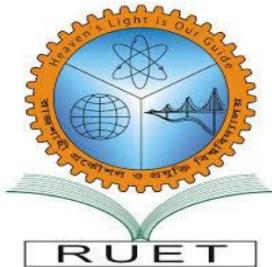


Heaven's Light is Our Guide



Rajshahi University of Engineering and Technology

Department of Computer Science and Engineering

Course No: CSE.2202

Course Title: Sessional based on CSE.2201 (Computer Algorithms)

Lab Report No: 03

Lab Report On: Comparison of Marge Sort and Quick Sort Algorithm.

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Title : Finding out the time and space complexity of the Merge Sort approach and comparing it with the performance of Quick Sort algorithm for (i) Best (ii) Average and (iii) Worst cases.

Introduction :

(i) Merge sort is an algorithm based on divide and conquer strategy. In this, the elements are split into two sub-array ($n/2$) again and again until only one element is left. It uses additional storage for sorting auxiliary array. In this ~~element~~ three arrays were used, two of them are for sending each half and third one for storing the the two half and merge these.

Finally the all sub array are merged in ' n ' element size of the array.

The best, average and worst cases ~~is~~ complexity is $O(n \log n)$ and additional ' n ' space is required

② Quick sort is an algorithm based on divide and conquer strategy. In this the array of elements is divided into parts repeatedly until to it is not possible to divide further. It uses a key element or pivot for partitioning the elements. One left partition contains all the elements that are smaller than pivot and one right partition contains all the elements that are greater than pivot.

The best and average case complexity is $O(n \log n)$ and the worst case complexity is $O(n^2)$.

Algorithm:

① For Merge Sort:

```
i) Mergesort (low, high) {  
    if (low < high) {  
        mid :=  $\lfloor (\text{low} + \text{high})/2 \rfloor$ ;  
        Mergesort (low, mid);  
        Mergesort (mid+1, high);  
        Merge (low, mid, high);  
    }  
}
```

⑩ Merge (low, mid, high) {

$h := \text{low}$; $i := \text{low}$; $j := \text{high}$;

 while (($h \leq \text{mid}$) and ($j \leq \text{high}$)) do {

 if ($a[h] \leq a[j]$) then {

$b[i] := a[h]$; $h := h + 1$;

 }
 else {

$b[i] := a[j]$; $j := j + 1$;

 }

~~else~~ $i := i + 1$;

}

 if ($h > \text{mid}$) then

 for $k := j$ to high do {

$b[i] := a[k]$; $i := i + 1$;

}

 else

 for $k := h$ to mid do {

$b[i] := a[k]$; $i := i + 1$;

}

 for $k := \text{low}$ to high do $a[k] := b[k]$;

}

⑩ For Quick Sort:

```

① Quicksort (left, right) {
    if (left < right) {
        j := Partition (left, right+1);
        Quicksort (left, j-1);
        Quicksort (j+1, right);
    }
}

```

② Partition (m, p) {

$v := a[m]; i := m; j := p;$

repeat {

repeat {

$i := i + 1;$ }

until ($a[i] \geq v$);

repeat {

$j := j - 1;$ }

until ($a[j] \leq v$);

if ($i < j$) then $t := a[i]; a[i] := a[j]; a[j] := t;$

} until ($i \geq j$)

