

DEEP LEARNING FOR ARTIFICIAL INTELLIGENCE

Master Course UPC ETSETB TelecomBCN Barcelona. Autumn 2017.



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#DLUPC

Day 4 Lecture 2

Loss functions



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Me



- **Javier Ruiz Hidalgo**

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- **Teaching experience**

- Basic signal processing
- Image processing & computer vision

- **Research experience**

- Master on hierarchical image representations by UEA (UK)
- PhD on video coding by UPC (Spain)
- Interests in image & video coding, 3D analysis and super-resolution

Outline

- **Introduction**
 - **Definition, properties, training process**
- **Common types of loss functions**
 - Regression
 - Classification
- **Regularization**
- **Example**

Definition

In a supervised deep learning context the **loss function** measures the **quality** of a particular set of parameters based on how well the output of the network **agrees** with the ground truth labels in the training data.

Nomenclature

loss function

=

cost function

=

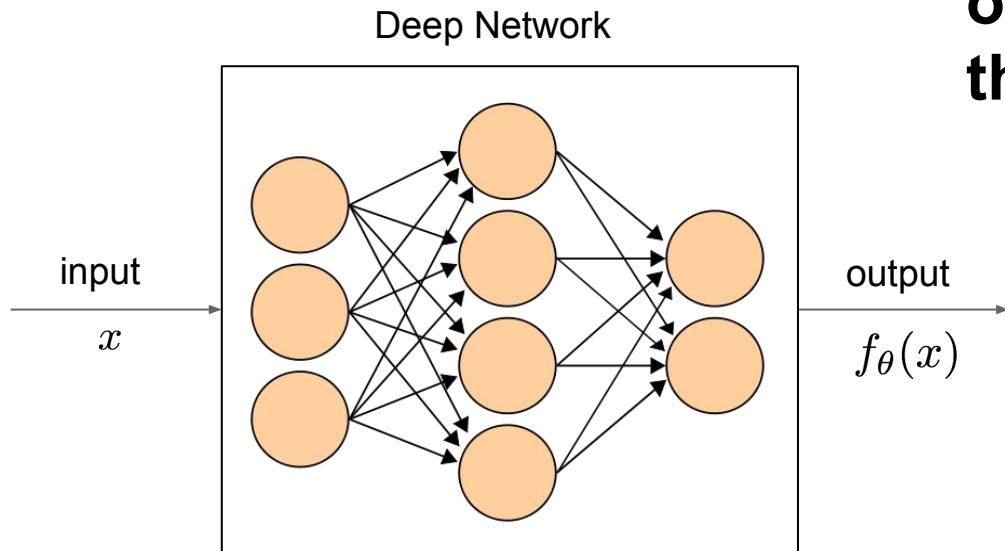
objective function

=

error function

Loss function (1)

**How good does
our network with
the training data?**



$$\mathcal{L}(w) = \text{distance}(f_{\theta}(x), y)$$

input → x

labels (ground truth) → y

error → $\mathcal{L}(w)$

parameters (weights, biases) → θ

Loss function (2)

- The loss function **does not** want to **measure** the **entire performance** of the network against a validation/test dataset.
- The loss function is used to **guide** the **training process** in order to find a set of parameters that reduce the value of the loss function.

Training process

Stochastic gradient descent

- Find a set of parameters which make the loss as small as possible.
- Change parameters at a rate determined by the partial derivatives of the loss function:

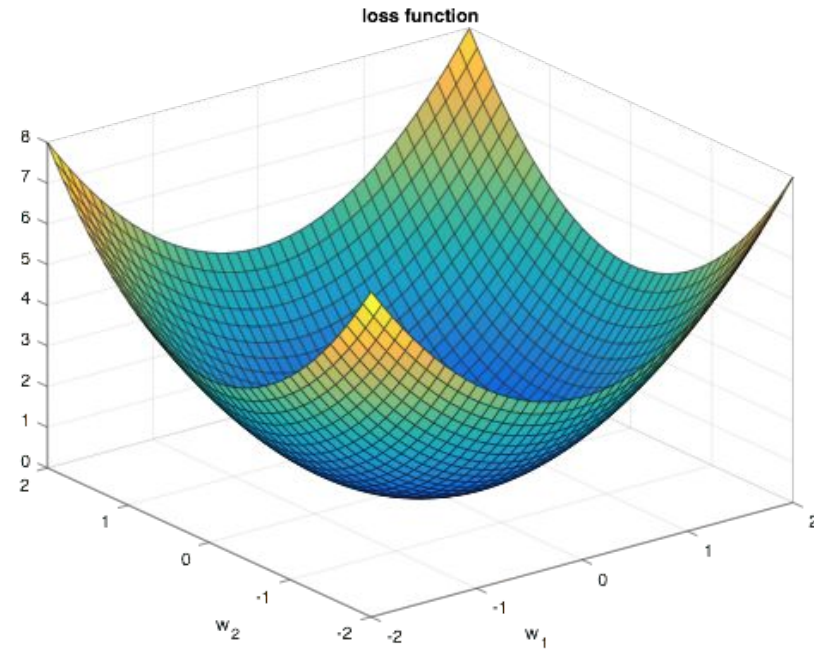
$$\frac{\partial \mathcal{L}}{\partial w} \quad \frac{\partial \mathcal{L}}{\partial b}$$

