

Tuesday Machine Learning Basis Quiz Answer



Part I: Deeper understanding on SVM

Problem 1: Non-seperable SVM

(i) The original constraint optimization problem:

The generalized Lagrangiun:

$$L(w,b,a,\mathbf{p}',\mathbf{g}) = \frac{1}{2}||w||^2 + C\sum_{i=1}^{\infty} \frac{1}{2}i + \sum_{i=1}^{\infty} \frac{1}{2}i[1-\frac{1}{2}i-\frac{1}{2}i(w^2x^2+b)] - \sum_{i=1}^{\infty} \frac{1}{2}i\frac{1}{2}i$$

min max $L(w,b,a,x^3)$ has the same solution as the original problem.

$$\begin{cases} \frac{\partial L}{\partial \omega} = \omega - \sum_{i=1}^{m} \partial_{i} y^{i} x^{i} = 0 \Rightarrow \omega = \sum_{i=1}^{m} \partial_{i} y^{i} x^{i} & \Theta \\ \frac{\partial L}{\partial \omega} = -\sum_{i=1}^{m} \partial_{i} y^{i} = 0 \Rightarrow \sum_{i=1}^{m} \partial_{i} y^{i} = 0 & \Theta \end{cases}$$

QOÐ ⇒ D =

$$39 \Rightarrow 0 = \frac{1}{2} ||w||^{2} + C_{2}^{\frac{11}{2}} s_{1} + \frac{1}{2} a_{1} \left[1 - s_{1} - y_{1}(w^{T}x^{2} + b)\right] - \frac{1}{2} r_{1} s_{1}$$

$$= \frac{1}{2} ||w||^{2} + C_{2}^{\frac{11}{2}} s_{1} + \sum_{i=1}^{m} a_{i} \left[1 - y_{1}(w^{T}x^{2})\right] - \sum_{i=1}^{m} a_{i} y_{1}^{2} b - \sum_{i=1}^{m} a_{i} s_{1}^{2} - \sum_{i=1}^{m} a_{i} y_{1}^{2} x_{2}^{2} = \frac{1}{2} ||w||^{2} + \sum_{i=1}^{m} a_{i} - \frac{1}{2} \sum_{i=1}^{m} a_{i} a_{i} y_{1}^{2} x_{2}^{2} = \frac{1}{2} ||w||^{2} = \sum_{i=1}^{m} a_{i} - \frac{1}{2} \sum_{i=1}^{m} a_{i} a_{i} y_{1}^{2} y_{1}^{2} (x_{1}^{2}, x_{1}^{2})$$

$$= \frac{1}{2} ||w||^{2} + \frac{1}{2} ||w||^{2} = \sum_{i=1}^{m} a_{i} - \frac{1}{2} \sum_{i=1}^{m} a_{i} a_{i} y_{1}^{2} y_{1}^{2} (x_{1}^{2}, x_{1}^{2})$$

s. the final result:

- C-> 00, the obnormal points will affect the classifier more, it will have a smaller margin hyperplane when it can seperate the points correctly
 - 600 the classifier will have a larger margin hyperplane even it will misclassify points.



Problem 2: Kernels

Please try to understand the kernel tricks basing on this question.

kernel
$$k(x,z) = (x^{T}z + C)^{2}$$

 $= (x_{1}z_{1} + x_{2}z_{2} + C)^{2}$
 $= x_{1}^{2}z_{1}^{2} + x_{2}z_{2}^{2} + 2x_{1}x_{2}z_{1}z_{2} + 2Cx_{1}z_{1} + 2Cx_{2}z_{2} + C^{2}$
 $\phi(x) = [x_{1}^{2}, \sqrt{x_{1}}x_{2}, x_{2}^{2}, \sqrt{x_{2}}x_{1}, \sqrt{x_{2}}x_{2}, C]^{T}$
 $\phi(z) = [z_{1}^{2}, \sqrt{z_{2}}z_{2}, z_{2}^{2}, \sqrt{x_{2}}z_{1}, \sqrt{x_{2}}z_{2}, C]^{T}$
 $\phi(x_{1}, \phi(z_{1})) = x_{1}^{2}z_{1}^{2} + 2x_{1}x_{2}z_{2} + x_{2}^{2}z_{2}^{2} + 2Cx_{1}z_{1} + 2Cx_{2}z_{2} + C^{2}$
 $\Rightarrow k(x_{1}z_{2}) = \zeta\phi(x_{1}, \phi(z_{2}))$

Part II: The basic knowledge on ANN

Problem 3: Backpropagation

$$\frac{\partial J(\omega,x,y)}{\partial \omega_{ji}^{(0)}} = \frac{\partial J}{\partial g_{\mu}} \cdot \frac{\partial g_{\nu}}{\partial h_{j}} \cdot \frac{\partial h_{j}^{(1)}}{\partial \omega_{ji}^{(0)}} \qquad \text{signoid function:}$$

$$\frac{\partial J}{\partial g_{\mu}} = \frac{\partial J}{\partial h_{j}^{(1)}} \cdot \frac{\partial J}{\partial h_{j}^{(2)}} \cdot \frac{\partial J}{\partial h_{j}^{(2)}} = \frac{\partial J}{\partial h_{j}^{(2)}} \cdot \frac{\partial J}{\partial h_{j}^{(2)}} \cdot \frac{\partial J}{\partial h_{j}^{(2)}} = \frac{\partial J}{\partial h_{j}^{(2)}} \cdot \frac{\partial J}{\partial h_{j}^{(2)}} \cdot \frac{\partial J}{\partial h_{j}^{(2)}} \cdot \frac{\partial J}{\partial h_{j}^{(2)}} \cdot \frac{\partial J}{\partial h_{j}^{(2)}} = \frac{\partial J}{\partial h_{j}^{(2)}} \cdot \frac{\partial J}{\partial h_{j}^{(2)}$$

Problem 4: What are the advantages of ReLU over sigmoid function?

Sigmoid function has the problem of vanish gradient because the gradient of sigmoid becomes increasingly small as the absolute value of x increases. But ReLU can **reduce the likelihood of the gradient to vanish** and the constant gradient of ReLU when x>0 will **result in faster learning**.

Data Application Lab

Another advantage of ReLU is **sparsity**, which arises when $x \le 0$. The more such units that exist in a layer the more sparse the resulting representation.