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# Lecture 04: From Chatbots to Agents

## **&** Learning Objectives

By the end of this lecture, you should be able to:

- Differentiate between traditional chatbots and agentic Al systems.
- Identify the limitations of basic conversational agents.
- Understand the essential features that define autonomous agents.
- Recognize the architectural shift from reactive dialogue to proactive action.

## Key Concepts

### Chatbots vs. Agents

#### Chatbots:

- Designed for turn-based conversation.
- Reactive: respond to user input without long-term goals.
- Typically stateless or short-term memory based.
- · No planning or action beyond replying with text.

#### Agents:

- Goal-driven and capable of initiating actions.
- Maintain memory, use tools, and perform multi-step reasoning.
- Operate over time to achieve complex tasks.
- Can perceive context and make decisions autonomously.

### **Key Agentic Features**

- **Autonomy**: Operate without continuous human intervention.
- **Memory**: Store and retrieve past interactions and facts.
- Tool Use: Call external APIs, databases, or perform computations.
- Planning: Break down tasks into sequential or parallel steps.
- Persistence: Maintain a loop of observation, decision, and action.

### **Required Tools/Libraries**

- LangChain (for exposure to agent architecture)
- OpenAl or Hugging Face models
- No setup required for conceptual understanding

### A Hands-on Exercise: Feature Comparison

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**Goal**: Identify what distinguishes a chatbot from an agent by experimentation.

#### Task:

- 1. Interact with a basic chatbot (e.g., OpenAl's ChatGPT or Hugging Face's basic models).
- 2. Record its behavior in different scenarios:
  - Does it remember facts from earlier?
  - o Can it initiate action or ask clarifying questions?
  - Is it goal-oriented?
- 3. Compare that with an open-source agent (e.g., AutoGPT or LangChain Agent).
- 4. Fill in the following comparison table:

| Capability       | Chatbot | Agentic System |
|------------------|---------|----------------|
| Memory           | ×       | $\checkmark$   |
| Tool use         | ×       |                |
| Planning         | X       |                |
| Multi-step tasks | ×       |                |
| Autonomy         | ×       | $oxed{oxed}$   |

#### Reflection:

- What was the biggest gap between the two systems?
- How does adding memory and tools transform the interaction?