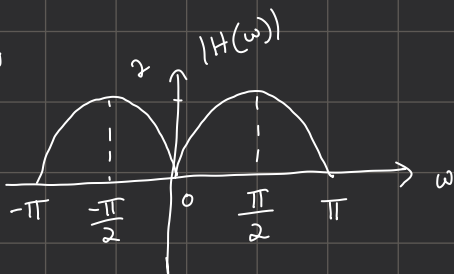


$$h(n) = \{1, 0, -1\}$$

$$\begin{aligned} a) H(\omega) &= \sum_n h(n) e^{-j\omega n} \\ &= 1 + 0 - e^{-j\omega} \\ &= 1 - e^{-j\omega} \quad \left(\frac{1}{2}\right) \\ &= 1 - \cos 2\omega + j \sin 2\omega \end{aligned}$$

$$\begin{aligned} |H(\omega)| &= \sqrt{2(1 - \cos 2\omega)} \\ &= 2|\sin \omega| \end{aligned}$$



$$\begin{aligned} b) H(\omega) &= 1 - e^{-j\omega} \\ &= 2j e^{-j\omega/2} \frac{e^{j\omega/2} - e^{-j\omega/2}}{2j} = 2j \sin \omega \cdot e^{-j\omega/2} = 2|\sin \omega| \cdot j e^{-j\omega/2} \cdot \text{sign}(\sin \omega) \end{aligned}$$

(or)  
tan<sup>-1</sup> with  
conditions for  
each quadrant  
↓  
full marks given even  
if tan<sup>-1</sup> is taken  
without piecewise

$$\angle H(\omega) = \begin{cases} \angle e^{-j(\omega - \frac{\pi}{2})} & \omega > 0 \\ \angle e^{-j(\omega + \frac{\pi}{2})} & \omega < 0 \end{cases}$$

linear phase for  $\omega > 0$

1.5

plot 0.5

$$\phi(\omega) = \boxed{\angle H(\omega) = -\omega + \frac{\pi}{2} \quad \forall \omega > 0}$$

$$c) x(n) = 1 + \sin\left(\frac{\pi n}{6}\right) + \sin\left(\frac{\pi n}{2}\right) + \cos(\pi n)$$

$\downarrow$   $\downarrow$   $\downarrow$   $\downarrow$   
 $\omega=0$   $\omega=\frac{\pi}{6}$   $\omega=\frac{\pi}{2}$   $\omega=\pi$

$$\frac{\partial \phi(\omega)}{\partial \omega} = -1 \Rightarrow \text{group delay of } -1$$

$$y(\omega) = H(\omega) \cdot X(\omega) \quad \xrightarrow{\text{calculating exact fourier and concluding}} \quad x(n) - x(n-2) \quad (1)$$

$\rightarrow$  passes  $\omega=\frac{\pi}{6}$  &  $\omega=\frac{\pi}{2}$

$$y(n) = \sin\left(\frac{\pi n}{6} - \frac{\pi}{3}\right) + 2\sin\left(\frac{\pi}{2}(n-1)\right)$$

final ans (3)

$\rightarrow$  wrong coefficients or phase 1.5m - 2.5m

$$d) h_1(n) = h(n-1)$$

$$X(\omega) = 2\pi \delta(\omega) + \frac{\pi}{j} \left( \delta(\omega - \frac{\pi}{6}) + \delta(\omega + \frac{\pi}{6}) \right) + \frac{\pi}{j} \left( \delta(\omega - \frac{\pi}{2}) + \delta(\omega + \frac{\pi}{2}) \right) + \pi \left( \delta(\omega - \pi) + \delta(\omega + \pi) \right)$$

$$H_1(\omega) = H(\omega) e^{-j\omega}$$

$$|H_1(\omega)| = |H(\omega)|$$

$$\angle H_1(\omega) = \angle H(\omega) - \omega \Rightarrow \text{linear phase}$$

$$Y_1(\omega) = H(\omega) X(\omega) e^{-j\omega}$$

$$y_1(n) = y(n-1) = \sin\left(\frac{\pi}{6}(n-2)\right) + \sin\left(\frac{\pi}{2}(n-1)\right)$$

