



# WrightEagle 2D

Multi-Agent Systems Lab.

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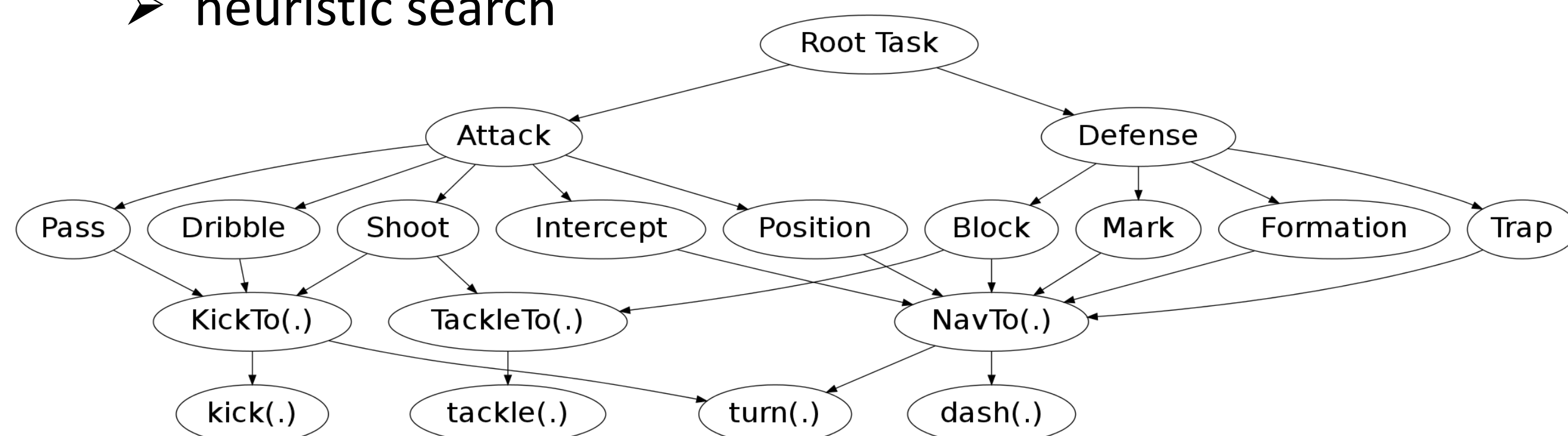
## Introduction

We are the WrightEagle 2D soccer simulation team, a branch of WrightEagle RoboCup team of USTC. We have participated in annual competitions of RoboCup since 1999 and have got 3 champions and 5 runners-up in the recent 8 years. We take RoboCup 2D soccer simulation as a typical problem of planning and learning in multi-agent systems. The key challenges of RoboCup 2D lie in the fact that it is a fully distributed, multi-agent stochastic domain with continuous state, action and observation space. Our research work mainly focus on addressing such challenges in a principled way.

