

KEYPOINT SUMMARY

Note: This summary is neither exhaustive nor formal. It is meant to give the intuition behind the mathematical concepts, and extract core idea for essential proofs.

I. CARDINALITY

1. A is a set, \overline{A} denote the cardinality of A .
 - $\overline{A} = \overline{B}$ if there exists a bijection $A \sim B$.
 - $\overline{A} \leq \overline{B}$ if there exists an injection $A \hookrightarrow B$.
 - $\overline{\emptyset} = 0$, $\overline{\{1, 2, \dots, n\}} = n$, $\overline{\mathbb{N}} = d$, $\overline{\mathbb{R}} = c$.
2. Schröder-Bernstein Theorem:
 - $A \hookrightarrow B$, $B \hookrightarrow A \Rightarrow A \sim B$
 - $\overline{A} \leq \overline{B}$, $\overline{B} \leq \overline{A} \Rightarrow \overline{A} = \overline{B}$
3. A is finite/denumerable/countable:

$$\left. \begin{array}{l} A \sim \emptyset \\ A \sim \{1, 2, \dots, n\} \\ A \sim \mathbb{N} \end{array} \right\} \begin{array}{l} \text{finite} \\ \\ \text{denumerable} \end{array} \left. \vphantom{\begin{array}{l} A \sim \emptyset \\ A \sim \{1, 2, \dots, n\} \\ A \sim \mathbb{N} \end{array}} \right\} \text{countable}$$

Otherwise, A is uncountable.

4. Important results on cardinality of sets:
 - $\mathbb{N}^k \sim \mathbb{N}$
Proof. Consider $f(n_1, \dots, n_k) = p_1^{n_1} \cdots p_k^{n_k}$.
 - $\mathbb{N}^{\mathbb{N}} \sim \mathbb{R}$
Proof. Code $\mathbb{N}^{\mathbb{N}}$ into binary strings and show it is uncountable. Consider $f(n_1, n_2, \dots) = \frac{1}{10^{n_1}} + \frac{1}{10^{n_1+n_2}} + \dots$.
 - $\mathcal{P}(\mathbb{N}) \sim \mathbb{R}$
Proof. $\mathcal{P}(\mathbb{N}) \rightarrow \mathbb{R}: (n_1, n_2, n_3, \dots) \rightarrow 0.b_1b_2b_3\dots$
 $\mathbb{R} \rightarrow \mathcal{P}(\mathbb{Q}): \{a \in \mathbb{Q} : a < x, x \in \mathbb{R}\}$.
 - $\mathbb{R} \times \mathbb{R} \sim \mathbb{R}$, $\mathbb{R}^k \sim \mathbb{R}$
Proof. $(0.a_1a_2\dots, 0.b_1b_2\dots) \rightarrow (0.a_1b_1a_2b_2\dots)$.
 - The set of all real valued functions on $[0, 1] \sim 2^c$
Proof. Note $A \hookrightarrow \mathcal{P}([0, 1] \times \mathbb{R})$.
 - A is any set, $\overline{A} < \overline{\mathcal{P}(A)}$.
Proof. Clearly there exists $f : A \hookrightarrow \mathcal{P}(A)$. But f cannot be surjective. Consider $X = \{a \in A : a \notin f(a)\}$.
 - The union of a countable family of countable sets is countable.
 - The union of a cardinality c family of sets each with cardinality c has cardinality c .
Proof. Consider $\{A_\alpha\}_{\alpha \in S}$. There exists a bijection $f_\alpha : A_\alpha \hookrightarrow \mathbb{R}$. Define $f : A \hookrightarrow S \times \mathbb{R}$ as $f(x) = (\alpha, f_\alpha(x))$ where $x \in A_\alpha$.