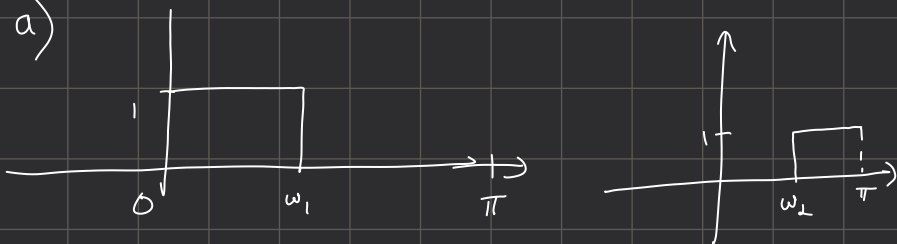
$\rightarrow$  or phase as  $\frac{\pi}{2} - \omega$

linear phase - (1)

mag & phase relation - (1)

$y(n) - (2)$

2) a)

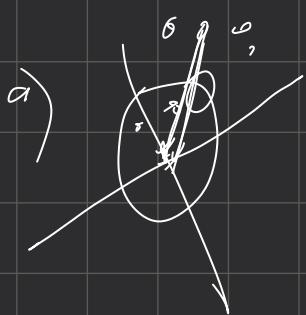


$$w_1 > w_2$$

$$w_2 < w_{\text{range}} < w_1 \quad (2)$$

b) in regions of  $\pi > w > w_1, 0 < w < w_2 \Rightarrow w=0$  (2)

3)  $H(z) \rightarrow$  stable, causal & linear phase  $\Leftarrow$  FIR



IR  $\rightarrow$  no linear phase

IR  $\rightarrow$  noncausal

stable, noncausal

without reasoning expect a 0

$\rightarrow$  cases of zeros inside & outside for stability

b) stable, not causal, FIR (1.5)

c)

FIR, case  $\left\{ \begin{array}{l} \text{odd} \\ \text{even} \end{array} \right.$  linear with reason - (1) (2)

causal stable - (1)

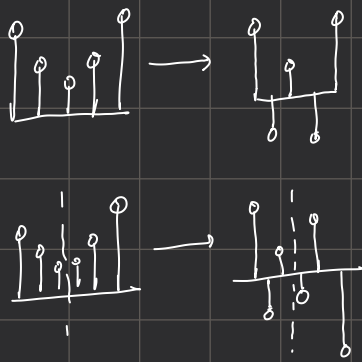
d)

causal stable, linear (1)

$$\sum h(n) z^{-n}$$

$$\sum (-1)^n h(n) z^{-n}$$

$$h'(n) = (-1)^n h(n)$$



## Q4 Solution

Shiva:  $s = 1 - \bar{z}^{-1} = \frac{z-1}{z}$  (derivative approximation of differential eqn.)

Madhuri:  $s = \frac{z}{z+1}$  (modified Bilinear)

(a) [3 marks] How does  $j\omega$ -axis map to  $z$ -plane?

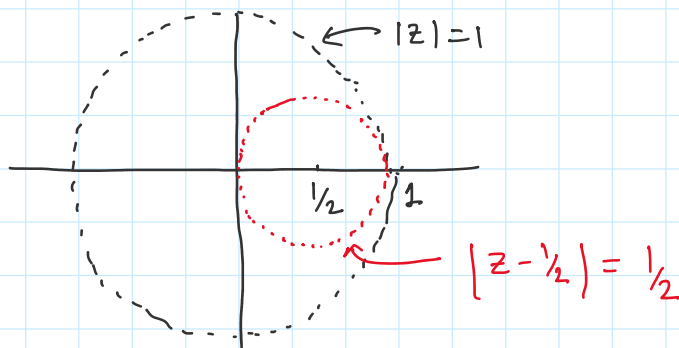
Shiva:  $s = 1 - \bar{z}^{-1} \Rightarrow \bar{z}^{-1} = 1 - s$

$$\Rightarrow z = \frac{1}{1-s} \quad \left(\frac{1}{z}\right)$$

$s = j\omega$  gives  $\rightarrow z = \frac{1}{1-j\omega}$

$$z - \frac{1}{2} = \frac{1}{1-j\omega} - \frac{1}{2} = \frac{1}{2} \frac{1+j\omega}{1-j\omega} \quad \left(\frac{1}{2}\right)$$

$$\left| z - \frac{1}{2} \right| = \frac{1}{2} \Rightarrow \text{Circle of radius } \frac{1}{2} \text{ with center at } \frac{1}{2}. \quad \left(\frac{1}{2}\right)$$



