Statistical Principals of Data Analysis

Dr. Felipe Teles

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A linear model in statistics is a model of the type

$$Y = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_{p-1} X_{p-1} + \beta_p X_p + \varepsilon,$$
 (1)

where Y is a response variable, $X_1, X_2, \ldots, X_{p-1}, X_p$ are explanatory variables, $\beta_0, \beta_1, \beta_2, \ldots, \beta_{p-1}, \beta_p$ are the coefficients of the linear model and $\varepsilon \sim \mathcal{N}(0, \sigma^2)$ is the error of the model.

Or, in matrix notation:

$$\begin{bmatrix} Y_{1} \\ Y_{2} \\ \vdots \\ Y_{n} \end{bmatrix} = \begin{bmatrix} 1 & X_{11} & X_{21} & X_{31} & \dots & X_{(p-1)1} & X_{p1} \\ 1 & X_{12} & X_{22} & X_{32} & \dots & X_{(p-1)2} & X_{p2} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 1 & X_{1n} & X_{2n} & X_{3n} & \dots & X_{(p-1)n} & X_{pn} \end{bmatrix} \begin{bmatrix} \beta_{0} \\ \beta_{1} \\ \vdots \\ \beta_{p} \end{bmatrix} + \begin{bmatrix} \varepsilon_{1} \\ \varepsilon_{2} \\ \vdots \\ \varepsilon_{n} \end{bmatrix}, (2)$$

which can be written as

$$Y = X\beta + \varepsilon, \tag{3}$$

where X is the design matrix (explanatory variables, treatments, groups, etc.).

Examples of linear models:

- $Y = \beta_0 + \beta_1 X_1$;
- $Y = \beta_0 + \beta_1 X_1 + \beta_2 X_1^2 + \beta_3 X_1^5$;
- $Y = \frac{\beta_1}{X_1};$
- $Y = \beta_1 X_1 + \beta_2 X_2 + \beta_3 X_3 + \beta_4 X_1 X_2 X_3$;

Examples of nonlinear models:

•
$$Y = \beta_0 + \beta_1 X_1 + \frac{\beta_2}{\beta_3 + X_1}$$
;

•
$$Y = \beta_0 + \beta_1 X_1 + \beta_2 X_2^{\beta_3 X_3}$$
;

•
$$Y = cos(\beta_1 X_1) + sin(\beta_2 X_1);$$

•
$$Y = \beta_0 e^{\beta_1 X_1}$$
;

•
$$\frac{dS}{dt} = -\frac{\mu_{max}S}{K_S + S}XY_{X/S}$$
, where $\mu_{max}, K_S, Y_{X/S}$ are parameters;

Least Squares Method

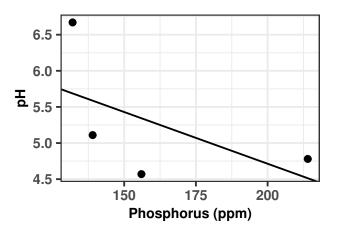


Figure: Linear Model: pH explained by nitrogen from Soil data set

Least Squares Method

Goal: minimize the residual sum of squares (RSS)

$$RSS = ||Y - X\beta||^2 \tag{4}$$

$$= (Y - X\beta)^{T} (Y - X\beta)$$
 (5)

$$= Y^T Y - Y^T X \beta - \beta^T X^T Y + \beta^T X^T X \beta \tag{6}$$

$$= Y^T Y - 2\beta^T X^T Y + \beta^T X^T X \beta. \tag{7}$$

Least Squares Method

Goal: minimize the residual sum of squares (RSS)

$$RSS = Y^{T}Y - 2\beta^{T}X^{T}Y + \beta^{T}X^{T}X\beta$$

$$\min_{\beta} RSS \implies \frac{\partial}{\partial \beta}RSS = 0$$
(8)

$$\frac{\partial}{\partial \beta}RSS = 0 \tag{9}$$

$$-2X^TY + 2X^TX\beta = 0 (10)$$

$$X^T X \beta = X^T Y \tag{11}$$

$$(X^T X)^{-1} X^T X \beta = (X^T X)^{-1} X^T Y$$
 (12)

$$\beta = (X^T X)^{-1} X^T Y. \tag{13}$$

$$\hat{\beta} = (X^T X)^{-1} X^T Y. \tag{14}$$

- In R, install and load the packages car, carData and ggplot2.
- 2 Load the data set Soils and, by using the function subset, filter the data for Gp=S1.
- Fit a linear model for pH using the explanatory variable P.
- Oheck the results with summary.
- **1** Theoretical check calculate $\hat{\beta}$ using Equation (14).

```
data01=subset (Soils, Gp="S1")
model1=lm(data=data01,pH~P)
summary (model1)
X=as.matrix(model.matrix(model1))
Y=as.matrix(data01$pH)
Beta=solve (t(X)\%*\%X)\%*\%t(X)\%*\%Y
ggplot(data=data01, aes(x=P, y=pH))+
geom_point(pch=19)+theme_bw()+
geom_abline(intercept=coef(model1)[1],
slope=coef(model1)[2]
```

Goodness of Fit

Based on what can we say if one model is good?

