

PYTORCH CHEAT SHEET

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HEEELLL00000!

I'm Andrei Neagoie, Founder and Lead Instructor of the Zero To Mastery Academy.

After working as a Senior Software Developer over the years, I now dedicate 100% of my time to teaching others valuable software development skills, help them break into the tech industry, and advance their careers.

In only a few years, **over 750,000 students** around the world have taken Zero To Mastery courses and many of them are now working at top tier companies like <u>Apple, Google, Amazon, Tesla, IBM, Facebook, and Shopify</u>, just to name a few.

This cheat sheet, created by our PyTorch instructor (<u>Daniel Bourke</u>) provides you with the key PyTorch commands and setups that you need to know and remember.

If you want to not only learn PyTorch but also get the exact steps to build your own projects and get hired as a Machine Learning Engineer then check out our Career Paths.

Happy Learning!

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PyTorch Cheatsheet

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Imports

You can install PyTorch on various platforms via the <u>PyTorch installation page</u>.

```
import torch

# Check the version
print(f"PyTorch version: {torch.__version__}")
```

You can also import the common abbreviation "nn" for "Neural Networks".

Data imports

Since most of machine learning is finding patterns in data, it's good to know how to work with datasets in PyTorch.

```
# Import PyTorch Dataset (you can store your data here) and DataLoader (you can load your data here) from torch.utils.data import Dataset, DataLoader
```

Creating Tensors

One of the main use cases of PyTorch is for accelerated deep learning computing.

And deep learning usually involves the manipulation of large tensors (big, multi-dimensional collections of numbers).

PyTorch has a number of methods to create tensors.

Note: For a more extensive overview of creating tensors with PyTorch, see <u>00. PyTorch</u> <u>Fundamentals.</u>

```
# Create a single number tensor (scalar)
scalar = torch.tensor(7)

# Create a random tensor
random_tensor = torch.rand(size=(3, 4)) # this will create a tensor of size 3x4 but you can manipulate the shape how you want

# Multiply two random tensors
random_tensor_1 = torch.rand(size=(3, 4))
random_tensor_2 = torch.rand(size=(3, 4))
random_tensor_3 = random_tensor_1 * random_tensor_2 # PyTorch has support for most math operators in Python (+, *, -, /)
```

Domain Libraries

Depending on the specific problem you're working on, PyTorch has several domain libraries.

- **TorchVision** PyTorch's resident computer vision library.
- **TorchText** PyTorch's in-built domain library for text.
- **TorchAudio** PyTorch's domain library for everything audio.



• TorchRec — PyTorch's newest in-built domain library for powering recommendation engines with deep learning.

Computer Vision

Note: For an in-depth overview of computer vision in PyTorch, see <u>03. PyTorch Computer Vision</u>.

```
# Base computer vision library
import torchvision

# Other components of TorchVision (premade datasets, pretrained models and image transforms)
from torchvision import datasets, models, transforms
```

Text and Natural Language Processing (NLP)

```
# Base text and natural language processing library
import torchtext

# Other components of TorchText (premade datasets, pretrained models and text transforms)
from torchtext import datasets, models, transforms
```

Audio and Speech

```
# Base audio and speech processing library import torchaudio

# Other components of TorchAudio (premade datasets, pretrained models and text transforms) from torchaudio import datasets, models, transforms
```

Recommendation systems

Note: This library is currently in beta release, see the <u>GitHub page for installation</u>.

```
# Base recommendation system library
import torchrec

# Other components of TorchRec
from torchrec import datasets, models
```

Device-agnostic code (using PyTorch on CPU, GPU or MPS)

Much of deep learning involves computing on tensors.

Computing on tensors generally happens much faster on GPUs (graphics processing units, typically from NVIDIA) than CPUs (computer processing units).

MPS stands for "Metal Performance Shader" which is Apple's GPU (M1, M1 Pro, M2 etc).

It is advised to perform training on the fastest piece of hardware you have available, which will generally be: NVIDIA GPU ("cuda") > MPS device ("mps") > CPU ("cpu").

• For more on seeing how to get PyTorch to run on NVIDIA GPU (with CUDA), see 00. PyTorch Fundamentals.



• For more on running PyTorch using an MPS backend (running PyTorch on Mac GPUs) see the PyTorch documentation.

