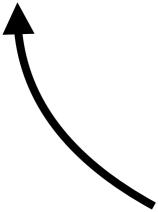


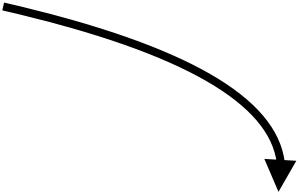
$$\mathcal{D} = \{(s, a, s', r)_n\}_{n=1}^{N}$$



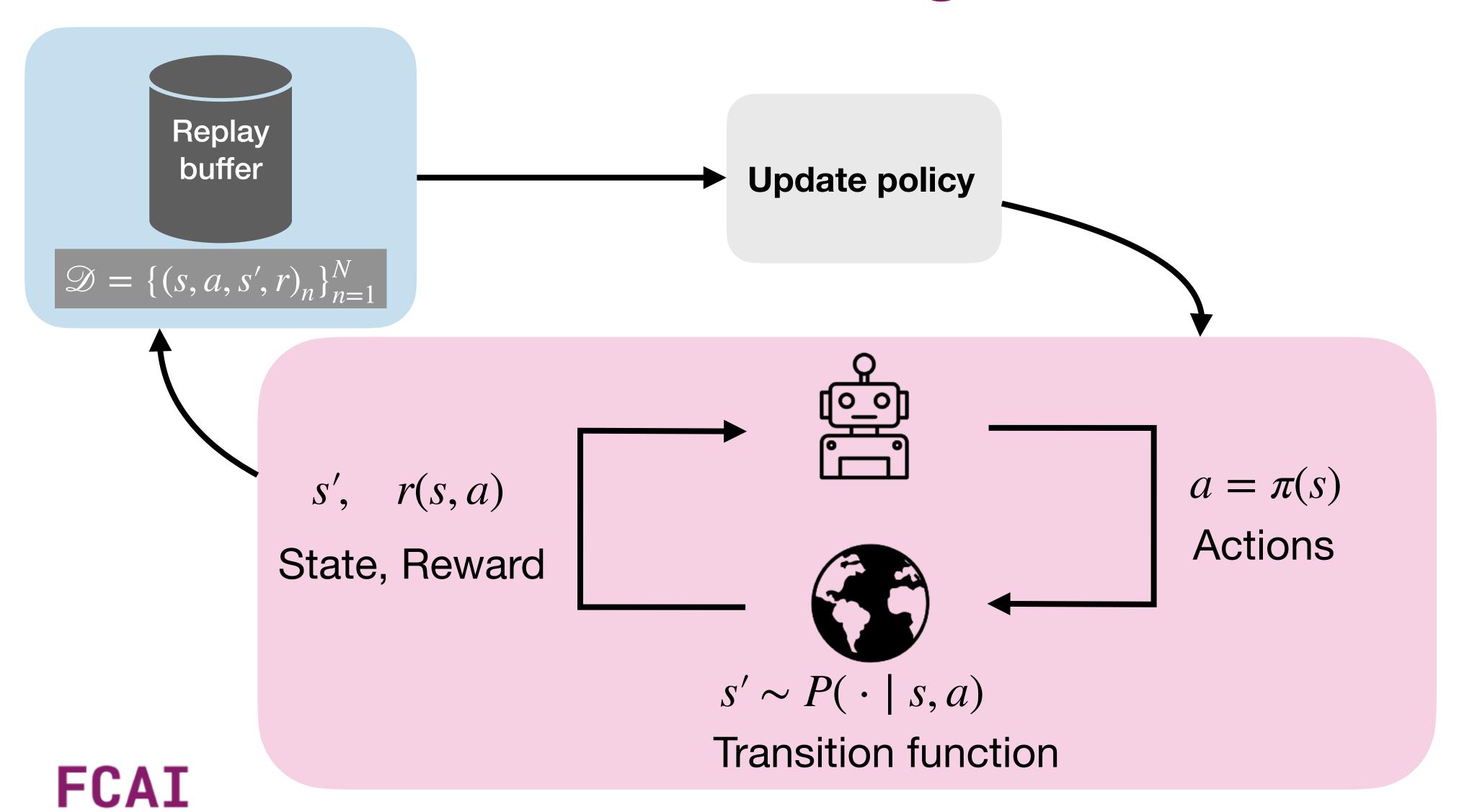
Update policy