II. VECTOR SPACES

1. A vector space (linear space) over \mathbb{R} is a set V with two operations addition and scalar multiplication such that
 - (a) $u + v = v + u$
 - (b) $(u + v) + w = u + (v + w)$
 - (c) $\exists 0 \in V, 0 + v = v$
 - (d) $(\alpha + \beta)u = \alpha u + \beta u$
 $\alpha(u + v) = \alpha u + \alpha v$
 - (e) $(\alpha\beta)u = \alpha(\beta u)$
 - (f) $1u = u$
 where $u, v, w \in V$ and $\alpha, \beta \in \mathbb{R}$.
 - A vector space is a space closed under addition and scalar multiplication, i.e. it is a space that allows linear operations.
 - A set of vectors $\{v_1, v_2, \dots, v_n\}$ in V is called linearly independent if $a_1v_1 + a_2v_2 + \dots + a_nv_n = 0 \Rightarrow a_1 = a_2 = \dots = a_n = 0$.
2. A normed vector space is a vector space V over \mathbb{R} with a function $\|\cdot\| : V \rightarrow \mathbb{R}$ such that
 - (a) $\|u\| \geq 0$, $\|u\| = 0$ iff $u = 0$
 - (b) $\|\alpha u\| = |\alpha| \|u\|$
 - (c) $\|u + v\| \leq \|u\| + \|v\|$
 - A normed vector space is a vector space where the length of vectors can be measured.
 - Euclidean norm: $\|x\| = \sqrt{x_1^2 + \dots + x_n^2}$
 - Infinity norm: $\|x\|_\infty = \max_{1 \leq i \leq n} |x_i|$
 - p -norm: $\|x\|_p = (|x_1|^p + \dots + |x_n|^p)^{\frac{1}{p}}$
Proof. Minkowski's inequality:
 $(\sum_k^n |x_k + y_k|^p)^{\frac{1}{p}} \leq (\sum_k^n |x_k|^p)^{\frac{1}{p}} + (\sum_k^n |y_k|^p)^{\frac{1}{p}}$
 - If $1 \leq p \leq q \leq \infty$, then $\|x\|_p \geq \|x\|_q$.
Proof. Normalize x to $\frac{x}{\|x\|_p}$ so that $\|x\|_p = 1$. Then it is easy to see $\|x\|_q \leq 1$ because for each element $|x_i|^q \leq |x_i|^p$.
3. An inner product space is a vector space V over \mathbb{R} with a function $\cdot : V \times V \rightarrow \mathbb{R}$ such that
 - (a) $u \cdot u \geq 0$, $u \cdot u = 0$ iff $u = 0$
 - (b) $u \cdot v = v \cdot u$
 - (c) $(u + v) \cdot w = u \cdot w + v \cdot w$
 - (d) $(\alpha u) \cdot v = \alpha(u \cdot v)$
 - Angle θ between u, v : $u \cdot v = \cos \theta \|u\| \|v\|$.
 - u, v are orthogonal if $u \cdot v = 0$.
 - Every inner product space is a normed space if define $\|u\| = (u \cdot u)^{\frac{1}{2}}$ as the norm.
 - Cauchy-Schwarz Inequality: $|u \cdot v| \leq \|u\| \|v\|$
Proof. $f(\lambda) = (u - \lambda v) \cdot (u - \lambda v) \geq 0, \forall \lambda$.
 Substitute in $\lambda = \frac{u \cdot v}{\|v\|^2}$.

III. METRIC SPACES

- A metric space (X, d) is a set X together with a function $d : X \times X \rightarrow \mathbb{R}$ such that
 - $d(x, y) \geq 0$, $d = 0$ iff $x = y$
 - $d(y, x) = d(x, y)$
 - $d(x, y) \leq d(x, z) + d(z, y)$
 - A metric space is a set for which distances between all members of the set are defined.
 - Any normed space $(V, \|\cdot\|)$ is a metric space.
- Suppose (X, d) is a metric space, and $S \subset X$. (S, d_S) is a metric subspace if we define $d_S(x, y) = d(x, y)$ for $x, y \in S$.
 - $\forall a \in S, B_r^S(a) = S \cap B_r^X(a)$
 - A is open in $S \Leftrightarrow A = S \cap U$, U is open in X ;
 A is closed in $S \Leftrightarrow A = S \cap C$, C is closed in X .
Proof. A open in $S \Rightarrow A = \cup_{x \in A} B_{r_x}^S(x) = \cup_{x \in A} (S \cap B_{r_x}(x)) = S \cap (\cup_{x \in A} B_{r_x}(x))$. Thus $U = \cup_{x \in A} B_{r_x}(x)$.
- Limit and Isolated Points
 - x is a limit point in A if every $B_r(x)$ contains points of A other than x .
 - x is a limit point iff $\exists (x_n) \subset A$ and $x_n \rightarrow x$.
 - x is a isolated point if $\exists r$ such that $B_r(x) \cap A = \{x\}$.
- Interior, Exterior and Boundary
 - $x \in \text{int } A$ if $\exists r(B_r(x) \subset A)$
 - $x \in \text{ext } A$ if $\exists r(B_r(x) \subset A^C)$
 - $\text{ext } A = \text{int } A^C$, $\text{int } A = \text{ext } A^C$
 - $x \in \partial A$ (boundary of A) if any $B_r(x)$ contains both points of A and points of A^C .
 - $X = \text{int } A \cup \text{ext } A \cup \partial A$
- Open Sets
 - A is open if $A = \text{int } A$.
 - A is open $\Rightarrow A = \cup_{x \in A} B_{r_x}(x)$
 - If A_i are open, $\cap_{i=1}^k A_i$ is open;
 If A_i are open, $\cup_{i \in I} A_i$ is open.
 - $\text{int } A$ is open; $\text{ext } A$ is open.
- Closed Sets
 - A is closed if A^C is open.
 - A is closed iff $\overline{A} = A$.
 - A is closed iff A contains all its limit points.
 - $A \subset \mathbb{R}^k$ is closed iff A is complete.
 - If B_i are closed, $\cup_{i=1}^k B_i$ is closed;
 If B_i are closed, $\cap_{i \in I} B_i$ is closed.
 - Closure of a set is closed.
 - Closed does *not* imply bounded.
- Closure
 - $\overline{A} = A \cup \{\text{limit point of } A\}$
 - $\overline{A} = \text{int } A \cup \partial A$
 - $\overline{A} = A \cup \partial A$
 - $\overline{A} = (\text{ext } A)^C$
 - $x \in \overline{A}$ iff every $B_r(x)$ contains a point of A .
 - $x \in \overline{A}$ iff there exists $(x_n) \subset A$ with $x_n \rightarrow x$.