## Key Techniques

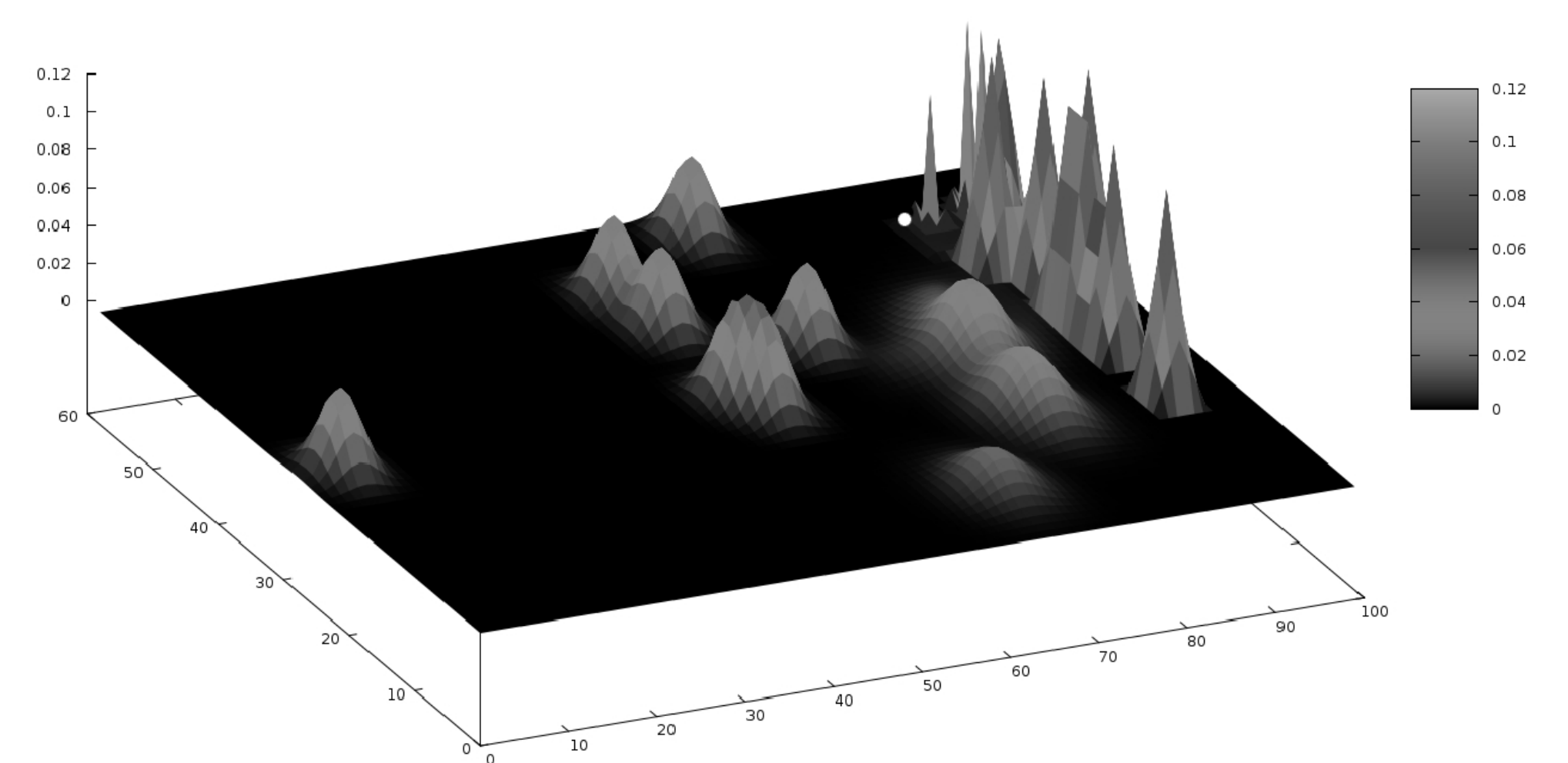
### ➤ Fundamental Decision-Making Architecture

- domain knowledge based behavior hierarchy
- MAXQ-OP based online planning method
  - RoboCup 2D modeled as an MDP
  - hierarchical decomposition
  - heuristic search



