Advanced: Quantum Dynamics Simulation

We will perform quantum dynamics (QD) simulation (cf. lecture 1) on a quantum computer for the transverse-field Ising model (TFIM) Hamiltonian (cf. lecture 2) for two spins,

$$H = -J\sigma_0^z \sigma_1^z - B \sum_{i=0}^1 \sigma_i^x, \tag{1}$$

where σ_i^z and σ_i^x are Pauli Z and X matrices acting on the j-th spin, J is the exchange coupling, and B is the magnetic field along the x axis.

Time evolution of a two-spin wave function, $|\Psi(t)\rangle = |\psi_0(t)\rangle |\psi_1(t)\rangle (|\psi_i(t)\rangle$ is the wave function of the j-th spin at time t), for small time step Δt is governed by (cf. https://aiichironakano.github.io/phys516/03QD.pdf)

$$|\Psi(t + \Delta t)\rangle = \exp(-iH\Delta t)|\Psi(t)\rangle$$
 (2)

in the atomic unit. Using Trotter expansion, the time-propagation operator is approximated as

$$\exp(-iH\Delta t) = \exp(i\Delta t J \sigma_0^z \sigma_1^z) \exp(i\Delta t B \sigma_0^x) \exp(i\Delta t B \sigma_1^x) + O(\Delta t^2). \tag{3}$$

Let us first consider the transverse-field propagator $\exp(i\Delta t B \sigma_i^x)$ acting on the j-th spin independent of the other spin. We use the eigendecomposition (see Appendix A) of Pauli X matrix,

$$\sigma^{x} = X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}. \tag{4}$$

Note that

$$\sigma^{x}H = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = H\sigma^{z}, \tag{5}$$

where H is the Hadamard gate (which is column-aligned eigenvectors $(1/\sqrt{2}, \pm 1/\sqrt{2})^T$ of σ^x with respective eigenvalues ± 1), or equivalently

$$\sigma^{x} = H\sigma^{z}H,\tag{6}$$

where we have used the fact H is a symmetric orthogonal matrix, i.e., $H^{-1} = H^T = H$ and thus

$$H^2 = I \tag{7}$$

(*I* is the identity matrix).

Using Taylor expansion of the time propagator and Eqs. (6) and (7) (the procedure is called telescoping),

$$\exp(i\Delta t B \sigma^{x}) = \sum_{n=0}^{\infty} \frac{(i\Delta t B)^{n}}{n!} \sigma^{x^{n}} = \sum_{n=0}^{\infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{n \text{ times}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{(i\Delta t B)^{n}}{n!} (H \sigma^{z} H)^{n} = \lim_{n \to \infty} \frac{($$

 $\sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} \widehat{H\sigma^z H H \sigma^z H \cdots H \sigma^z H} \text{ (every internal HH product becomes } I) =$

$$H\sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} \sigma^{z^n} H = H\sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} {1 \choose 0}^n - 1^n H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \end{pmatrix} H = H \begin{pmatrix} \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta t$$

$$H\sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} \sigma^{z^n} H = H\sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}^n H = H\begin{pmatrix} \sum_{n=0}^{\infty} \frac{(i\Delta tB)^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{(-i\Delta tB)^n}{n!} \end{pmatrix} H = H\begin{pmatrix} e^{i\Delta tB} & 0 \\ 0 & e^{-i\Delta tB} \end{pmatrix} H = HR_z(-2\Delta tB)H = \frac{1}{2} \begin{pmatrix} e^{i\Delta tB} + e^{-i\Delta tB} & e^{i\Delta tB} - e^{-i\Delta tB} \\ e^{i\Delta tB} - e^{-i\Delta tB} & e^{i\Delta tB} + e^{-i\Delta tB} \end{pmatrix} = \begin{pmatrix} \cos(\Delta tB) & i\sin(\Delta tB) \\ i\sin(\Delta tB) & \cos(\Delta tB) \end{pmatrix} = R_x(-2\Delta tB).$$
(8)

