# **Derivative Free Optimization**

Lecture 2: Exhaustive & Grid Search

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### **DFO** framework



### **DFO Framework**

We seek to solve

$$(arg) min\{f(x) : x \in \Omega\}$$

where  $f: \mathbb{R}^n \mapsto \mathbb{R}$ 

The DFO/BBO framework assumes, given a point  $x \in \mathbb{R}^n$ 

- we can check if  $x \in \Omega$  or  $x \notin \Omega$
- we can acquire a function value f(x)
- but, we cannot 'look' at f

### **Exhaustive Search**

### Countable Dense subsets

**Definition:** A set  $S \subseteq \mathbb{R}^n$  is **countable** if it can be ordered: i.e.,  $S = \{x^0, x^1, \ldots\}$ .

**Definition:** A set  $S \subseteq \mathbb{R}^n$  is a **dense subset** of  $\Omega$  if

- $S \subseteq \Omega$ , and
- given any  $x \in \Omega$  and  $\delta > 0$ , there exists a point  $\tilde{x} \in S$  such that  $\|x - \tilde{x}\| < \delta$ .

### Countable Dense subsets

**Example:** Show that the set

$$S = \left\{ x : x = \frac{a}{b}, a \in \mathcal{Z}, b \in \mathcal{Z}, 0 < a < b \right\}$$

is countable and dense in  $[0,1]\subseteq\mathbb{R}^1$ 

**Example:** Create a countable dense subset of  $[0,1]^2 \subseteq \mathbb{R}^2$ 

# Algorithm: Exhaustive Search (ES)

Given  $f: \mathbb{R}^n \mapsto \mathbb{R}$ , and  $\Omega \subseteq \mathbb{R}^n$ 

#### 0. Initialization

$$\begin{array}{ll} S = \{x^0, x^1, x^2, \ldots\} & \text{a countable dense subset of } \Omega \\ k \leftarrow 0 & \text{iteration counter} \\ x_{\text{best}} = x^0 \in S & \text{best point found so far} \\ f_{\text{best}} = f(x_{\text{best}}) & \text{best objective function value found so far} \\ \end{array}$$

### 1. Update

```
evaluate f(x^{k+1})

if f(x^{k+1}) < f_{\text{best}}, then

update x_{\text{best}} \leftarrow x^{k+1}, f_{\text{best}} \leftarrow f(x_{\text{best}})

increment k \leftarrow k+1 and go to 1
```

# Convergence of ES

**Theorem:** Suppose  $f \in \mathcal{C}^0$ ,  $\Omega \subseteq \mathbb{R}^n$  and

$$X^* = \operatorname{argmin}_x \{ f(x) : x \in \Omega \} \neq \emptyset.$$

Denote the value  $f_{\text{best}}$  at iteration k of ES by  $f_{\text{best}}^k$  and the point  $x_{\text{best}}$  at iteration k by  $x_{\text{best}}^k$ . Then

$$\lim_{k\to\infty} f_{\mathtt{best}}^k = f^* := \min_{x} \{f(x) \ : \ x\in\Omega\}$$

and moreover, if  $\Omega$  is *compact*, then

$$\liminf_{k\to\infty} \operatorname{dist}(x_{\mathtt{best}}^k, X^*) = 0.$$

### **Exhaustive Search**

#### Pros:

It works

#### Cons:

- Need to construct S
- Requires infinite time
- No way to know when you can stop

#### Conclusion

- Debatable if it is a DFO method
- Not a good approach for BBO

### **Grid Search**

### Grid search

**Example:** Let  $\Omega = [0, 1]^2$ 

Suppose S is an  $p \times p$  grid of equally spaced points in  $\Omega$ 

- How many points are in S?
- **2** What is the farthest any point in  $\Omega$  is from S?

# Algorithm: Grid Search (GS)

Given  $f: \mathbb{R}^n \mapsto \mathbb{R}$ , and  $[\ell, u] \subset \mathbb{R}^n$ 

- 0. Initialization
  - $p_i \in \mathbb{N}$  with  $p_i \geq 2$  number of grid points for each variable
- 1. Sample f at all grid points

$$\begin{array}{l} \text{define } \delta_i = (u_i - \ell_i)/(p_i - 1) \text{ for each } i \in \{1, 2, \ldots, n\} \\ \text{create } G = \left\{ \begin{array}{ll} x \in [\ell, u] & : & x_i = \ell_i + z \delta_i, \\ & i = 1, 2, \ldots, n, z = 0, 1, \ldots, p - 1 \end{array} \right\} \\ \text{choose } x_{\mathsf{best}} \in \operatorname{argmin} \{ f(t) : t \in G \} \end{array}$$

# Convergence of GS

Suppose  $f \in \mathcal{C}^{0+}$  with constant KSuppose GS is used to minimize f over  $x \in [\ell, u] \subseteq \mathbb{R}^n$ The optimal value  $f^* = \min_x \{f(x) : x \in [\ell, u]\}$  satisfies

$$f_{\mathsf{best}} - K\sqrt{n}\frac{\delta}{2} \le f^* \le f_{\mathsf{best}}$$

where  $f_{\text{best}} = f(x_{\text{best}})$  and  $\delta = \max \delta_i$ 

# GS example

**Example:** Let  $\Omega = [0,5]^4$ . Suppose  $f \in \mathcal{C}^{0+}$  with constant K = 0.25.

- What value of p is required to ensure  $f_{\text{best}} f^* \le 10^{-3}$ ?
- How many function evaluations are required to ensure  $f_{\text{hest}} f^* < 10^{-3}$ ?



# GS example

**Example:** Suppose  $\Omega = [-1, 1]^n$ . Suppose  $f \in \mathcal{C}^{0+}$  with constant K = 3. As a function of n,

- **1** What value of *p* is required to ensure  $f_{\text{best}} f^* \leq 10^{-3}$ ?
- Mow many function evaluations are required to ensure  $f_{\text{best}} f^* \le 10^{-3}$ ?
- **3** If you can do 1000 function evaluation per second, what is the largest value of n that you can solve before this course is over ( $\approx 8 \times 10^6$  seconds)?

### Grid Search

#### Pros:

- Finite time
- Quality of result is known

#### Cons:

- The value of K is seldom known
- In  $\mathbb{R}^n$  the number of points evaluated grows at  $p^n$
- Most function evaluations are a waste of time

#### Conclusion

- A DFO method
- Generally not a good idea for BBO



## **DFO**



### **DFO Framework**

### The basic approach

- $\bullet$  Evaluate f at some points
- 2 Use the information we gathered to decide where to evaluate next

# **Example:** Suppose $f: \mathbb{R}^2 \mapsto \mathbb{R}$ and $\Omega = [0, 10]^2$ Suppose

$$f(0,0) = 4$$
  
 $f(0,10) = 4$   
 $f(10,0) = 5$   
 $f(10,10) = 7$   
 $f(5,5) = 4$ 

Where should we evaluate next?



# Assignment 2



# Assignment 2

#### **MATH 462**

- Textbook # 3.2(abc), 3.4
- Textbook # 3.5 (this requires reading Example 3.1)

#### COSC 419K

- Textbook # 3.2(a), 3.4
- ullet Write a MATLAB script that numerical solves Textbook # 3.2(bc)
- Textbook # 3.5 (this requires reading Example 3.1)

#### **MATH 562**

- All MATH 462 and COSC 419K questions
- ullet Write a MATLAB script that numerical completes Textbook # 3.6
- Textbook # 3.8