Note: It is advised to setup device-agnostic code at the start of your workflow.

```
# Setup device-agnostic code
if torch.cuda.is_available():
    device = "cuda" # NVIDIA GPU
elif torch.backends.mps_is_available():
    device = "mps" # Apple GPU
else:
    device = "cpu"

print(f"Using device: {device}")
```

Sending a tensor to target device

You can move objects (models and tensors) in PyTorch to different devices via the ..to("device_name") method.

```
# Create a tensor
x = torch.tensor([1, 2, 3])
print(x.device) # defaults to CPU

# Send tensor to target device
x = x.to(device)
print(x.device)
```

Setting random seeds

A lot of machine learning and deep learning involves taking random numbers in tensors and then shaping those random numbers to find/represent patterns in real data.

However, sometimes you'll want "reproducible" randomness.

To do so, you can set the random seeds, see Reproducibility (trying to take the random out of random) for more.

```
import torch

# Set the random seed (you can set this to any number you like, it will "flavour"

# the randomness with that number.
torch.manual_seed(42)

# Create two random tensors
random_tensor_A = torch.rand(3, 4)

torch.manual_seed(42) # set the seed again (try commenting this out and see what happens)
random_tensor_B = torch.rand(3, 4)

print(f"Tensor A:\n{random_tensor_A}\n")
print(f"Tensor B:\n{random_tensor_B}\n")
print(f"Does Tensor A equal Tensor B? (anywhere)")
random_tensor_A == random_tensor_B
```

You can also set the random seed on the GPU (CUDA devices).

```
# Set random seed on GPU
torch.cuda.manual_seed(42)
```

Neural Networks

PyTorch has a very comprehensive library of pre-built neural network components (many of these are referred to as "modules" in the PyTorch ecosystem).

At a fundamental level neural networks are stacks of *layers*. Each of these layers performs some kind of operation on an input and produces an output.

How these layers stack together will depend on the problem you're working on.

One of the most active areas of research in machine learning is how to stack neural network layers together (and the best answer to this is constantly changing).

The vast majority of neural network components in PyTorch are contained within the <u>torch.nn</u> <u>package</u> (<u>nn</u> is short for neural networks).

```
from torch import nn
```

Linear layers

PyTorch has several in-built linear layers.

Convolutional Layers (for making Convolutional Neural Networks or CNN's)

PyTorch has several in-built convolutional layers.

Naming of convolutional layers usually follows torch.nn.convxd where x can be a value of 1, 2 or 3.

The x value represents the number of dimensions the convolution will operate over, for example, 1 for singular dimension text, 2 for two dimension images (height x width) and 3 for 3D objects such as video (video is considered a series of images with a time dimension, height x width x time).



Note: You can see more on building convolutional neural networks for computer vision with PyTorch in <u>03</u>. PyTorch Computer Vision.

Transformer Layers (for making Transformer models)

PyTorch has in-built Transformer layers as described in the paper Attention Is All You Need.

Using in-built PyTorch Transformer layers has the benefit of potential speedups thanks to PyTorch's BetterTransformer.

Note: You can see the use of PyTorch's in-built Transformer layers to build a Vision Transformer in <u>08. PyTorch Paper Replicating.</u>



Recurrent Layers (for making Recurrent Neural Networks or RNN's)

PyTorch has in-built support for <u>Recurrent Neural Network layers</u> such as <u>long short-term memory (LSTM)</u> and <u>gated recurrent unit (GRU)</u>.

Activation Functions

<u>Activation functions</u> often go between layers in a neural network to add non-linear (non-straight) capabilities to linear (straight) functions.

In essence, a neural network is often comprised of a large amount of linear and non-linear functions.

PyTorch has <u>several non-linear activation functions</u> built into <u>torch.nn</u>.

Some of the most common are:

- nn.ReLU also known as rectified linear unit.
- nn.Sigmoid also known as the sigmoid function.
- nn.Softmax also known as the softmax function.

Note: See <u>02. PyTorch Neural Network Classification</u> for more.

```
# ReLU
relu = nn.ReLU()

# Sigmoid
sigmoid = nn.Sigmoid()

# Softmax
softmax = nn.Softmax()
```

Loss Functions

A loss function measures how wrong your model is. As in, how far are its predictions off where they should be.



Ideally, with training, data and an optimization function, this loss value goes as low as possible.

Loss functions in PyTorch (and deep learning in general) are also often referred to as: criterion, cost function.

PyTorch has <u>several loss functions</u> built into <u>torch.nn</u>.