Madhuri:  $s = \frac{z}{1+z} \Rightarrow \frac{1}{s} = \frac{z+1}{z} = 1 + \frac{1}{z}$

$$\Rightarrow \frac{1}{z} = \frac{1}{s} - 1 = \frac{1-s}{s}$$

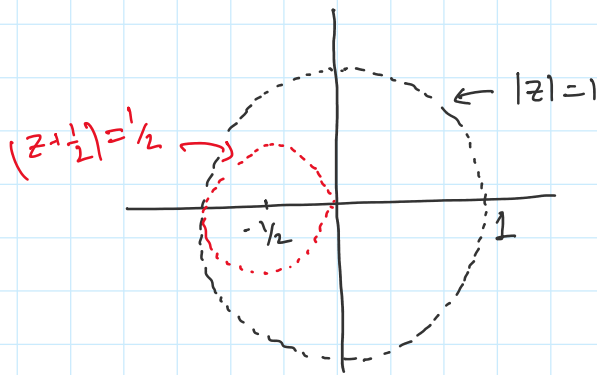
$$\Rightarrow \frac{1}{z} = \frac{1}{s} - 1 = \frac{1-s}{s}$$

$$\Rightarrow z = \frac{s}{1-s} \quad \left(\frac{1}{2}\right)$$

$$\text{for } s = j\omega, \quad z = \frac{j\omega}{1-j\omega}$$

$$z + \frac{1}{2} = \frac{j\omega}{1-j\omega} + \frac{1}{2} = \frac{1}{2} \frac{1+j\omega}{1-j\omega} \quad \left(\frac{1}{2}\right)$$

$$\therefore \left| z + \frac{1}{2} \right| = \frac{1}{2} \Rightarrow \text{circle of radius } \frac{1}{2} \text{ with centre at } -\frac{1}{2} \quad \left(\frac{1}{2}\right)$$



(b) [3 Marks]

Stable & Causal

$$s = \sigma + j\omega$$

$$\text{Shiva: } z = \frac{1}{1-s} = \frac{1}{1-\sigma-j\omega}$$

$$z - \frac{1}{2} = \frac{1}{1-\sigma-j\omega} - \frac{1}{2} = \frac{1}{2} \frac{1+\sigma+j\omega}{1-\sigma-j\omega}$$

$$\left| z - \frac{1}{2} \right| = \frac{1}{2} \sqrt{\frac{(1+\sigma)^2 + \omega^2}{(1-\sigma)^2 + \omega^2}}$$

$$\text{For } \sigma < 0, \quad \left| z - \frac{1}{2} \right| < \frac{1}{2} \quad \text{as } (1-\sigma)^2 > (1+\sigma)^2$$

$$\Rightarrow \operatorname{Re}(s) = \sigma < 0 \Rightarrow \left| z - \frac{1}{2} \right| < \frac{1}{2} \quad (1)$$

$\therefore$  Left half  $s$ -plane (i.e.  $\sigma < 0$ ) maps to inside the circle  $\left| z - \frac{1}{2} \right| = \frac{1}{2}$ , which is inside the unit circle.

$\therefore$  If the continuous-time filter is causal & stable i.e. poles are in the left half  $s$ -plane, they map to poles inside unit circle in  $z$ -plane  $\Rightarrow$  the discrete-time filter is also causal & stable. (1/2)

Madhuri: Similarly show that,

$$z + \frac{1}{2} = \frac{1}{2} \frac{1 + \sigma + j\omega}{1 - \sigma - j\omega}$$

$$\therefore \operatorname{Re}(s) = \sigma < 0 \Rightarrow \left| z + \frac{1}{2} \right| < \frac{1}{2} \quad (1)$$

using same argument as above,

Stable & Causal in C-T  $\Rightarrow$  Stable & Causal in D-T (1/2)

(c) [4 Marks]

Shiva: Analog Filter  $H_a(s) = \frac{1}{s+2}$

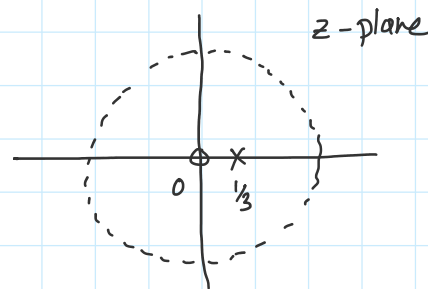
Digital Filter  $H(z) = H_a(s) \Big|_{s=1-\frac{1}{z}}$

$$H(z) = \frac{1}{1 - \bar{z}^{-1} + 2} = \frac{1}{3 - \bar{z}^{-1}} = \frac{z}{3z - 1}$$

$$H(z) = \frac{1}{3} \frac{z}{z - 1/3} \quad (1)$$

zero :  $z = 0$

pole :  $z = 1/3$



(1/2)