Properties (1)

- Minimum (0 value) when the output of the network is equal to the ground truth data.
- Increase value when output differs from ground truth.

Properties (2)


- Ideally \rightarrow convex function
- In reality \rightarrow some many parameters (in the order of millions) than it is not convex
 - Varies smoothly with changes on the output
 - Better gradients for gradient descent
 - Easy to compute small changes in the parameters to get an improvement in the loss



Assumptions

- For **backpropagation** to work:
 - Loss function can be written as an average over loss functions for individual training examples:

empirical risk


$$\mathcal{L} = \frac{1}{n} \sum_{i=1}^n \mathcal{L}_i$$

- Loss functions can be written as a function of the output activations from the neural network.

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Common types of loss functions (1)

- Loss functions depend on the type of task:
 - Regression: the network predicts **continuous, numeric** variables
 - Example: Length of fishes in images, temperature from latitude/longitude
 - Absolute value, square error

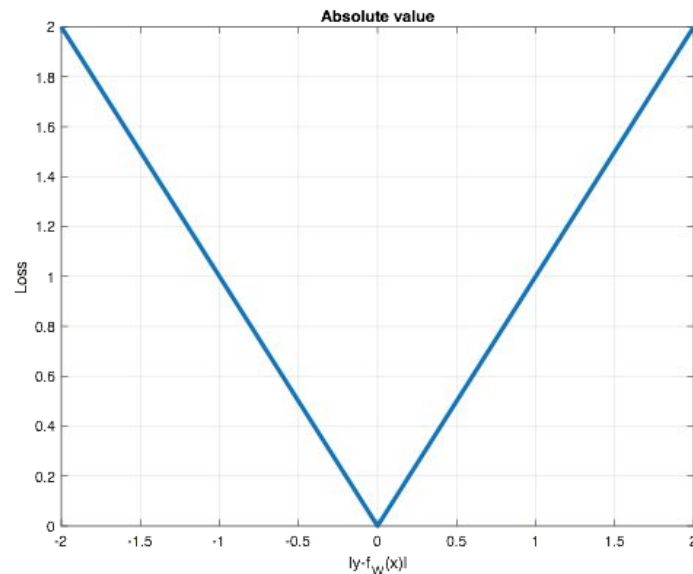
Common types of loss functions (2)

- Loss functions depend on the type of task:
 - Classification: the network predicts **categorical** variables (fixed number of classes)
 - Example: classify email as spam, predict student grades from essays.
 - hinge loss, Cross-entropy loss

Absolute value, L1-norm

- Very intuitive loss function
 - produces sparser solutions
 - good in high dimensional spaces
 - prediction speed
 - less sensitive to outliers

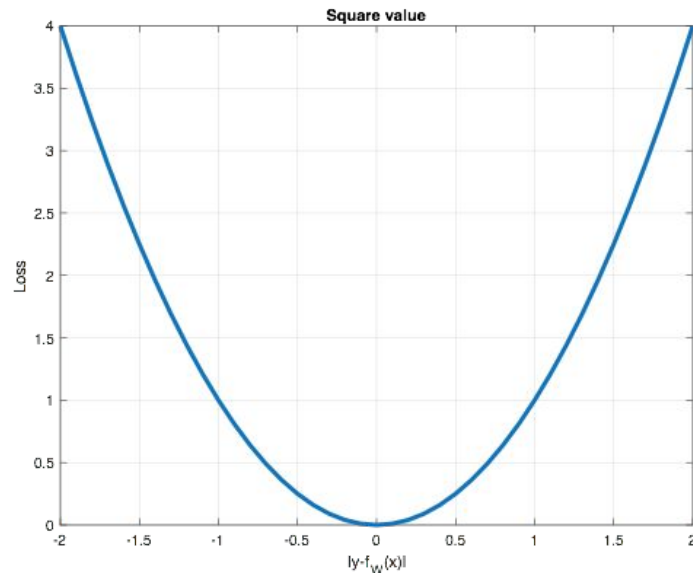
$$\mathcal{L} = \frac{1}{n} \sum_{i=1}^n |y_i - f_{\theta}(x_i)|$$