And some of the most common are:

- nn.L1Loss also referred to as MAE or mean absolute error (this loss is often used for regression problems or predicting a number such as the price of houses).
- <u>nn.MSELOSS</u> also referred to as L2Loss or <u>mean squared error</u> (this loss is often used for regression problems or predicting a number such as the price of houses).
- <u>nn.BCEWithLogitsLoss</u> also known as <u>binary cross entropy</u> this loss function is often used for binary classification probelms (classifying something as one thing or another).
- nn.crossEntropyLoss this loss function is often used for multi-class classification problems (classifying something as one thing or another).

```
# L1Loss
loss_fn = nn.L1Loss() # also known as MAE or mean absolute error

# MSELoss
loss_fn = nn.MSELoss() # also known as MSE or mean squared error

# Binary cross entropy (for binary classification problems)
loss_fn = nn.BCEWithLogitsLoss()

# Cross entropy (for multi-class classification problems)
loss_fn = nn.CrossEntropyLoss()
```

Optimizers

An optimizer's job is to change the neural network weights in such a way that it reduces the loss function value.

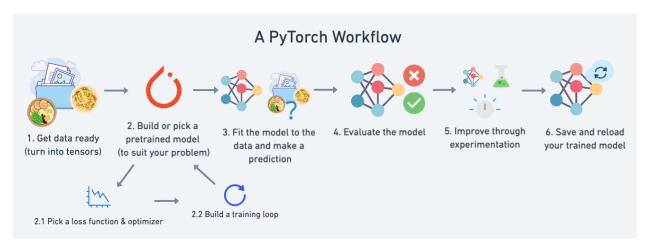
PyTorch has <u>several optimization functions</u> built into the <u>torch.optim</u> module.

Two of the main optimizer functions include:

- <u>torch.optim.SGD(lr=0.1,_params=model.parameters())</u> SGD also known as <u>stochastic gradient descent</u> (<u>lr</u> stands for "learning rate", the multiplier of how much to modify neural network weights at each step, small value = small adjustments, big value = big adjustments).
- <u>torch.optim.Adam(lr=0.001, params=model.parameters())</u> The Adam optimizer (<u>params</u> stands for "model parameters", in other words, the model parameters/weights you'd like the optimization function to optimize during training).

End-to-end example workflow

Let's put everything together in a quick end-to-end workflow.



This workflow has been taken from 01. PyTorch Workflow Fundamentals.

Create data

```
# Create *known* parameters
weight = 0.7
bias = 0.3

# Create data
start = 0
end = 1
step = 0.02
X = torch.arange(start, end, step).unsqueeze(dim=1) # data
y = weight * X + bias # labels (want model to learn from data to predict these)

X[:10], y[:10]
```

```
# Create train/test split
train_split = int(0.8 * len(X)) # 80% of data used for training set, 20% for testing
X_train, y_train = X[:train_split], y[:train_split]
X_test, y_test = X[train_split:], y[train_split:]
len(X_train), len(y_train), len(X_test), len(y_test)
```

Create a model

Two main ways to create a model in PyTorch:

- 1. Subclass torch.nn.Module more code but can be very flexible, models that subclass torch.nn.Module must implement a forward() method.
- 2. Use torch.nn.Sequential less code but less flexibility.

Let's start with option 1.

```
from torch import nn
# Option 1 - subclass torch.nn.Module
class LinearRegressionModel(nn.Module):
```



Now let's create the same model as above but using torch.nn.Sequential.

Setup loss function and optimizer

Create a training/testing loop

Our goal is to reduce the loss of our model (how much our model's predictions are different to the actual data).

If our training/testing loops are implemented right and the model is capable of learning patterns in the data, the training and test losses should go down.

See the following for steps in a PyTorch training/testing loop:

1. PyTorch Optimization Loop:

<u>Click here</u> for the PyTorch Optimization Loop song.

2. PyTorch Training Loop

For the training loop, build the following steps:

Number	Step name	What does it do?	Code example
1	Forward pass	The model goes through all of the training data once, performing its forward() function calculations.	model(x_train)
2	Calculate the loss	The model's outputs (predictions) are compared to the ground truth and evaluated to see how wrong they are.	<pre>loss = loss_fn(y_pred, y_train)</pre>
3	Zero gradients	The optimizers gradients are set to zero (they are accumulated by default) so they can be recalculated for the specific training step.	<pre>optimizer.zero_grad()</pre>
4	Perform backpropagation	Computes the gradient of the loss with respect for every model parameter to be updated (each parameter with requires_grad=True).	loss.backward()

	on the loss	This is known as backpropagation , hence "backwards".	
5	Update the optimizer (gradient descent)	Update the parameters with requires_grad=True with respect to the loss gradients in order to improve them.	optimizer.step()