IV. SEQUENCES AND CONVERGENCE

- (x_n) converges to x if $\forall \epsilon, \exists N, [\forall n > N \Rightarrow d(x, x_n) < \epsilon]$.
- (x_n) is Cauchy if $\forall \epsilon, \exists N, [\forall m, n > N \Rightarrow d(x_m, x_n) < \epsilon]$.
 - Every convergent/Cauchy sequence is bounded.
Proof. convergence $\Rightarrow (x_n)$ is bounded after some N , left only finite elements.
 - \mathbb{R}^k : sequence (x_n) converges $\Leftrightarrow (x_n)$ is Cauchy.
 - X : sequence (x_n) converges $\not\Leftrightarrow (x_n)$ is Cauchy.
- A metric space is complete if every Cauchy sequence converges in itself.
 - $S \subset \mathbb{R}^k$ is complete *iff* it is closed.
- Monotone Convergence Theorem: if a sequence is increasing (decreasing) and bounded by a supremum (infimum), it will converge to the supremum (infimum).
Proof. Let $c = \sup_n \{a_n\}$. $\forall \epsilon > 0, \exists N$ s.t. $c - \epsilon < a_N \leq a_n \leq c, \forall n > N$. As $\epsilon \rightarrow 0, a_n \rightarrow c$.
- Banach Fixed-Point Theorem: If (X, d) is a *complete* metric space, and $f : X \rightarrow X$ is a *contraction*, i.e. $\exists \lambda \in [0, 1)$ such that $d(f(x), f(y)) \leq \lambda d(x, y)$, then there exists a unique fixed point $f(x) = x$.
Proof. First show (x_n) is Cauchy, then prove $d(x, f(x)) \rightarrow 0$.

V. SEQUENCES AND COMPACTNESS

- Bolzano-Weierstrass Theorem: Every bounded sequence in \mathbb{R}^k has a convergent subsequence.
Proof. Geometric intuition: if a sequence in \mathbb{R}^k is bounded, we can always trap it in a whatever small subspace. Construct a convergent subsequence by trapping it a smaller and smaller subspace.
- A metric space is (sequentially) compact if every sequence has a convergent subsequence.
 - \mathbb{R}^k : compact \Leftrightarrow closed, bounded (Heine-Borel Thm)
 - X : compact $\not\Leftrightarrow$ closed, bounded.
Proof. Consider $X = C[0, 1]$. $\overline{B_1(\mathbf{0})} \subset X$ is closed and bounded, but *not* compact.
 - Compactness is sort of a topological generalization of finiteness. For example, if a set A is finite then every function $f : A \rightarrow \mathbb{R}$ is bounded and has max/min. If A is compact, the every *continuous* function $f : A \rightarrow \mathbb{R}$ is bounded and has max/min.

VI. LIMITS AND CONTINUITY

- Let $f : X \rightarrow Y$. The following are equivalent:
 - $\lim_{x \rightarrow a} f(x) = b$;
 - $x_n \rightarrow a \Rightarrow f(x_n) \rightarrow b$;
 - $x \in B_\delta^X(a) \setminus \{a\} \Rightarrow f(x) \in B_\epsilon^Y(b)$.

