

FCAI

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Decision-time Planning





common to CEM

• Avoids local optima

• **Can handle deterministic and stochastic dynamics**

• Avoid exploding/vanishing gradients

Use MPC to make CEM closed loop

Consider infinite horizon via learned $Q_{\theta}(s, a)$

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Main Takeaways

Common to use CEM

- Avoids local optima
- Can handle deterministic and stochastic dynamics
- Avoids exploding/vanishing gradients

Use MPC to make CEM closed loop

Consider infinite horizon via learned $Q_{\theta}(s, a)$

Learning Objectives

Understand

1. ~~What a “model” is in model-based RL~~
2. ~~How a “model” can aid decision making~~
3. ~~Differences between background and decision-time planning~~
4. ~~Decision-time planning strategies for continuous actions~~
5. Sources of uncertainty in model-based RL
6. Rationale and insights for decision-making under uncertainty