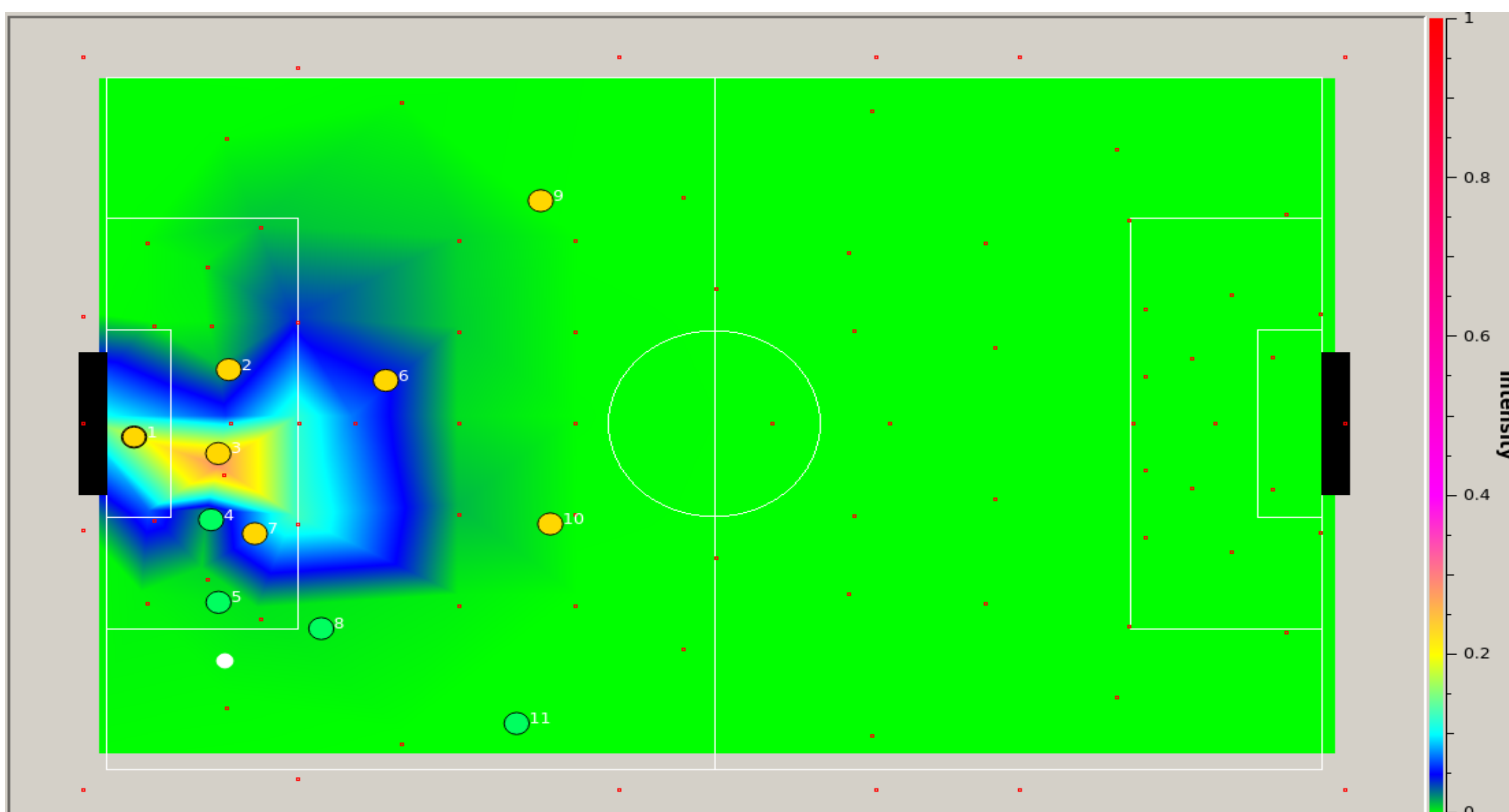
### ➤ Belief State

- position distributions of all players and ball
- updated by Monte Carlo methods