- Coefficient of Determination R^2 ;
- Distribution of Errors;
- Unusual observations;
- Structure of the model.

Goodness of Fit - Coefficient of Determination

The coefficient of determination is the percentage of data variability explained by the model:

$$R^{2} = 1 - \frac{\sum_{i=i}^{n} (\hat{y}_{i} - y_{i})^{2}}{\sum_{i=i}^{n} (y_{i} - \bar{y})^{2}}$$
(15)

Some

- **1** $0 \le R^2 \le 1$;
- ② If $R^2 = 1$, then RSS = 0;

A linear model:

$$Y = X\beta + \varepsilon, \varepsilon \sim N(0, \sigma^2). \tag{16}$$

Check:

- **1** Distribution of errors around zero: $E[\varepsilon] = 0$;
- **2** Homoscedasticity: $Var[\varepsilon] = \sigma^2$;
- Normality of residuals: Q-Q plot;

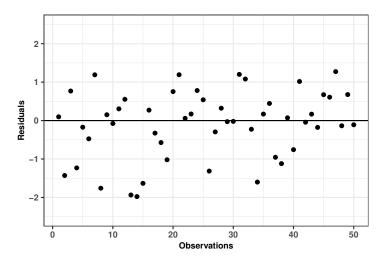


Figure: Residuals normally distributed with homoscedastic variance structure.

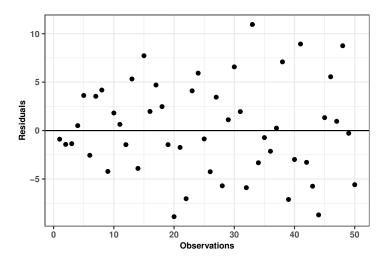


Figure: Residuals normally distributed with mild disturbance.

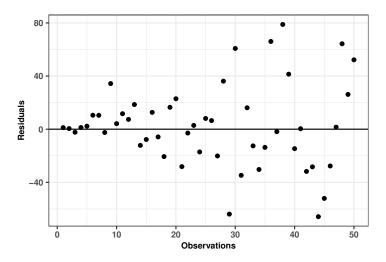


Figure: Residuals normally distributed with heteroscedastic variance structure.

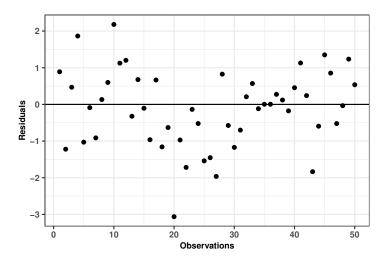


Figure: Nonlinear residuals.

Normal Q-Q Plot

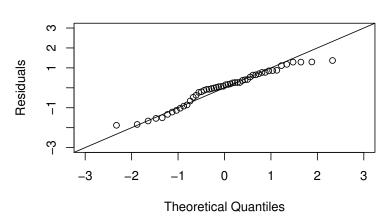


Figure: Q-Q plot.

Test of normality - Shapiro-Wilk test (shapiro.test)

$$H_0: \varepsilon \sim N(\mu, \sigma^2)$$
 (17)

$$H_1: \varepsilon \nsim N(\mu, \sigma^2)$$
 (18)

Using the data set *Soils*:

- Fit the following model: $pH = \beta_0 + \beta_1 N + \beta_2 P + \beta_3 Ca + \beta_4 Mg + \beta_5 K + \beta_6 Na + \varepsilon.$
- Make the analysis of diagnostics plot the residuals and identify possible leverage points and outliers.
- Based on ANOVA, is there any variable that is not significant to explain pH?
- What happens when we fit the following model: $pH = \beta_1 N + \beta_2 P + \beta_3 Ca + \beta_4 Mg + \beta_5 K + \beta_6 Na + \varepsilon$? Repeat analyses 1, 2 and 3.
- Now include Block effects. What can we see?
- Is there any significant block effect?
- Is there any variable deviating from normality? Is there any transformation possible?
- Is there some normalization that we could apply?

Variance

- We are mostly interested in analysing the variance of a data set, but why?
- ② Can we calculate the variance of a variable always with the same formula?
- What is the difference between sample and population variances?
- What is between group variance? And within group variance?
- What about covariance?