Square error, Euclidean loss, L2-norm

- Very common loss function
 - More precise and better than L1-norm
 - Penalizes large errors more strongly
 - Sensitive to outliers

$$\mathcal{L} = \frac{1}{n} \sum_{i=1}^n (y_i - f_{\theta}(x_i))^2$$

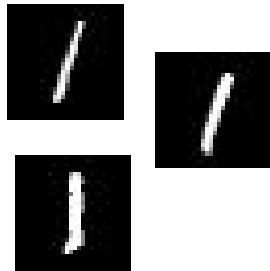


Outline

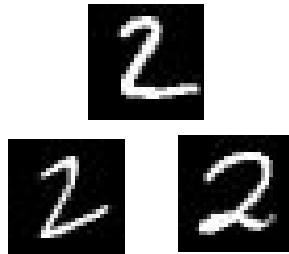
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Classification (1)

We want the network to classify the input into a fixed number of classes



class "1"



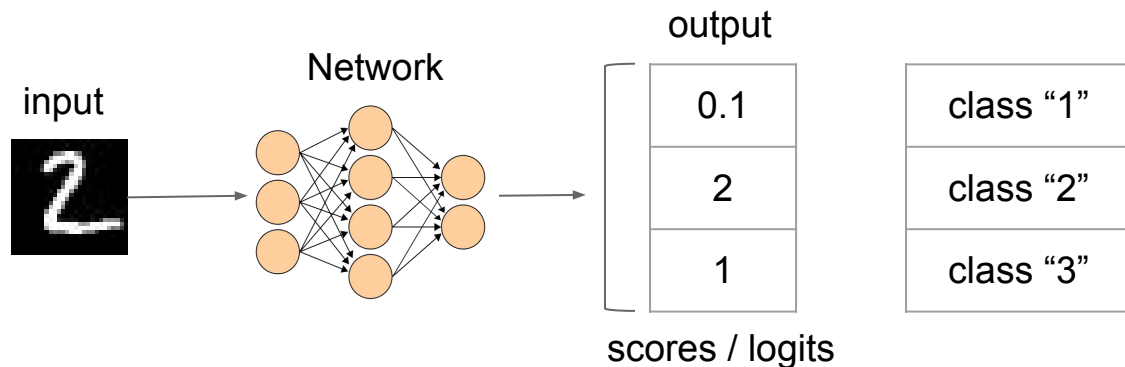
class "2"



class "3"

Classification (2)

- Each input can have only one label
 - One prediction per output class
 - The network will have “k” outputs (number of classes)



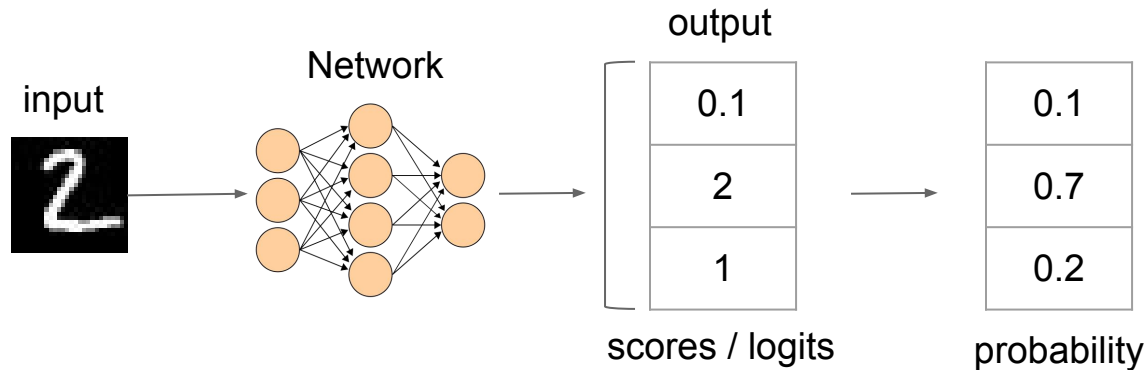
Classification (3)



- How can we create a loss function to improve the scores?
 - Somehow write the labels (ground truth of the data) into a vector → One-hot encoding
 - Non-probabilistic interpretation → **hinge loss**
 - Probabilistic interpretation: need to transform the scores into a probability function → Softmax

