

CSCI 362 : Data Structure

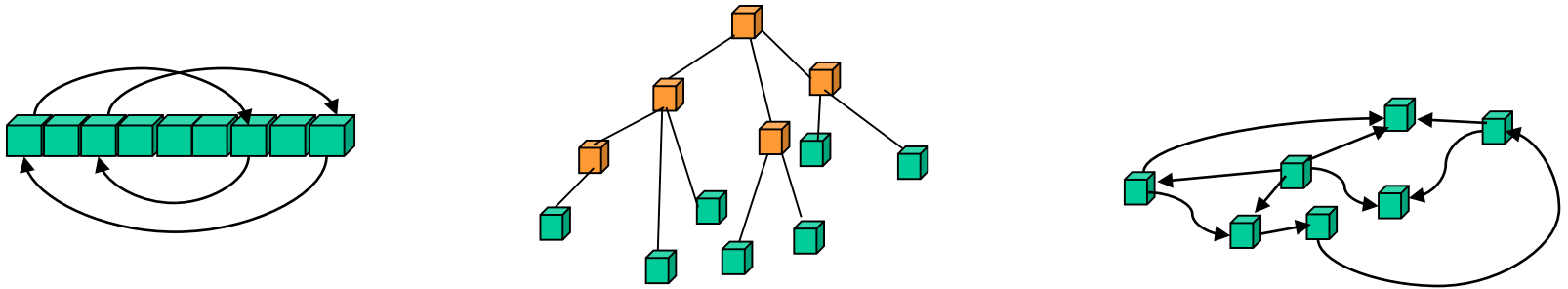
Spring, 2015

Part I: Data Structures & Algorithm Analysis

Chap. 1 Introduction

1.1 Introduction

- Data Structures: methods of organizing large amount of data (input data, output data, run-time data)

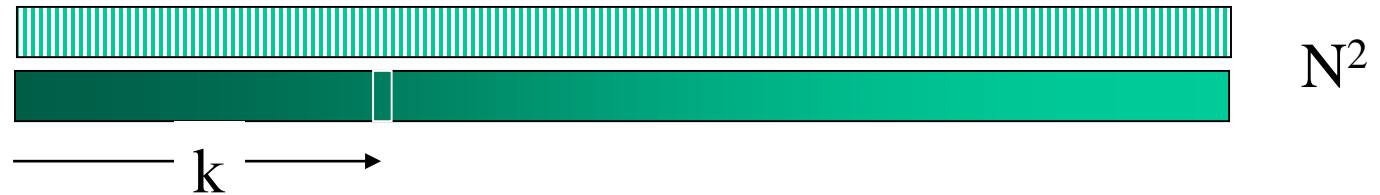


- Algorithm analysis: estimation of running time of algorithms
- Goals
 - Various data structures, their properties, operations, implementations, & applications
 - Data structure design skills for problem solving
 - Algorithm design and analysis skill

– Algorithm analysis examples

- Finding the k^{th} largest number among a group of N numbers

Bubble sort



6 5 3 1 8 7 2 4

http://en.wikipedia.org/wiki/Bubble_sort#mediaviewer/File:Bubble-sort-example-300px.gif

1.2 Mathematics review

– Exponents

$$X^A X^B = X^{A+B}$$

$$(X^A)^B = X^{AB}$$

$$X^A / X^B = X^{A-B}$$

– Logarithms

$$X^A = B \Leftrightarrow \log_X B = A \quad (B, X > 0, X \neq 1)$$

$$\log_A B = \log_C B / \log_C A$$

$$\log AB = \log A + \log B$$

$$\log A / B = \log A - \log B$$

$$\log(A^B) = B \log A$$

$$\log X < X \quad (\text{for all } X > 0)$$

$$\log 1 = 0, \log 2 = 1, \log 1024 = 10, \dots$$

$$\log_2 A = \log A$$

$$\log_{10} A = \lg A$$

$$\log_e A = \ln A$$

– Series

$$\sum_{i=0}^N A^i = \frac{A^{N+1} - 1}{A - 1}, \quad \sum_0^N 2^i = 2^{N+1} - 1$$

$$\text{If } 0 < A < 1 \Rightarrow \sum_0^N A^i \leq \frac{1}{1-A}$$

$$\sum_{i=0}^{\infty} A^i = \frac{1}{1-A} \quad (0 < A < 1): \text{ geometric series}$$