Based on location of pole & zero, this is a low pass filter (1/2)

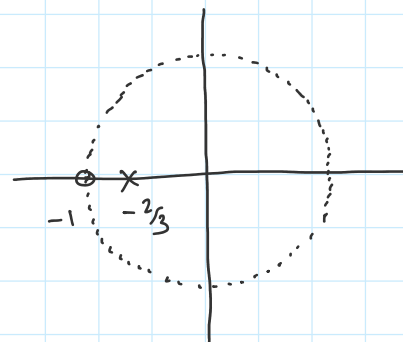
Madhuri :

$$\text{digital filter } H(z) = H_a(s) \Big|_{s = \frac{z}{z+1}}$$

$$H(z) = \frac{1}{\frac{z}{z+1} + 2} = \frac{z+1}{3z+2} = \frac{1}{3} \frac{z+1}{z+2/3} \quad (1)$$

zero :  $z = -1$

pole :  $z = -2/3$



(1/2)

From above pole-zero plot, this is also a low pass filter. (1/2)

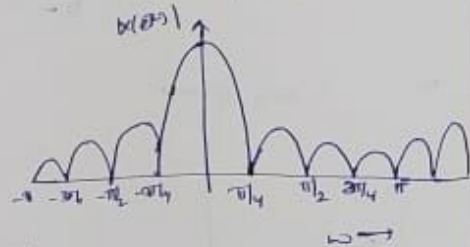
$$X(e^{j\omega}) = \sum_{n=0}^7 e^{-j\omega n} = \sum_{n=0}^7 e^{-j\omega n} + \sum_{n=8}^{\infty} e^{-j\omega n} - \sum_{n=8}^{\infty} e^{-j\omega n}$$

$$\frac{1}{1-e^{-j\omega}} - e^{-j\omega 8} \frac{1}{1-e^{-j\omega}} \Rightarrow |X(e^{j\omega})| = \frac{\sin 4\omega}{\sin \omega/2}$$

$$X(e^{j\omega}) = \frac{1-e^{-j\omega 8}}{1-e^{-j\omega}}$$

$$\int_{-\pi}^{\pi} |X(e^{j\omega})|^2 d\omega = \sum_{n=0}^7 |x[n]|^2$$

now prove this



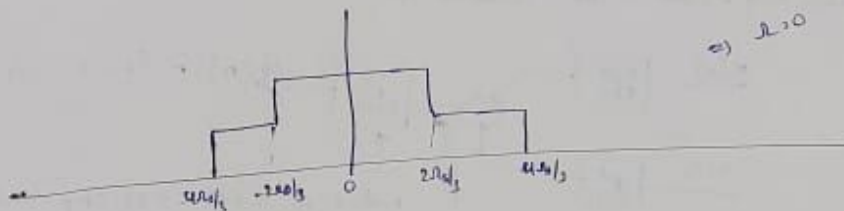
8

$$X_R(e^{j\omega}) \cdot e^{j\omega 4} \Rightarrow x_e[n] = \left\{ \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, 1, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2} \right\}$$

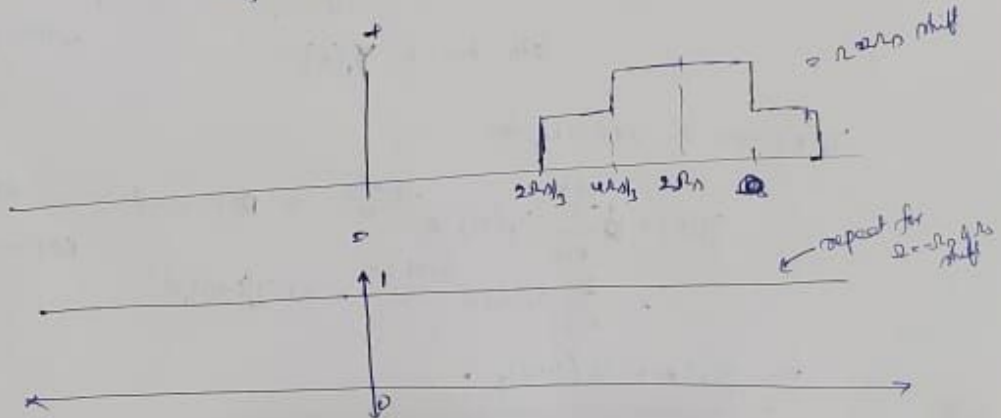
$$X[k] = X(e^{j\omega}) \Big|_{\omega = \frac{2\pi k}{16} = 2\pi \frac{k}{8}}$$