$a[m] := a[j]; a[j] := v;$

return $j;$

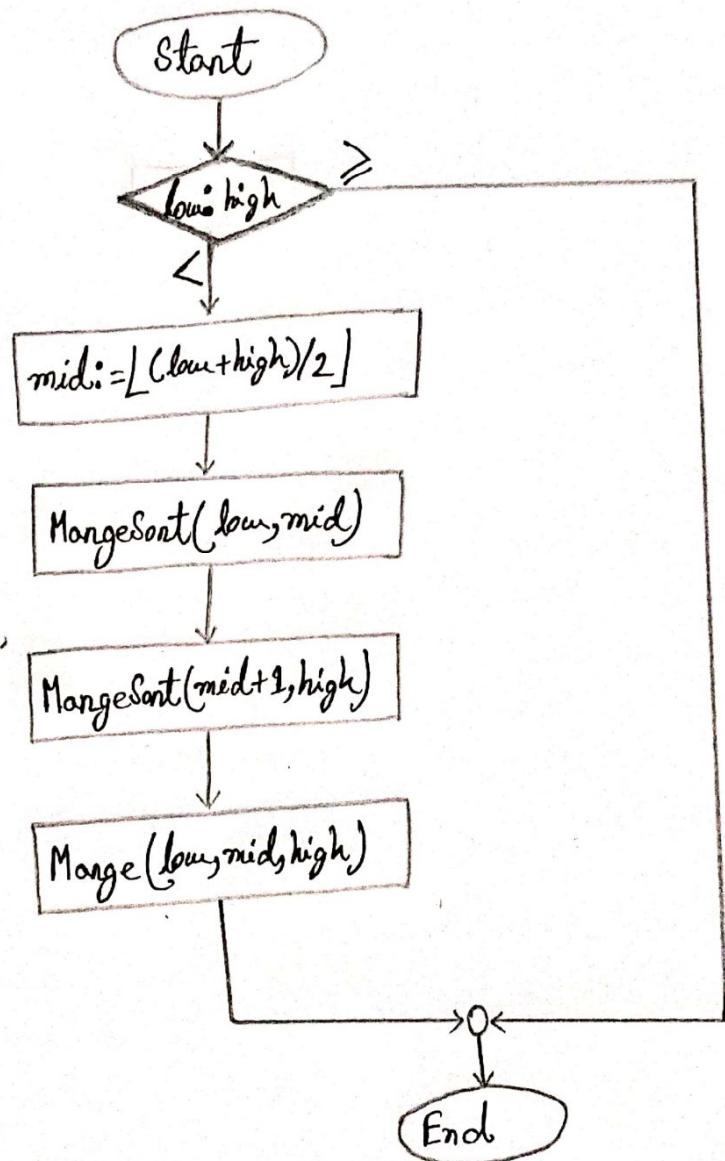