$$\sum_1^N i = \frac{N(N+1)}{2} \approx N^2 / 2$$

$$\sum_1^N i^2 = \frac{N(N+1)(2N+1)}{6} \approx N^3 / 3 \quad \text{ex. } 2+5+8+\dots+(2k-1)$$

$$\sum_1^N i^k \approx N^{k+1} / |k+1| \quad (k \neq -1)$$

Harmonic number

Euler's Constant:

$$H_N = \sum_1^N \frac{1}{i} \approx \log_e N = \ln N$$

$$\gamma = \lim_{N \rightarrow \infty} |H_N - \ln N| = 0.57721566$$

$$\sum_{i=1}^N f(N) = Nf(N)$$

$$\sum_{i=n_0}^N f(N) = \sum_{i=1}^N f(i) - \sum_{i=1}^{n_0-1} f(i)$$

– Modular Arithmetic

- A is congruent to B modulo $N \Leftrightarrow A \equiv B \pmod{N}$

$\Leftrightarrow N$ divides $A - B$

e.g. $81 \equiv 61 \equiv 1 \pmod{10}$

- If $A \equiv B \pmod{N}$ then $A + C \equiv B + C \pmod{N}$

and $AD \equiv BD \pmod{N}$

– Mathematical proof techniques

- Deriving some statement from
 - (a) Assumption or hypothesis
 - (b) Statement that are already derived
 - (c) Other generally accepted facts

- Proof by construction

Example: for any integers a & b , if a, b are odd, then ab is also odd.

- Proof by contradiction

Example: There is an infinite number of primes. $N = P_1 P_2 \dots P_n + 1$

- Proof by counterexample

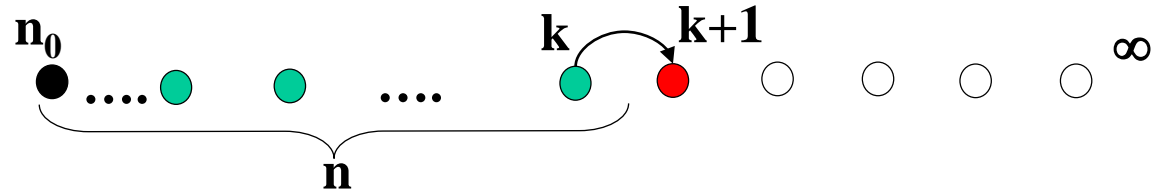
Example: $F_k \leq k^2$, True?

- Mathematical induction

- Suppose $P(n)$ is a statement involving an integer n , then to prove that $P(n)$ is true for every $n \geq n_0$, it is sufficient to show:

- (a) $P(n_0)$ is true (**base case**)

- (b) For any $k \geq n_0$, if $P(n)$ is true for any $n_0 \leq n \leq k$ (**inductive hypothesis**), then $P(k+1)$ is also true (**induction**).



Example:

$$\sum_{i=1}^n i = \frac{n(n+1)}{2}$$

Example:

Fibonacci number are defined as:

$$F_0=1, F_1=1, \dots \quad F_k=F_{k-1}+F_{k-2}$$

Prove: $F_i < (5/3)^i$

Example:

for any integer $n \geq 2$, n is either a prime or a product of two or more primes.

1.3 Recursion

- Defining a function in terms of itself
- Fundamental rules of recursion
 - 1.) Base cases
 - 2.) Making progress through recursion
 - 3.) Design rule: assuming all recursive call work (details hidden)
 - 4.) Compound interest rule: do not duplicate recursive calls
- Fibonacci number is a recursive function

$$F_k = F_{k-1} + F_{k-2}, \quad F_0 = 1, F_1 = 1$$

Example:

$$f(x) = 2f(x-1) + x^2, \quad f(0) = 0;$$

Example:

$$n! = \begin{cases} 1 & n=0 \\ n(n-1)! & n>0 \end{cases}$$

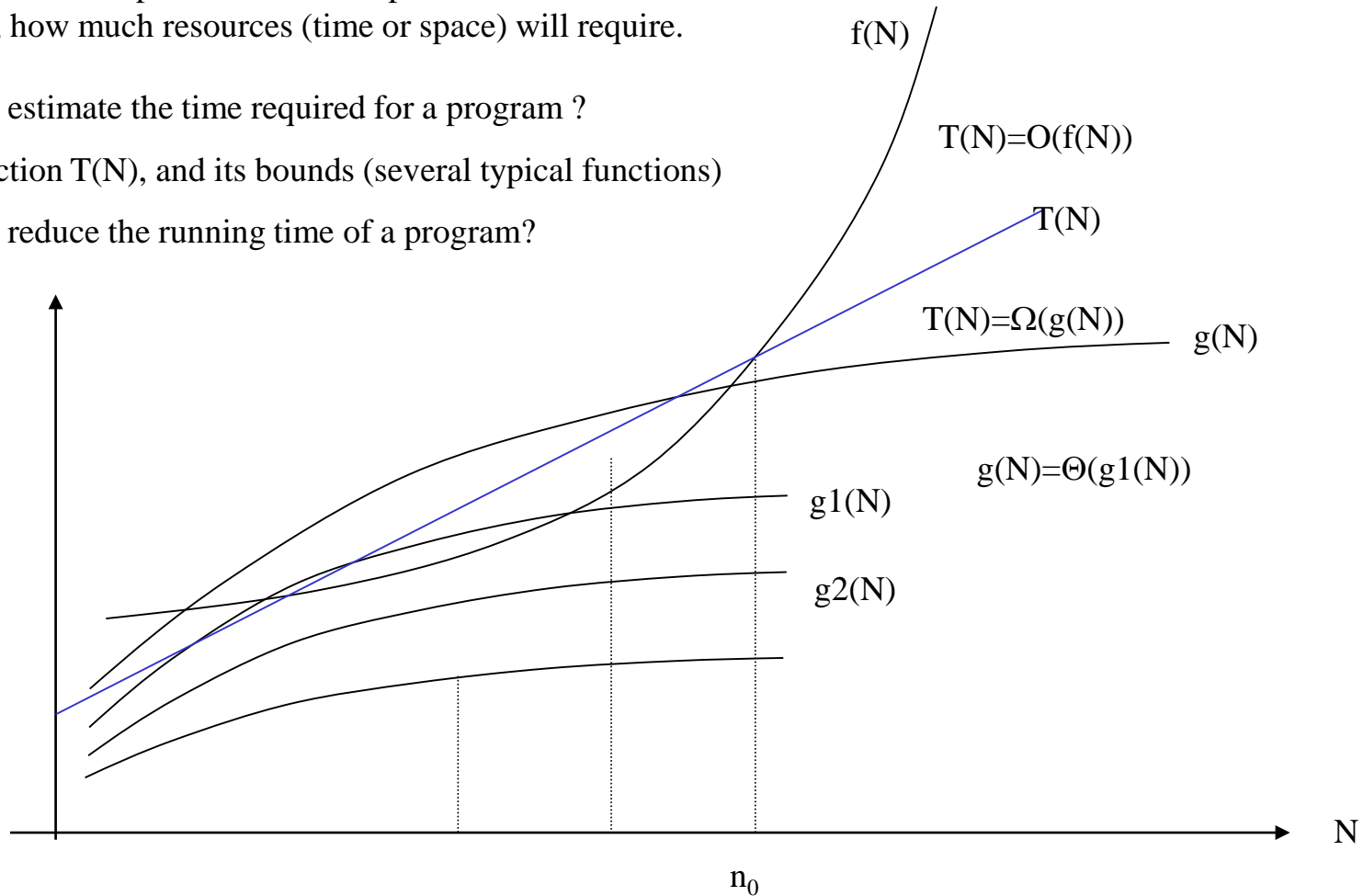
Algorithm Complexity

- An algorithm is specified set of simple instructions
- Totally, how much resources (time or space) will require.

How to estimate the time required for a program ?

→ function $T(N)$, and its bounds (several typical functions)

How to reduce the running time of a program?



