Sample-efficient Reinforcement Learning with Implicitly Quantized Representations

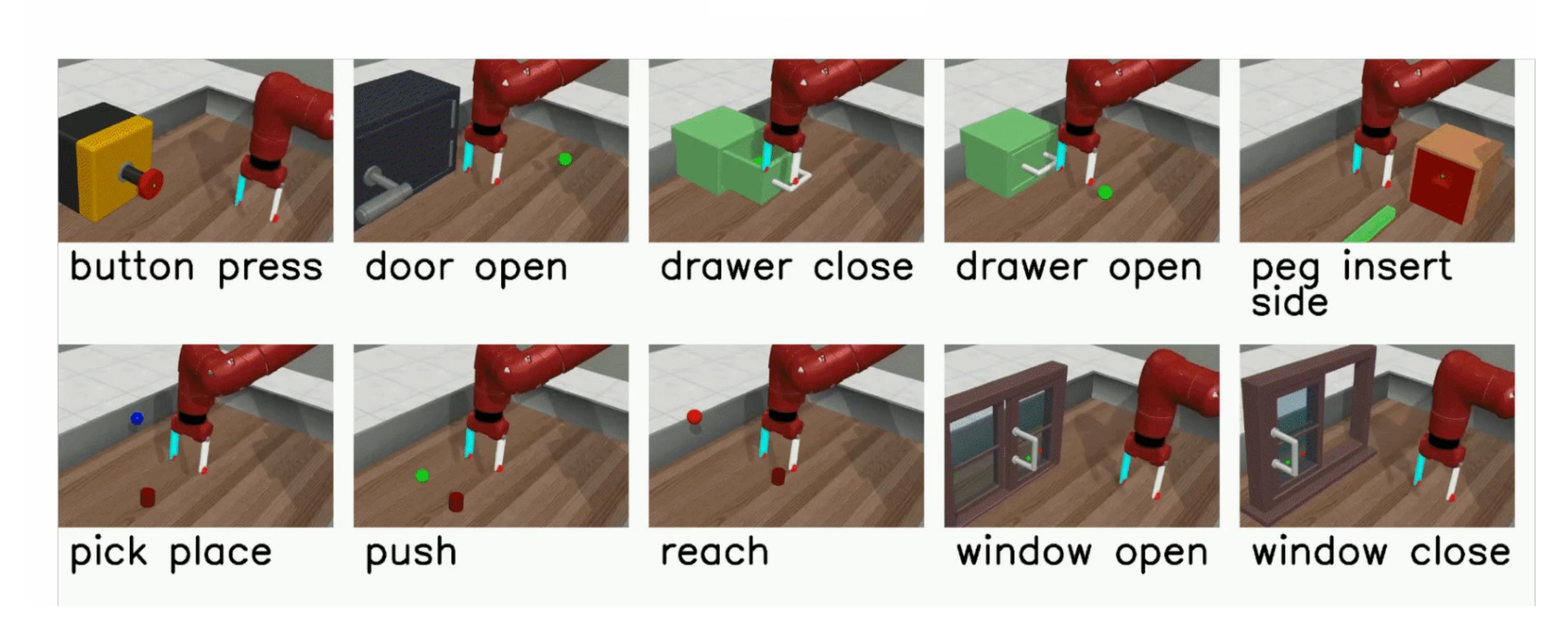
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Motivation: Robotic Manipulation



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