Other ways to run a process

Manually triggering a robot from the Assistant interface

- Go to the Robot Interface in the **System Tray** and click on the **UI** icon.

- Find the "OrchestratorHelloWorld_DemoEnvironment" process, which should be available.

- Click the **Play** button next to the process. You may be required to download the process before fulfilling this step. Watch what happens after pressing **Play**.

*Note that the two message boxes are different. This happens because the version you have just uploaded to Orchestrator hasn't been deployed yet.

To remedy this, go back to Orchestrator. Under **Processes** identify the "OrchestratorHelloWorld" process. Notice the download icon next to it. Click the **View Process** button. The Active version is the one currently deployed. Click the **Latest** button to update the version of the package to the newest deployed one. Run the process manually from the tray again.

Terminating and stopping a process

Run the OrchestratorHelloWorld process from the Jobs section in Orchestrator, but don't press the OK button yet. Notice that the currently running process has a **Running** state associated with it.

Select the check box to the left of this process to see the two buttons - **Stop** and **Kill**.

Pressing **Kill** is the equivalent of stopping a process from the Studio. Orchestrator will connect to your Robot and send a stop command to the process.

Pressing **Stop** requires you to use the **Should Stop** activity in Studio while developing the process. The activity returns a boolean value. It informs whether the **Stop** button has been pressed in Orchestrator by the time the Control Flow reached the **Should Stop** activity. This is similar to a **Save Game** function in a computer game.

This allows you to instruct the Robot to exit the running the process in a "clean" manner, by closing all running applications, logged in systems like SAP and database connections.