Chap. 2 Algorithm Analysis

2.1 Math. Background

– Some definitions on Computation Order

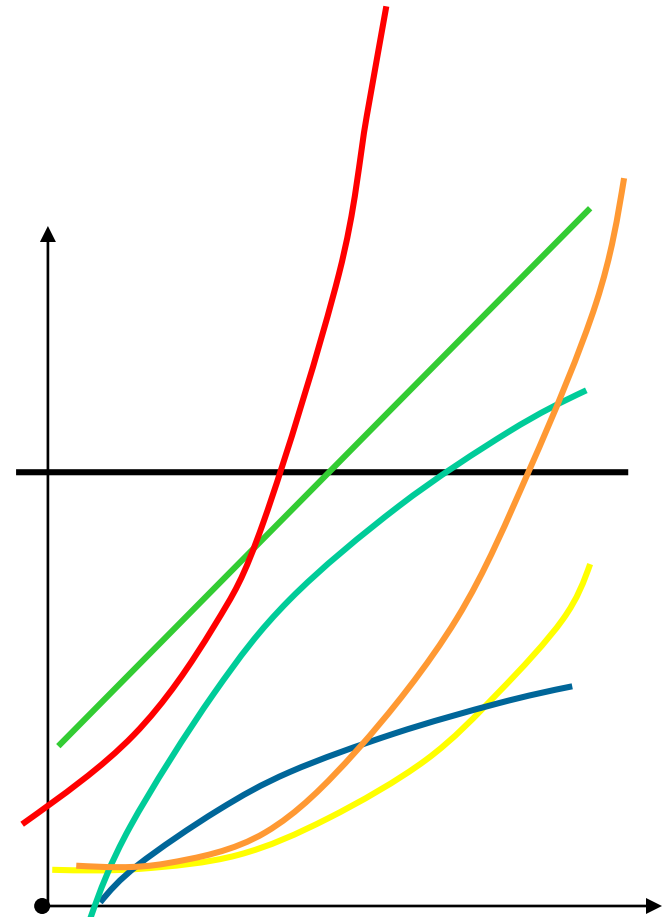
- $T(N) = O(f(N))$ if there is constant $c > 0$ and $n_0 > 0$ such that $T(N) \leq c f(N)$ when $N \geq n_0$
- $T(N) = \Omega(g(N))$: if there is constant $c > 0$ and $n_0 > 0$ such that $T(N) \geq c g(N)$ when $N \geq n_0$
- $T(N) = \Theta(h(N))$: if and only if $T(N) = O(h(N))$ and $T(N) = \Omega(h(N))$
- $T(N) = o(p(N))$: if $T(N) = O(p(N))$ and $T(N) \neq \Theta(p(N))$

– Function growth rate (relative rate of growth or computation order)

- establish a relative order among functions
- only interested in large N . ($N \geq n_0$)
- constant factor is ignored $Cf(N) = O(f(N))$, $C+f(N) = O(f(N))$
- $T(N) = O(f(N))$: f is an upper bound on $T(N)$, and T is a lower bound on f (i.e. $f(N) = \Omega(T(N))$)

Typical growth rates bounding running time

- Function Name
 - 2^N Exponential
 - N^3 Cubic
 - N^2 Quadratic
 - $N \log N$ NLogN
 - N Linear
 - $\log^2 N$ Log-squared
 - $\log N$ Logarithmic
 - C constant



– Computing growth rates

- If $T_1(N) = O(f(N))$ and $T_2(N) = O(g(N))$
 - a) $T_1(N) + T_2(N) = O(\max(f(N), g(N)))$
 - b) $T_1(N) * T_2(N) = O(f(N) * g(N))$
- If $T(N)$ is a polynomial of degree k , then $T(N) = \Theta(N^k)$
- $\log^k N = O(N)$, for any constant k .
- Minimal upper-bound and maximal lower-bound
- Let $L = \lim_{N \rightarrow \infty} f(N) / g(N)$
 - If $L = 0$ then $f(N) = o(g(N))$ (also $O(g(N))$)
 - If $L \neq 0$ then $f(N) = \Theta(g(N))$
 - If $L = \infty$ then $g(N) = o(f(N))$
 - If L doesn't exist, then $f(N)$ and $g(N)$ do not have a relationship

Example: $f(N) = N \log N$, $g(N) = N^{1.5}$

$$\lim_{N \rightarrow \infty} \frac{f(N)}{g(N)} = \lim_{N \rightarrow \infty} \frac{N \log N}{N \sqrt{N}} = \lim_{N \rightarrow \infty} \frac{\log N}{\sqrt{N}} = \lim_{N \rightarrow \infty} \frac{1/N}{\frac{1}{2} N^{-\frac{1}{2}}} = 0$$

$$\Rightarrow f(N) = o(g(N)) \text{ and } f(N) = O(g(N))$$

$$\text{or } N = O(N), \quad \log N = O(\sqrt{N})$$

$$\Rightarrow N \log N = O(N^{1.5})$$

2.2 Computational Model

- Turing machine based
- Simple operations (+, -, X, /, =, ==, ...)
- All operations have the same execution time (one unit per operation)
- Sequential computation
- Ignore complex issues such as memory paging, caching, I/O, compiler, etc.