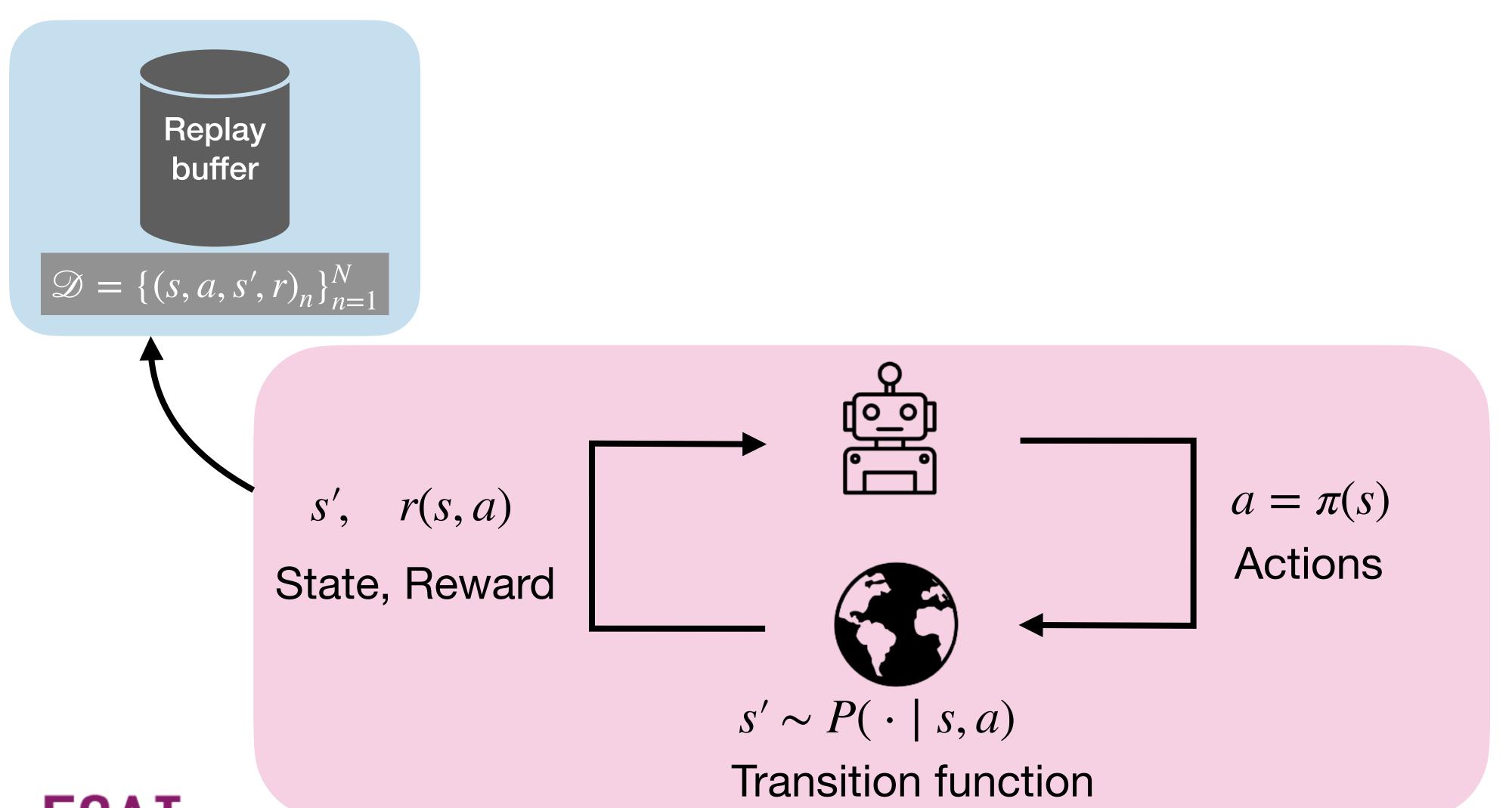


Reinforcement Learning



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Model-based Reinforcement Learning



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