Proof. (ii) \Rightarrow (iii): Suppose the opposite. Let $x_n \in B_{1/n}^X(a)$, then $x_n \rightarrow a$ and $f(x_n) \rightarrow b$, but by assumption $\exists \epsilon$ s.t. $f(x_n) \notin B_\epsilon^Y(b)$. contradiction. (iii) \Rightarrow (ii): Suppose $x_n \rightarrow a$. (iii) $\Rightarrow \forall \epsilon \exists \delta \exists x_n \in B_\delta^X(a) \Rightarrow f(x_n) \in B_\epsilon^Y(b) \Rightarrow f(x_n) \rightarrow b$.

2. $f : X \rightarrow Y$ is continuous at $a \in X$ if a is an isolated point, or $\lim_{x \rightarrow a} f(x) = f(a)$.

- Every function is continuous at isolated points.
- Intuitively, a continuous function is a function for which sufficiently small changes in the input result in arbitrarily small changes in the output.

3. Quantitative Measures of Continuity

- $f : X \rightarrow Y$ is Lipschitz continuous if there exists a constant M such that $d_Y(f(x_1), f(x_2)) \leq M d_X(x_1, x_2)$. M is called the Lipschitz constant.
 - If $f : (a, b) \rightarrow \mathbb{R}$ is differentiable and f is bounded then f is Lipschitz continuous. This follows from the mean value theorem: if $|f(\xi)| \leq L$ for all $\xi \in (a, b)$ then $|f(x) - f(y)| \leq |f(\xi)| |x - y| \leq L |x - y|$ for all $x, y \in (a, b)$.
 - If f is Lipschitz continuous and differentiable at x then $f'(x)$ is bounded by the Lipschitz constant.
- $f : X \rightarrow Y$ is Hölder continuous with exponent $\alpha \in (0, 1]$ if there exists a constant M such that $d_Y(f(x_1), f(x_2)) \leq M [d_X(x_1, x_2)]^\alpha$.

4. Continuity and Compactness: $f : X \rightarrow Y$ is continuous, if $K \subset X$ is compact, then $f(K)$ is compact in Y .

Proof. $\forall (y_n) \subset f(K), \exists (x_n) : f(x_n) = y_n$. K compact $\Rightarrow \exists (x_{n_j}) \rightarrow x$; f continuous $\Rightarrow f(x_{n_j}) \rightarrow f(x) \Rightarrow y_{n_j} \rightarrow f(x)$.

Cor. Continuous function on a compact set is bounded.

5. Extreme Value Theorem: Each continuous function on a compact set attains its maximum and minimum.

Proof. K compact $\Rightarrow f(K)$ compact $\Rightarrow f(K)$ closed and bounded \Rightarrow exist least upper bound γ and $\gamma \in f(K)$ (take a sequence approaching γ and extract its convergent subsequence). Therefore, $\exists x_0 \in K$ s.t. $\gamma = f(x_0)$.

6. Continuity and Open Sets: The following statements are equivalent:

- $f : X \rightarrow Y$ is continuous on X ;
- $f^{-1}(E)$ is open whenever E is an open set in Y ;
- $f^{-1}(E)$ is closed whenever E is a closed set in Y .

Proof. f continuous $\Rightarrow \forall \epsilon \exists \delta f(B_\delta(x)) \subset B_\epsilon(f(x)) \subset E \Rightarrow B_\delta(x) \subset f^{-1}(E)$. On the other hand, $f^{-1}(B_\epsilon(f(x)))$ is an open set $\Rightarrow \exists B_\delta(x) \subset f^{-1}(B_\epsilon(f(x))) \Rightarrow f(B_\delta(x)) \subset B_\epsilon(f(x)) \Rightarrow f$ is continuous.

Note. Continuous functions do *not* necessarily map open sets to open sets, or closed sets to closed sets.

Cor. If $f : X \rightarrow \mathbb{R}$ is continuous, $\{x : f(x) < 0\}$ is open.

7. The function $f : X \rightarrow Y$ is uniformly continuous if for each $\epsilon > 0$ there exists $\delta > 0$ such that $d(x, x') < \delta \Rightarrow d(f(x), f(x')) < \epsilon$, for all $x, x' \in X$.

- In general continuity, δ depends on both ϵ and x .
- In uniform continuity, δ depends only on ϵ , not on x .
- If f is continuous and X is *compact*, then f is uniformly continuous.

- A continuous real-valued functions defined on closed and bounded subset of \mathbb{R}^n is uniformly continuous.
- If f is Lipschitz continuous then it is uniformly continuous. The converse is not true, for example, $f(x) = \sqrt{|x|}$ is uniformly continuous but not Lipschitz.