2.3 Analysis

– Running time analysis

- $T_{worst}(N)$: worst case analysis
- $T_{avg}(N)$: average case analysis
- The implementation of the algorithm should not change the big O s.

– Example: Maximum subsequence sum problem

- The problem: given integers A_1, A_2, \dots, A_N , find the maximum value of

$$\sum_{k=i}^j A_k$$



- Four algorithms with different running time estimates:

$O(N^3)$, $O(N^2)$, $O(N \log N)$, $O(N)$

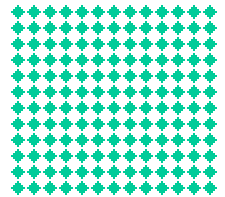
(Textbook, Weiss, pp.46)

2.4 Running Time Calculations

– General rules

- *for loop*: at most the running time of the loop body times the number of iterations
- *nested loop*: the running time of the loop body multiplied by the product of the sizes of all the loops

```
for (i=0; i<n; i++)  
  for (j=0; j<n; j++)  
    k++
```

$$\Rightarrow O(N^2)$$


- *consecutive statement*: adding their running times

```
for (i=0; i<n; i++)  
  a[i]=0;  
for (i=0; i<n; i++)  
  for (j=0; j<n; j++)  
    a[i]+=a[j]+i+j;
```

$$\Rightarrow O(N)$$
$$\Rightarrow O(N^2)$$
$$\Rightarrow O(N^2)$$

- *If/else*: at most the running time of test plus the larger of the running times of the two branches

```
if (condition)  
  S1  
else  
  S2
```


– Recursion

- convert to loops if possible
- running time is a recursive function
- example:

```
long factorial(int n) {  
    if (n <= 1)  
        return 1;  
    else  
        return n * factorial(n-1);  
}
```

- example:

$$f(n) = \begin{cases} 1 & n \leq 1 \\ f(n-1) + f(n-2) & \text{otherwise} \end{cases}$$

```
long fib(int n) {  
    if (n <= 1)  
        return 1;  
    else  
        return fib(n-1) + fib(n-2);  
}
```

$T(N) = T(N-1) + T(N-2) + 2$
 $Fib(N) < (5/3)^N$

– Solutions for the maximum subsequence sum problem

- Algr. 1: exhaustive searching (Fig. 2.5, page 50)
 \Rightarrow running time $T(N) = O(N^3)$
- Algr. 2: (Fig. 2.6, page 52) $\Rightarrow T(N) = O(N^2)$
- Algr. 3: (Fig. 2.7, page 53) $\Rightarrow T(N) = O(N \log N)$
- Algr. 4: (Fig. 2.8, page 55) $\Rightarrow T(N) = O(N)$

```
#include <iostream.h>
```

```
#include "vector.h"
```

```
/* START: Fig02_05.txt */
```

```
/* Cubic maximum contiguous  
subsequence sum algorithm.*/
```

```
int maxSubSum1( const vector<int> & a )
```

```
{
```

```
/* 1*/ int maxSum = 0; O(N3)
```

```
/* 2*/ for( int i = 0; i < a.size(); i++ ) _____
```

```
/* 3*/ for( int j = i; j < a.size(); j++ ) _____  
{
```

```
/* 4*/ int thisSum = 0;
```

```
/* 5*/ for( int k = i; k <= j; k++ ) _____
```

```
/* 6*/ thisSum += a[ k ];
```

