

## Week 9 - Problem Sheet 8

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$$1. \quad f(z) = \frac{3\cos^2(z)}{\sin^2(2z)}$$

(a)  $\text{ord}(f, 0)$  :

Use series expansion for  $\cos$  and  $\sin$  around 0 :

$$\cos(z) = 1 - \frac{1}{2}z^2 + \dots$$

$$\sin(z) = z - \frac{1}{6}z^3 + \dots$$

$$\Rightarrow 3\cos^2(z) = 3 - 3z^2 + \dots$$

$$\sin^2(2z) = 4z^2 - \frac{16}{3}z^4 + \dots$$

$$\begin{aligned} \text{so } f(z) &= \frac{3 - 3z^2 + \dots}{4z^2 - \frac{16}{3}z^4 + \dots} \\ &= \frac{1}{z^2} \left( \frac{3 - 3z^2 + \dots}{4 - \frac{16}{3}z^2 + \dots} \right) \end{aligned}$$

Write this as  $\frac{1}{z^2} h(z)$

Then  $h(0) = 3/4$  so expansion of  $h(z)$  around  $z=0$  looks like

$$h(z) = 3/4 + (\text{higher order terms})$$

$$\text{So } f(z) = \frac{3}{4} z^{-2} + (\text{higher order terms})$$

$$\therefore \text{ord}(f, 0) = -2.$$

$$(b) \text{ Res}(f, 0)$$

By def  $\text{Res}(f, 0)$  means:

coefficient of  $z^{-1}$  in the expansion of  $f$  around 0.

Remark: remember  $f(z) =$

$$\frac{1}{z^2} \left( \frac{3 - 3z^2 + \dots}{4 - \frac{16}{3}z^2 + \dots} \right)$$

Everything appearing only has even powers of  $z$ .  $\therefore$  coefficient of  $z^{-1}$  in the series expansion equals 0.

$$\therefore \text{Res}(f, 0) = 0.$$

(c) Calculate  $\int_{\gamma} f(z) dz$

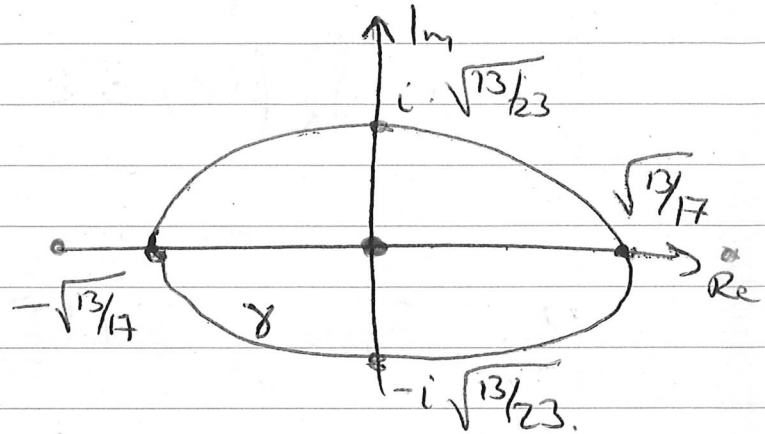
$\gamma$  is defined by  $17 \operatorname{Re}(z)^2 + 23 \operatorname{Im}(z)^2 = 13$

Residue Thm:

$$\int_{\gamma} f(z) dz$$

$$= 2\pi i \sum_{i=1}^n \operatorname{Res}(f, z_i)$$

where  $z_1, \dots, z_n$  are the poles of  $f$  inside  $\gamma$ .



What are the poles of  $f$ ?

$$f = \frac{3 \cos^2(z)}{\sin^2(2z)}$$

Only (possible) poles of  $f$  are where

$$\sin^2(2z) = 0.$$

$$\Leftrightarrow \sin(2z) = 0$$

$$\Leftrightarrow z = \frac{k}{2} \pi \quad k \in \mathbb{Z}$$

If  $k \neq 0$  then  $|\frac{k}{2} \pi| > 1 \therefore z$  is not inside  $\gamma$

So the only pole of  $f$  inside  $\gamma$

is at  $z=0$ , and we saw

$$\text{Res}(f, 0) = 0$$

$$\therefore \int_{\gamma} f(z) dz = 0$$

□

2. Suppose  $\text{ord}(f, z_0) = k$

So:

$$f(z) = a_k (z - z_0)^k + a_{k+1} (z - z_0)^{k+1} + \dots$$

with  $a_k \neq 0$ .