8. Uniform continuity and Cauchy sequences: If $f : X \rightarrow Y$ is uniformly continuous, then (x_n) is Cauchy in $X \Rightarrow (f(x_n))$ is Cauchy in Y . If f is only continuous, $(f(x_n))$ may not converge (consider $f(x) = \frac{1}{x}$ on $(0, \infty)$).
9. Continuous Extension Theorem: If $f : A \rightarrow Y$ is uniformly continuous, then f can be uniquely extended to \bar{A} maintaining the uniform continuity. $\bar{f}(x)$ on the boundary of A can be unambiguously defined by $\lim_{n \rightarrow \infty} f(x_n)$ for $x \in \partial A$ with $(x_n) \subset A$ and $x_n \rightarrow x$.

VII. CONVERGENCE OF FUNCTIONS

1. Let S be a set and (Y, ρ) a metric space. A sequence of functions $f_n : S \rightarrow Y$ converges to a function $f : S \rightarrow Y$ pointwise if for each $x \in S$ and any $\epsilon > 0$, $\exists N \in \mathbb{N}$ such that $n > N \Rightarrow \rho(f_n(x), f(x)) < \epsilon$. (Note: N depends on both x and ϵ)
2. A sequence $f_n : S \rightarrow Y$ converge uniformly to a function $f : S \rightarrow Y$ if $\forall \epsilon > 0$, $\exists N \in \mathbb{N}$ such that $n > N \Rightarrow \rho(f_n(x), f(x)) < \epsilon, \forall x \in S$. (Note: convergence is uniform with respect to x . N depends only on ϵ , not on x)

- Uniform convergence $\not\Rightarrow$ Pointwise convergence
- (f_n) converging to f uniformly is equivalent to $f_n \rightarrow f$ in uniform metric: $d_u(f_n, f) = \sup_{x \in S} \rho(f_n(x), f(x))$.

3. A sequence (f_n) is uniformly Cauchy if $\forall \epsilon > 0$, $\exists N \in \mathbb{N}$, such that $m, n > N \Rightarrow \rho(f_m(x), f_n(x)) < \epsilon, \forall x \in S$.

- (f_n) is uniformly Cauchy if and only if it is Cauchy in uniform metric.

4. Theorem: Let $\mathcal{F} = \{f : S \rightarrow Y\}$. If (Y, ρ) is complete, then every Cauchy sequence $(f_n) \subset \mathcal{F}$ converges uniformly to some $f \in \mathcal{F}$, i.e. \mathcal{F} is complete.

Proof. Let (f_n) be Cauchy $\Rightarrow \sup |f_m(x) - f_n(x)| < \epsilon \Rightarrow |f_m(x) - f_n(x)| < \epsilon, \forall x \Rightarrow \forall x, (f_n(x))$ is Cauchy in Y . Y is complete $\Rightarrow f_n(x) \rightarrow f(x) \in Y$. $\rho(f_m(x), f(x)) \leq \rho(f_m(x), f_n(x)) + \rho(f_n(x), f(x))$. Let $n \rightarrow \infty$, we have $\rho(f_m(x), f(x)) \leq \epsilon, \forall x$. i.e. $f_m \rightarrow f$ uniformly.

5. Theorem: Suppose (f_n) is a sequence of continuous functions from X to Y . Suppose $f_n \rightarrow f$ uniformly. Then f is also continuous (uniform limits of continuous functions are continuous).

Proof. $f_n \rightarrow f$ uniformly $\Rightarrow \rho(f_n(x), f(x)) < \epsilon$. f_n continuous $\Rightarrow d(x, x_0) < \delta \Rightarrow \rho(f_n(x), f_n(x_0)) < \epsilon$. $\rho(f(x), f(x_0)) \leq \rho(f(x), f_n(x)) + \rho(f_n(x), f_n(x_0)) + \rho(f_n(x_0), f(x_0)) < 3\epsilon$. Therefore f is continuous at x_0 .

6. Corollary: Let $C_b(X, Y)$ be the set of continuous and bounded functions from X to Y . If (Y, ρ) is complete, then $C_b(X, Y)$ is a complete metric space when equipped with the uniform metric.

7. Suppose $f_n \rightarrow f$ uniformly, then

- $\int_a^b f_n(x) dx \rightarrow \int_a^b f(x) dx$ uniformly;
- $\int_a^x f_n(t) dt \rightarrow \int_a^x f(t) dt$ uniformly;

- $\lim_{n \rightarrow \infty} \int_a^b f_n(x) dx = \int_a^b \lim_{n \rightarrow \infty} f_n(x) dx$;
- The limit of differentiable may not be differentiable.