Softmax (1)

- Convert scores into probabilities
 - From 0.0 to 1.0
 - Probability for all classes adds to 1.0

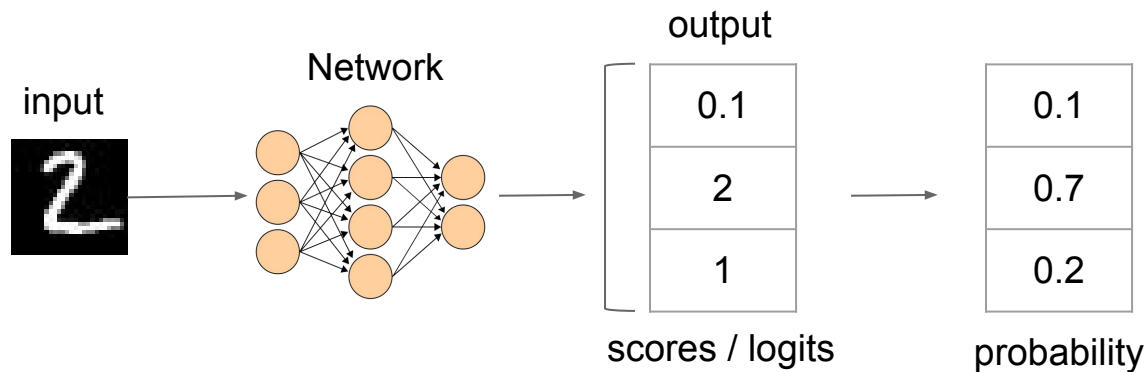


Softmax (2)

- Softmax function

scores (logits)

$$S(l_i) = \frac{e^{l_i}}{\sum_k e^{l_k}}$$

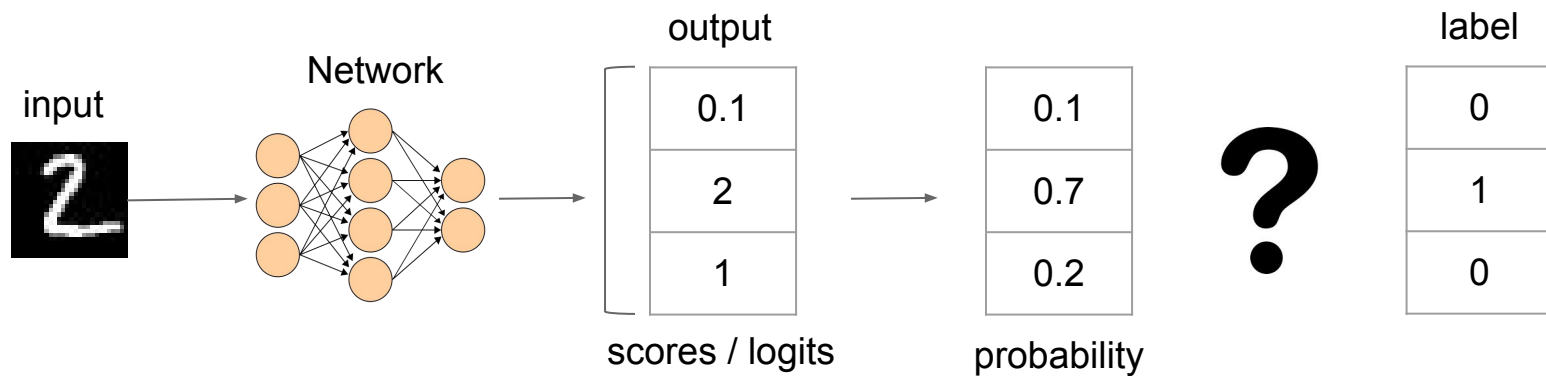


One-hot encoding

- Transform each label into a vector (with only 1 and 0)
 - Length equal to the total number of classes “k”
 - Value of 1 for the correct class and 0 elsewhere

