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(1)

	Course Scheduling	Deepyaman Datte
	Stanford CS 221 Fall 2015-2016	November 4,2015
C	a. $X=(X_1,,X_m)$, where $X_j \in \mathbb{Z}_{\geq 0}$ for each	button j=1,, m
	$f_{i} = \left[\sum_{j=1}^{\infty} (x_{j} [i \in T_{j}]) \text{ is odd} \right]$	
	b. i. {x,:0, x2:1, x3:0}, {x:1, x2:0, x3:1}	
	ii. backtrack (Ø, 1, ({0,13, {0,13, {0,13})})	
)	choose X,	
	0 V= ()	
	8 = 1	
	backtrack ({x:03,1,({03,{0,13,{0,13})}}	
	choose X2	
	*v=0	
	S = 1	
	backtrack (EX:0, X3:03, 1, (803, 80,13, 80	3))
	choose X2	
A constant	· v = O	
	8=0	
	• N=	and the second s
Control of the Contro	48=1	
	backtrack ({x;0,x2:1,x3:03,1, (303, 8	13 503))
	· V= 1	13,803)
	8=1	
	backtrack ({x;0,x3:13, 1({603, 80,13, {13})}	
	choose X2	
	8=0	
	V=	
	8=0	
		->

	• V = \
× 2	8=1
	backtrack ({×,:13,1,({13,10,13,50,13)}
	choose ×3
	• v= O
	8=1
	backtrack({x;·1,x3:03,1,({13,}0,13,{03)})
	choose X2
	*V=O
	8=0
	· y=
	98=0
	• V= 1
	S=1
	backtrack ({x,:1,x3:13,1,({13,{0,13,{13})}}
	choose X2
	* v=()
	8=1
	backtrack({x,1,x2:0,x3:13,1,({13,503,513)}
	· v=1
	8=0
	[9]
	iii, backtrack (Ø, 1({0,13,20,13,20,13))
	choose X,
	° v = ()
	8= \
	backtrack ({x,:03,1,({03,{13,903)}}
	choose Xz
	• v= O
	8=1
	\rightarrow

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backtrack ( {x, : 0, x3.03, 1, ({03, 113, {03}))
               choose X2
                 · v = 1
                  8=1
                  backtrack( {x:0,x2:1,x3:03,1({03, {13,503})}
         · v = 1
          8=1
          backtrack ({X,: 13, 1, ({ 13, { 03, { 13})}}
           choose Xz
            · v=1
              8=1
             back track ( {x,:1, x3:13,1,(**** [13, {03, {13})})
             Choose X2
                'V=0
                8=0
                 backtrack ( {x;:1, x2:0, x3:13,1,({13,503,{13})}
2. a. Inilialization: [B, E1]= O]
      Processing: [B;[2]=B;[1]+X;]
      Final Output: [B3[2] < K]
       Consistency: [B;-1[2]=B;[1]]
       We introduce auxillary variables
         · B, with domain {(0,0),(0,1),(0,2)}
         · B2 with domain {(0,0), (0,0),(0,2), (1,1), (1,2),(1,3),
                                 (2,2), (2,3),(2,4)3
          ·Bz with domain {(0,0),(0,1),(0,2),(1,1),(1,2),(1,3),
                                 (2,2), (2,3), (2,4), (3,3), (3,4), (3,5),
                                 (4,4), (4,5), (4,6) }
      The initialization constraint can be eliminated because
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B, 's domain already constrains B[1].

My scheme works similar to the or example from lecture. First, we break down the computation of the ternary constraint into three simple steps. As a Pirst attempt, ne introduce an auxiliag voriable A; for i=1,2,3 which represents He sum [AD=0] of variables X,,..., Xi. Then we can write constraints enforcing a simple recurrence that updates A; with A; -1: [A; = A; -1 + X;]. The constraint [A 3 K] enforces that the sum of all the variables is low than orienal to k. To turn the ternary constraint [A;=A;-,+X;] into a binary constraint, we merge Ai-1 and A; into one variable, represented as one variable B; The variable B; represents a pair of booleans, where B; [1] represents A; -1 and B,[2] represents A: A: is represented twice, so we need to (Processing) add another binary constraint to enforce that the two are equal (Consistency). The Initralization and Final Output factors are the some as before

3. C. The schedule produced is correct: CS347 is picked over CS224N (not offered), and DANCE46 is taken in Spr over Win to maximize units. Here's the best schedule: Win2016 3 S245
Win2016 4 CS246
Win2016 3 STATS315A

Spr 2016 3 STATS315B

Spr 2016 3 CS347
Spr 2016 1 DANCE 46