}

Flow Chart :

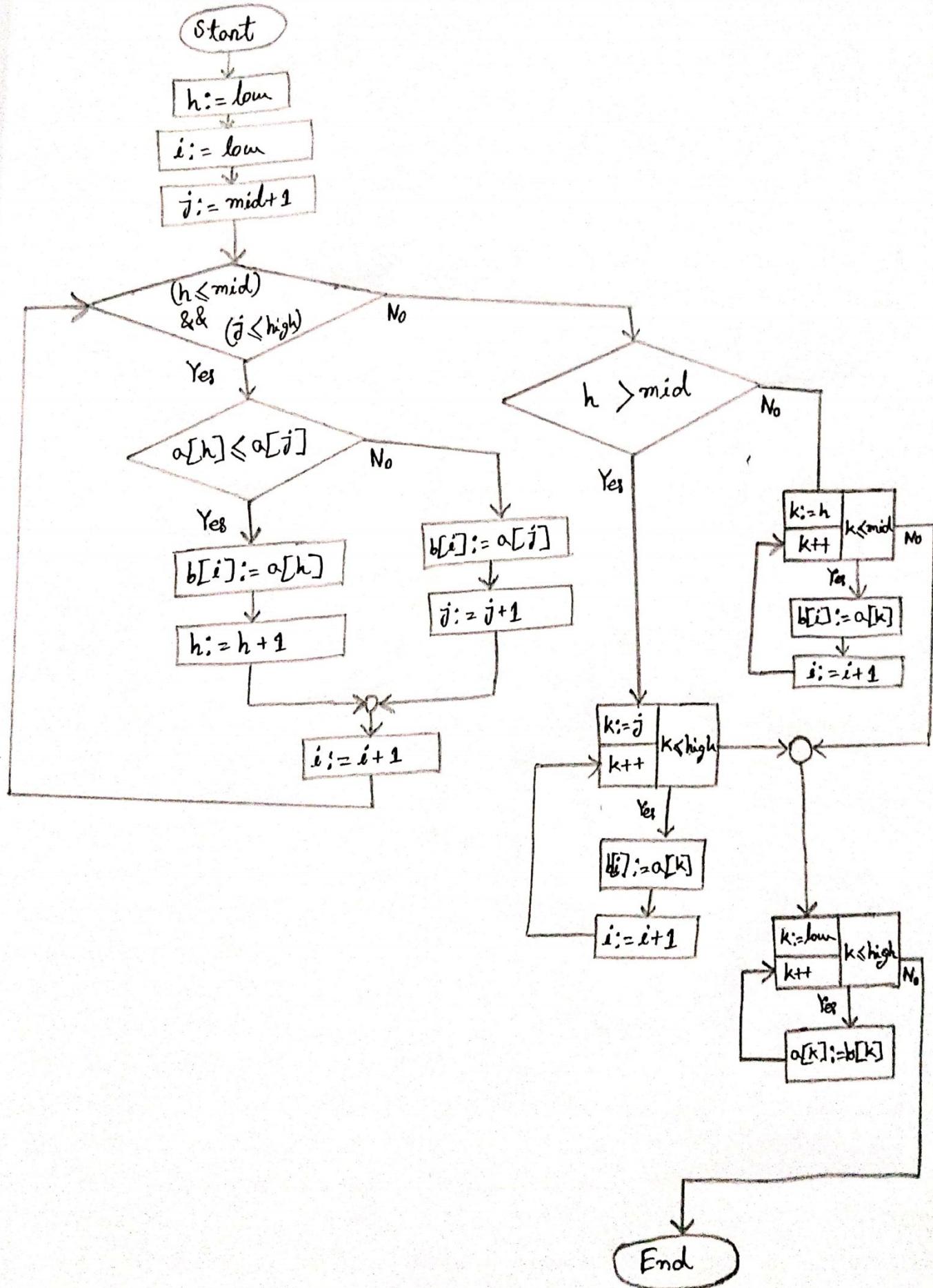
① for Merge Sort:

i)

Merge Sort

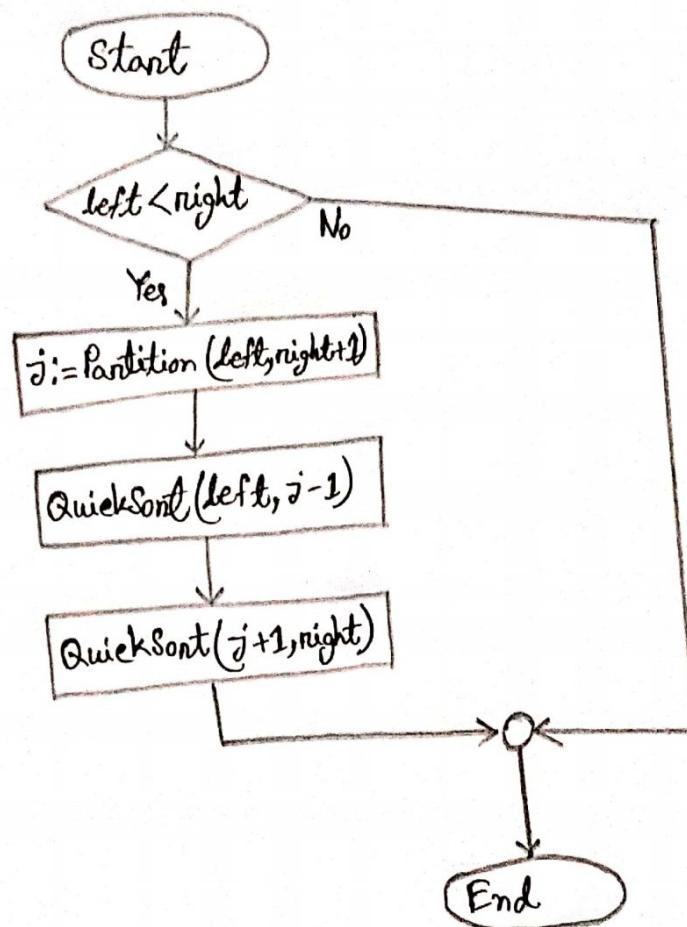


(ii) Mange

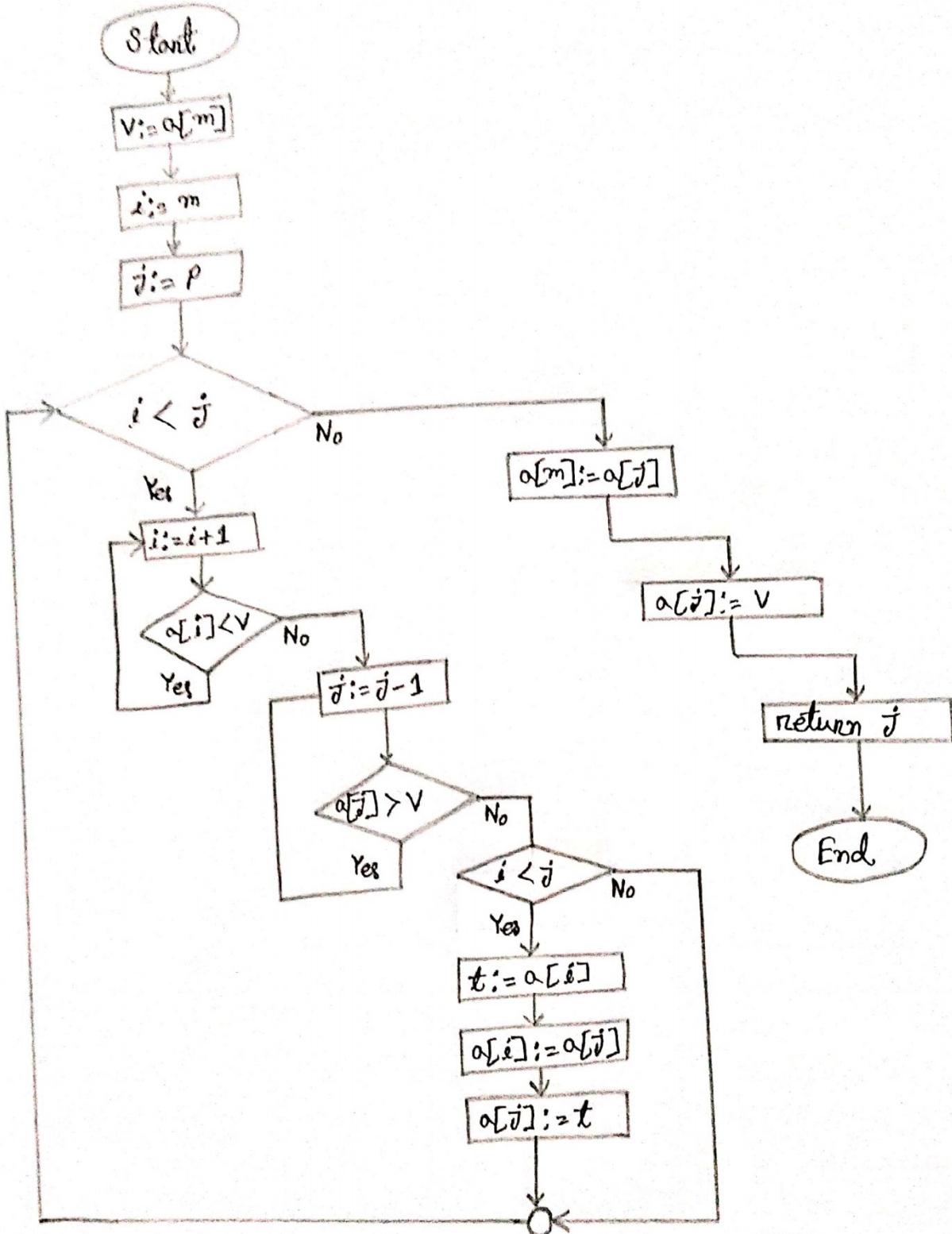


(11) For Quick Sort:

i) QuickSort



⑩ Partition :