In terms of the native gates on IBM Q computers, Eq. (8) can be implemented using either rotation around the z axis, $R_z(\theta)$, along with Hadamard gate H, or solely using rotation around the x axis, $R_x(\theta)$. Here, R_z and R_x gates are defined as

$$R_z(\theta) = \begin{pmatrix} e^{-i\theta/2} & 0\\ 0 & e^{i\theta/2} \end{pmatrix},\tag{9}$$

$$R_{x}(\theta) = \begin{pmatrix} \cos(\theta/2) & -i\sin(\theta/2) \\ -i\sin(\theta/2) & \cos(\theta/2) \end{pmatrix}. \tag{10}$$

(see https://github.com/Qiskit/qiskit-tutorials/blob/master/tutorials/circuits/3 summary of quantum operations.ipynb).

Next, we consider the exchange-coupling propagator $\exp(i\Delta t J \sigma_0^z \sigma_1^z)$. We first consider a tensor product of operators multiplied by a scalar constant,

$$i\Delta t J \sigma_0^z \otimes \sigma_1^z = i\Delta t J \begin{pmatrix} 1 \cdot \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} & 0 \cdot \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \\ 0 \cdot \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} & -1 \cdot \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \end{pmatrix} = \begin{pmatrix} i\Delta t J & 0 & 0 & 0 \\ 0 & -i\Delta t J & 0 & 0 \\ 0 & 0 & -i\Delta t J & 0 \\ 0 & 0 & 0 & i\Delta t J \end{pmatrix}. \tag{11}$$

Since this is a diagonal matrix, it can be exponentiated element by element as

$$\exp(i\Delta t J \sigma_0^z \sigma_1^z) = \begin{pmatrix} \exp(i\Delta t J) & 0 & 0 & 0 \\ 0 & \exp(-i\Delta t J) & 0 & 0 \\ 0 & 0 & \exp(-i\Delta t J) & 0 \\ 0 & 0 & 0 & \exp(i\Delta t J) \end{pmatrix} = \begin{pmatrix} R_z(-2\Delta t J) & 0 \\ 0 & R_z(2\Delta t J) \end{pmatrix}.$$
(12)

Now consider the following sequence of quantum gates operating on two qubits, q_0 and q_1 ,

$$G = CX(q_0, q_1) \cdot R_1^z(-2\Delta t J) \cdot CX(q_0, q_1), \tag{13}$$

where

$$CX(q_0, q_1) = \begin{pmatrix} I & 0 \\ 0 & X \end{pmatrix} \tag{14}$$

is the controlled X(CNOT) gate, with q_0 and q_1 being the control and target bits, and R_1^z is the R^z gate acting on q_1 . When operating on two qubits, R_1^z signifies a tensor product,

$$I \otimes R^{z}(-2\Delta tJ) = \begin{pmatrix} 1 \cdot R^{z}(-2\Delta tJ) & 0 \cdot R^{z}(-2\Delta tJ) \\ 0 \cdot R^{z}(-2\Delta tJ) & 1 \cdot R^{z}(-2\Delta tJ) \end{pmatrix} = \begin{pmatrix} R^{z}(-2\Delta tJ) & 0 \\ 0 & R^{z}(-2\Delta tJ) \end{pmatrix}. \tag{15}$$

Substituting Eqs. (14) and (15) in Eq. (13), we obtain

$$G = \begin{pmatrix} I & 0 \\ 0 & X \end{pmatrix} \begin{pmatrix} R^z(-2\Delta tJ) & 0 \\ 0 & R^z(-2\Delta tJ) \end{pmatrix} \begin{pmatrix} I & 0 \\ 0 & X \end{pmatrix} = \begin{pmatrix} R^z(-2\Delta tJ) & 0 \\ 0 & XR^z(-2\Delta tJ)X \end{pmatrix}. \tag{16}$$

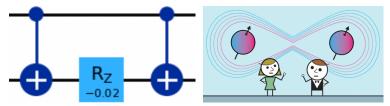
Here,

$$XR^{z}(-2\Delta tJ)X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \exp(i\Delta tJ) & 0 \\ 0 & \exp(-i\Delta tJ) \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & \exp(-i\Delta tJ) \\ \exp(i\Delta tJ) & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} \exp(-i\Delta tJ) & 0 \\ 0 & \exp(i\Delta tJ) \end{pmatrix} = R^{z}(2\Delta tJ).$$
(17)