Expectation

Before we start with variance, let us remember what is expectation:

$$E[X] = \sum_{X \in \Omega} X \mathbb{P}[x = X] \tag{19}$$

or

$$E[X] = \int_{\Omega} X \mathbb{P}[x = X] dx, \tag{20}$$

where X is a variable defined in $(\mathcal{F}, \Omega, \mathbb{P})$.

Expectation

For example, when $X \sim U(a, b)$, whose probability density function is

$$\mathbb{P}[x = X] = \frac{1}{b - a}:$$

$$E[X] = \int_{a}^{b} x \mathbb{P}[x = X] dx \qquad (21)$$

$$= \int_{a}^{b} x \left(\frac{1}{b - a}\right) dx \qquad (22)$$

$$= \int_{a}^{b} x \left(\frac{1}{b - a}\right) dx \qquad (23)$$

$$\int_{a}^{a} \left(b - a \right)^{\frac{1}{2}} dx$$

$$= \left(\frac{1}{b - a} \right) \left[\frac{x^{2}}{2} \right]_{a}^{b}$$

$$= \left(1 \right) \left(b^{2} - a^{2} \right)$$

$$= \left(\frac{1}{b-a}\right) \frac{(b^2 - a^2)}{2}$$
$$= \left(\frac{1}{b-a}\right) \frac{(b-a)(b+a)}{2}$$

$$= \left(\frac{1}{b-a}\right) \left[\frac{x^2}{2}\right]_a^b$$

$$= \left(\frac{1}{b-a}\right) \frac{(b^2-a^2)}{a^2}$$
(23)

$$\frac{a^2 - a^2}{2}$$

- What is the expectation of X when $X \sim U(3,7)$? Use the function runif(n,a,b).
- Plot a histogram for 10, 100, 1000, 10000 and 100000 values of X. Use the function hist().
- **3** What is the mean of 4, 50 and 100 values generated from U(3,7)? Is the mean the expected value?
- Plot the function f, such that: $f(n) = E[X|\#\Omega = n]$. What can you observe?
- Maurício: Exponential, Ailton: Binomial, Thalita: Gamma, Gabriel: Weibull, Fernanda: Normal.

Some distributions

Table: Expectation and Variance for some distributions.

Definition	Expected value	Variance
$N(\mu, \sigma^2)$	μ	σ^2
U(a,b)	$\frac{b+a}{2}$	$\frac{(b-a)^2}{12}$
$\textit{Exp}(\lambda)$	$\frac{1}{\lambda}$	$rac{1}{\lambda^2}$
$Poisson(\lambda)$	$\stackrel{\curvearrowleft}{\lambda}$	$\stackrel{\frown}{\lambda}$
$ extit{Gamma}(lpha,eta)$	$rac{lpha}{eta}$	$rac{lpha}{eta^2}$
$\mathit{Weibull}(lpha,eta)$	$\alpha\Gamma(1+1/eta)$	$\alpha^2 \left(\Gamma(1+2/\beta) - (\Gamma(1+1/\beta))^2 \right)$
Binomial(n, p)	np	np(1-p)

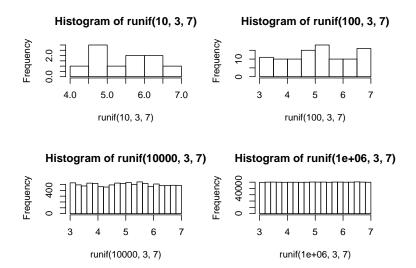


Figure: Histogram for U(3,7) for different number of generated points.

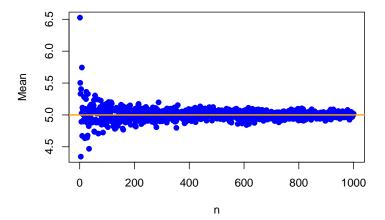


Figure: Mean of U(3,7) for different values of n. In orange, the expected value.

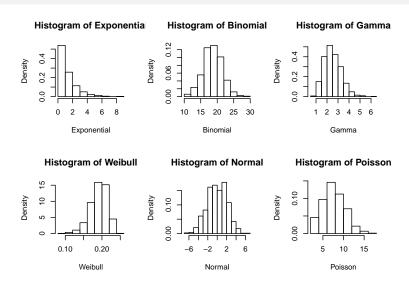


Figure: Histogram for different distributions of probability.

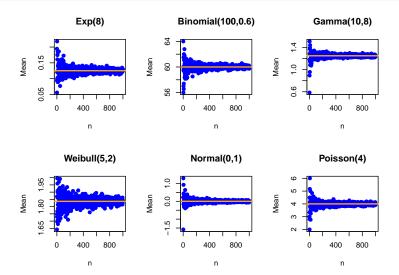


Figure: Mean of different distributions for different values of n. In organge, the expected value