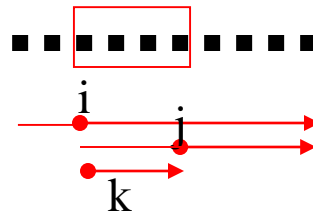
```
/* 7*/ if( thisSum > maxSum )
```

```
/* 8*/ maxSum = thisSum;
```

```
}
```

```
/* 9*/ return maxSum;
```

```
}
```



```
/* START: Fig02_06.txt Quadratic maximum  
contiguous subsequence sum algorithm. */
```

```
int maxSubSum2( const vector<int> & a )
```

```
{
```

```
/* 1*/ int maxSum = 0; O(N2)
```

```
/* 2*/ for( int i = 0; i < a.size(); i++ ) _____
```

```
{
```

```
/* 3*/ int thisSum = 0;
```

```
/* 4*/ for( int j = i; j < a.size(); j++ ) _____
```

```
{
```

```
/* 5*/ thisSum += a[ j ]; _____
```

```
/* 6*/ if( thisSum > maxSum )
```

```
/* 7*/ maxSum = thisSum;
```

```
}
```

```
}
```

```
/* 8*/ return maxSum;
```

```
}
```

```
/** Return maximum of three integers.*/
```

```
int max3( int a, int b, int c )
```

```
{ return a > b ? a > c ? a : c : b > c ? b : c;
```

```
}
```

```
/* START: Fig02_07.txt */
```

```
/* * Driver for divide-and-conquer maximum contiguous
subsequence sum algorithm. */
```

```
/** Recursive maximum contiguous subsequence sum algorithm.
Finds maximum sum in subarray spanning a[left..right].* Does not
attempt to maintain actual best sequence. */
```

```
int maxSubSum3( const vector<int> & a )
```

```
{ return maxSumRec( a, 0, a.size() - 1 );
}
```

```
int maxSumRec( const vector<int> & a, int left, int right ) {
```

```
* 1*/ if( left == right ) // Base case
```

```
* 2*/ if( a[ left ] > 0 )
```

```
* 3*/ return a[ left ];
```

```
else
```

```
* 4*/ return 0;
```

```
* 5*/ int center = ( left + right ) / 2;
```

```
* 6*/ int maxLeftSum = maxSumRec( a, left, center );
```

```
* 7*/ int maxRightSum = maxSumRec( a, center + 1, right );
```

```
* 8*/ int maxLeftBorderSum = 0, leftBorderSum = 0;
```

```
* 9*/ for( int i = center; i >= left; i-- ) {
```

```
* 10*/ leftBorderSum += a[ i ];
```

```
* 11*/ if( leftBorderSum > maxLeftBorderSum )
```

```
* 12*/ maxLeftBorderSum = leftBorderSum;
```

```
}
```

```
* 13*/ int maxRightBorderSum = 0, rightBorderSum = 0;
```

```
* 14*/ for( int j = center + 1; j <= right; j++ ) {
```

```
* 15*/ rightBorderSum += a[ j ];
```

```
* 16*/ if( rightBorderSum > maxRightBorderSum )
```

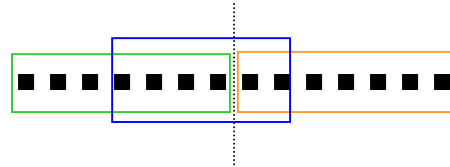
```
* 17*/ maxRightBorderSum = rightBorderSum;
```

```
}
```

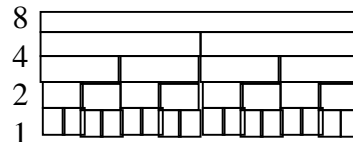
```
* 18*/ return max3( maxLeftSum, maxRightSum,
```

```
* 19*/ maxLeftBorderSum + maxRightBorderSum );
```

```
}
```



$$T(N) = 2T(N/2) + O(N) \\ = O(N \log N)$$



$$\begin{aligned} T(N) &= 2T(N/2) + O(N) \\ T(N/2) &= 2T(N/4) + O(N/2) \\ T(N/4) &= 2T(N/8) + O(N/4) \\ T(N/8) &= 2T(N/16) + O(N/8) \\ &\dots \end{aligned}$$