VIII. COMPACTNESS

1. A metric space (X, d) is sequentially compact if every sequence in X has a convergent subsequence.
2. A space K is compact if every open cover of K ($K \subset \bigcup_{i \in I} U_i$) has a finite subcover ($K \subset \bigcup_{i=1}^N U_i$).
3. If (X, d) is a metric space, $K \subset X$ is compact iff K is sequentially compact. This is not true in general topological space.
4. Consequences of compactness:
 - K compact $\Rightarrow K$ is closed and bounded;
 - In \mathbb{R}^n , K is compact $\Leftrightarrow K$ is closed and bounded;
 - A closed subset of a compact space is compact;
Proof. Let $A \subset X$ be closed. Let $\{U_i\}$ cover A . Then $(\bigcup_i U_i) \cup (X \setminus A)$ is an open cover for X . There exists finite subcover $(\bigcup_{i=1}^N U_i) \cup (X \setminus A)$. Then $\bigcup_{i=1}^N U_i$ is a finite subcover for A .
 - $f : X \rightarrow Y$ being continuous, if $K \subset X$ is compact, then $f(K)$ is compact in Y ;
Proof. Let $\{U_i\}$ cover $f(K)$. Then $f^{-1}(\bigcup U_i) = \bigcup f^{-1}(U_i)$ cover K . K is compact $\Rightarrow \exists$ finite subcover $\bigcup_{i=1}^N f^{-1}(U_i)$. Then $\bigcup_{i=1}^N U_i$ is a finite subcover for $f(K)$.
 - $f : X \rightarrow Y$ being continuous, if $K \subset X$ is compact, then f is uniformly continuous on K ;
Proof. f is continuous $\Rightarrow \forall \epsilon > 0, \forall x \in X, \exists \delta_x > 0$ such that $|x - x'| < \delta_x \Rightarrow |f(x) - f(x')| < \epsilon$. $\bigcup_{x \in X} B(x, \delta_x)$ cover X , X is compact, there exists finite subcover. Let $\delta = \min\{\delta_{x_1}, \dots, \delta_{x_n}\}$. Then there exists a δ independent of x .
 - $f : X \rightarrow Y$ being continuous, if $K \subset X$ is compact, then f achieves its maximum and minimum on K .
5. A set X is totally bounded if for any δ , there exist finitely many points $x_1, \dots, x_N \in X$ such that $X \subset \bigcup_{i=1}^N B_\delta(x_i)$.
 - Totally boundedness $\not\Leftrightarrow$ boundedness.
 - A subset E in \mathbb{R}^n is totally bounded iff E is bounded.
 - A subset of a metric space is totally bounded iff its closure is totally bounded.
6. Theorem: A space X is compact if and only if it is complete and totally bounded.
Proof. (\Rightarrow) $\{B_\delta(x)\}_{x \in X}$ cover $X \Rightarrow$ finite subcover \Rightarrow totally bounded. (\Leftarrow) Let $(x_n) \subset X$. Cover X with finite many balls of radius 1. There must be a subsequence $(x_n^1) \subset (x_n)$ trapped in of one these balls, i.e. $(x_n^1) \subset B_1$. Cover X with finite many balls of radius $\frac{1}{2}$, then $\exists (x_n^2) \subset B_{\frac{1}{2}}$. Keep going, $(x_n^3) \subset B_{\frac{1}{3}}, \dots$. Let $y_k = x_n^k$. Then (y_n) is Cauchy, by completeness, (y_n) is a convergent subsequence of (x_n) .
7. Let $\mathcal{F} \subset C(X, Y)$ (continuous functions from X to Y) \mathcal{F} is uniformly equicontinuous if $\forall \epsilon > 0, \exists \delta > 0$, such that $d(x, x') < \delta \Rightarrow \rho(f(x), f(x')) < \epsilon, \forall x, x' \in X, \forall f \in \mathcal{F}$. (The same δ holds for all $x \in X$ and all $f \in \mathcal{F}$)

- Uniformly continuity is usually shown by showing the family of functions \mathcal{F} is Lipschitz with the same constant for all $f \in \mathcal{F}$; or every f is Holder continuous with the same α and the same Holder constant.

8. Arzela-Ascoli theorem: $\mathcal{F} \subset C(X, \mathbb{R}^n)$ is compact iff X is compact and \mathcal{F} is closed, bounded and uniformly equicontinuous.

Proof.