Substituting Eq. (17) in Eq. (16) and compare the result with Eq. (12), we arrive at the identity,

$$G = CX(q_0, q_1)R_1^z(-2\Delta tJ)CX(q_0, q_1) = \begin{pmatrix} R^z(-2\Delta tJ) & 0\\ 0 & R^z(2\Delta tJ) \end{pmatrix} = \exp(i\Delta tJ\sigma_0^z\sigma_1^z).$$
 (18)

where the last equality results from Eq. (12). Namely, $G = CX(q_0, q_1) \cdot R_1^z(-2\Delta tJ) \cdot CX(q_0, q_1)$ is a quantum-gate implementation of the exchange-coupling propagator $\exp(i\Delta tJ\sigma_0^z\sigma_1^z)$.



Combining Eqs. (8) and (18) for the transverse-field and exchange-coupling time propagators, respectively, quantum-circuit implementation for a single time step of time evolution for the TFIM model, Eq. (1), is given by

$$\exp(-iH\Delta t) = \exp(i\Delta t J \sigma_0^z \sigma_1^z) \exp(i\Delta t B \sigma_0^x) \exp(i\Delta t B \sigma_1^x) = CX(q_0, q_1) R_1^z (-2\Delta t J) CX(q_0, q_1) R_0^x (-2\Delta t B) R_1^x (-2\Delta t B).$$

$$\tag{18}$$

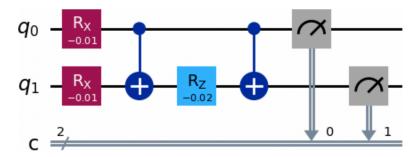
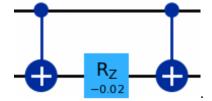


Fig. 1: Quantum circuit for time evolution of TFIM in IBM Quantum Lab.

In summary, time evolution is simply a rotation around an eigen-axis of the Hamiltonian operator, e.g.,

R_X

or concerted rotations of multiple qubits mediated by, e.g., the CNOT gate,



Hands-on Exercise (try it in Jupyter Notebook using Qiskit AerSimulator)

Execute the following Qiskit program to perform a single time step of QD simulation. Here, we have used model parameters, J = 1, B = 0.5 and $\Delta t = 0.01$, in atomic units. Appendix B shows how to set up an environment for the exercise.

```
##### Single step of Trotter propagation in transverse-field Ising model #####
import numpy as np
# Import standard Qiskit libraries
from qiskit import QuantumCircuit
from qiskit_aer import AerSimulator
from qiskit.visualization import *
### Physical parameters (atomic units) ###
J = 1.0
        # Exchange coupling
B = 0.5
          # Transverse magnetic field
dt = 0.01 # Time-discretization unit
### Build a circuit ###
circ = QuantumCircuit(2, 2) # 2 quantum & 2 classical registers
circ.rx(-2*dt*B, 0) # Transverse-field propagation of spin 0
circ.rx(-2*dt*B, 1) # Transverse-field propagation of spin 1
circ.cx(0, 1)
                     # Exchange-coupling time propagation (1)
circ.rz(-2*dt*J, 1)
                                                          (2)
circ.cx(0, 1)
                                                          (3)
circ.measure(range(2), range(2)) # Measure both spins
circ.draw('mpl')
```

This will build a circuit and draw it, which should then be transpiled and run on a simulator as follows.

```
### Simulate on Aer backend ###

# Use Aer simulator
backend = AerSimulator()
# Transpile the quantum circuit to low-level QASM instructions
from qiskit import transpile
circ_compiled = transpile(circ, backend)
# Execute the circuit on the simulator, repeating 1024 times
job_sim = backend.run(circ_compiled, shots=1024)
# Grab the results from the job
result_sim = job_sim.result()
# Get the result
counts = result_sim.get_counts(circ_compiled)
# Plot histogram
from qiskit.visualization import plot_histogram
plot_histogram(counts)
```

Table I: Qiskit program for single-time-step QD simulation of TFIM: tfim-1step.qiskit (https://aiichironakano.github.io/phys516/src/QComp/tfim-1step.qiskit).