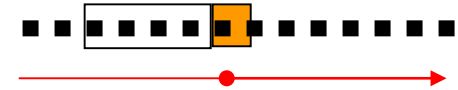
K
N=2^k

$$\begin{aligned} T(4) &= 2T(2) + O(4) \\ T(2) &= 2T(1) + O(2) \end{aligned}$$

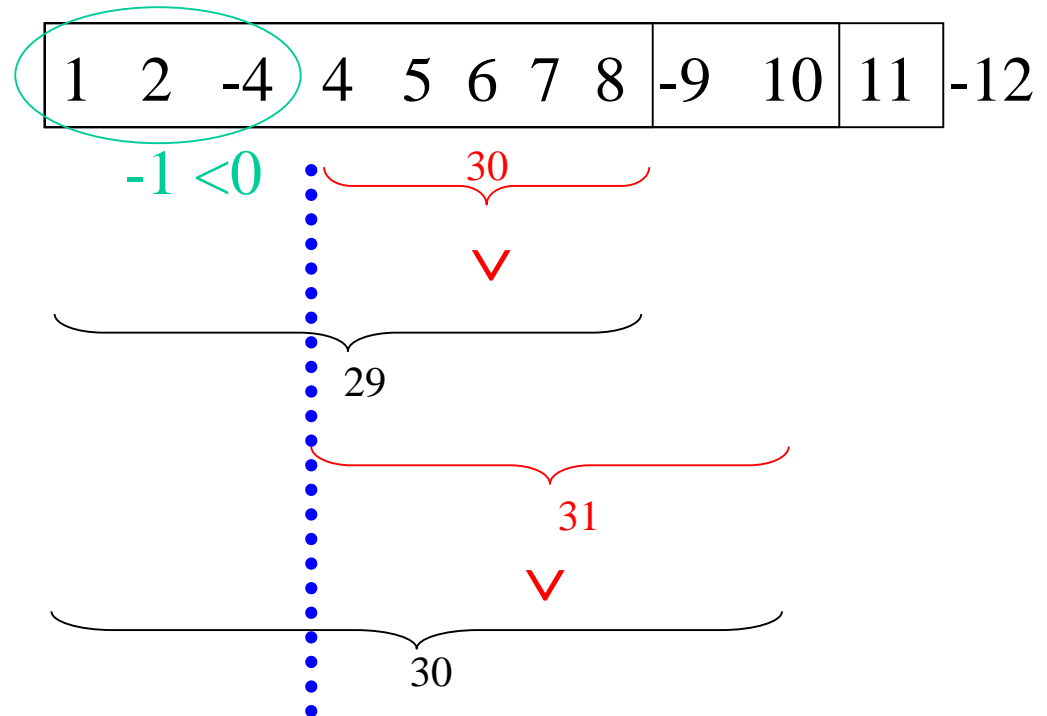
$$\begin{aligned} T(N) &= O(N) \\ &\quad + 2O(N/2) \\ &\quad + 2^2O(N/4) \\ &\quad + \dots \\ &\quad + 2^kO(N/2^k) \\ &= O(N) \log N = N \log N \end{aligned}$$

/* START: Fig02_08.txt Linear-time
maximum contiguous subsequence sum
algorithm. */

$O(N)$

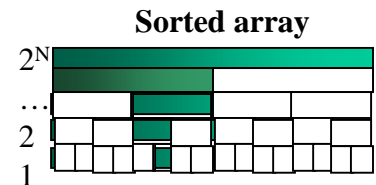


```
int maxSubSum4( const vector<int> & a )
{
    /* 1*/   int maxSum = 0, thisSum = 0;
    /* 2*/   for( int j = 0; j < a.size( ); j++ ) {
    /* 3*/       thisSum += a[ j ];
    /* 4*/       if( thisSum > maxSum )
    /* 5*/           maxSum = thisSum;
    /* 6*/       else if( thisSum < 0 )
    /* 7*/           thisSum = 0;
    }
    /* 8*/   return maxSum;
}
/* END */
```



– Logarithms

- Divide-and-conquer strategy with a constant dividing cost
- Binary search: (Fig. 2.9, page 57) $\Rightarrow T(N) = O(\log N)$
- Euclid's algr: GCD problem (Fig. 2.10, page 58)
- $X^N = X^{(N-1)/2} X^{(N-1)/2} X \Rightarrow T(N) = O(\log N)$



– Checking your analysis

- checking actual program's running time with number of inputs changing as: $N, 2N, 4N, 8N, \dots$, and then measure the running times
- If $T(N) = O(f(N))$, let $r = \frac{T(N)}{f(N)}$ test program with $N, 2N, 4N, \dots$ Inputs.

If $r \rightarrow \text{constant}$, $T(N) = \Theta(f)$

If $r \rightarrow 0$, $T(N) = O(f)$

(Fig. 2.13, page 60)