$$X[k] = \frac{1-e^{-j\frac{2\pi k}{8} \cdot 8}}{1-e^{-j\frac{2\pi k}{8}}} = \frac{1-e^{-j2\pi k}}{1-e^{-j\frac{2\pi k}{8}}} \Rightarrow X[k] = \{1, 0, 0, 0, 0, 0, 0\}$$

Q.

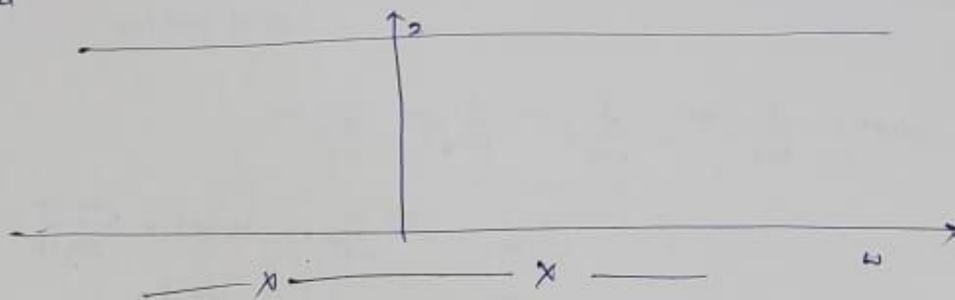


2, 0



Result

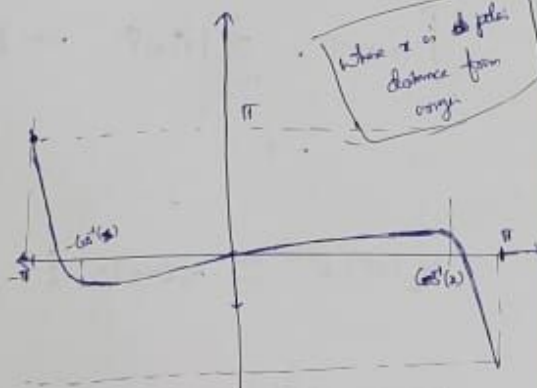
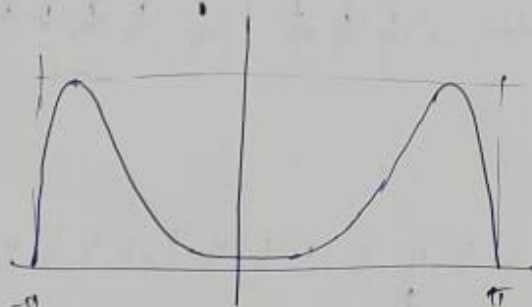
(2)



3.

mag spectrum

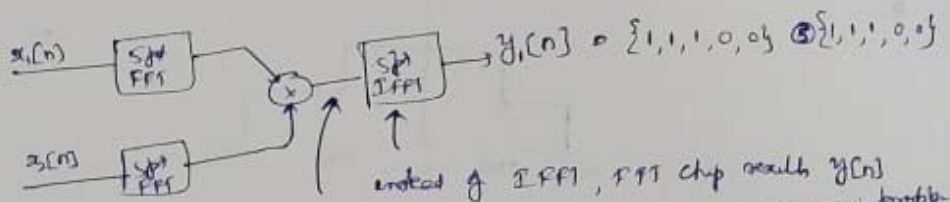
phase spectra



4. Based on Ques-2 solution only



5. ~~Ques-2~~ mid-exam solution available for to below



Let's have  $y_1[k]$

$y_1[k]$  goes to FFT chip the

$$y[n] = \frac{1}{N} \sum_{k=0}^{N-1} Y_1[k] e^{-j \frac{2\pi k n}{N}} \quad \text{is DFT equation} \quad \therefore \text{FFT chip copy DFT into ypt}$$

$$= \sum_{k=0}^{N-1} Y_1[k] e^{\frac{j 2\pi k (-n)}{N}} = N \cdot y_1[(-n)]_N$$

$$\text{e.g. } y[n] = 5 y_1[(-n)]_5$$