After creating a new Python notebook, you can copy and paste the above code into a cell in the notebook. Actual quantum dynamics simulation [L. Bassman *et al.*, *Phys. Rev. B* **101**, 184305 ('20)] will iterate this unit-time stepping for many time steps. For Python programming underlying Qiskit, see A. Scopatz and K. D. Huff, *Effective Computation in Physics* (O'Reilly, '15).

Appendix A: Eigendecomposition

For a 2×2 Hermitian matrix,

$$\mathbf{A} = \begin{bmatrix} a & b \\ b^* & a \end{bmatrix},\tag{A1}$$

where a and b are real and complex numbers, respectively, consider an eigenvalue problem,

$$\begin{bmatrix} a & b \\ b^* & a \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \varepsilon \begin{bmatrix} u \\ v \end{bmatrix}. \tag{A2}$$

or equivalently

$$\begin{bmatrix} \varepsilon - a & -b \\ -b^* & \varepsilon - a \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}. \tag{A3}$$

For nontrivial solutions (i.e., other than u = v = 0), the determinant of the matrix in Eq. (A3) should be zero. (Otherwise, one can invert Eq. (A3) to get u = v = 0.) Hence,

$$\begin{vmatrix} \varepsilon - a & -b \\ -b^* & \varepsilon - a \end{vmatrix} = (\varepsilon - a)^2 - |b|^2 = 0,$$
Secular (characteristic) equation (A4)

which has two solutions,

$$\varepsilon_{\pm} = a \pm |b|$$
. Eigenvalues (A5)

The corresponding eigenvectors can be obtained by solving Eq. (A3) for these eigenvalues

$$\begin{bmatrix} |b| & -b \\ -b^* & |b| \end{bmatrix} \begin{bmatrix} u_+ \\ v_+ \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}; \begin{bmatrix} -|b| & -b \\ -b^* & -|b| \end{bmatrix} \begin{bmatrix} u_- \\ v_- \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
(A6)

with the answers (note the degeneracy of the two linear equations for each eigenvalue, e.g., $|b|u_+ - bv_+ = 0 \Rightarrow \left(\times \frac{-b^*}{|b|} \right) - b^*u_+ + |b|v_+ = 0$)

$$\mathbf{w}_{\pm} = \begin{bmatrix} u_{\pm} \\ v_{\pm} \end{bmatrix} = \frac{1}{\sqrt{2}|b|} \begin{bmatrix} b \\ \pm |b| \end{bmatrix}. \text{ Eigenvectors}$$
 (A7)

In Eq. (A7), we have normalized each eigenvector so that

$$\mathbf{w}_{\pm}^{\dagger}\mathbf{w}_{\pm} = \begin{bmatrix} u_{\pm}^* & v_{\pm}^* \end{bmatrix} \begin{bmatrix} u_{\pm}^* \\ v_{\pm} \end{bmatrix} = \frac{b^{2}}{b^*b + |b|^2} = 1, \tag{A8}$$

where $\mathbf{w}_{\pm}^{\dagger}$ denotes the Hermitian conjugate (or conjugate transpose) of \mathbf{w}_{\pm} . Also, the two eigenvectors are orthogonal:

$$\mathbf{w}_{+}^{\dagger}\mathbf{w}_{\pm} = \begin{bmatrix} u_{+}^{*} & v_{+}^{*} \end{bmatrix} \begin{bmatrix} u_{\pm} \\ v_{\pm} \end{bmatrix} = \frac{\tilde{b}^{*}\tilde{b} - |b|^{2}}{2|b|^{2}} = 0.$$
 (A9)