- Uniform equicontinuous $\Rightarrow d(x, y) < \delta \Rightarrow |f(x) - f(y)| < \epsilon$;
- X totally bounded $\Rightarrow \exists x_1, \dots, x_n, |x - x_i| < \delta$, and this implies $|f(x) - f(x_i)| < \epsilon$;
- $|f(X)| \leq K$ totally bounded $\Rightarrow \exists y_1 \dots y_m, |f(x) - y_i| < \epsilon$;
- Construct discrete function $\alpha : \{x_1 \dots x_n\} \rightarrow \{y_1 \dots y_m\}$ (there are at most m^n such α);
- Find g_α for each α such that $|g_\alpha(x_i) - \alpha(x_i)| < \epsilon$;
- For any $f \in \mathcal{F}$, choose the α such that $|f(x_i) - \alpha(x_i)| < \epsilon$ and the corresponding g_α , then choose x_i such that $|x - x_i| < \delta$, then we have $|f(x) - g_\alpha(x)| \leq |f(x) - f(x_i)| + |f(x_i) - \alpha(x_i)| + |\alpha(x_i) - g_\alpha(x_i)| + |g_\alpha(x_i) - g_\alpha(x)|$;
- So all $f \in \mathcal{F}$ are within the balls of finitely many g_α .

IX. CONNECTEDNESS

1. A space X is connected if there do not exist nonempty open sets U, V such that $U \cap V = \emptyset$ and $X = U \cup V$.
 - Equivalently, X is connected if there do not exist nonempty closed sets U, V such that $U \cap V = \emptyset$ and $X = U \cup V$.
 - X is connected if and only if the only subset of X that are both open and closed are \emptyset and X .
 - If A is connected, then \bar{A} is connected.
 - Let A_1, A_2, \dots be connected, if $A_i \cap A_{i+1} \neq \emptyset$, then $\bigcup_{i=1}^\infty A_i$ is connected.
2. A space X is path connected if $\forall a, b \in X$, there exists a continuous function $f : [0, 1] \rightarrow X$ such that $f(0) = a, f(1) = b$.
 - Path connected \Rightarrow connected. The converse is not true, counter-example: $X = \{(x, y) : y = \sin \frac{1}{x}\} \cup \{(0, y) : -1 \leq y \leq 1\}$ is connected but not path-connected.
3. Connectedness in \mathbb{R}^n :
 - $S \subset \mathbb{R}$ is connected iff it is an interval.
 - $U(\text{open}) \subset \mathbb{R}^n$ is connected iff it is path-connected.
4. Theorem: The continuous image of a connected set is connected.
Proof. Let $f : X \rightarrow Y$ be continuous. Suppose $f(X)$ is not connected. Then $\exists E \subset f(X)$ that is both open and closed. $\exists E', E'' \subset Y$ s.t. $E = E' \cap f(X), E = E'' \cap f(X)$. Then we have $f^{-1}(E) = f^{-1}(E') = f^{-1}(E'') \neq \emptyset$ which is also both open and closed $\Rightarrow X$ is not connected — contradiction.
5. Corollary (Intermediate value theorem) Suppose X is connected, $f : X \rightarrow \mathbb{R}$ is continuous. Let $x, y \in X, f(x) = a, f(y) = b, a < b$. Then for any $c \in (a, b), \exists z \in X$, such that $f(z) = c$.
Proof. $f(X)$ is connected because f is continuous. $f(X) \subset \mathbb{R}$, so it is an interval. It then follows $c \in f(X)$ for any $c \in (a, b)$.

X. APPLICATION: DIFFERENTIAL EQUATIONS

1. Assume U (open) $\subset \mathbb{R} \times \mathbb{R}^n$, and $f : U \rightarrow \mathbb{R}^n$ is continuous. The problem of the form

$$\begin{cases} \frac{d\mathbf{x}}{dt} = f(t, \mathbf{x}) \\ \mathbf{x}(t_0) = \mathbf{x}_0 \end{cases}$$

is called an initial value problem (IVP). A solution to an IVP is a function $\mathbf{x} : I \rightarrow \mathbb{R}^n$ for some open interval I containing (t_0, \mathbf{x}_0) such that \mathbf{x} solves the differential equation and the initial condition.

- Solving the IVP is equivalent to solving the integral equation:

$$\mathbf{x}(t) = t_0 + \int_{t_0}^t f(s, \mathbf{x}(s)) ds$$

2. Peano's existence theorem: Assume f is continuous on $U \subset \mathbb{R} \times \mathbb{R}^n$. Let $(t_0, \mathbf{x}_0) \in U$. Then there exists $h > 0$ such that the IVP has a C^1 solution for $t \in [t_0 - h, t_0 + h]$.

Proof.

