COC202 Computer Vision Lab 3 - Morphological image processing - Solutions

```
1.
   myim = logical([ ...
       0 0 0 0 0 0 0 0; ...
       0 0 0 1 1 1 0 0; ...
       0 0 1 1 1 1 0 0; ...
       0 1 1 1 1 0 0 0; ...
       0 0 0 1 0 0 0 0; ...
       0 1 1 1 0 0 0 0; ...
       0 0 0 0 0 0 0 0; ...
       0 0 0 0 0 0 0 0]);
   mystrel = logical([0 1 0; 1 1 1; 0 1 0]);
2.
   function eim = erode(im, sel)
   % morphological erosion
   % for simplicity we assume that the SEL is of size 3x3
   [dimy dimx] = size(im);
   eim = logical(zeros(dimy, dimx));
   tim = padarray(im, [1 1], 0, 'both'); % pad image
   for i=2:dimy+1
       for j=2:dimx+1
           block = tim(i-1:i+1,j-1:j+1); % current window
           block = block & sel; % extract window pixels where SEL=1
           if (block == sel) % SEL fits block
               eim(i-1, j-1) = 1;
           else
               eim(i-1, j-1) = 0;
           end
       end
   end
```

eim1 = erode(myim, mystrel)
eim2 = imerode(myim, mystrel)

```
3.
   function dim = dilate(im, sel)
   % morphological dilation
   \mbox{\%} for simplicity we assume that the SEL is of size 3\mbox{x3}
   [dimy dimx] = size(im);
   dim = logical(zeros(dimy, dimx));
   tim = padarray(im, [1 1], 0, 'both'); % pad image
   for i=2:dimy+1
       for j=2:dimx+1
           block = tim(i-1:i+1,j-1:j+1); % current window
           block = block & sel; % extract window pixels where SEL=1
           if (sum(sum(block)) > 0) % SEL hits block
               dim(i-1,j-1) = 1;
           else
               dim(i-1,j-1) = 0;
           end
       end
   end
   dim1 = dilate(myim, mystrel)
   dim2 = imdilate(myim, mystrel)
4.
   function oim = mopen(im, sel)
   % morphological opening
   oim = dilate(erode(im, sel),sel);
   oim1 = mopen(myim, mystrel)
   oim2 = imopen(myim, mystrel)
   function cim = mclose(im, sel)
   % morphological closing
   cim = erode(dilate(im, sel), sel);
   cim1 = mclose(myim, mystrel)
   cim2 = imclose(myim, mystrel)
6.
   imshow(mclose(mopen(imread('fingerprint.tif'),ones(3))),ones(3)));
```

7.

end

```
function bim = boundary(im)
   % morphological boundary extraction
   sel = ones(3,3);
   bim = im - erode(im, sel);
   im = imread('head.tif');
   bim = boundary(im);
   imshow(bim);
8.
   imb = imread('headboundary.tif');
   imshow(imb);
   [x,y] = getpts; % obtain point inside boundary from user
   imf = logical(zeros(size(imb)));
   imf(y,x) = 1;
   imshow(imf);
   imc = imcomplement(imb);
   strel = [0 1 0; 1 1 1; 0 1 0];
   newimf = (dilate(imf, strel)) & imc; % intersection of dilation and
   complement
   imshow(newimf)
   while (any(any(imf~=newimf))) % as long as region is growing
       imf = newimf;
       imshow(imf); % show current result
       newimf = (dilate(imf, strel)) & imc;
```