class “1”	class “2”	class “3”
1	0	0
0	1	0
0	0	1

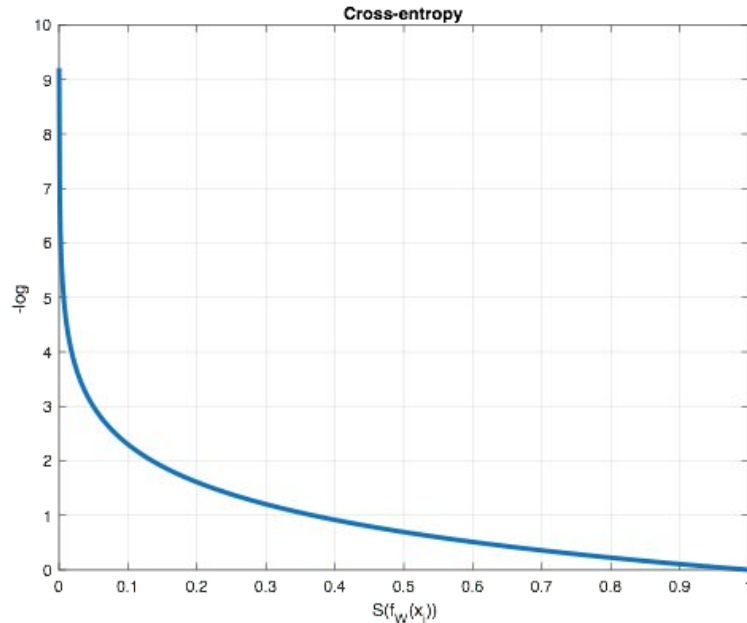
Cross-entropy loss (1)



$$\mathcal{L}_i = - \sum_k y_k \log(S(l_k)) = - \log(S(l))$$

Cross-entropy loss (2)

$$\mathcal{L}_i = - \sum_k y_k \log(S(l_k)) = -\log(S(l))$$



Cross-entropy loss (3)

- For a set of n inputs $\mathcal{L} = \frac{1}{n} \sum_{i=1}^n \mathcal{L}_i$

$$\mathcal{L} = - \sum_{i=1}^n \mathbf{y}_i \log(S(f_{\theta}(\mathbf{x}_i)))$$

labels (one-hot)

Softmax

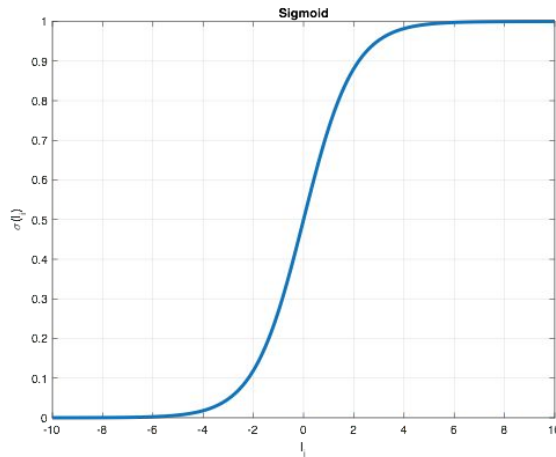
Cross-entropy loss (4)

- In general, cross-entropy loss works better than square error loss:
 - Square error loss usually gives too much emphasis to incorrect outputs.
 - In square error loss, as the output gets closer to either 0.0 or 1.0 the gradients get smaller, the change in weights gets smaller and training is slower.

Multi-label classification (1)

- Outputs can be matched to more than one label
 - “car”, “automobile”, “motor vehicle” can be applied to a same image of a car.
- Use sigmoid at each output independently instead of softmax

$$\sigma(l_i) = \frac{1}{1 + e^{-l_i}}$$



Multi-label classification (2)

- Cross-entropy loss for multi-label classification:

$$\mathcal{L}_i = - \sum_k y_k \log(\sigma(l_i)) + (1 - y_k) \log(1 - \sigma(l_i))$$


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Regularization

- Control the capacity of the network to **prevent overfitting**

- L2-regularization (weight decay): regularization parameter

$$\mathcal{L}_{new} = \mathcal{L} + \frac{\lambda}{2} W^2$$


- L1-regularization:

$$\mathcal{L}_{new} = \mathcal{L} + \frac{\lambda}{2} |W|$$

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Example

$$\mathcal{L} = - \sum_{i=1}^n y_i \log(S(f_{\theta}(\mathbf{x}_i)))$$

0.1	0.3	0.3
0.2	0.4	0.3
0.7	0.3	0.4

"1"	"2"	"3"
1	0	0
0	1	0
0	0	1

Classification accuracy = 2/3
cross-entropy loss = 4.14

0.3	0.1	0.1
0.4	0.7	0.2
0.3	0.2	0.7

"1"	"2"	"3"
1	0	0
0	1	0
0	0	1

Classification accuracy = 2/3
cross-entropy loss = 1.92

References

- [About loss functions](#)
- [Neural networks and deep learning](#)
- [Are loss functions all the same?](#)
- [Convolutional neural networks for Visual Recognition](#)
- [Deep learning book, MIT Press, 2016](#)
- [On Loss Functions for Deep Neural Networks in Classification](#)

Thanks! Questions?



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