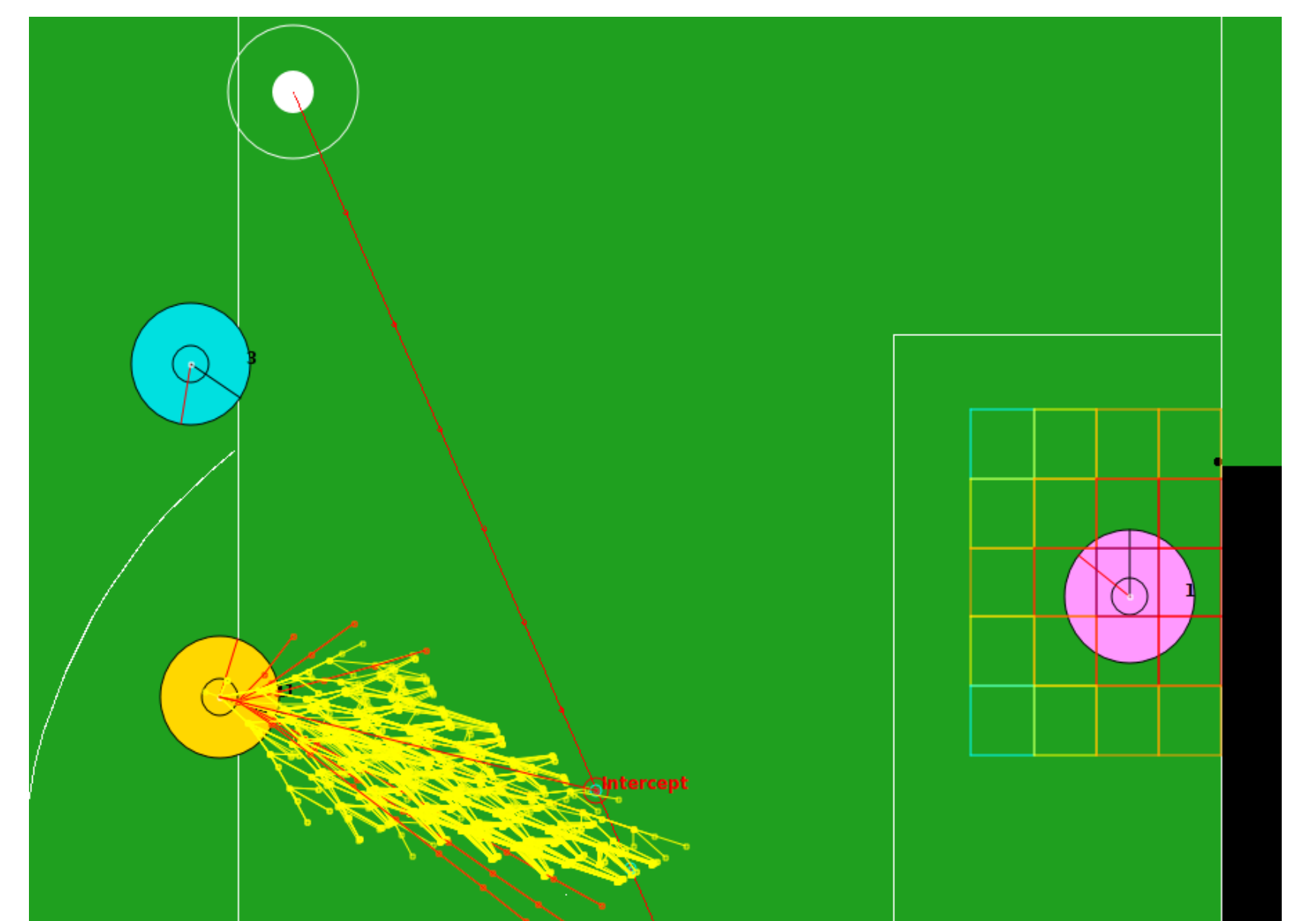
### ➤ Zonal Defense System

- ensure the safety of a region rather than just defend an opponent
- defensive zone: area where a player often appears during defending
- represented as probability distributions over positions
- obtained by statistical methods both online and offline



### ➤ Intention-aware Motion Planning

- modeled as POMDPs
- opponent model defined as intentions
- probability distribution over intentions
- updated using Bayes' theorem
- sampling of intentions
- heuristic search



## Publications

- [1] Aijun Bai, Feng Wu, and Xiaoping Chen. Towards a Principled Solution to Simulated Robot Soccer. RoboCup-2012: Robot Soccer World Cup XVI, Lecture Notes in Artificial Intelligence, Vol. 7500, Springer Verlag, Berlin, 2013.
- [2] Aijun Bai, Feng Wu, and Xiaoping Chen. Online Planning for Large MDPs with MAXQ Decomposition. Proceedings of the 11<sup>th</sup> International Conference on Autonomous Agents and Multiagent Systems (AAMAS 2012), Valencia, Spain, June 2012.
- [3] Aijun Bai, Xiaoping Chen, Patrick MacAlpine, Daniel Urieli, Samuel Barrett, and Peter Stone. WrightEagle and UT Austin Villa: RoboCup 2011 Simulation League Champions. RoboCup-2011: Robot Soccer World Cup XV, Lecture Notes in Artificial Intelligence, Vol. 7416, Springer Verlag, Berlin, 2012.
- [4] Feng Wu and Xiaoping Chen. Solving Large-Scale and Sparse-Reward DEC-POMDPs with Correlation-MDPs. RoboCup-2007: Robot Soccer World Cup XI, Lecture Notes in Artificial Intelligence, Vol. 5001, Springer Verlag, Berlin, 2008.
- [5] Changjie Fan and Xiaoping Chen. Bounded Incremental Real-Time Dynamic Programming. IEEE Proceedings of Frontiers in the Convergence of Bioscience and Information Technologies, Jeju Island, Korea, 2007.