$$\text{So } f'(z) = k a_k (z - z_0)^{k-1} + (k+1) a_{k+1} (z - z_0)^k + \dots$$

$$\text{So } g = \frac{f'(z)}{f(z)} = \frac{k a_k (z - z_0)^{k-1} + (k+1) a_{k+1} (z - z_0)^k + \dots}{a_k (z - z_0)^k + a_{k+1} (z - z_0)^{k+1} + \dots}$$

Divide top & bottom by  $a_k (z - z_0)^k$  to get:

$$g(z) = \frac{k (z - z_0)^{-1} + \dots}{1 + \frac{a_{k+1}}{a_k} (z - z_0) + \dots}$$

The function  $\frac{1}{\cancel{h(z)} \left( 1 + \frac{a_{k+1}}{a_k} (z-z_0) + \dots \right)}$   $= h(z)$  is holomorphic at  $z_0$  with value 1 there.

So if we expand it around  $z_0$  we get

$$1 + b_k (z-z_0) + \dots$$

$$\text{So we get } g(z) = \frac{k(z-z_0)^{-1} + \dots}{\cancel{h(z)}} h(z)$$

$$= (k(z-z_0)^{-1} + \dots)(1 + b_k(z-z_0) + \dots)$$

$$= k(z-z_0)^{-1} + \dots$$

$$\therefore \text{Res}(g, z_0) = k = \text{ord}(f, z_0) \quad \square$$

3. Solution.

$$\underline{\quad\quad\quad} \omega_1, \omega_2$$

$$m, n, r, s \in \mathbb{Z}$$

$$\tau_1 = m\omega_1 + n\omega_2$$

$$\tau_2 = r\omega_1 + s\omega_2$$

$$L = \{ a\omega_1 + b\omega_2 \mid a, b \in \mathbb{Z} \}$$

$$L' = \{ a\tau_1 + b\tau_2 \mid a, b \in \mathbb{Z} \}$$

• Suppose  $L = L'$ .

$$\text{Want to show } \det \begin{pmatrix} m & n \\ r & s \end{pmatrix} = \pm 1.$$

Since  $L = L'$  and  $\omega_1, \omega_2 \in L$

we have  $\omega_1, \omega_2 \in L'$  too.

$\therefore \exists \mu, \nu, \rho, \sigma$  s.t.

$$\omega_1 = \mu\tau_1 + \nu\tau_2$$

$$\omega_2 = \rho\tau_1 + \sigma\tau_2$$

Substituting the given expressions  
for the  $T_i$  in terms of the  $\omega_i$  we  
get

$$\omega_1 = \mu(\overbrace{m\omega_1 + n\omega_2}^{T_1}) + \nu(\overbrace{r\omega_1 + s\omega_2}^{T_2})$$

$$\omega_2 = \rho(m\omega_1 + n\omega_2) + \sigma(r\omega_1 + s\omega_2)$$

Simplify: get

$$\omega_1 = (\mu m + \nu r)\omega_1 + (\mu n + \nu s)\omega_2$$

$$\omega_2 = (\rho m + \sigma r)\omega_1 + (\rho n + \sigma s)\omega_2$$

Write as a matrix eq:

$$\begin{pmatrix} \omega_1 \\ \omega_2 \end{pmatrix} = \begin{pmatrix} \mu & \nu \\ \rho & \sigma \end{pmatrix} \cdot M \cdot \begin{pmatrix} \omega_1 \\ \omega_2 \end{pmatrix}$$

If we write  $\omega_1 = x_1 + iy_1$   
 $\omega_2 = x_2 + iy_2$

or compare real + imag. parts we get

$$\begin{pmatrix} x_1 & y_1 \\ x_2 & y_2 \end{pmatrix} = \begin{pmatrix} \mu & \nu \\ \rho & \sigma \end{pmatrix} \cdot M \begin{pmatrix} x_1 & y_1 \\ x_2 & y_2 \end{pmatrix}$$

Since  $\omega_1 \neq \omega_2$  are not real multiples of each other

we have  $\begin{pmatrix} x_1 & y_1 \\ x_2 & y_2 \end{pmatrix}$  is invertible.

$$\therefore \begin{pmatrix} \mu & \nu \\ \rho & \sigma \end{pmatrix} \cdot M = Id_2$$

$$\therefore \det(M) \cdot \det \begin{pmatrix} \mu & \nu \\ \rho & \sigma \end{pmatrix} = 1$$

$\begin{matrix} m \\ \mathbb{Z} \end{matrix} \qquad \begin{matrix} m \\ \mathbb{Z} \end{matrix}$

$$\therefore \det(M) = \pm 1.$$

(converse: see typed solutions.