Now, define a 2×2 matrix composed of column aligned eivenvectors,

$$\mathbf{U} = \begin{bmatrix} \mathbf{w}_{+} & \mathbf{w}_{-} \end{bmatrix} = \begin{bmatrix} u_{+} & u_{-} \\ v_{+} & v_{-} \end{bmatrix} = \frac{1}{\sqrt{2}|b|} \begin{bmatrix} b & b \\ |b| & -|b| \end{bmatrix}, \tag{A10}$$

then

$$\mathbf{U}^{\dagger}\mathbf{U} = \begin{bmatrix} \mathbf{w}_{+}^{\dagger} \\ \mathbf{w}_{-}^{\dagger} \end{bmatrix} [\mathbf{w}_{+} \quad \mathbf{w}_{-}] = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \mathbf{I}, \tag{A11}$$

where **I** is the 2 × 2 identity matrix and we have used the orthonormalization relations, Eqs. (A8) and (A9). Using the explicit formula for **U** in Eq. (A10), we can also verify that $\mathbf{U}\mathbf{U}^{\dagger} = \mathbf{I}$ and hence **U** is a unitary matrix:

$$\mathbf{U}^{\dagger}\mathbf{U} = \mathbf{U}\mathbf{U}^{\dagger} = \mathbf{I}. \text{ Unitary} \tag{A12}$$

The two solutions of Eq. (A2) can now be combined into a matrix form as

$$\begin{cases}
\begin{bmatrix} a & b \\ b^* & a \end{bmatrix} \begin{bmatrix} u_+ \\ v_+ \end{bmatrix} = \varepsilon_+ \begin{bmatrix} u_+ \\ v_+ \end{bmatrix} \\
\begin{bmatrix} a & b \\ b^* & a \end{bmatrix} \begin{bmatrix} u_- \\ v_- \end{bmatrix} = \varepsilon_- \begin{bmatrix} u_- \\ v_- \end{bmatrix} \Leftrightarrow \underbrace{\begin{bmatrix} a & b \\ b^* & a \end{bmatrix}}_{\mathbf{A}} \underbrace{\begin{bmatrix} u_+ & u_- \\ v_+ & v_- \end{bmatrix}}_{\mathbf{U}} = \underbrace{\begin{bmatrix} u_+ & u_- \\ v_+ & v_- \end{bmatrix}}_{\mathbf{U}} \underbrace{\begin{bmatrix} \varepsilon_+ & 0 \\ 0 & \varepsilon_- \end{bmatrix}}_{\mathbf{D}}, \tag{A13}$$

i.e.,

$$\mathbf{AU} = \mathbf{UD},\tag{A14}$$

where we have defined a diagonal matrix,

$$\mathbf{D} = \begin{bmatrix} \varepsilon_+ & 0 \\ 0 & \varepsilon_- \end{bmatrix}. \tag{A15}$$

Multiplying both sides of Eq. (A14) by \mathbf{U}^{\dagger} from the right hand and using the unitary, Eq. (A12), we obtain

$$A = UDU^{\dagger}$$
. Eigendecomposition (A16)

or more explicitly

$$\begin{bmatrix} a & b \\ b^* & a \end{bmatrix} = \frac{1}{\sqrt{2}|b|} \begin{bmatrix} b & b \\ |b| & -|b| \end{bmatrix} \begin{bmatrix} a+|b| & 0 \\ 0 & a-|b| \end{bmatrix} \frac{1}{\sqrt{2}|b|} \begin{bmatrix} b^* & |b| \\ b^* & -|b| \end{bmatrix}. \tag{A17}$$

(Example) Pauli X matrix, i.e., a = 0 and b = 1

$$\mathbf{X} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = \mathbf{HZH}.$$
 (A18)

where **H** and **Z** are matrix representations of Hadamard and Pauli Z gates.

Appendix B: Setting an Environment

Use a Python notebook environment such as qBraid Lab (https://account.qbraid.com/) and open a new Python notebook. Type the following command in the code cell to set up an environment.

pip install qiskit qiskit ibm runtime qiskit aer matplotlib pylatexenc

In qBraid, you can add a predefined Qiskit environment and open a new Python [Qiskit] notebook. In this way, you can skip the above command.