- Let $A_{h,k}(t_0, \mathbf{x}_0) = \{(t, \mathbf{x}) : |t - t_0| \leq h, |\mathbf{x} - \mathbf{x}_0| \leq k\}$.
- $A_{h,k}$ is a compact $\Rightarrow f$ is bounded, $|f(t, \mathbf{x})| \leq M$.
- Let $h \leq \frac{k}{M}$.
- Approximate $x(t)$ at t_0 with

$$x_n(t) = \begin{cases} x_0 + (t - t_0)f(t_0, x_0) & \text{for } t \in [t_0, t_0 + \frac{h}{n}] \\ x_n(t_0 + \frac{h}{n}) + (t - (t_0 + \frac{h}{n}))f(t_0 + \frac{h}{n}, x_n(t_0 + \frac{h}{n})) & \text{for } t \in [t_0 + \frac{h}{n}, t_0 + \frac{2h}{n}] \\ \vdots \\ x_n(t_0 + i\frac{h}{n}) + (t - (t_0 + i\frac{h}{n}))f(t_0 + i\frac{h}{n}, x_n(t_0 + i\frac{h}{n})) & \text{for } t \in [t_0 + i\frac{h}{n}, t_0 + (i+1)\frac{h}{n}] \\ \vdots \end{cases}$$

- $|\frac{d}{dt}x_n(t)| = |f(\cdot)| \leq M$, so x_n is Lipschitz on $A_{h,k}$ with constant M .
- (x_n) is a sequence of closed, bounded and uniformly equicontinuous functions. Therefore (x_n) is a compact subset of $C[t_0 - h, t_0 + h]$. There exists (x_{n_j}) such that $x_{n_j} \rightarrow x$.
- x is the solution to the IVP problem.

3. Assume $f : U \subset \mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ is continuous. f is locally Lipschitz with respect to x if for every $A_{h,k}(t_0, \mathbf{x}_0) \subset U$, there exists K such that

$$|f(t, x_1) - f(t, x_2)| \leq K|x_1 - x_2|$$

for all $(t, x_1), (t, x_2) \in A_{h,k}(t_0, \mathbf{x}_0)$.

4. Local uniqueness: Assume f is continuous on $U \subset \mathbb{R} \times \mathbb{R}^n$ and locally Lipschitz with respect to x . Let $(t_0, \mathbf{x}_0) \in U$. Then there exists $h > 0$ such that the IVP has a unique C^1 solution for $t \in [t_0 - h, t_0 + h]$.

Proof.

- Define $A_{h,k}(t_0, \mathbf{x}_0) = \{(t, \mathbf{x}) : |t - t_0| \leq h, |\mathbf{x} - \mathbf{x}_0| \leq k\}$.
- $A_{h,k}$ is a compact $\Rightarrow f$ is bounded, $|f(t, \mathbf{x})| \leq M$.
- f is locally Lipschitz on $A_{h,k}(t_0, \mathbf{x}_0)$, so $\exists K$ s.t. $|f(t, x_1) - f(t, x_2)| \leq K|x_1 - x_2|$, for all $x_1, x_2 \in A_{h,k}$.
- Assume $h \leq \min\{\frac{k}{M}, \frac{1}{2K}\}$.
- Define $C^*[t_0 - h, t_0 + h] = C[t_0 - h, t_0 + h] \cap \{x : |x(t) - x_0| \leq k\}$. $C^*[t_0 - h, t_0 + h]$ can be shown to be a complete space.
- Define $T : C^*[t_0 - h, t_0 + h] \rightarrow C^*[t_0 - h, t_0 + h]$

$$(Tx)(t) = x_0 + \int_{t_0}^t f(s, x(s)) ds$$

- Show T is a contraction: $|(Tx_1)(t) - (Tx_2)(t)| \leq \int_{t_0}^t |f(s, x_1(s)) - f(s, x_2(s))| ds \leq K \int_{t_0}^t |x_1(s) - x_2(s)| ds \leq Kd(x_1, x_2)h \leq \frac{1}{2}d(x_1, x_2)$.
- T has a fixed point, which is the solution to the IVP for $t \in [t_0 - h, t_0 + h]$.

Usually we show the solution exists on $[t_0 - h, t_0 + h]$ and then show it can be extended beyond this scope.

Proof.

- Go back by $\frac{h}{2}$. Consider the IVP:

$$\begin{cases} y' = f(t, y) \\ y(t_0 + \frac{h}{2}) = x(t_0 + \frac{h}{2}) \end{cases}$$

- Solution exists on $[t_0 - \frac{h}{2}, t_0 + \frac{3}{2}h]$.
- x and y overlap on $[t_0 - \frac{h}{2}, t_0 + h]$. By uniqueness of the solution, x and y must coincide.
- Solution x can be extended to $[t_0 - h, t_0 + \frac{3}{2}h]$.
- Iterate the argument until reach the boundary of U .