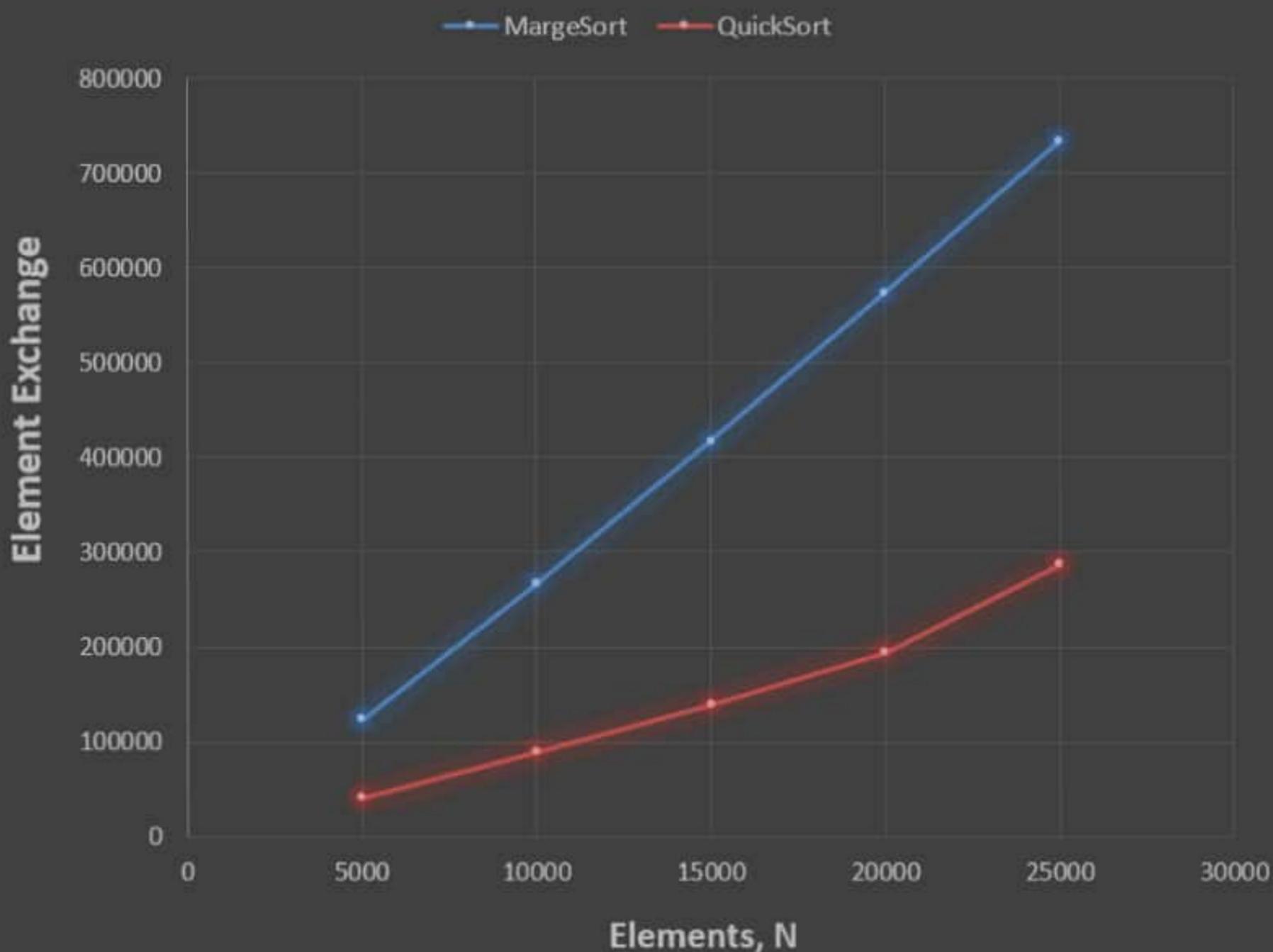


Output :

<u>n</u>	Merge Sort		Quick Sort	
5000	Exchange	123616	Exchange	40877
	Time	2993 μ s	Time	995 μ s
	Space(II)	10000 bytes	Space(II)	5000 bytes
10000	Exchange	267292	Exchange	89425
	Time	2992 μ s	Time	2026 μ s
	Space(II)	20000 bytes	Space(II)	10000 bytes
15000	Exchange	417232	Exchange	139649
	Time	5552 μ s	Time	2991 μ s
	Space(II)	30000 bytes	Space(II)	15000 bytes
20000	Exchange	574964	Exchange	194030
	Time	7000 μ s	Time	1093989 μ s
	Space(II)	40000 bytes	Space(II)	20000 bytes
25000	Exchange	734464	Exchange	287842
	Time	8041 μ s	Time	5068 μ s
	Space(II)	50000 bytes	Space(II)	25000 bytes

Graph :

Exchange vs N Graph



Conclusion: From the sample output and graph we can see that the number of steps in merge sort is required more than the number of steps in quick sort.

And the required time is greater in merge sort than quick sort.

We have used array to store data. The merge sort may have worked faster in linked list.