3. PyTorch Testing Loop

For the testing loop (evaluating our model), the typical steps include:

Number	Step name	What does it do?	Code example
1	Forward pass	The model goes through all of the training data once, performing its forward() function calculations.	model(x_test)
2	Calculate the loss	The model's outputs (predictions) are compared to the ground truth and evaluated to see how wrong they are.	<pre>loss = loss_fn(y_pred, y_test)</pre>
3	Calculate evaluation metrics (optional)	Alongside the loss value you may want to calculate other evaluation metrics such as accuracy on the test set.	Custom functions

Note: the testing loop doesn't contain performing backpropagation (loss.backward()) or stepping the optimizer (optimizer.step()). This is because no parameters in the model are being changed during testing, they've already been calculated. For testing, we're only interested in the output of the forward pass through the model.

4. Training

Time to build a training and testing loop:

```
torch.manual_seed(42)
# Set the number of epochs
epochs = 1000
# Put data on the available device
# Without this, an error will happen (not all data on target device)
X_train = X_train.to(device)
X_test = X_test.to(device)
y_train = y_train.to(device)
y_test = y_test.to(device)
# Put model on the available device
# With this, an error will happen (the model is not on target device)
model_1 = model_1.to(device)
for epoch in range(epochs):
    ### Training
    model_1.train() # train mode is on by default after construction
    # 1. Forward pass
   y_pred = model_1(X_train)
    # 2. Calculate loss
    loss = loss_fn(y_pred, y_train)
    # 3. Zero grad optimizer
    optimizer.zero_grad()
    # 4. Loss backward
    loss.backward()
    # 5. Step the optimizer
    optimizer.step()
    ### Testing
    model_1.eval() # put the model in evaluation mode for testing (inference)
    # 1. Forward pass
```

```
with torch.inference_mode():
    test_pred = model_1(X_test)

# 2. Calculate the loss
    test_loss = loss_fn(test_pred, y_test)

if epoch % 100 == 0:
    print(f"Epoch: {epoch} | Train loss: {loss} | Test loss: {test_loss}")
```

```
>>> Epoch: 0 | Train loss: 0.7185534834861755 | Test loss: 0.8503350615501404
Epoch: 100 | Train loss: 0.008362660184502602 | Test loss: 0.005596184637397528
Epoch: 200 | Train loss: 0.008362660184502602 | Test loss: 0.005596184637397528
Epoch: 300 | Train loss: 0.008362660184502602 | Test loss: 0.006596184637397528
Epoch: 400 | Train loss: 0.008362660184502602 | Test loss: 0.005596184637397528
Epoch: 500 | Train loss: 0.008362660184502602 | Test loss: 0.005596184637397528
Epoch: 500 | Train loss: 0.008362660184502602 | Test loss: 0.005596184637397528
Epoch: 700 | Train loss: 0.008362660184502602 | Test loss: 0.005596184637397528
Epoch: 700 | Train loss: 0.008362660184502602 | Test loss: 0.005596184637397528
Epoch: 800 | Train loss: 0.008362660184502602 | Test loss: 0.005596184637397528
Epoch: 900 | Train loss: 0.008362660184502602 | Test loss: 0.005596184637397528
Epoch: 900 | Train loss: 0.008362660184502602 | Test loss: 0.005596184637397528
```

Our loss value goes down! That means our model and training setup are working!

Extras

You can find this cheatsheet as a <u>runnable Jupyter/Google Colab notebook</u> on the Zero to Mastery PyTorch for Deep Learning GitHub.

Note: If you're stuck with something, one of the best ways to get help for PyTorch specific functions and use cases is to search "pytorch how to make a convolutional neural network" or "pytorch transformer layers" or "pytorch loss functions". I do this regularly.

Here are some good places to find out more:

- PyTorch official cheatsheet.
- Zero To Mastery Learn PyTorch course a comprehensive yet beginner-friendly deep dive into using PyTorch for deep learning all the way from the fundamentals to deploying a model to the real-world so other people can use it.
- <u>PyTorch Performance Tuning Guide</u> a resource from the PyTorch team on how to tune performance of PyTorch models.
- <u>PyTorch Extra Resources</u> a curated list of helpful resources to extend PyTorch and learn more about the engineering side of things around deep learning.
- <u>Effective PyTorch by vahidk</u> a GitHub repo with a fantastic overview of some of the main functionality in PyTorch in a straight-forward manner.